

# Electric Circuits for Physicists

2016

Shingo Katsumoto

2016年度  
電子回路論 第1回

東京大学  
理学部・理学系研究科  
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勝本信吾

# ノート・資料等の置き場



勝本信吾

Shingo Katsumoto



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[「半導体」講義ノート \(2016 May-2016 July\)](#)

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- 研究紹介
- メンバー
- 実験装置
- 投稿
- 出版リスト
- 「半導体の基礎」
- アルバム
- 物性研トップ
- 共同利用

2週に1回簡単な練習問題を出題 → 2週間以内に解答を提出  
TAが採点してコメントをメール送付します  
試験は期末レポート。練習問題と合わせて採点します



# シラバス

1. 電磁場と電子回路
  - 1.1 この講義について
  - 1.2 電子回路とは
  - 1.3 2端子素子
  - 1.4 回路図
  - 1.5 抵抗器
  - 1.6 キャパシタ
  - 1.7 インダクタ
2. 線形回路序論
  - 2.1 線形システムと電子回路
  - 2.2 電源
  - 2.3 回路網
  - 2.4 4端子(2端子対)回路
  - 2.5 端子対回路の諸定理
  - 2.6 双対性
  - 2.7 受動素子と能動素子
3. 伝達関数と周波数応答・過渡応答
  - 3.1 受動素子2端子回路の伝達関数
  - 3.2 2端子受動素子回路
  - 3.3 受動素子回路の過渡応答
4. 増幅回路
  - 4.1 増幅回路と系の制御
  - 4.2 OPアンプ
  - 4.3 トランジスタ
  - 4.4 電場効果トランジスタ
5. 分布定数回路
  - 5.1 伝送路
  - 5.2 伝送路の伝播現象
  - 5.3 S行列(Sパラメタ)
  - 5.4 シュレディンガー方程式とLC伝送路

# シラバス2

- 6. 信号, 雑音, 波形解析
  - 6.1 ゆらぎ
  - 6.2 増幅器の雑音
  - 6.3 変調とアナログ信号伝送
  - 6.4 離散化信号
  
- 7. デジタル信号とデジタル回路
  - 7.1 デジタル信号序論
  - 7.2 論理ゲート
  - 7.3 論理ゲートの実装
  - 7.4 論理演算の回路化と簡単化
  - 7.5 A-D/D-A コンバータ
  - 7.6 デジタルフィルター
  - 7.7 ハードウェア記述言語 : HDL



1. Electromagnetic field and electric circuits
  - 1.1 About this lecture
  - 1.2 What is electric circuit?
  - 1.3 Two-terminal devices
  - 1.4 Circuit diagrams
  - 1.5 Resistors
  - 1.6 Capacitors
  - 1.7 Inductors
2. Introduction to linear circuits
  - 2.1 Linear systems and electric circuits
  - 2.2 Power sources
  - 2.3 Networks
  - 2.4 4-terminal (2-terminal pair) circuits
  - 2.5 Theorems in terminal pair circuits
  - 2.6 Duality
  - 2.7 Passive devices, active devices

3. Transfer function and transient response
  - 3.1 Transfer function of passive two-terminal pair circuits
  - 3.2 Two-terminal passive circuits
  - 3.3 Transient response of passive circuits
4. Amplifiers
  - 4.1 System control and amplifiers
  - 4.2 Operational amplifiers
  - 4.3 Transistors
  - 4.4 Field effect transistors
5. Distributed constant circuits
  - 5.1 Transmission lines
  - 5.2 Propagation through transmission lines
  - 5.3 S matrix (S parameters)
  - 5.4 Schrodinger equation and LC transmission circuit



6. Signal, noise, waveform analysis
  - 6.1 Fluctuation
  - 6.2 Noise from amplifiers
  - 6.3 Modulation and analog signal transfer
  - 6.4 Discrete signal
7. Digital signal and digital circuits
  - 7.1 Introduction to digital signal
  - 7.2 Logic gates
  - 7.3 Logic circuits implementation
  - 7.4 Circuit implementation and simplification of logic operation
  - 7.5 AD/DA converters
  - 7.6 Digital filters
  - 7.7 Language to describe hardware: HDL

# Outline Today

1. Electromagnetic field and electric circuits
  - 1.1 About this lecture
  - 1.2 What is electric circuit?
  - 1.3 Circuit diagrams
  - 1.4 Two-terminal devices
  - 1.5 Resistors
  - 1.6 Capacitors
  - 1.7 Inductors
2. Introduction to linear circuits
  - 2.1 Linear systems and electric circuits



# Ch.1 Electromagnetic field and electric circuits



# For what this lecture is?

Experimentalists:

Knowledges on electric circuit are indispensable.

Purposes:

Understand how circuits work.

Design circuits along research plans

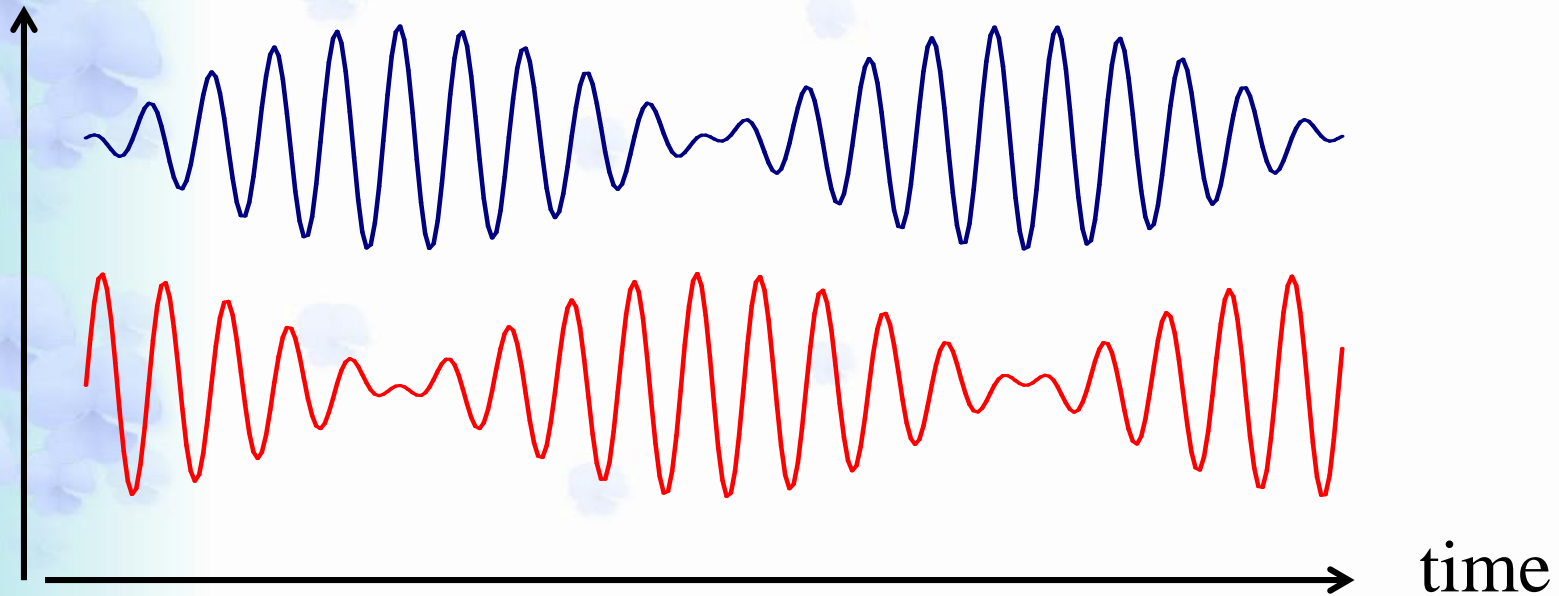
General physicists:

Meta physics

# Coupled pendulum and neutrino oscillation



Pendulum oscillation



# Electric Circuit: A treasure house of concept and language

Electric Circuit

Electromagnetic Field

- Lumped constant Circuit
- Distributed constant Circuit

Signal

- Noise
- Modulation
- Discrete signal

Material Science

- Metal
- Semi-conductor
- Ferromagnet

Linear response

- Transfer function
- Resonance
- Transient response

System stability

- Amplifier
- Feedback
- Nyquist diagram

Analog and digital

- Fourier tr.- z-tr.
- Analog filter - Digital filter



# 1.2 What is electric circuits?: Thunderbolt struck a plane!



# Your answer?

1.



Fell down and crashed

2.



Damaged

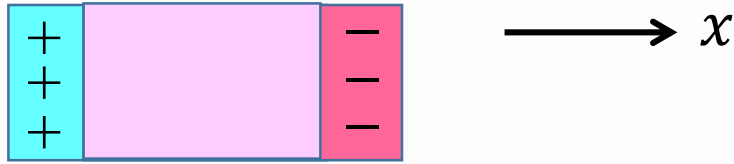
3.



Nothing happened

# Plasma frequency

$$m \frac{d^2 x}{dt^2} = -eE$$



$$E = E_0 e^{-i\omega t}, \quad x = x_0 e^{-i\omega t} \rightarrow m\omega^2 x_0 = eE_0$$

$$\text{Electric polarization: } P = -n e x_0 = -\frac{n e^2 E_0}{m \omega^2}$$

$$\epsilon(\omega) = \frac{D(\omega)}{\epsilon_0 E(\omega)} = 1 + \frac{P(\omega)}{\epsilon_0 E(\omega)} = 1 - \frac{n e^2}{\epsilon_0 m \omega^2} = 1 - \frac{\omega_p^2}{\omega^2}$$

$$\omega_p^2 \equiv \frac{n e^2}{\epsilon_0 m} \quad : \text{ Plasma frequency}$$

$$\text{Cu: } n = 8.5 \times 10^{22} / \text{cc} \quad m^* = 1.3 m_0$$

$$f_p = \omega_p / (2\pi) = 2.3 \times 10^{15} \text{ Hz} \quad \lambda = 130 \text{ nm Near ultra-violet}$$

Metals are super-screening materials!

Equipotential lines

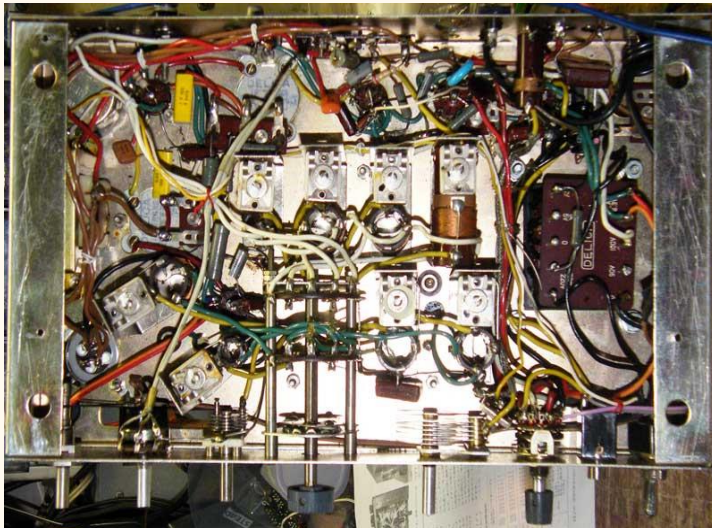
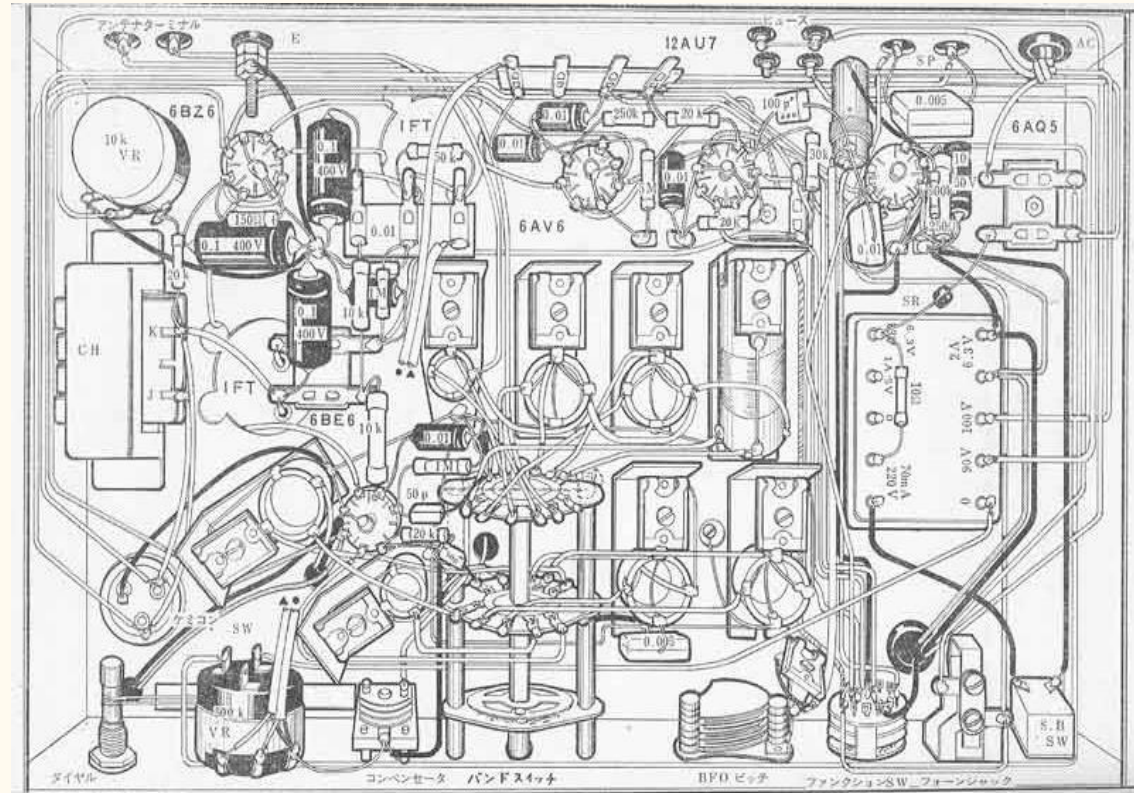


# 1.3 Various circuit diagrams



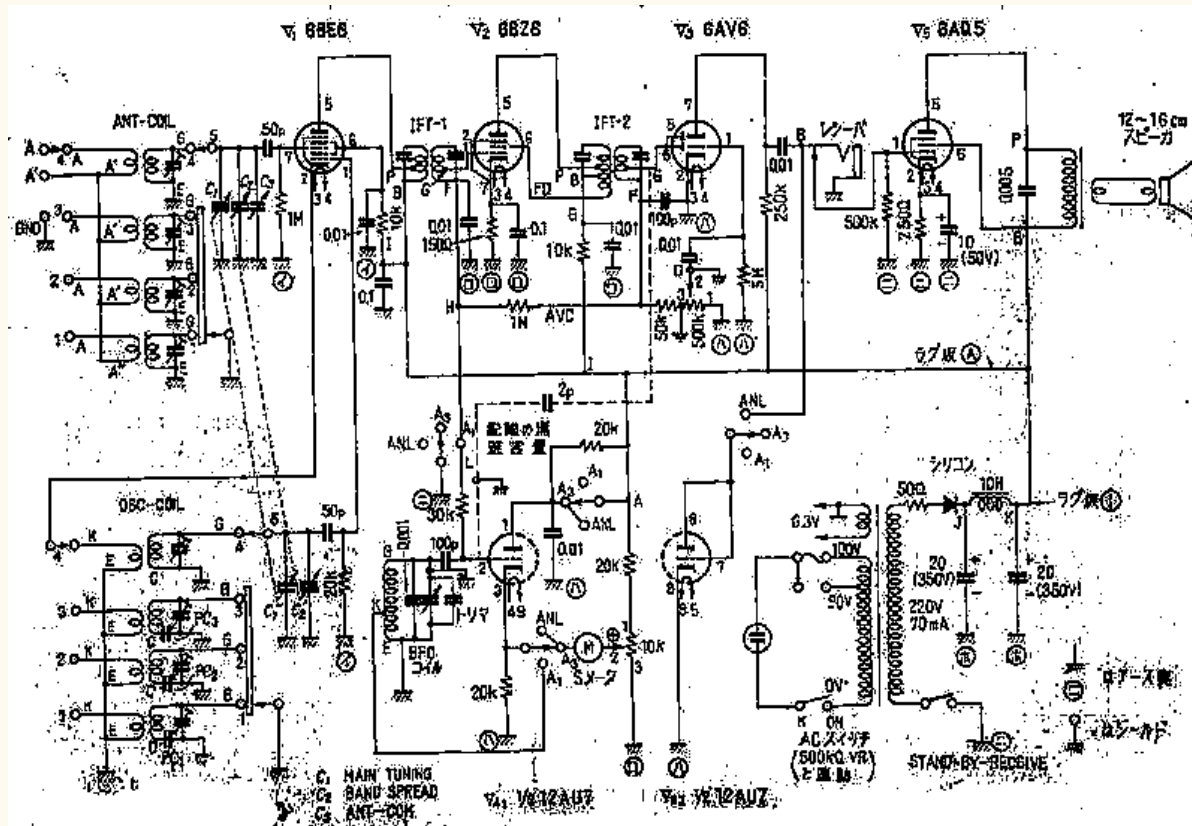
三田無線研究所  
DELICA DX-CS-7

Picture diagram



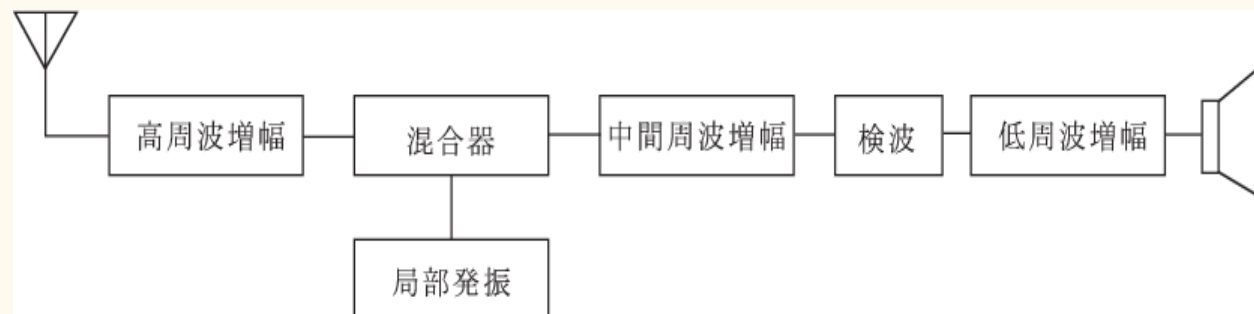


# Various circuit diagrams

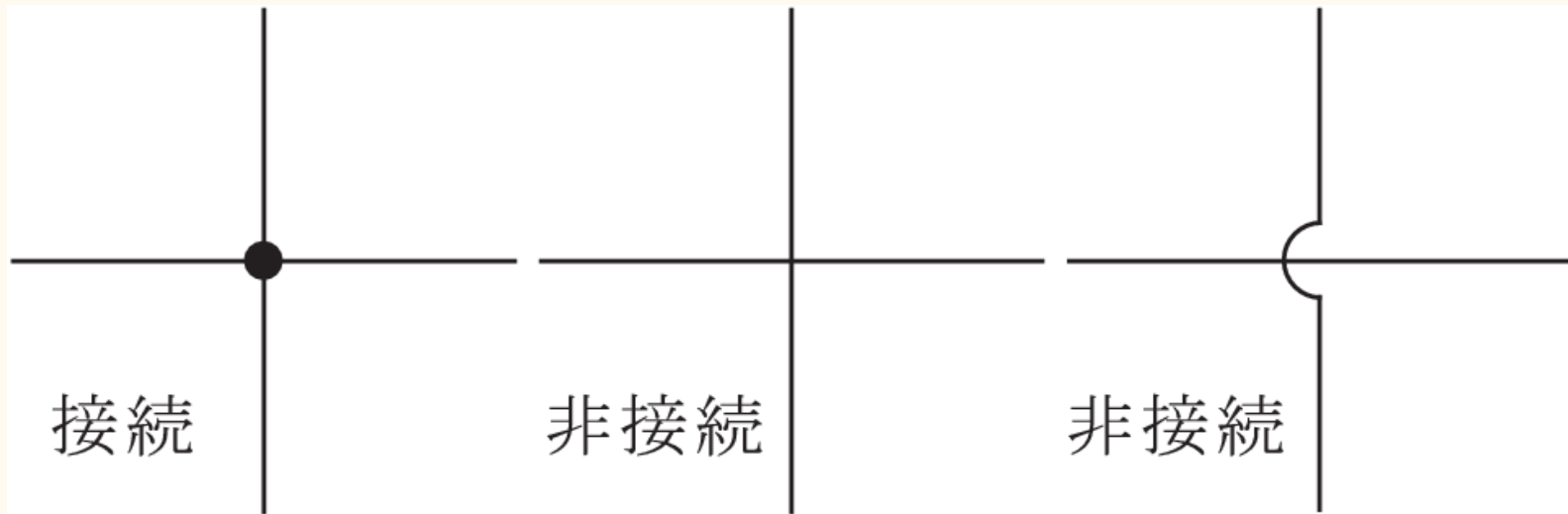


Parts + Wiring  
= Wiring (Circuit) diagram

Block diagram



# Wirings in electric circuits



Connected

Not connected

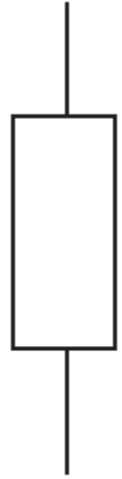
Not connected

Violate electromagnetism theory

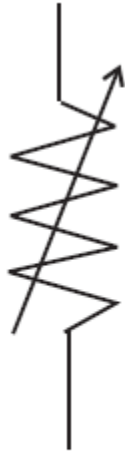
Concept of local electromagnetic field

= Lumped constant circuits (集中定数回路)

# Circuit symbols for two-terminal devices



固定抵抗器



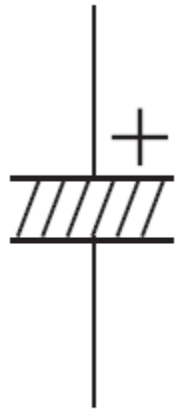
可変抵抗器



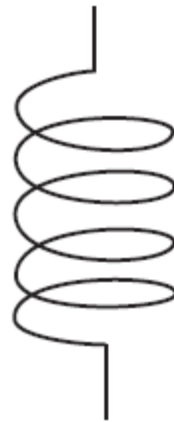
コンデンサ



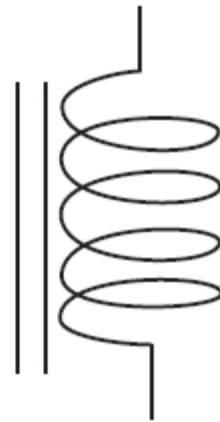
可変  
コンデンサ



極性電解  
コンデンサ

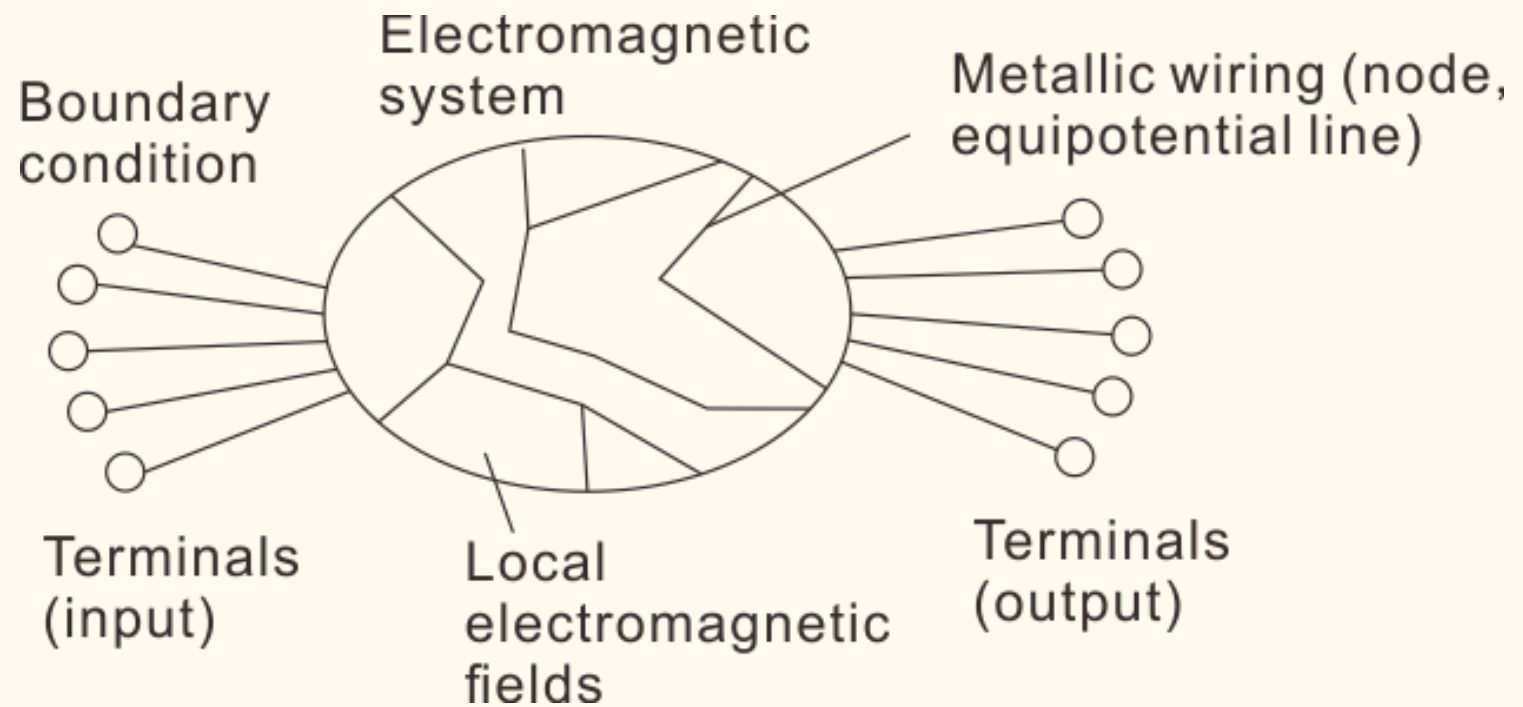


空芯コイル



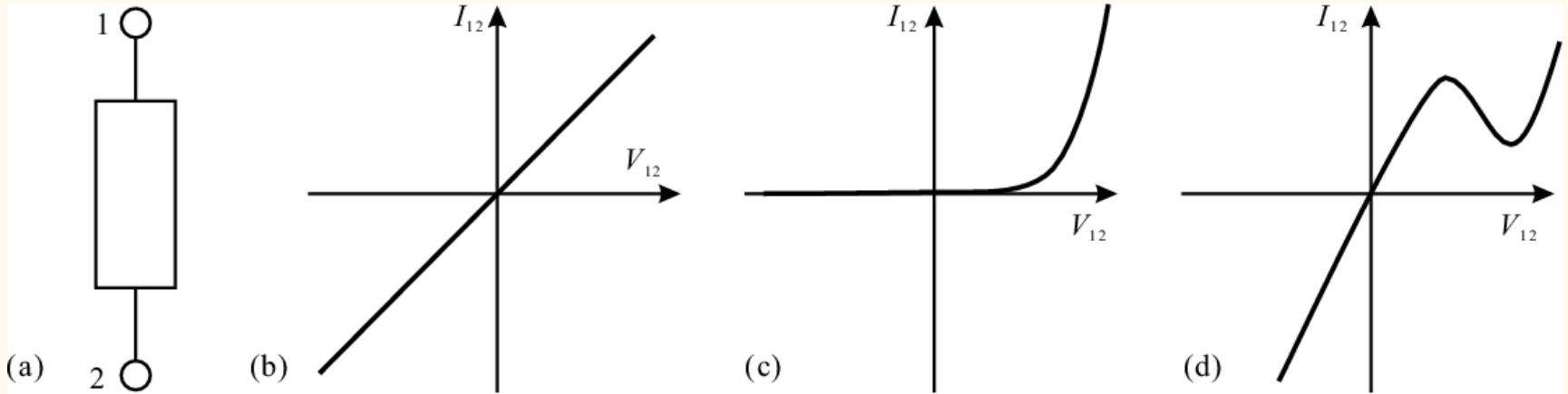
磁性体入り  
コイル

# Basic concepts in electric circuits





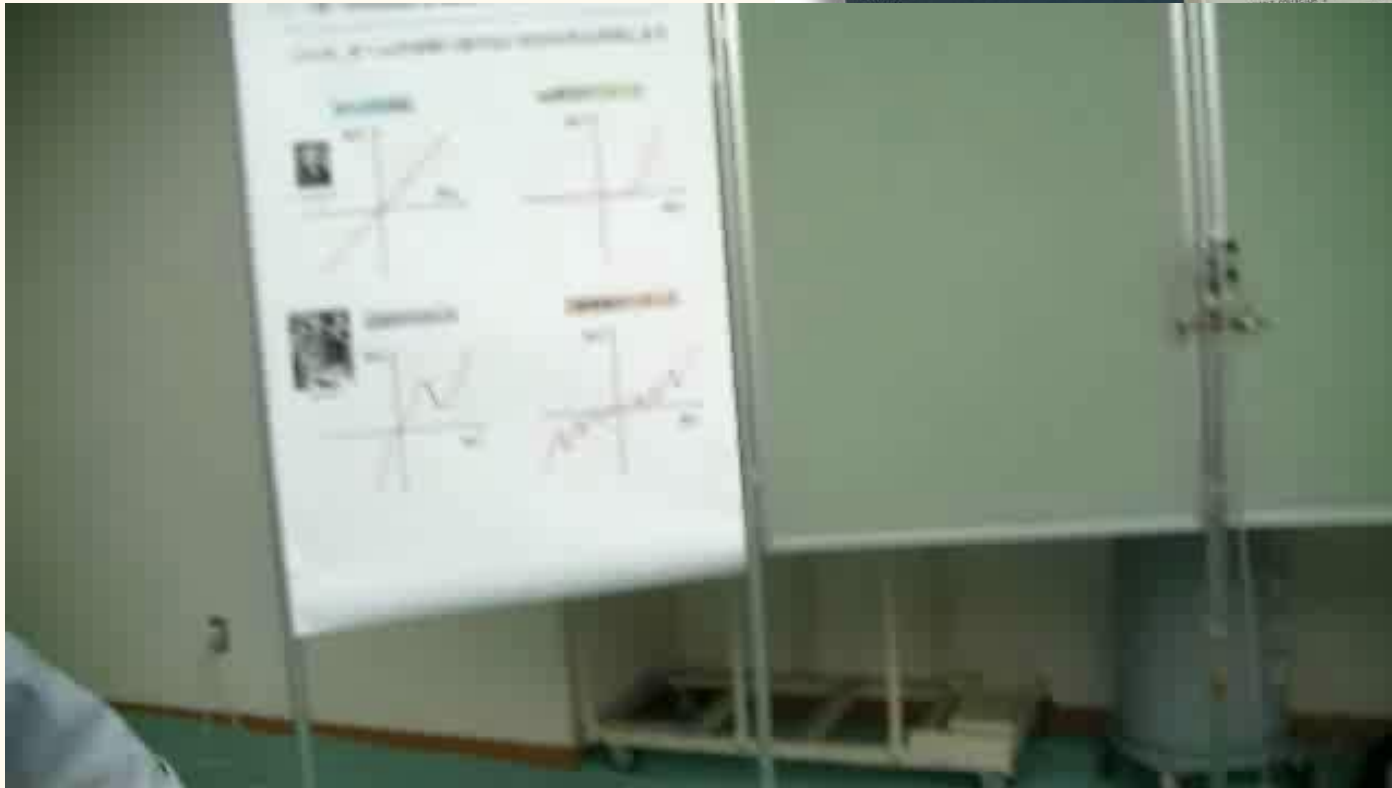
# What is current-voltage characteristics?



Resistor

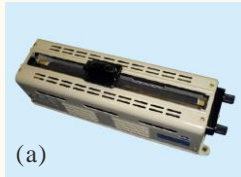
# What is current-voltage characteristics?

Curve tracer



# Variable resistors

Slide



(a)



(b)



(c)

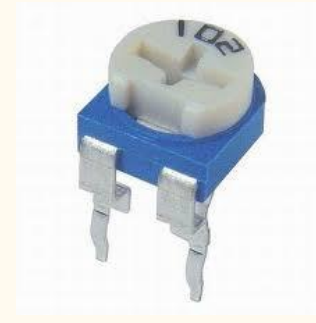
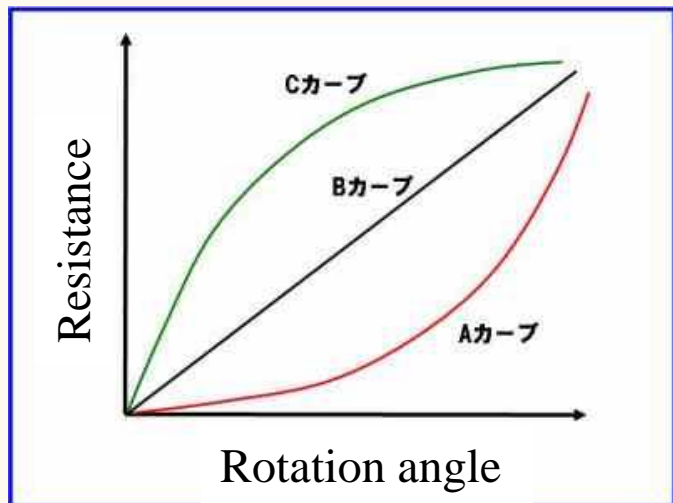


(d)

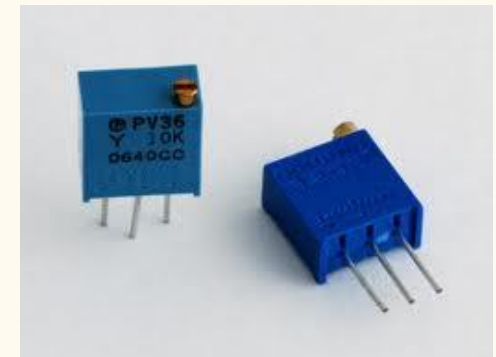
Carbon helical

Helical  
potentiometer

Rotary switch  
potentiometer

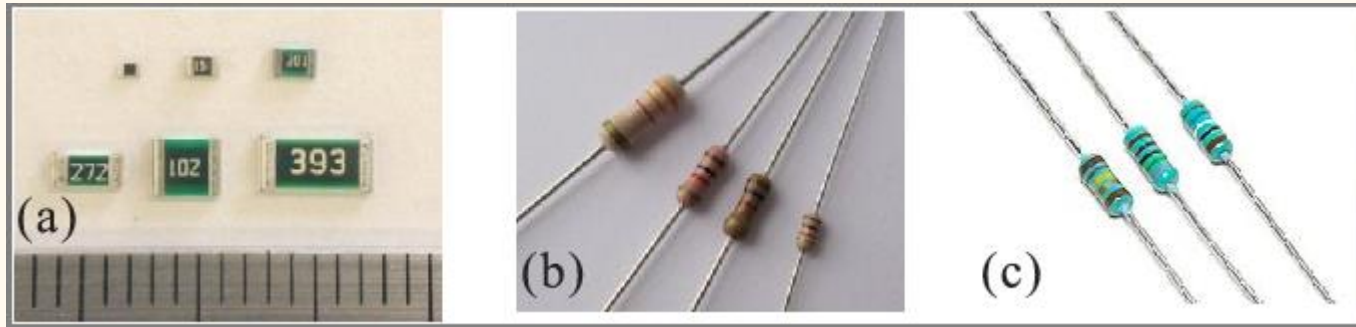


trimmer



Cermet trimmer

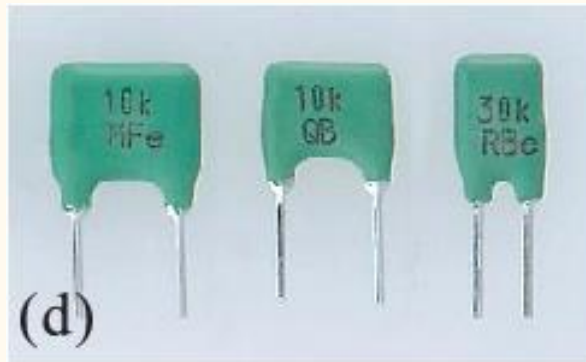
# Fixed resistors



Chip resistors

Carbon film resistors

Metallic film resistors (spiral)



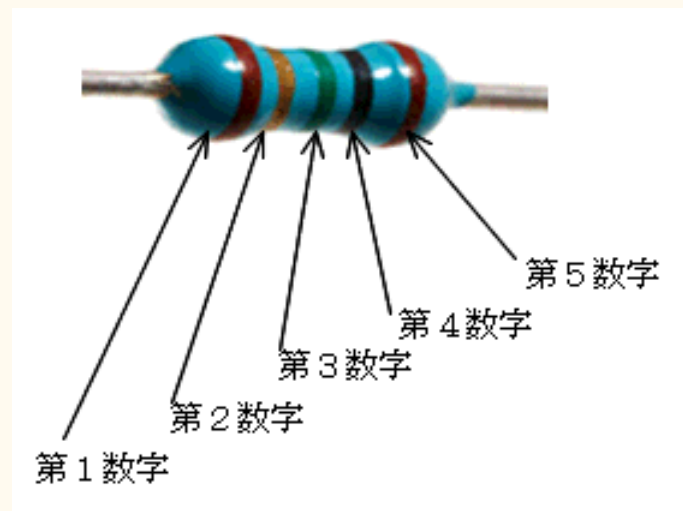
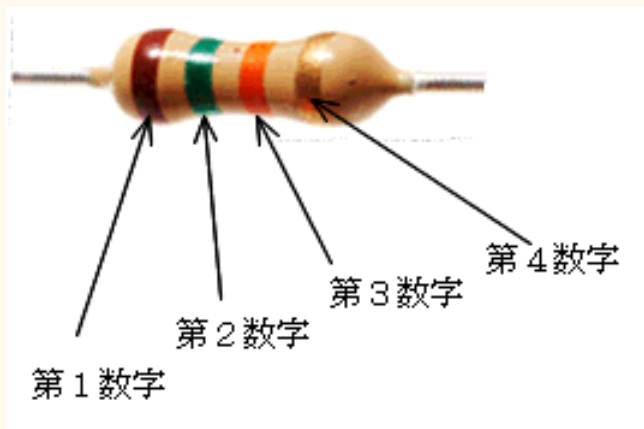
Metallic film resistors (meander)



High power type

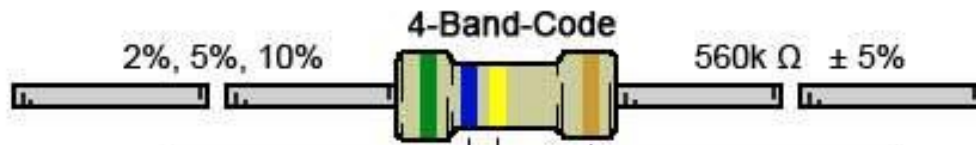


# 抵抗器のカラーコード



色	第1数字	第2数字	第3数字	第4数字	第5数字
黒	0	0	0	$10^0$	X
茶	1	1	1	$10^1$	±1%
赤	2	2	2	$10^2$	±2%
橙	3	3	3	$10^3$	X
黄	4	4	4	$10^4$	X
緑	5	5	5	$10^5$	X
青	6	6	6	$10^6$	X
紫	7	7	7	$10^7$	X
灰	8	8	8	$10^8$	X
白	9	9	9	$10^9$	X
金	X	X	X	$10^{-1}$	±5%
銀	X	X	X	$10^{-2}$	±10%
無色	X	X	X	X	±20%

# Color code for resistors



COLOR	1 <sup>ST</sup> BAND	2 <sup>ND</sup> BAND	3 <sup>RD</sup> BAND	MULTIPLIER	TOLERANCE
Black	0	0	0	1 $\Omega$	
Brown	1	1	1	10 $\Omega$	$\pm$ 1% (F)
Red	2	2	2	100 $\Omega$	$\pm$ 2% (G)
Orange	3	3	3	1K $\Omega$	
Yellow	4	4	4	10K $\Omega$	
Green	5	5	5	100K $\Omega$	$\pm$ 0.5% (D)
Blue	6	6	6	1M $\Omega$	$\pm$ 0.25% (C)
Violet	7	7	7	10M $\Omega$	$\pm$ 0.10% (B)
Grey	8	8	8		$\pm$ 0.05%
White	9	9	9		
Gold				0.1 $\Omega$	$\pm$ 5% (J)
Silver				0.01 $\Omega$	$\pm$ 10% (K)



Big  
boys  
race  
our  
young  
girls  
but  
Violet  
generally  
wins.

# Variable capacitors

$$C = \epsilon\epsilon_0 \frac{S}{d}$$



(a)

Steatite



(b)

Tandem



(c)

Poly-Ethylene



(d)

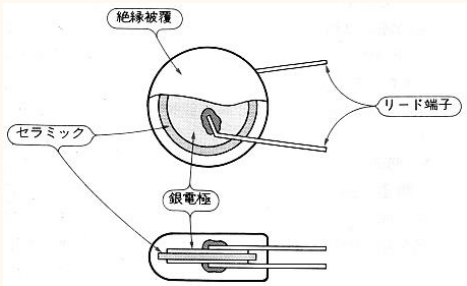
Ceramic

Air capacitor

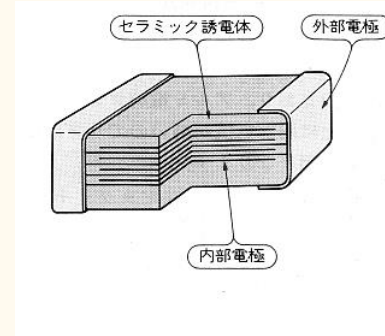
# Fixed capacitors

## Ceramic capacitors

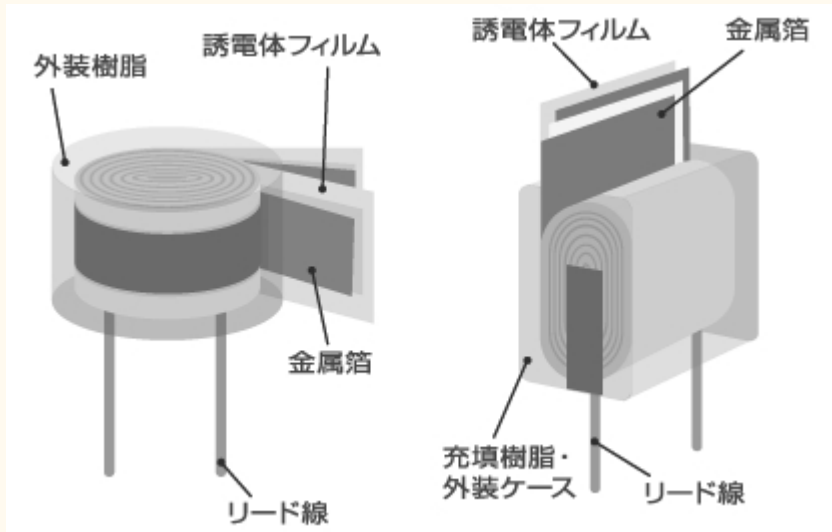
### Single disk pair type



### Stacked type

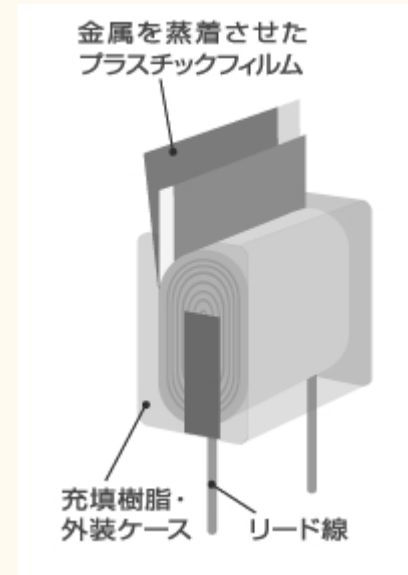


## Film capacitors



誘導

無誘導



蒸着無誘導

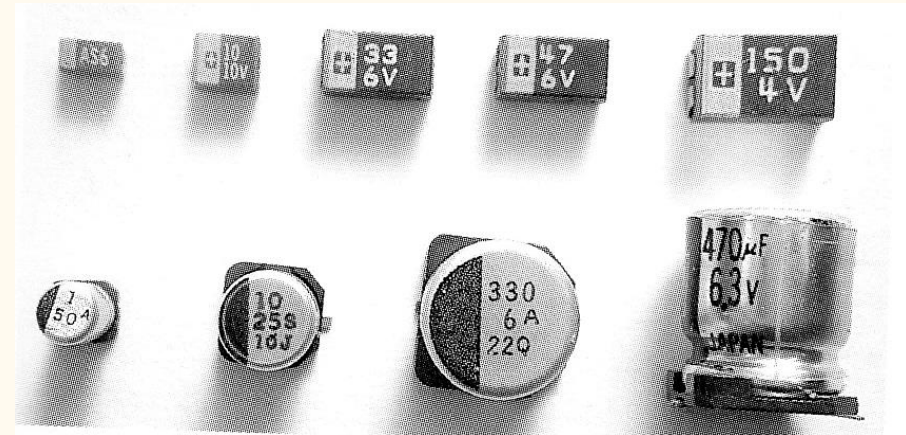
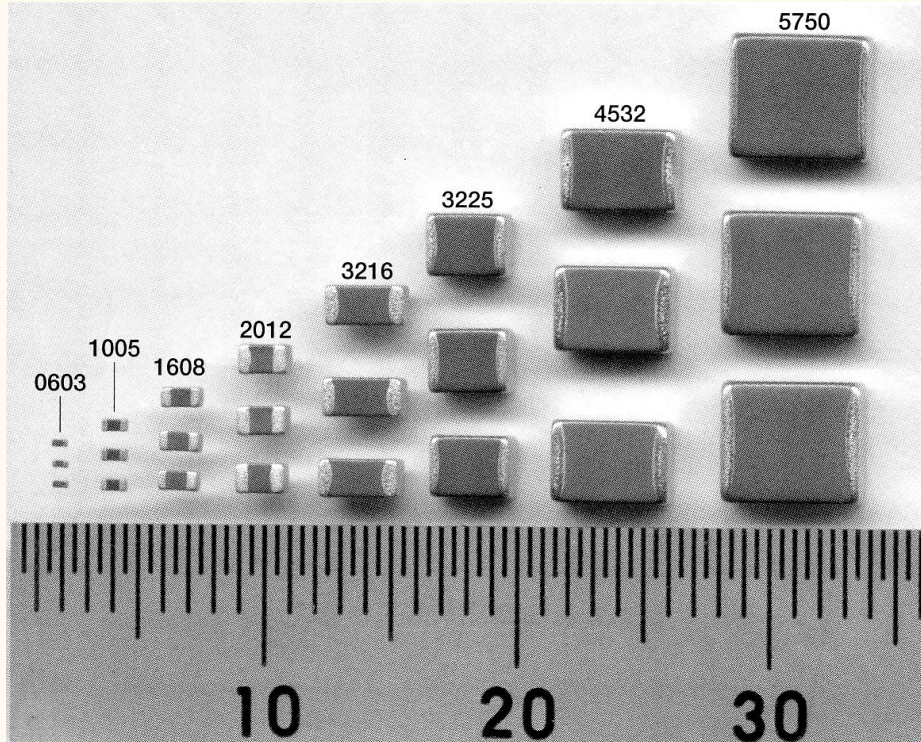








# Surface mount chip capacitors

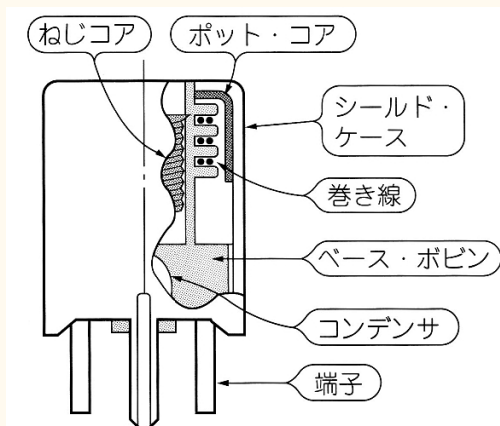


# Variable inductors

$$L = K \times \mu \frac{N^2}{l} S = K \times \mu n N S$$

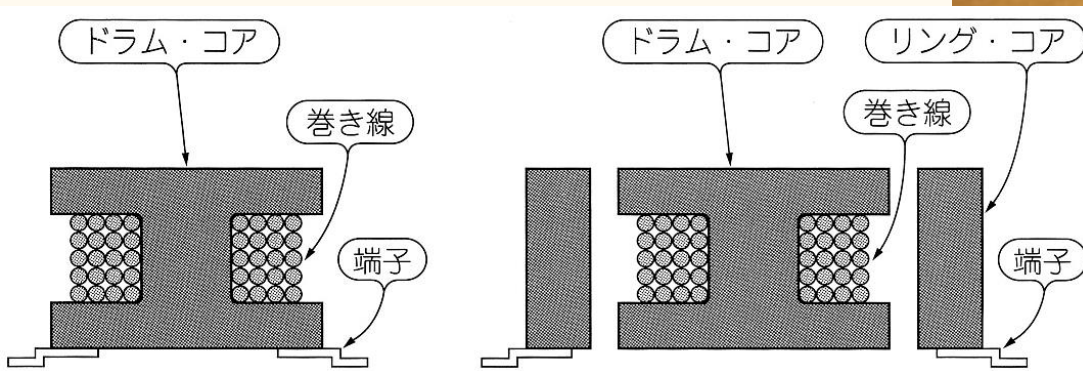
$$K(\text{Nagaoka coef.}) = \frac{4}{3\pi\sqrt{1-k^2}} \left[ \frac{1-k^2}{k^2} K(k) - \frac{1-2k^2}{k^2} E(k) - k \right]$$

$$\frac{L}{2a} = \frac{\sqrt{1-k^2}}{k}$$



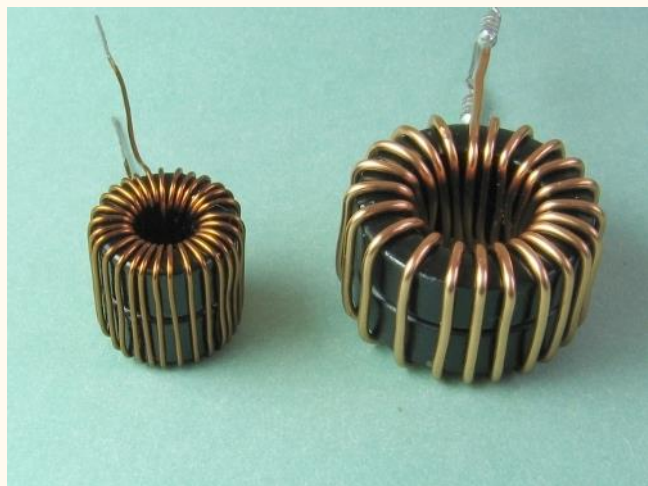


# Fixed inductors

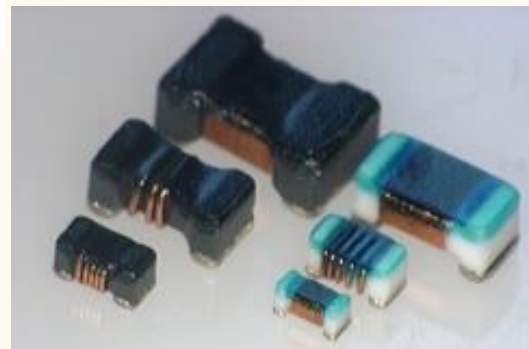


Open flux path

Closed flux path



Toroidal coil



Chip inductor



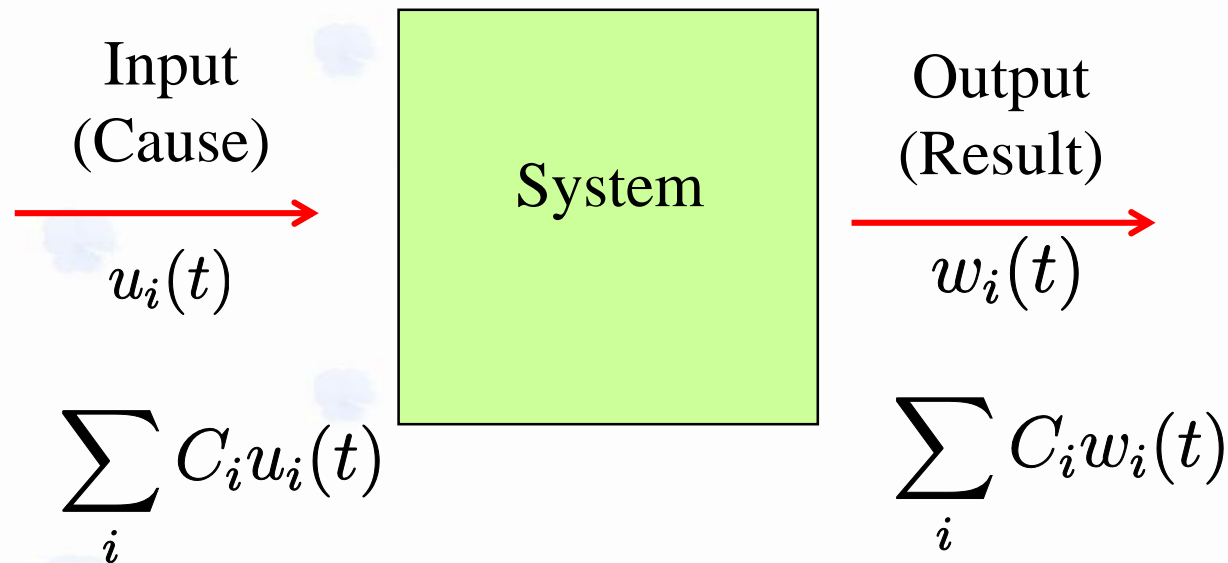


# Ch.2 Introduction to linear circuits

# 2.1 Linear system and electric circuit

## 2.1.1 What is linear system?

$$f(C_1x_1 + C_2x_2) = C_1f(x_1) + C_2f(x_2)$$





# Linear system: definition

$$w(t) = \mathcal{R}\{u(t)\} \quad : \text{Response}$$

Requirements

Invariance:  $\forall t_1 \quad w(t - t_1) = \mathcal{R}\{u(t - t_1)\}$

Causality:  $u(t) = 0 \ (t < t_1) \rightarrow w(t) = 0 \ (t < t_1)$

**Principle of superposition:**

$$\forall C_1, C_2 \in C, \quad \mathcal{R}\{C_1 u_1(t) + C_2 u_2(t)\} = C_1 w_1(t) + C_2 w_2(t)$$

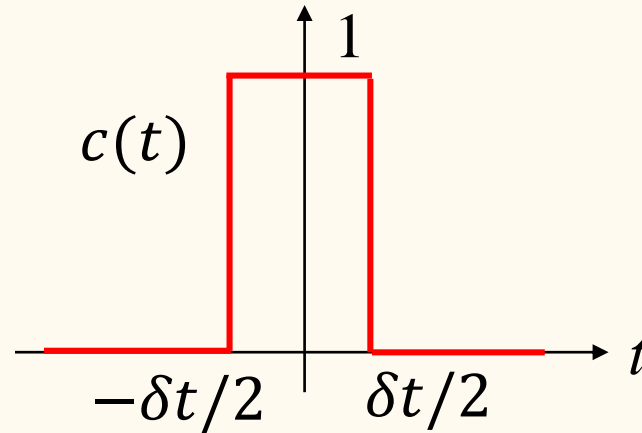
$$\mathcal{R}\left\{\sum_i C_i u_i(t)\right\} = \sum_i C_i w_i(t)$$

$$\mathcal{R}\left\{\int_{-\infty}^{\infty} c(q) u(q, t) dq\right\} = \int_{-\infty}^{\infty} c(q) \mathcal{R}\{u(q, t)\} dq$$

# Transfer function

Variable  $q \rightarrow$  time  $t$

$$c(t) = \begin{cases} 1 & |t| \leq \delta t/2, \\ 0 & \text{others} \end{cases}$$



$$u(t) = \sum_i u(t_i) c(t - t_i) \quad \rightarrow \quad u(t) = \int_{-\infty}^{\infty} dt' u(t') c'(t - t')$$
$$c'(t - t') = \delta(t - t')$$

$$w(t) = \mathcal{R}\{u(t)\} = \mathcal{R}\left\{ \int_{-\infty}^{\infty} u(t') \delta(t - t') dt' \right\}$$
$$= \int_{-\infty}^{\infty} u(t') \mathcal{R}\{\delta(t - t')\} dt' = \int_{-\infty}^{\infty} u(t') \xi(t, t') dt'$$

# Transfer function (Impulse response)

$\xi(t, t') \equiv \mathcal{R}\{\delta(t - t')\}$  : Impulse response, weight function

Invariance  $\rightarrow \xi(t, t_1) = \xi(t - t_1)$

$$w(t) = \int_{-\infty}^{\infty} u(t')\xi(t - t')dt' = \int_{-\infty}^{\infty} u(t - t')\xi(t')dt'$$

Convolution

Fourier transform:

$$X(\omega) = \int_{-\infty}^{\infty} x(t)e^{-i\omega t}dt, \quad x(t) = \int_{-\infty}^{\infty} X(\omega)e^{i\omega t}\frac{d\omega}{2\pi}$$

$$W(\omega) = U(\omega)\underline{\Xi(\omega)}$$

Transfer function



# Summary

## 1. Electromagnetic field and electric circuits

Metals: super screening material

Circuit diagrams

Local electromagnetic field

## 2. Introduction to linear circuits

Transfer function

# 電子回路論 第2回

理学系研究科・物理専攻 (物性研究所) 勝本信吾

2016.10.5

## Electric Circuits No.2

Shingo Katumoto



# ノート・資料等の置き場

<http://kats.issp.u-tokyo.ac.jp/kats/>



勝本信吾

Shingo Katsumoto



[自己紹介](#)

現在の研究テーマ

[論文リスト](#)

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2週に1回簡単な練習問題を出題 → 2週間以内に解答を提出

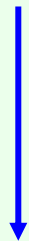
試験は期末レポート。練習問題と合わせて採点します

## Ch.1 Electromagnetic field and electric circuits

### Metals: super-screening material

(but not superconducting. The difference is important in designing superconducting circuits.)

### Local electromagnetic field



→ **Lumped constant circuits** (集中定数回路)

local magnetic fields (parts) are connected by

metallic wires → **Circuit diagrams**

### Resistors, Capacitors and Inductors

## Ch.2 Introduction to linear response systems

# Outline Today

1. Transfer function (伝達関数) (continued)
2. Representative passive devices in the linear treatment
3. Impedance, admittance and other parameters in the linear treatment
4. Power sources
5. Circuit networks
6. Four terminal (two terminal-pair) circuits
7. Circuit theorems

# Linear response: Transfer function

response      input

$$\begin{aligned} \underline{w(t)} &= \mathcal{R}\{\underline{u(t)}\} = \mathcal{R}\left\{\int_{-\infty}^{\infty} u(t')\delta(t-t')dt'\right\} = \int_{-\infty}^{\infty} u(t')\underline{\mathcal{R}\{\delta(t-t')\}}dt' \\ &= \int_{-\infty}^{\infty} u(t')\xi(t-t')dt' = \int_{-\infty}^{\infty} u(t-t')\xi(t')dt' \end{aligned}$$

impulse response

$$X(\omega) = \int_{-\infty}^{\infty} x(t)e^{-i\omega t}dt \quad W(\omega) = U(\omega)\Xi(\omega)$$

Transfer function

Laplace:

$$X(s) = \int_0^{\infty} e^{-st}x(t)dt \quad W(s) = U(s)\Xi(s)$$

Expansion to the complex plane:  $s \rightarrow \sigma + i\omega$

On the imaginary axis (the frequency space)

$$W(i\omega) = U(i\omega)\Xi(i\omega)$$

# Impedance

Current to voltage

$$V_{12} = \hat{A}I_{12} \quad \left\{ \begin{array}{ll} V_{12} = RI_{12} & \text{resistor} \\ V_{12} = \frac{q(t)}{C} = \frac{1}{C} \int^t I_{12}(t') dt' & \text{capacitor} \\ V_{12} = L \frac{dI_{12}}{dt} & \text{inductor} \end{array} \right.$$

$$\Xi(i\omega) = \left\{ \begin{array}{ll} \int_{-\infty}^{\infty} e^{-st} [R\delta(t)] dt = R & \text{resistor} \\ \int_{-\infty}^{\infty} e^{-i\omega t} \left[ \frac{1}{C} \int^t \delta(t') dt' \right] dt = \frac{1}{i\omega C} & \text{capacitor} \\ \int_{-\infty}^{\infty} e^{-st} \left[ L \frac{d}{dt} \delta(t) \right] dt = i\omega L & \text{inductor} \end{array} \right.$$



Impedance  $Z(i\omega)$



Voltage to current

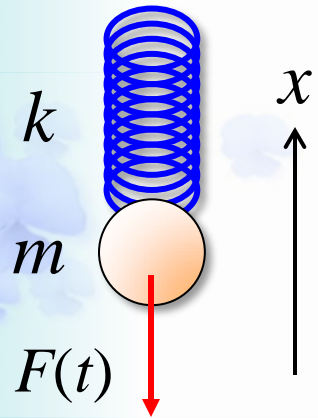
$$\mathcal{J}(i\omega) = Y(i\omega)\mathcal{V}(i\omega)$$

Admittance  $Y(i\omega)$

$$Y(i\omega) = \frac{1}{Z(i\omega)}$$

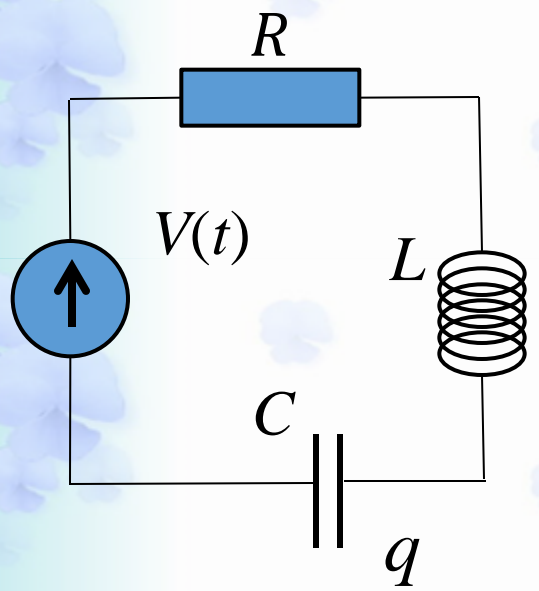
# Example of equivalent circuit 「等価回路」の例

Spring pendulum (ばね振り子)



$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = F(t)$$

RLC circuit with electromotive force (電源を接続したRLC回路)



$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = V(t)$$

Parallelism

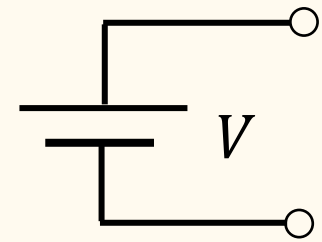
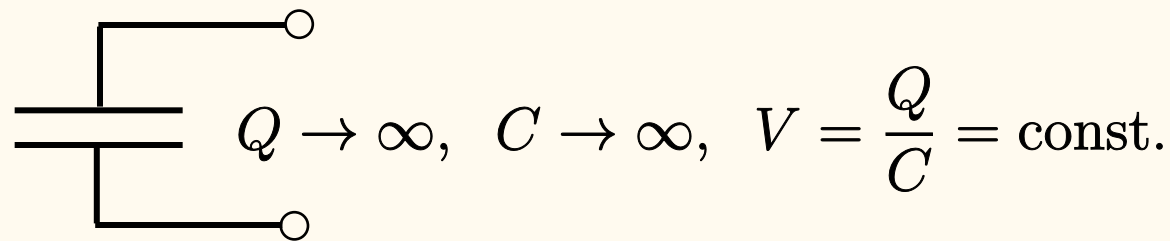
並行論

## 2.2 Power sources

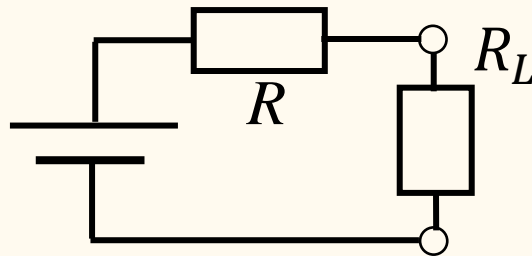
An active device: electric power source, electromotive force

Realistic power source: ideal power source + non-ideal factors

Ideal voltage source



Voltage source  
+resistor

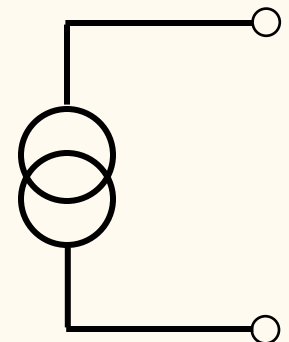
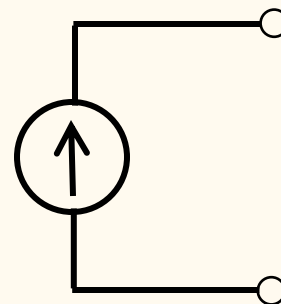


$$J = \frac{V}{R + R_L}$$

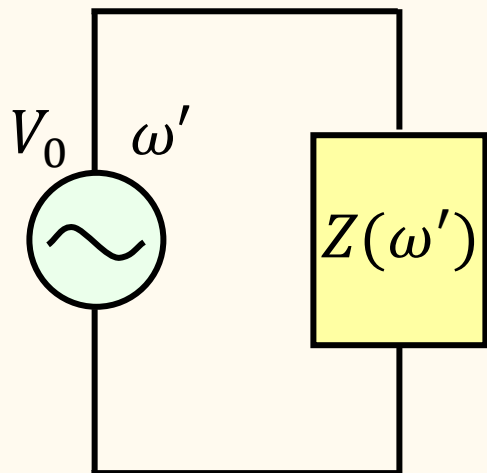
$$V_{out} = \frac{R_L}{R_L + R} V$$

Ideal current source

$$R \rightarrow \infty, V \rightarrow \infty, J = \frac{V}{R} = \text{const.}$$



# Power consumption



Energy dissipation per unit time:  $P = VJ$

Electric power consumption

$$V(\omega', t) = V_0 e^{i\omega' t}$$

$$\mathcal{V}(i\omega) = \mathcal{F}\{V\} = 2\pi V_0 \delta(\omega - \omega')$$

$$J(\omega', t) = 2\pi \int_{-\infty}^{\infty} \frac{V_0}{Z(i\omega)} \delta(\omega - \omega') e^{i\omega t} \frac{d\omega}{2\pi} = \frac{V_0}{Z(i\omega')} e^{i\omega' t} = \frac{V(\omega', t)}{Z(i\omega')}$$

$$V = V_0 \cos \omega' t \quad W(\omega', t) = V(\omega', t)J(\omega', t) = V_0^2 \cos^2 \omega' t / Z(\omega')$$

Complex instantaneous power

$$\bar{W}(\omega') = \frac{V_0^2}{2Z(\omega')} \quad P(\omega') \equiv \text{Re}[\bar{W}(\omega')]$$

$$Q(\omega') \equiv \text{Im}[\bar{W}(\omega')]$$

Effective power  
(有効電力)

Reactive power  
(無効電力)



# Power consumption (2)

$|\overline{W}(\omega')|$  Apparent power (皮相電力)

$$I_M \equiv \frac{\operatorname{Re}[\overline{W}(\omega')]}{|\overline{W}(\omega')|} = \cos [\arg(\overline{W}(\omega'))] \equiv \cos \phi$$

Moment (力率)

$\phi$ : Phase shift between voltage and current

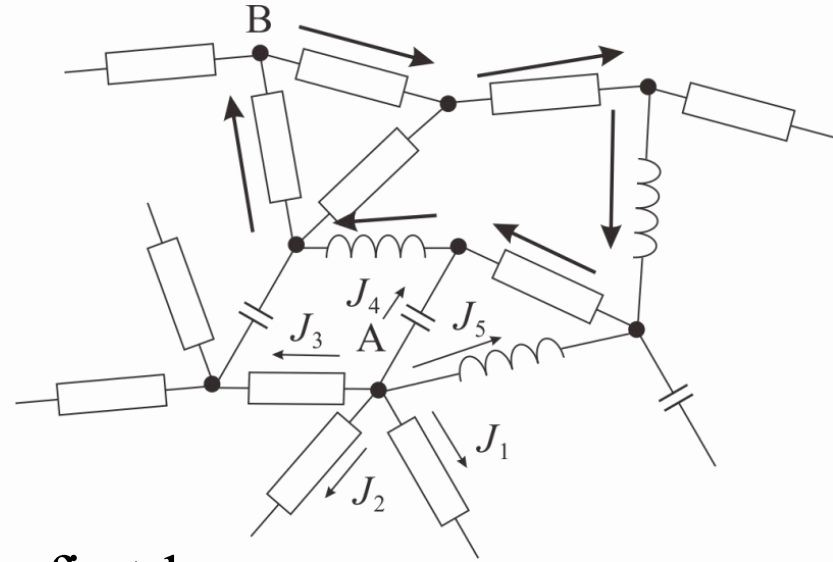
$$\overline{W}(\omega') = |\overline{W}(\omega')|e^{i\phi} \quad : \text{generally holds}$$

$$\overline{W}(\omega') = V^*(\omega')J(\omega')$$

$$W = P = \frac{V_0^2}{2R} \quad \frac{V_0}{\sqrt{2}} \quad : \text{effective value}$$

## 2.3 Circuit network

### 2.3.1 Kirchhoff's law



At all nodes  $\sum_i J_i = 0$  Kirchhoff's first law

↑ Charge conservation  $\frac{\partial \rho}{\partial t} + \text{div} \mathbf{J} = 0$   
 $\frac{\partial \rho}{\partial t}$   
 $= 0$

For all looping paths  $\sum_j V_j = 0$  Kirchhoff's second law

↑ Single-valuedness of electric potential

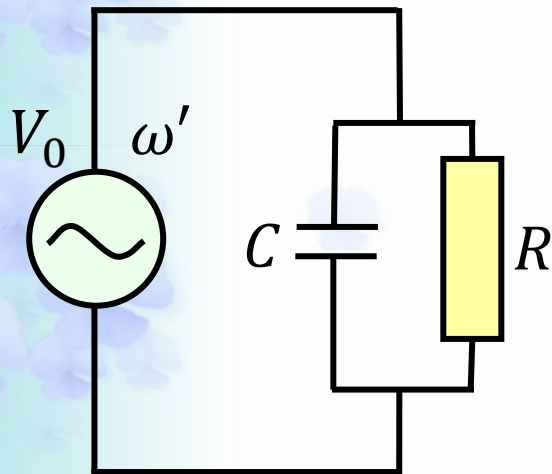
## 2.3 Circuit network (2)

From Kirchhoff's law, synthetic admittance and impedance are

for parallel connection: 
$$Y_{\text{tot}} = \sum_{i=1}^n Y_i, \quad Z_{\text{tot}} = \left( \sum_{i=1}^n Z_i^{-1} \right)^{-1}$$

for series connection: 
$$Y_{\text{tot}} = \left( \sum_{i=1}^n Y_i^{-1} \right)^{-1}, \quad Z_{\text{tot}} = \sum_{i=1}^n Z_i$$

Ex.)



$$Z(i\omega) = \left( \frac{1}{R} + i\omega C \right)^{-1}, \quad Y(i\omega) = \frac{1}{R} + i\omega C$$

$$P(\omega) = \frac{V_0^2}{R} \cos^2 \omega t, \quad Q(\omega) = \omega C V_0^2 \cos^2 \omega t$$

$$\frac{P(\omega)}{Q(\omega)} = \frac{1}{\omega C R} = \tan \delta \quad : \text{Dissipation factor}$$

## 2.3.3 Superposition theorem

Network: node, (directional) branch : directional graph (digraph)

All the branches: electromotive force  $E_i$ , resistance  $R_i$

$$A\{(R)\} \begin{pmatrix} J_1 \\ \vdots \\ J_m \end{pmatrix} = \begin{pmatrix} E_1 \\ \vdots \\ E_m \end{pmatrix} \quad \mathbf{R} = \begin{pmatrix} R_1 \\ \vdots \\ R_m \end{pmatrix}$$

Superposition theorem:

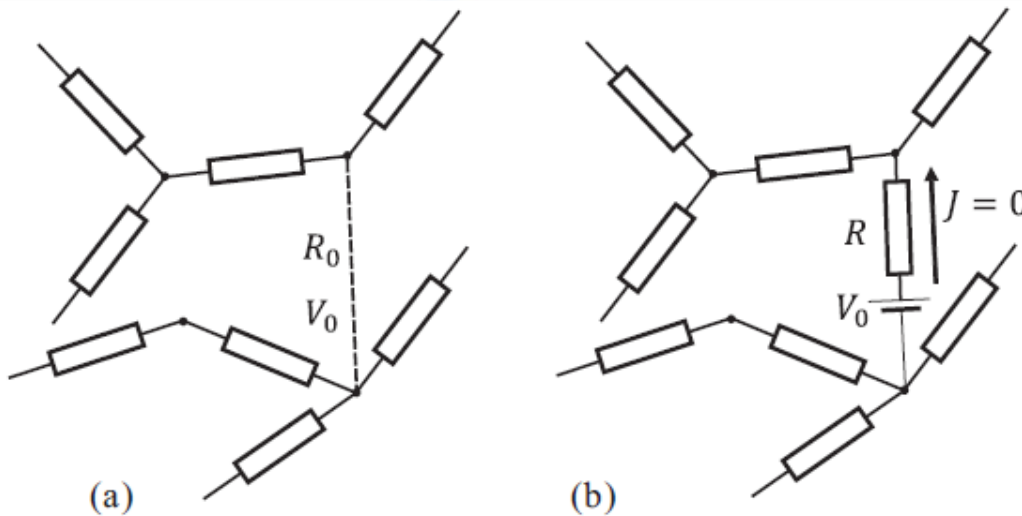
The total current distribution is the superposition of those for single electromotive forces.



## 2.3.4 Ho (鳳) – Thevenin's theorem

Pick up two nodes in the network under consideration. The voltage between these two nodes is  $V_0$ . Set all the electromotive forces to zero and measure the resistance between the two nodes. The result is  $R_0$ . Now connect the two nodes with resistance  $R$  and reset the electromotive forces to the original values. Then the current through resistance  $R$  is

$$J = V_0 / (R + R_0)$$



## 2.3.5 Tellegen's theorem

$i = 1, \dots, n$ : index of nodes,  $j = 1, \dots, m$ : index of branches

$$a_{ij} = \begin{cases} 1 & : i \text{ is the start of } j, \\ -1 & : i \text{ is the end of } j, \\ 0 & : \text{others} \end{cases} \quad \text{incidence matrix}$$

$$\forall j : \sum_{i=1}^n a_{ij} = 0 \quad : \text{redundancy in } \{a_{ij}\}$$

$\rightarrow (n - 1) \times m$  matrix  $D$  : irreducible incidence matrix

Kirchhoff's first law:  $D\mathbf{J} = 0$   $J_j$ : current along branch  $j$

$\mathbf{W}$ :  $W_i$  electrostatic potential of node  $i$ ,  $\mathbf{V}$ :  $V_j$  voltage across branch  $j$

$$i \bullet \xrightarrow{j} \bullet k \quad V_j = W_i - W_k = a_{ij}W_i - a_{kj}W_k$$

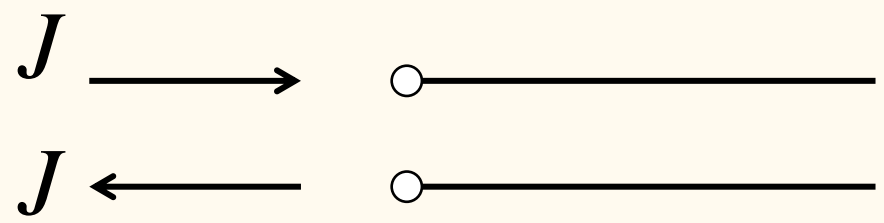
$$\mathbf{V} = {}^t\mathcal{D}\mathbf{W} \quad ({}^t\mathcal{D}: \text{transpose}) \quad (\text{Kirchhoff's second law})$$

$$\sum_{i=1}^m V_i J_i = ({}^t\mathcal{D}\mathbf{W}) \cdot \mathbf{J} = {}^t\mathbf{W}\mathcal{D}\mathbf{J} = 0 \quad \mathbf{V} \perp \mathbf{J}$$

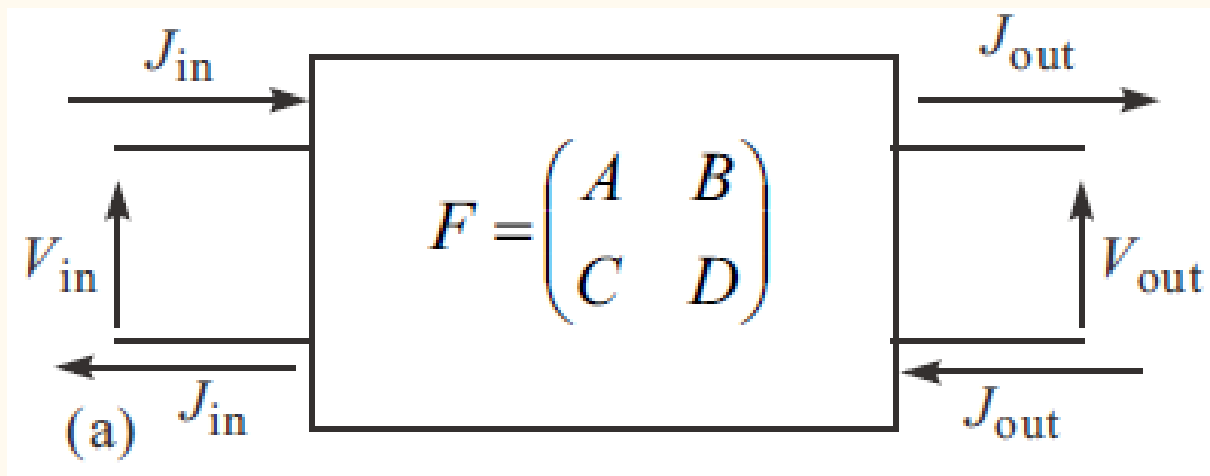
# 4-terminal (2-terminal pair) circuits 4端子回路

Terminal pair (端子对)

Current: circulation, no net current

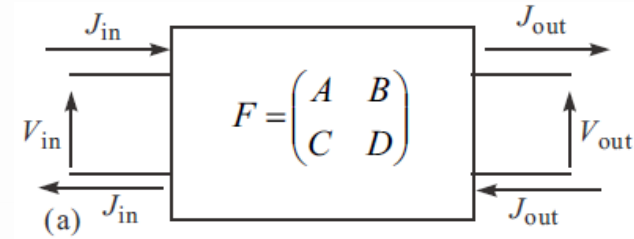


2-terminal pair (4-terminal) circuit



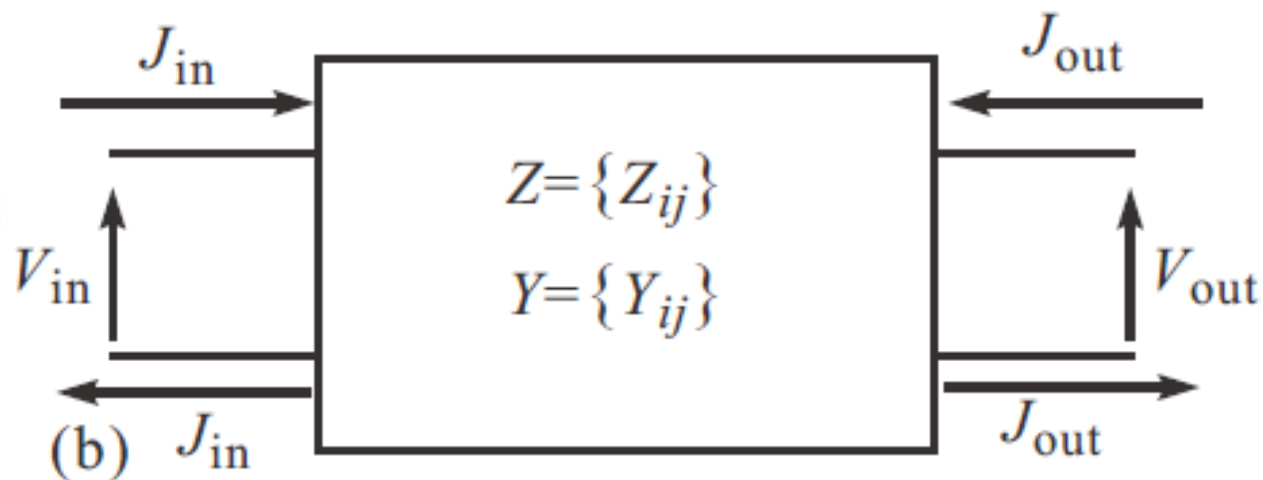
# F-matrix of 4-terminal circuit

$$\begin{pmatrix} V_{in} \\ J_{in} \end{pmatrix} = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} V_{out} \\ J_{out} \end{pmatrix} \equiv F \begin{pmatrix} V_{out} \\ J_{out} \end{pmatrix}$$



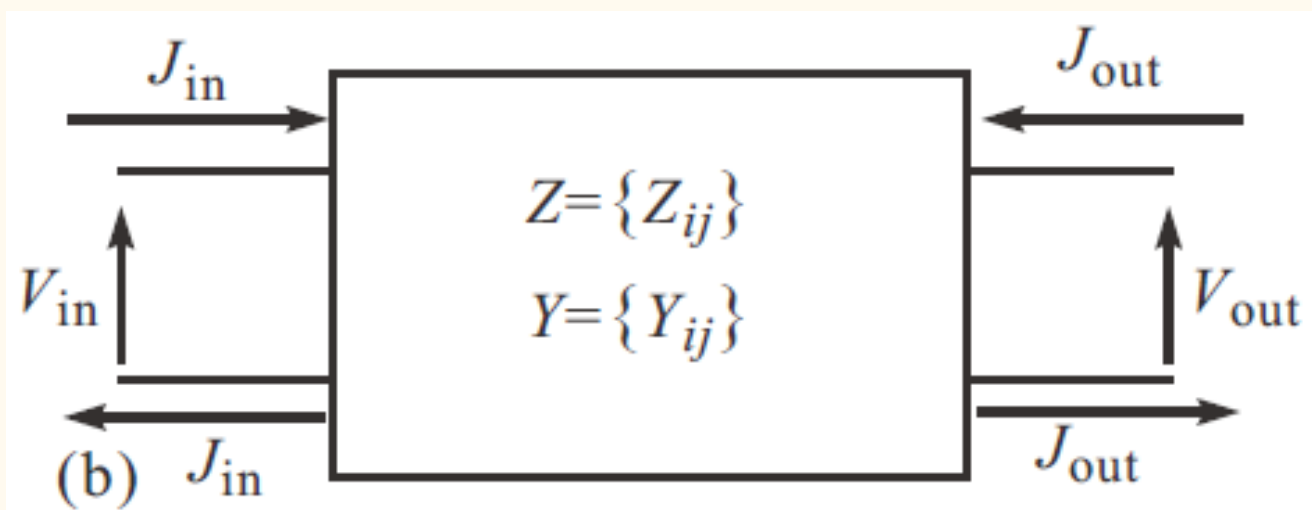
$$A = \left( \frac{V_{in}}{V_{out}} \right)_{J_{out}=0}, \quad B = \left( \frac{V_{in}}{J_{out}} \right)_{V_{out}=0}, \quad C = \left( \frac{J_{in}}{V_{out}} \right)_{J_{out}=0}, \quad D = \left( \frac{J_{in}}{J_{out}} \right)_{V_{out}=0}.$$

$$\begin{pmatrix} V_{out} \\ J_{out} \end{pmatrix} = \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} V_{in} \\ J_{in} \end{pmatrix} \equiv K \begin{pmatrix} V_{in} \\ J_{in} \end{pmatrix}$$





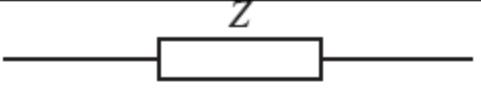
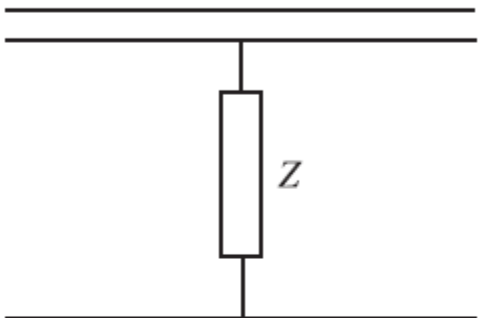
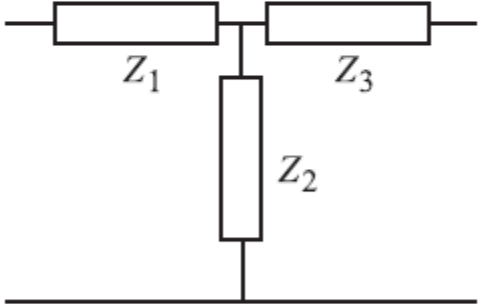
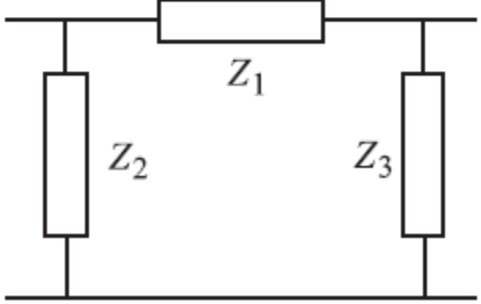
# Impedance matrix, Admittance matrix



$$\begin{pmatrix} V_{in} \\ V_{out} \end{pmatrix} = \begin{pmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{pmatrix} \begin{pmatrix} J_{in} \\ J_{out} \end{pmatrix} \equiv Z \begin{pmatrix} J_{in} \\ J_{out} \end{pmatrix}$$

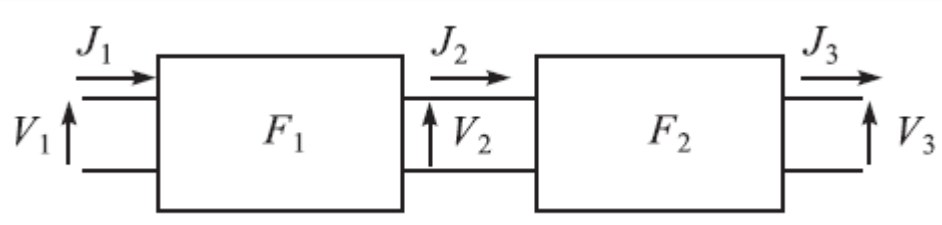
$$\begin{pmatrix} J_{in} \\ J_{out} \end{pmatrix} = \begin{pmatrix} Y_{11} & Y_{12} \\ Y_{21} & Y_{22} \end{pmatrix} \begin{pmatrix} V_{in} \\ V_{out} \end{pmatrix} \equiv Y \begin{pmatrix} V_{in} \\ V_{out} \end{pmatrix}$$

# Examples with impedances

	A	B	C	D
	1	$Z$	0	1
	1	0	$\frac{1}{Z}$	1
	$1 + \frac{Z_1}{Z_2}$	$\frac{Z_1 Z_2 + Z_2 Z_3 + Z_3 Z_1}{Z_2}$	$\frac{1}{Z_2}$	$1 + \frac{Z_3}{Z_2}$
	$1 + \frac{Z_1}{Z_3}$	$Z_1$	$\frac{Z_1 + Z_2 + Z_3}{Z_2 Z_3}$	$1 + \frac{Z_1}{Z_2}$

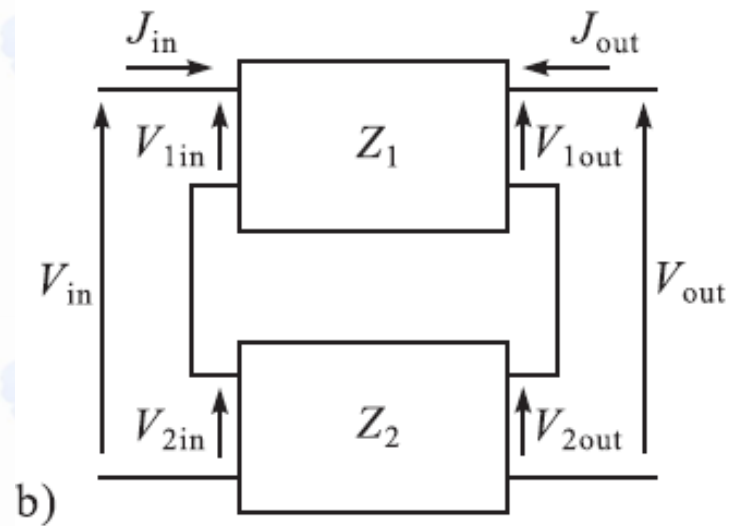
# Connections of 4-terminal circuits

Cascade



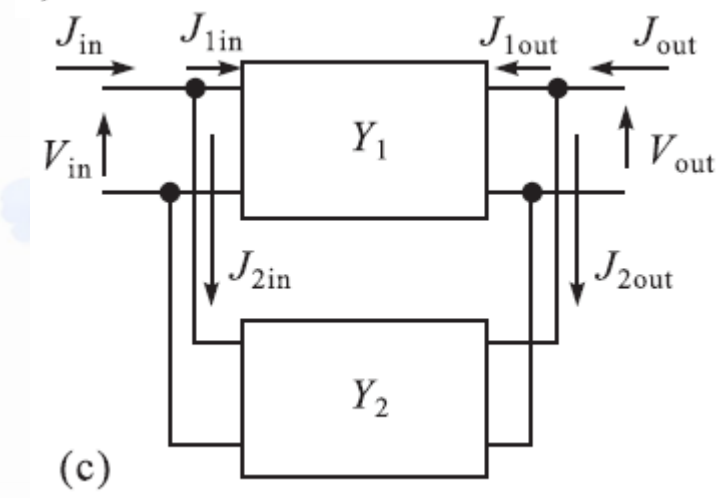
$$F_{\text{tot}} = \prod_{i=1}^N F_i$$

Series



$$Z_{\text{tot}} = \sum_{i=1}^N Z_i$$

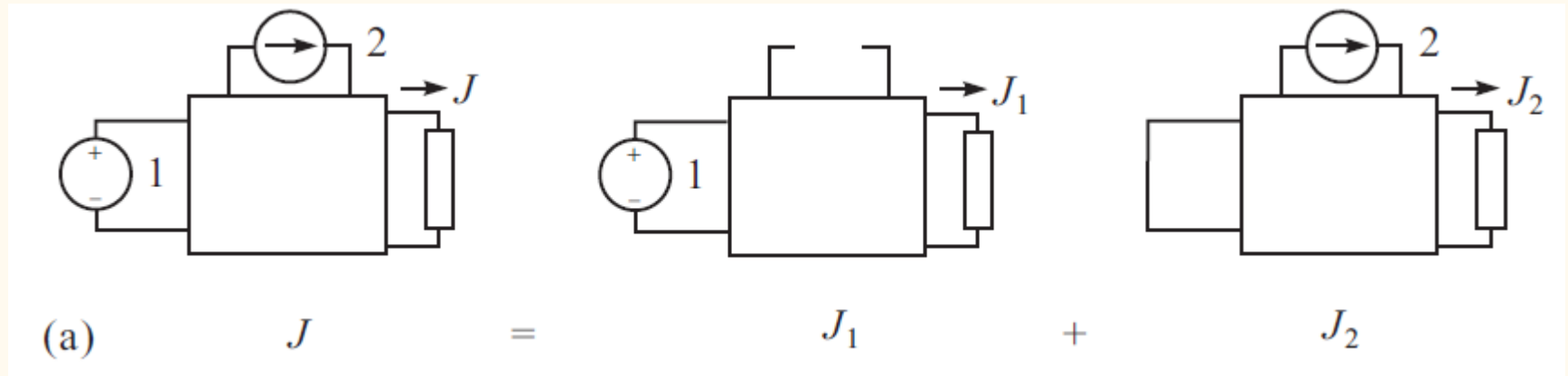
Parallel



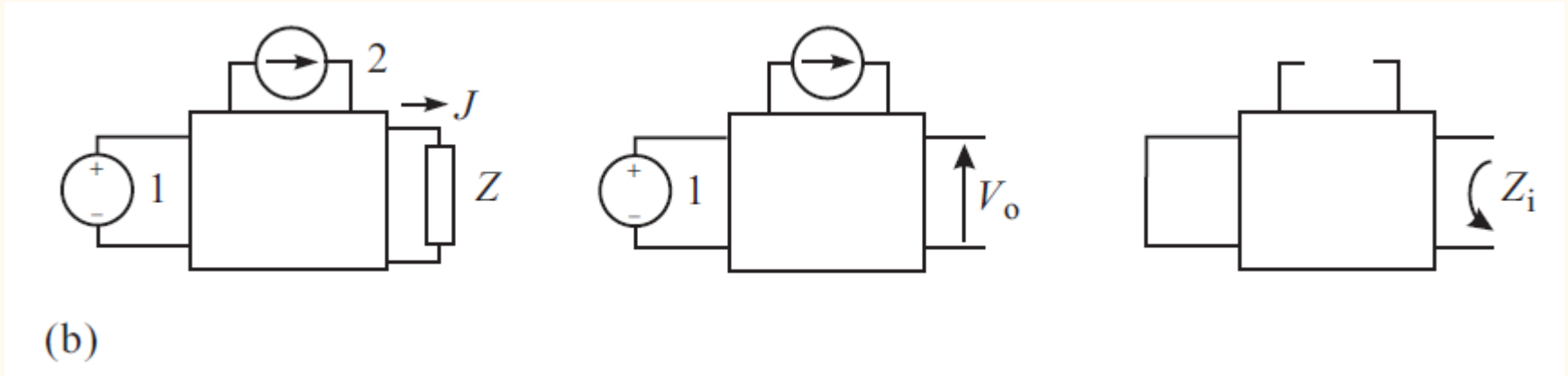
$$Y_{\text{tot}} = \sum_{i=1}^N Y_i$$

# Theorems for terminal-pair circuits

## Superposition theorem

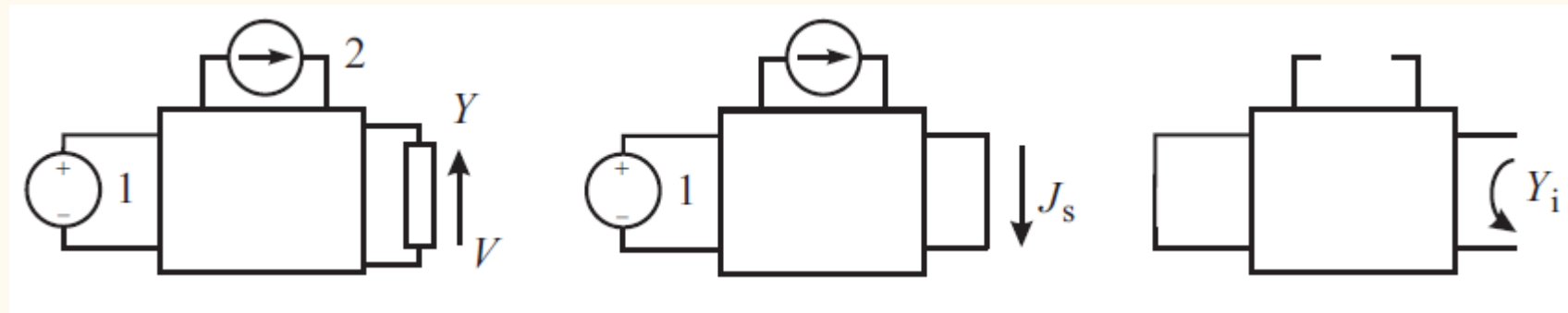


## Ho-Thevenin's theorem





# Norton's theorem



$$V = \frac{J_s}{Y + Y_i}$$

# Duality 双対性

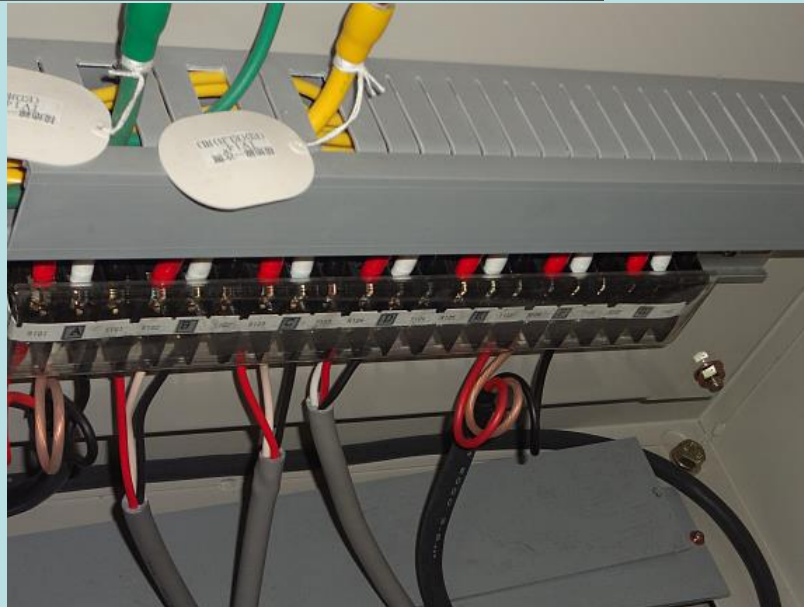
直列接続	並列接続
開放	短絡
電場	磁場
キルヒホッフの第2法則	キルヒホッフの第1法則
電圧	電流
インピーダンス	アドミッタンス
抵抗	コンダクタンス
静電容量	インダクタンス
鳳-テブナンの定理	ノートンの定理

# Duality

Series	Parallel
Open	Short
Voltage	Current
Impedance	Admittance
Capacitance	Inductance
Electric field	Magnetic field
Resistance	Conductance
Ho-Thevenin	Norton
Kirchhoff's 2 <sup>nd</sup> law	Kirchhoff's 1 <sup>st</sup> law

# Power Sources in Lab. 電源の雑知識

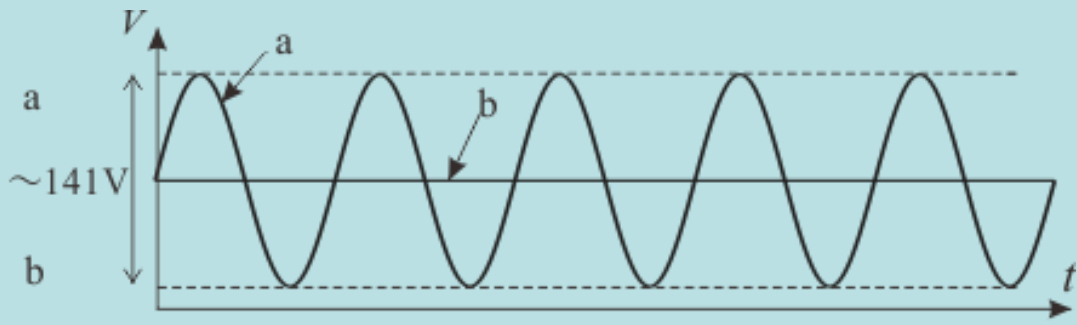
AC Power from distribution board 配電盤からの電力供給



# AC Power from distribution board 配電盤からの電力供給

単相 2 線式  
(100 V)

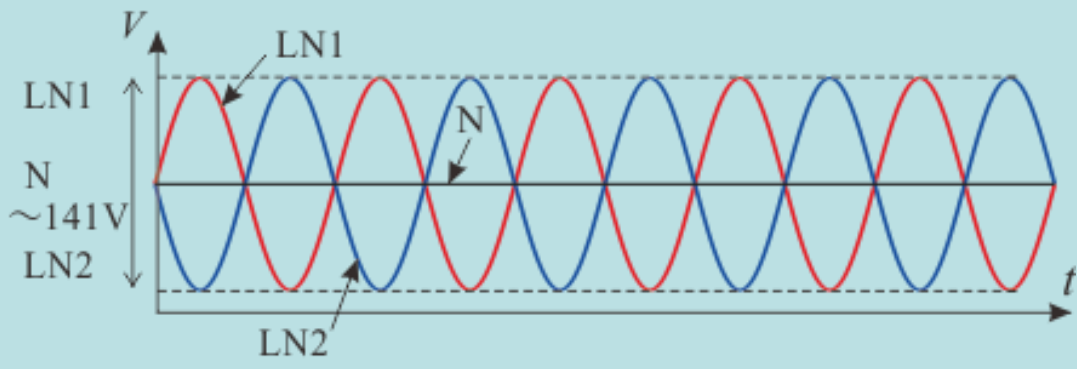
電圧線 ————— a  
Single-phase 2-wire  
中性線 (GND) ————— b



単相 3 線式  
(100 V, 200 V)

電圧線 ————— LN1  
中性線 (GND) ————— N  
電圧線 ————— LN2

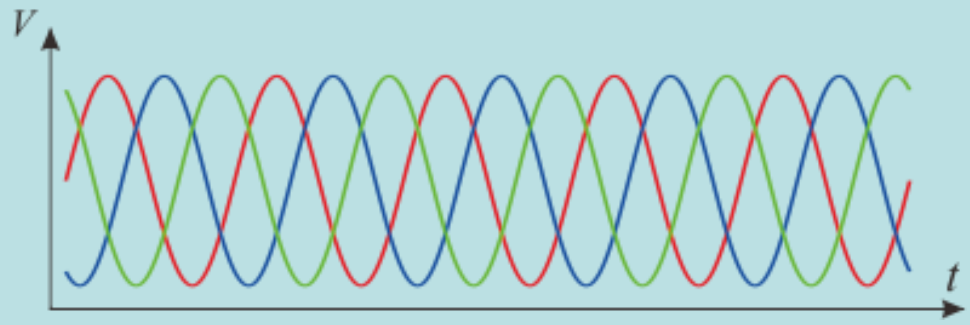
Single-phase 3-wire



3 相 3 線式

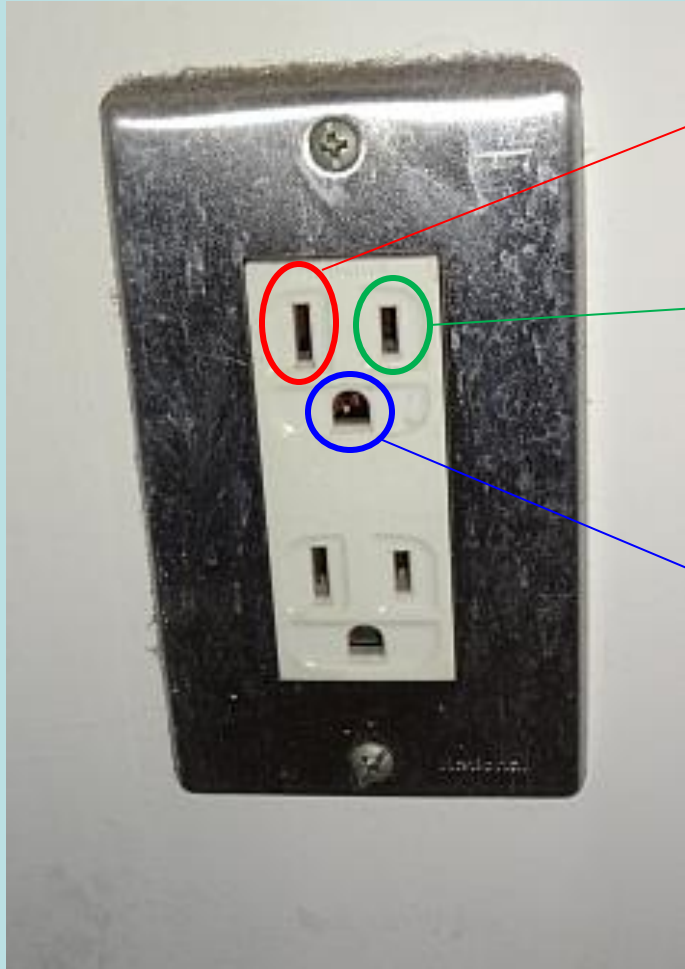
第一相 ————— R  
第二相 ————— S  
第三相 ————— T

Three-phase 3-wire





# Japanese outlet tap definition 日本式コンセント



Cold line 中性線

Hot line 電圧線

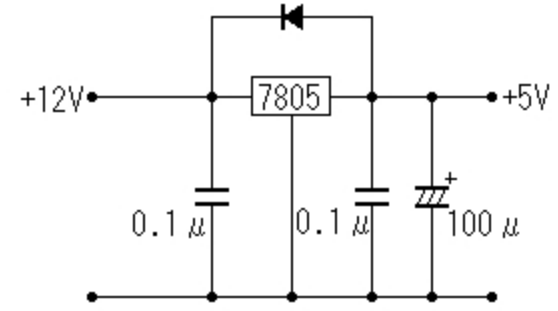
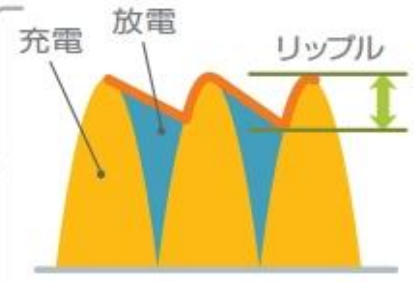
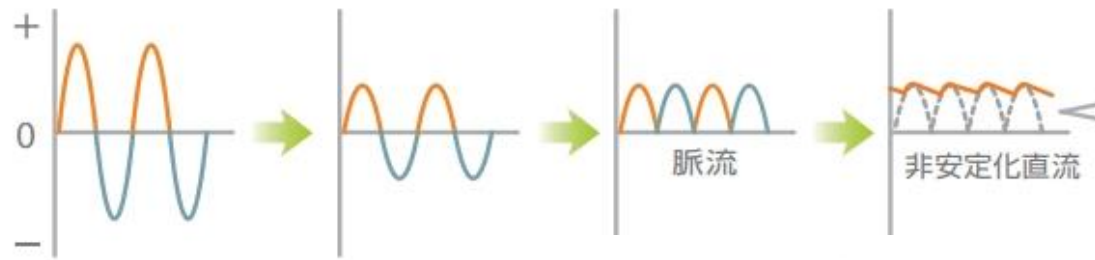
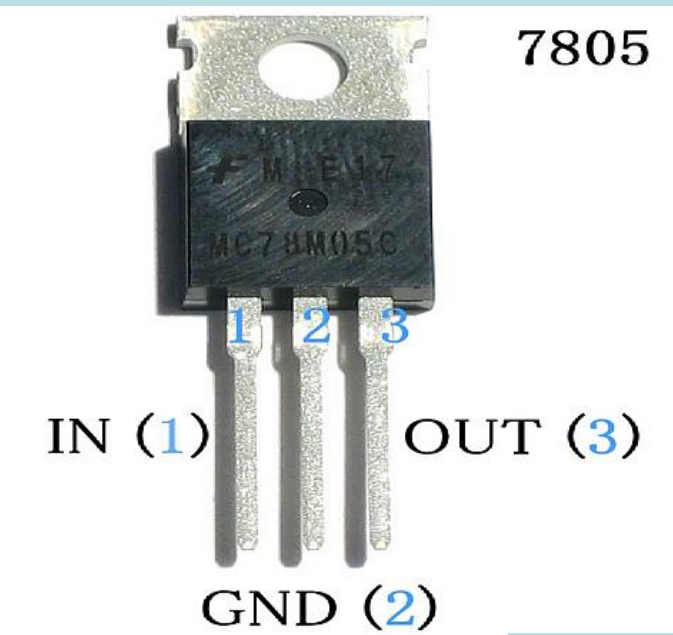
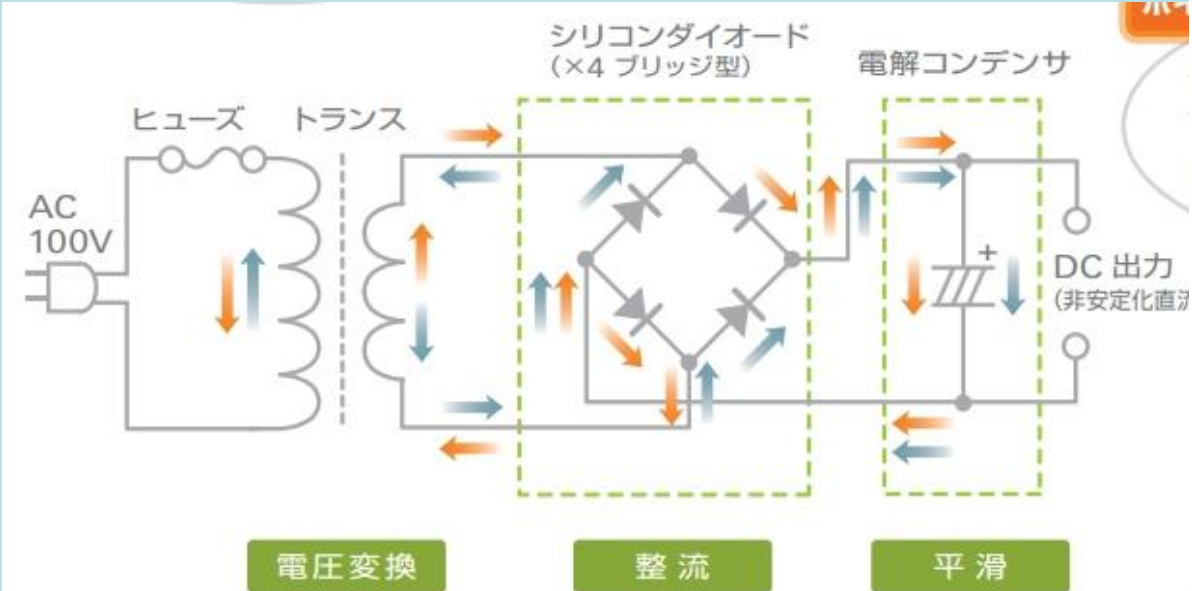
Ground 接地線

検電ドライバー  
Electroscopic  
Screwdriver



# DC Stabilized Power Supply 直流安定化電源

## Series (Dropper) regulation



From TDK web page

# Series regulator power supply



Uni-polar



Dual tracking

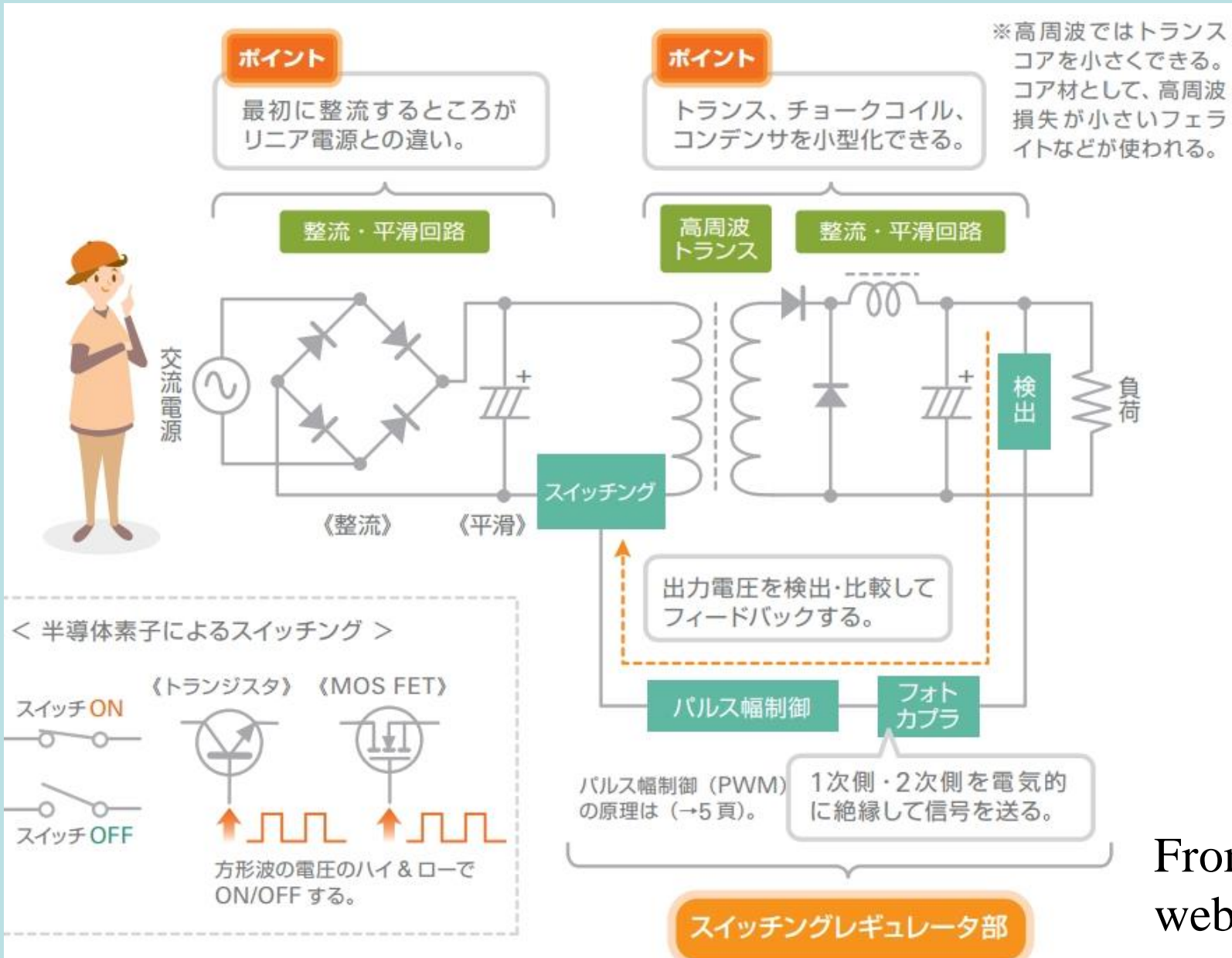


High precision



Bi-polar current source

# Switching regulation



From TDK web page



# Switching regulator power supply

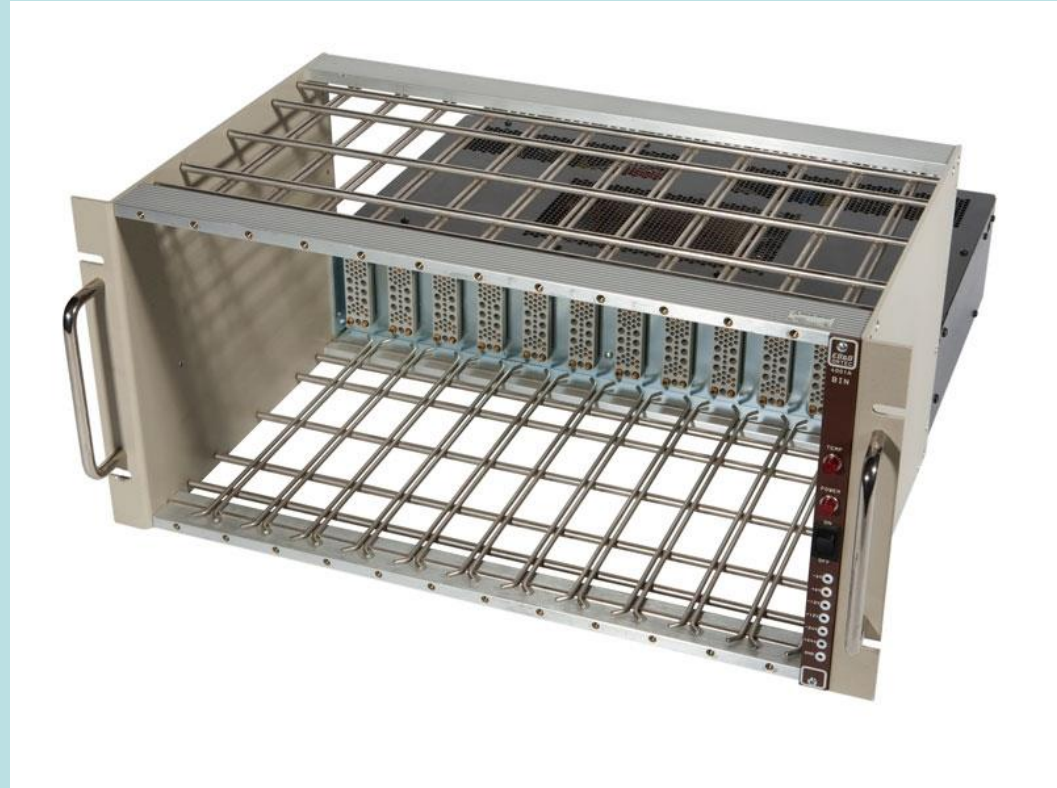
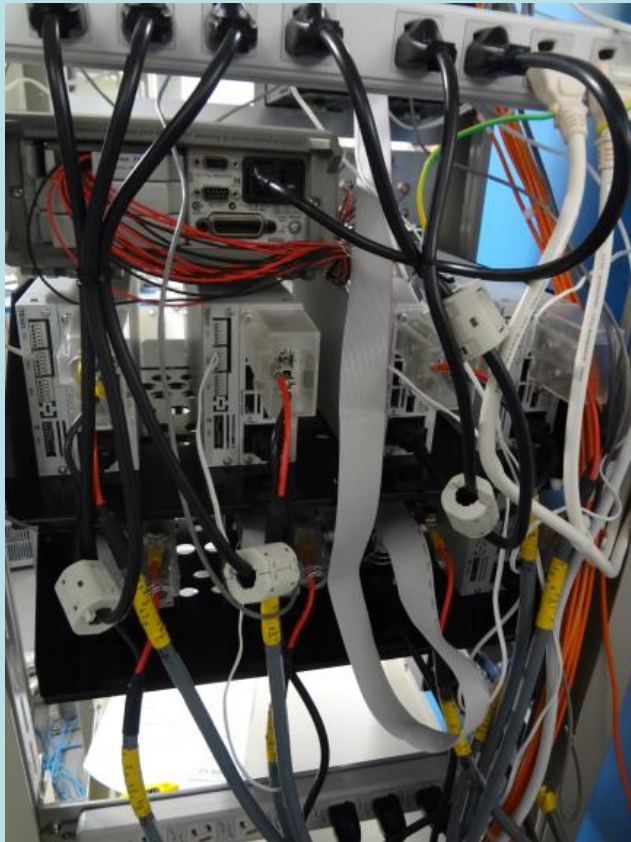


Molecular beam epitaxy  
Control panel





# Bin 電源ビン



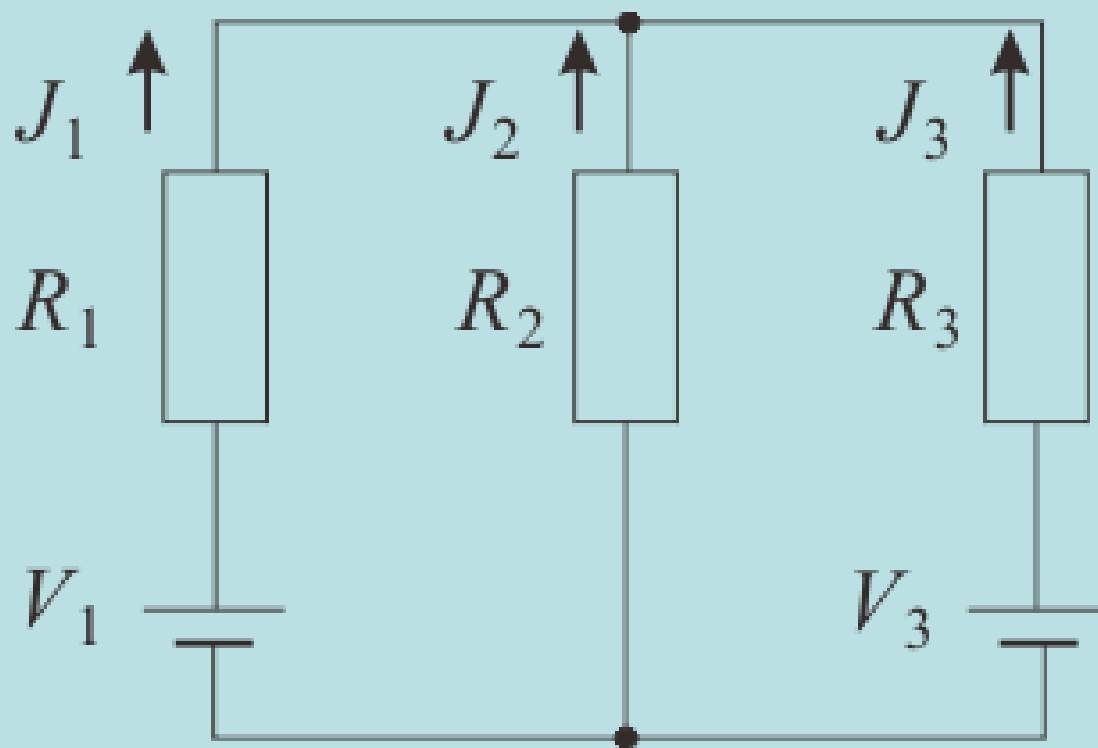
Complicated power lines



Bin

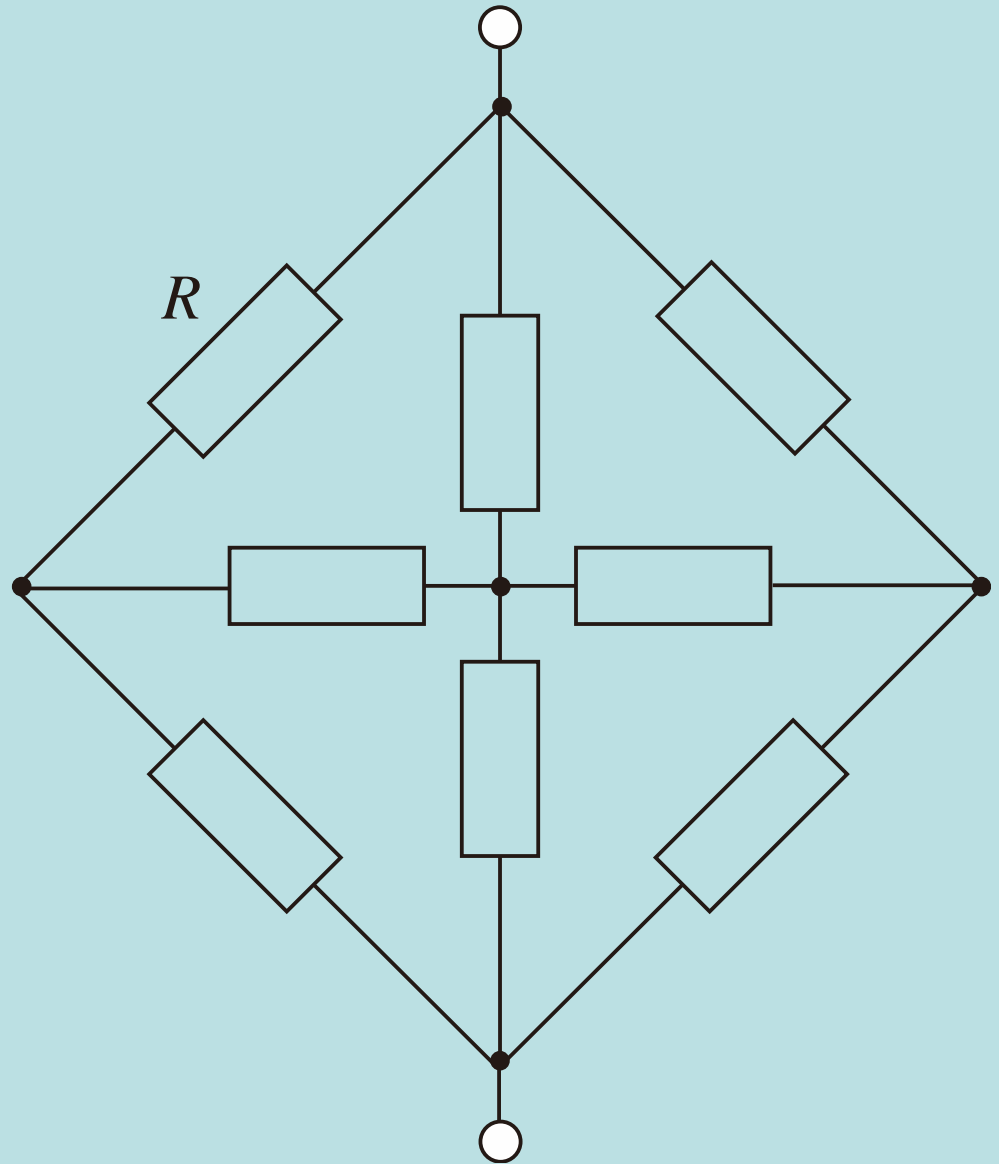
# Exercise A-1

Express  $J_1$ ,  $J_2$ ,  $J_3$  with other parameters.



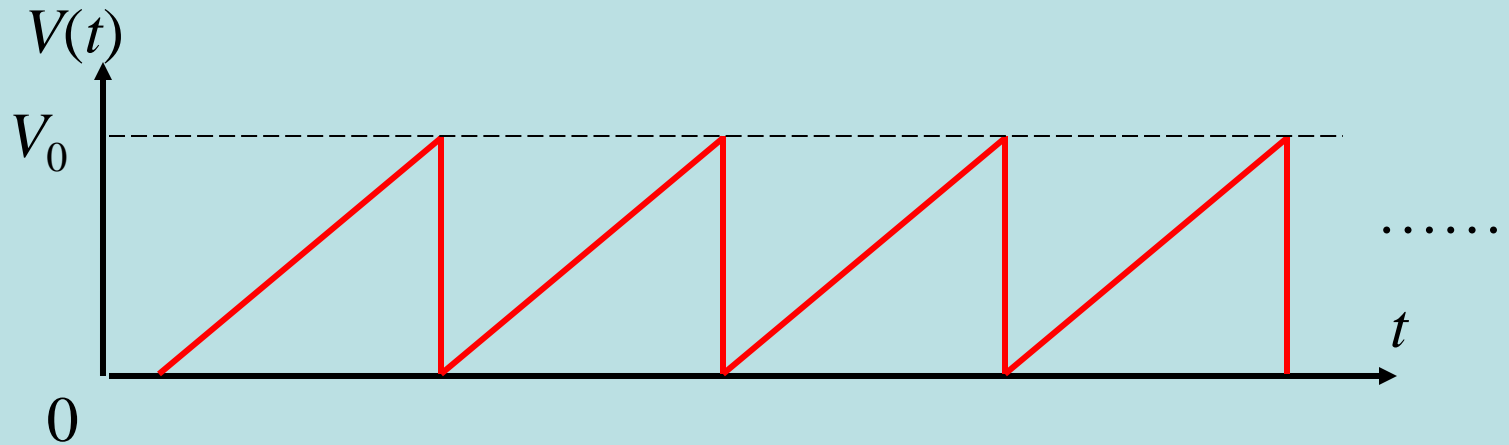
# Exercise A-2

All the resistors have the same resistance  $R$ . Obtain the combined resistance.



# Exercise A-3

Obtain the effective value of voltage for the saw tooth wave.



# 電子回路論第3回

## Electric Circuits for Physicists

東京大学理学部・理学系研究科

物性研究所

勝本信吾

Shingo Katsumoto



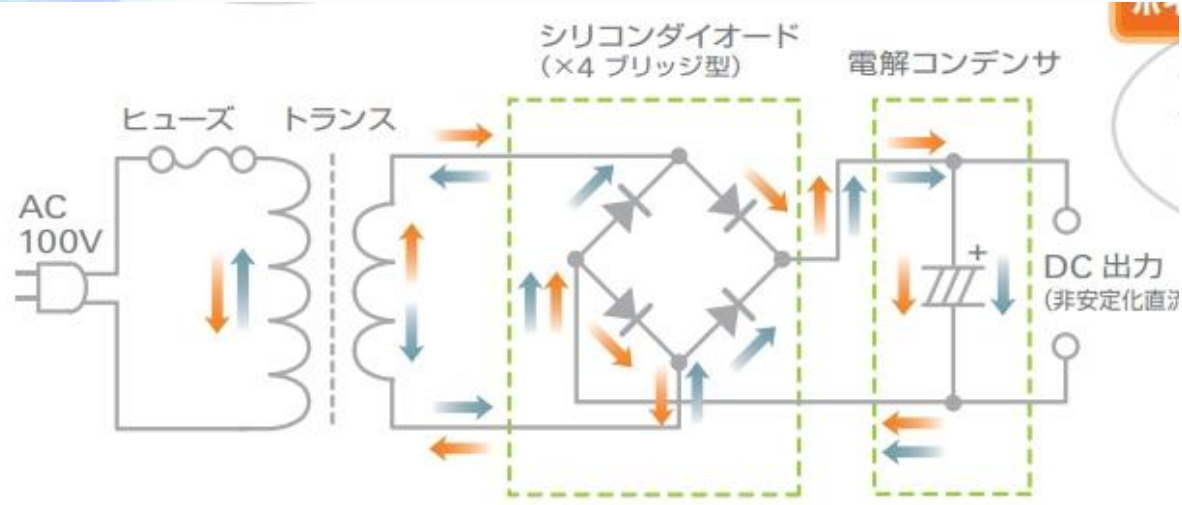


# 電源の雑知識 (続き)

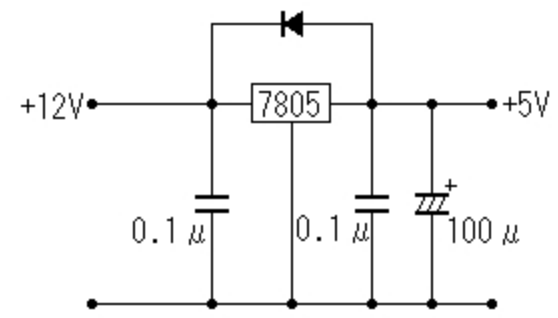
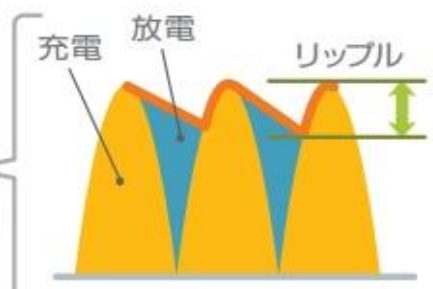
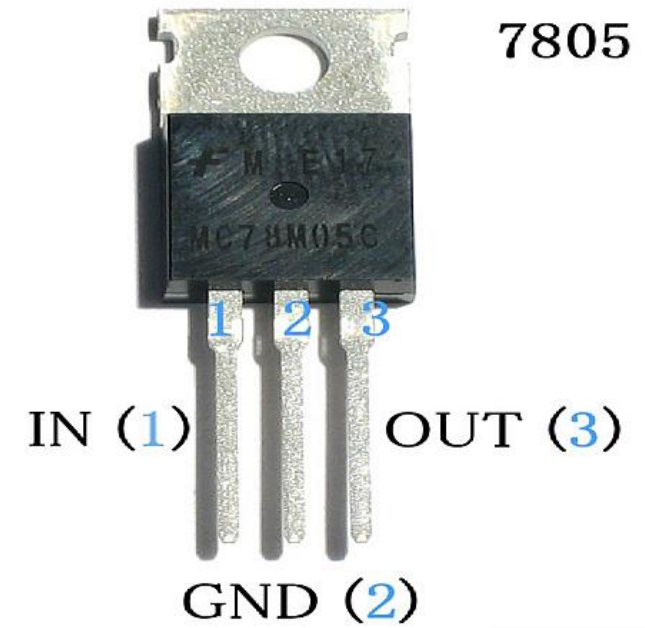
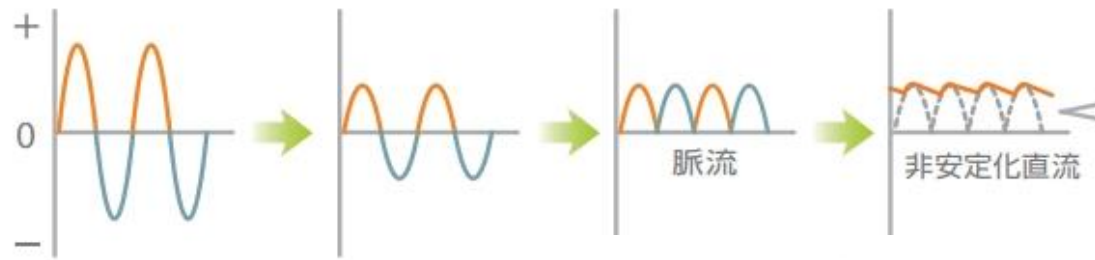
Miscellaneous knowledge  
on power supplies (continued)

# DC Stabilized Power Supply 直流安定化電源

## Series (Dropper) regulation



電圧変換      整流      平滑



From TDK web page



# Series regulator power supply



Uni-polar



Dual tracking

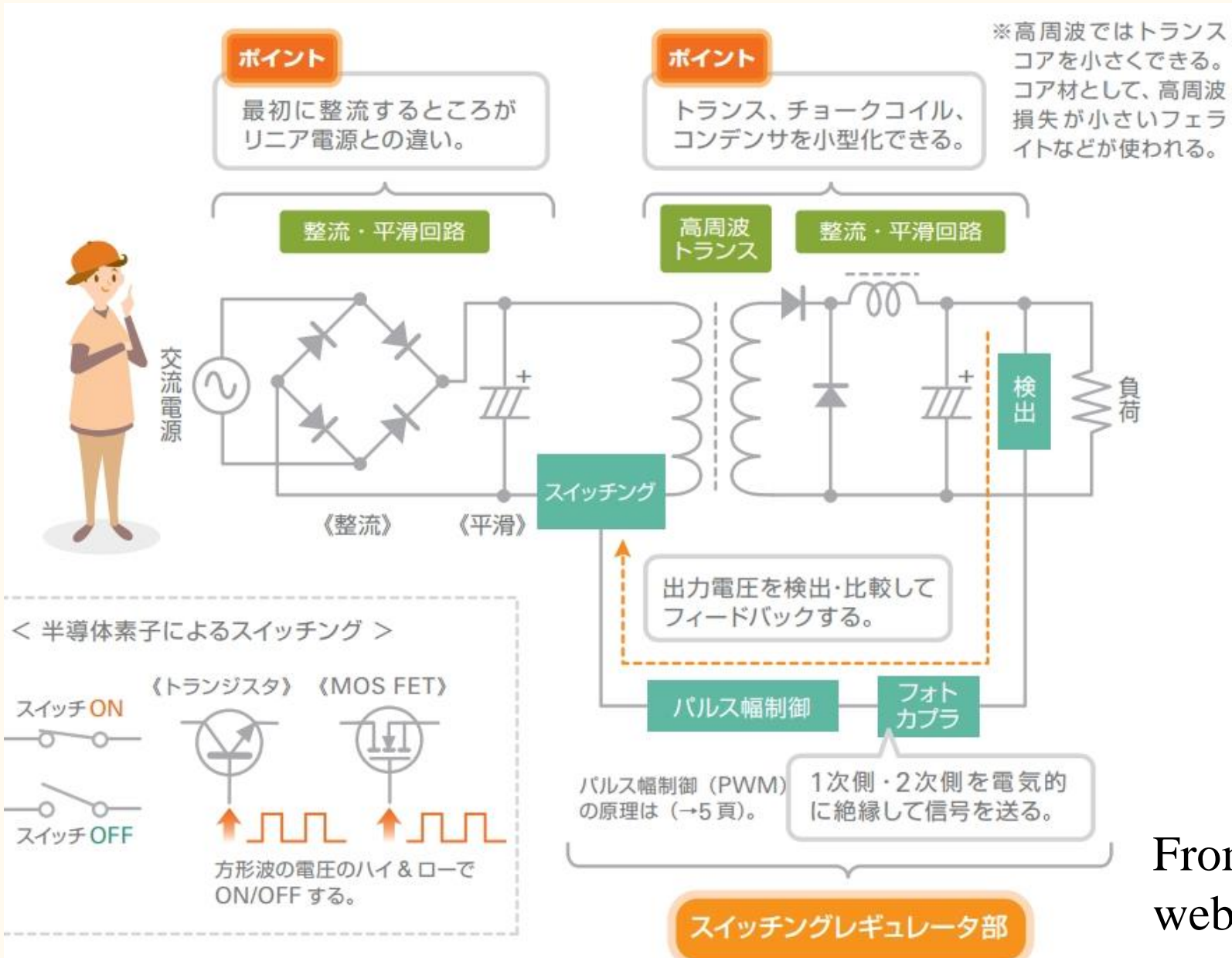


High precision



Bi-polar current source

# Switching regulation



From TDK web page

# Switching regulator power supply



Molecular beam epitaxy  
Control panel

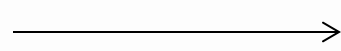




# Bin 電源ビン



Complicated power lines



Bin



# Outline Today

2.5 Theorems for paired terminal circuits

Superposition, Ho-Tevenin, Reciprocity

2.6 Duality

2.7 Passive devices (elements) and active devices

## **Ch.3 Transfer function and transient response**

3.1 Transfer function of single-pair terminal circuits

Resonance circuit

Bode plot

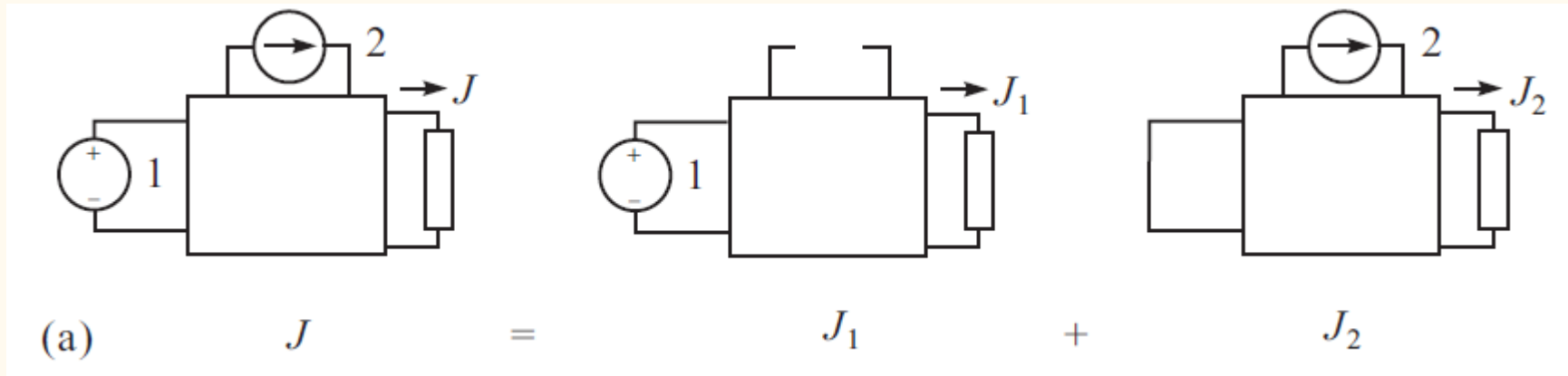
General properties

Appendix B Bridges and balance circuits

Appendix C General properties of resonance circuits

# Theorems for terminal-pair circuits

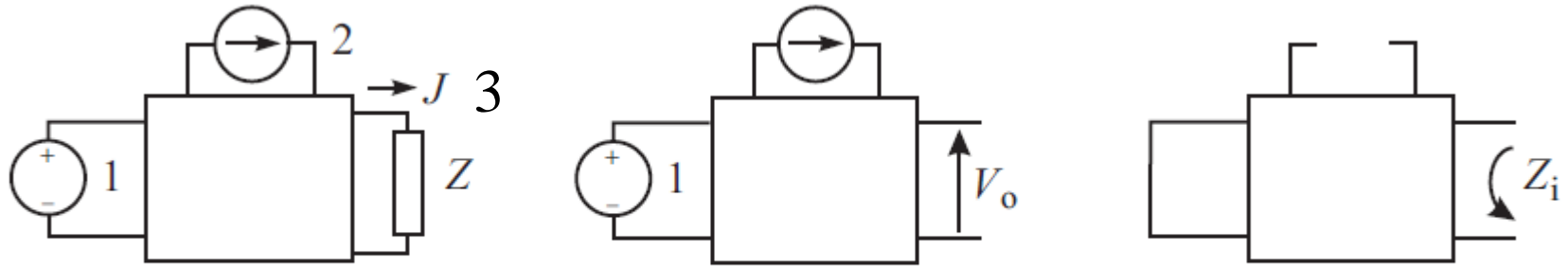
## Superposition theorem



$$J = \sum_i J_i$$

$J_i$ : The current caused by  $i$ -th power source.

# Ho-Thevenin's theorem



(b)

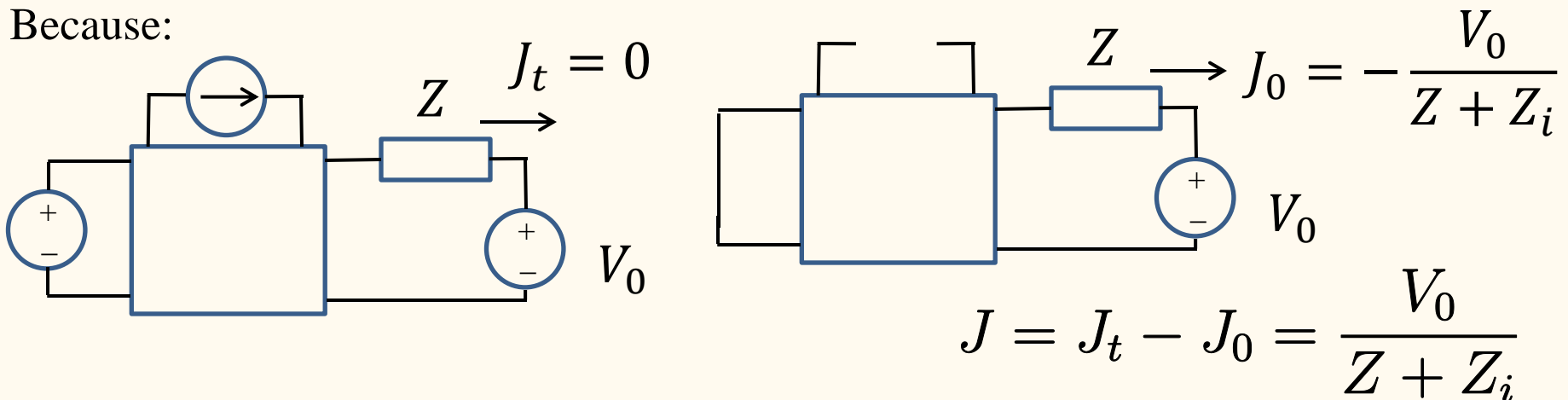
Consider a circuit with an open terminal pair (No.3). Obtain current  $J$  when the open pair is connected with impedance  $Z$ .

1. Measure the open terminal voltage  $V_0$ .
2. Turn off all the power sources (voltage sources: short, current sources: open). Measure the open circuit impedance  $Z_i$ .

Then

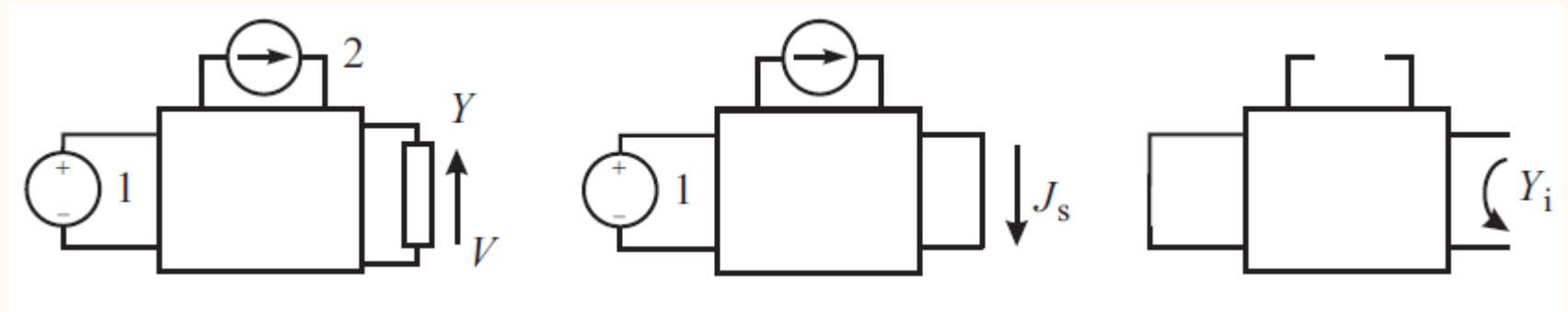
$$J = \frac{V_0}{Z + Z_i}$$

Because:



$$J = J_t - J_0 = \frac{V_0}{Z + Z_i}$$

# Norton's theorem



$$V = \frac{J_s}{Y + Y_i}$$

Dual theorem for Ho-Tevenin.



# Comments on Tellegen's theorem

$i = 1, \dots, n$ : index of nodes,  $j = 1, \dots, m$ : index of branches

$$a_{ij} = \begin{cases} 1 & : i \text{ is the start of } j, \\ -1 & : i \text{ is the end of } j, \\ 0 & : \text{others} \end{cases} \quad \text{incidence matrix}$$

redundancy  $\rightarrow (n - 1) \times m$  matrix  $D$  : irreducible incidence matrix

$J_j, V_j$  : current and voltage along branch  $j$ ,  $W_i$  : potential of node  $i$ .

Kirchhoff's first law:  $DJ = 0$       Second law:  $V = {}^tDW$

$$\sum_{i=1}^m \underbrace{V_i J_i}_{\text{Power of } i\text{-th branch}} = ({}^tDW) \cdot J = {}^tW D J = 0 \quad V \perp J$$

## Comments

1. Power conservation law
2. Holds for any kind of circuit (irrespective of linear, or non-linear)
3. Holds for two independent circuit conditions (as long as  $D$  is the same)

# Reciprocity theorem

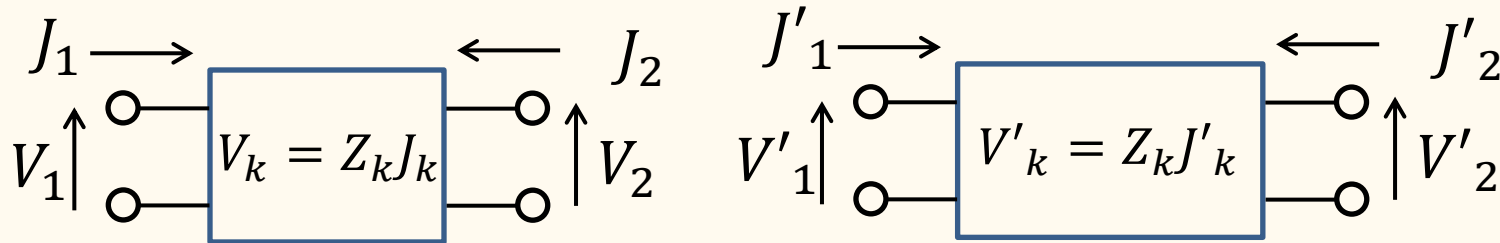
An  $n$ -terminal pair linear circuit

At one state  $(V_1, J_1), (V_2, J_2), \dots, (V_n, J_n),$

at another state  $(V'_1, J'_1), (V'_2, J'_2), \dots, (V'_n, J'_n)$

$$\sum_{i=1}^n V_i J'_i = \sum_{i=1}^n V'_i J_i$$

Proof: Consider a two terminal-pair circuit with  $m$  branches.



Tellegen's theorem  
(and comment no.3)

$$-V_1 J'_1 - V_2 J'_2 + \sum_k V_k J'_k = 0$$

$$-V'_1 J_1 - V'_2 J_2 + \sum_k V'_k J_k = 0$$

$$V_k J'_k = V'_k J_k = Z_k J_k J'_k$$

$$\therefore V_1 J'_1 + V_2 J'_2 = V'_1 J_1 + V'_2 J_2 \quad //$$

(This also holds for circuits with mutual inductances.)

## 2.6 Duality 双対性

直列接続	並列接続
開放	短絡
電場	磁場
キルヒホッフの第2法則	キルヒホッフの第1法則
電圧	電流
インピーダンス	アドミッタンス
抵抗	コンダクタンス
静電容量	インダクタンス
鳳-テブナンの定理	ノートンの定理

## 2.6 Duality

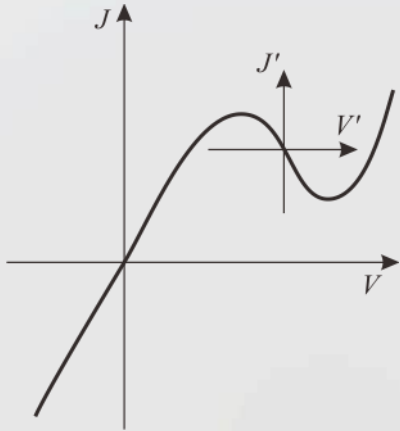
Series	Parallel
Open	Short
Voltage	Current
Impedance	Admittance
Capacitance	Inductance
Electric field	Magnetic field
Resistance	Conductance
Ho-Thevenin	Norton
Kirchhoff's 2 <sup>nd</sup> law	Kirchhoff's 1 <sup>st</sup> law

## 2.7 Definition: Passive elements and active elements

Two terminal: current  $J$ , voltage  $V$

$JV \geq 0$ : passive element

$JV < 0$ : active element



Locally active two-terminal element

More than three-terminal: treat as a terminal pair circuit



$$P = J_{in}V_{in} + J_{out}V_{out}$$

$P \geq 0$ : passive element

$P < 0$ : active element





# Ch.3 Transfer function and transient response

# 3.1 General Properties of Resonance and Resonance Circuits

## 3.1.1 Resonance Phenomena

Harmonic oscillator:  $\frac{d^2q}{dt^2} = -\omega_0^2q$

Kirchhoff's law

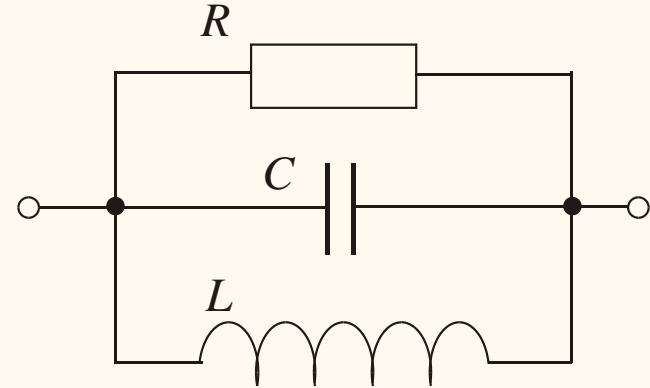
$$L \frac{dJ_L}{dt} = -L \frac{d^2q_L}{dt^2} = \frac{q}{C} = RJ_R = R \frac{dq_R}{dt}$$

$$dq_L + dq_R + dq = 0$$

$$\frac{d^2q}{dt^2} + \frac{1}{CR} \frac{dq}{dt} + \frac{1}{LC}q = \frac{d^2q}{dt^2} + \frac{1}{\tau} \frac{dq}{dt} + \omega_0^2q = 0$$

$$q = \exp(\lambda t) \quad \lambda = \frac{1}{2\tau} \left[ -1 \pm \sqrt{1 - 4(\omega_0\tau)^2} \right] \approx -\frac{1}{2\tau} \pm i\omega_0 \quad (\omega_0\tau \gg 1)$$

Resonant (angular) frequency  $\omega_0 \equiv \frac{1}{\sqrt{LC}}$



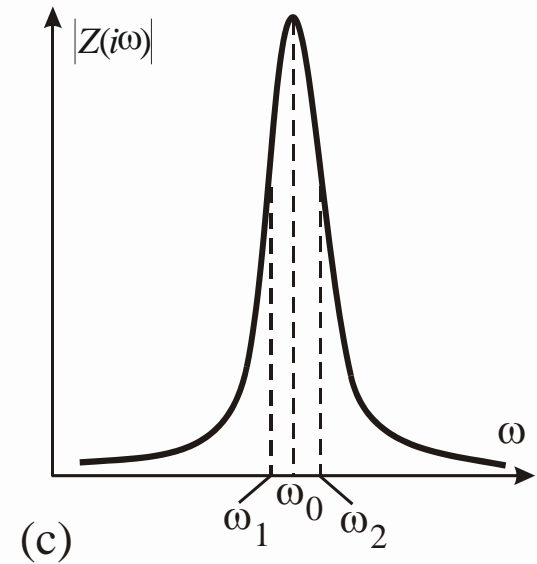
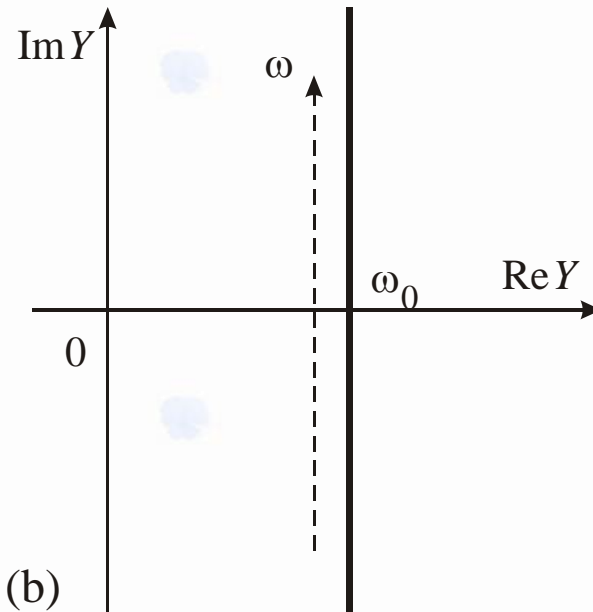
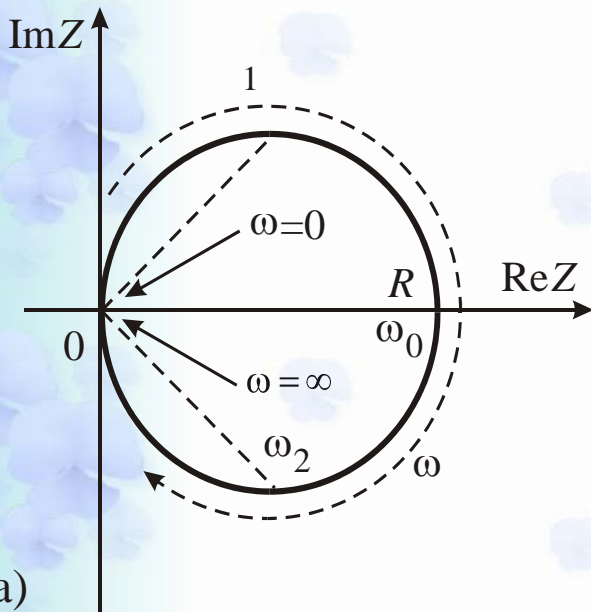
# Transfer function, resonance and phase shift

$$Z_{\text{tot}}(i\omega) = \left[ \frac{1}{R} + i \left( \omega C - \frac{1}{\omega L} \right) \right]^{-1}$$

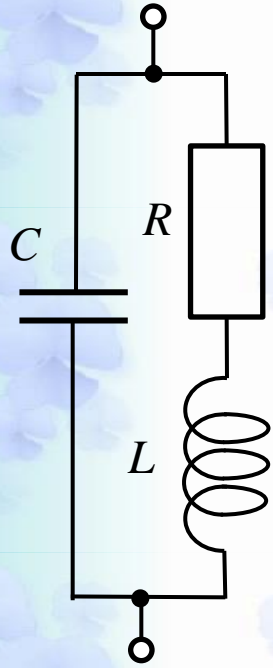
$$\omega_0 \equiv \frac{1}{\sqrt{LC}}$$

Resonance: Reactance = 0

Total Phase Shift Change:  $\pi$

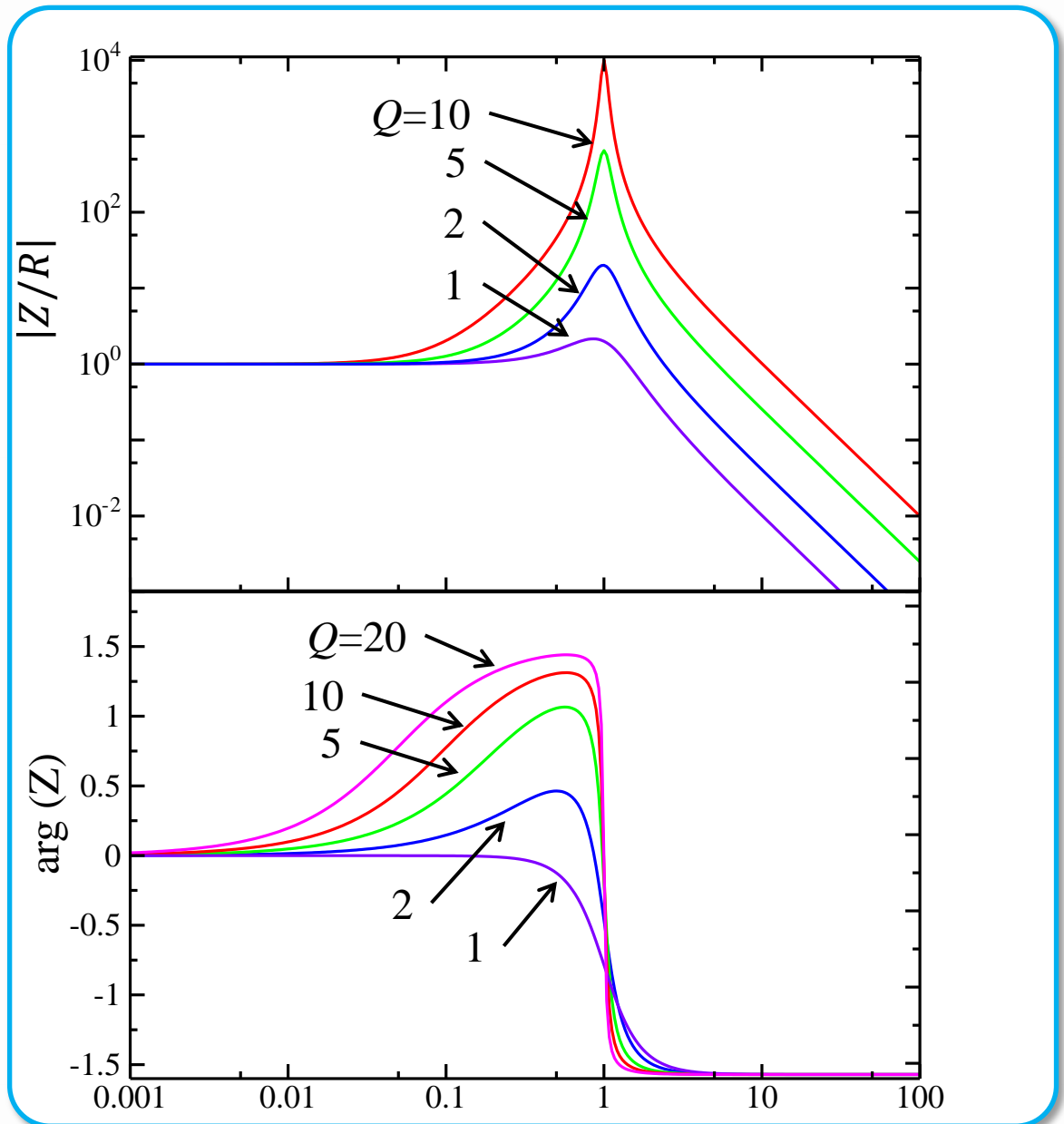


# Bode diagram

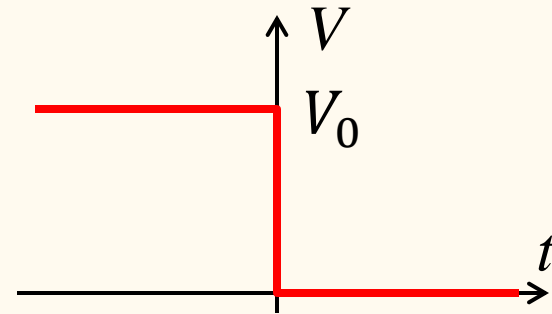
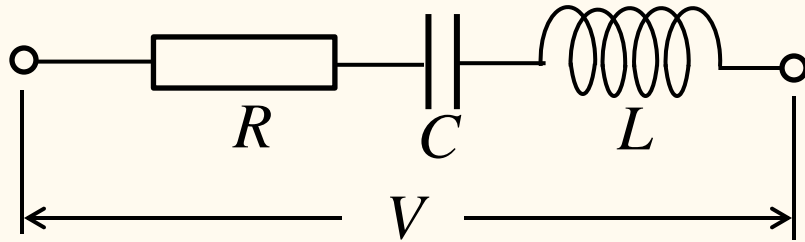


$$Q \approx \omega_0 \frac{L}{R}$$

$$Z(i\omega) = \frac{R + i\omega L}{1 - \omega^2 LC + i\omega CR} = \frac{R + i\omega L}{1 - \frac{\omega^2}{\omega_0^2} + i\omega CR}$$



# Transient response of resonant circuit



$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{q}{C} = 0 \quad (t > 0), \quad q(0) = CV_0$$

$$q(t) = CV_0 e^{st} \rightarrow Ls^2 + Rs + C^{-1} = 0$$

$$s = (-\omega_0 \pm \sqrt{\omega_0^2 - 4\alpha^2}) / (2\alpha) \quad \alpha \equiv (CR)^{-1}$$

$(\omega_0/2) < \alpha \rightarrow$  imaginary part

$$q(t) = CV_0 \exp[(-\gamma \pm i\omega_s)t], \quad \gamma \equiv \frac{\omega_0^2}{2\alpha}, \quad \omega_s \equiv \omega_0 \left(1 - \frac{\omega_0^2}{4\alpha^2}\right)^{1/2}$$

Damped oscillation with time constant  $\gamma^{-1}$ , frequency  $\omega_s$



# Transient response of resonance circuit (transfer function)

Synthesized impedance, admittance

$$Z_{\text{tot}}(s) = sL + R + \frac{1}{sC}, \quad Y_{\text{tot}}(s) = Z_{\text{tot}}(s)^{-1}$$

Zero (pole) of  $Z_{\text{tot}}(s)$  ( $Y_{\text{tot}}(s)$ )  $s = (-\omega_0 \pm \sqrt{\omega_0^2 - 4\alpha^2}) / (2\alpha)$

$Z_{\text{tot}}(s_0) = 0$       Time constant:  $\text{Re}(s_0)$     Frequency:  $\text{Im}(s_0)$

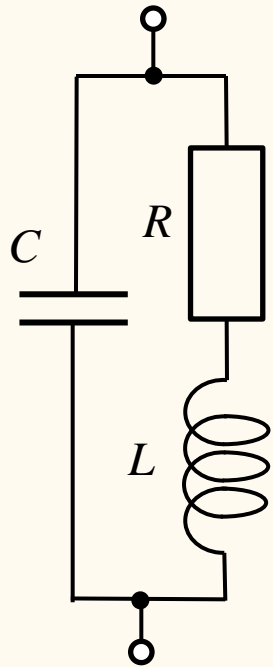
Laplace transformation of voltage:  $V(s)$

$$\underline{J(t)} = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} Y(s)V(s)e^{st} ds = \sum_i R(s_i)V(s_i)e^{s_i t} \quad (c > 0)$$

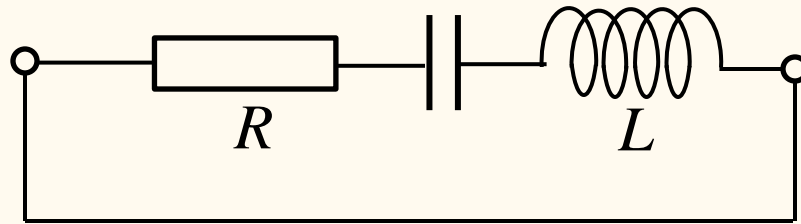
Natural current

$s_i$ : poles of  $Y(s)$      $R(s_i) = Y(s)(s - s_i)|_{s=s_i}$

# Driving point impedance



Open



Short

=

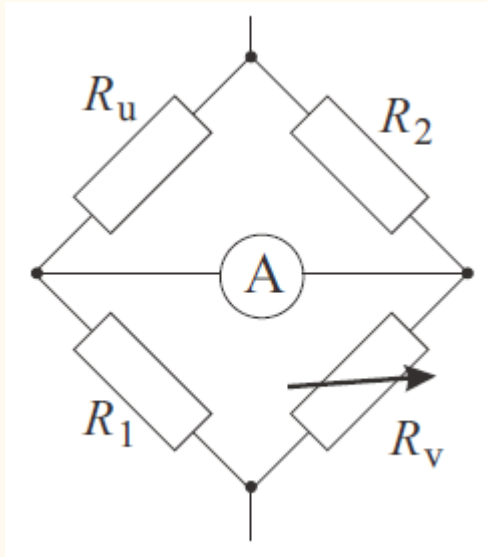
$$Z_{\text{tot}}(s) = sL + R + \frac{1}{sC}$$

$$Z_{\text{tot}}^{(2)}(s) = \left( \frac{1}{R + sL} + sC \right)^{-1} = \frac{sL + R}{s^2LC + sRC + 1}$$

$Z_{\text{tot}}(s)$  zero is pole for  $Z_{\text{tot}}^{(2)}(s)$

# Resistance bridge 抵抗ブリッジ

## Wheatstone bridge

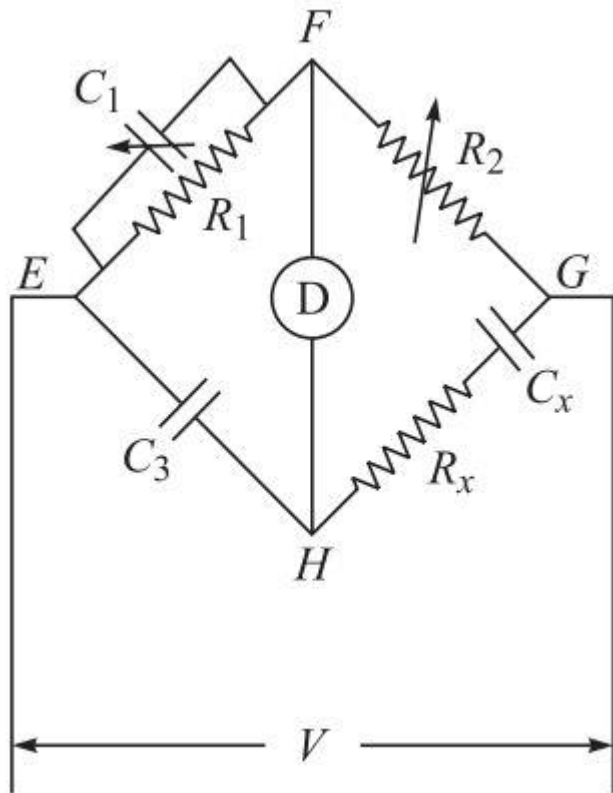


AVS-47 Resistance bridge

Not a “bridge” circuit!



# Schering Bridge



$$Z_1 Z_x = Z_2 Z_3, \quad Z_x = Z_2 Z_3 Y_1$$

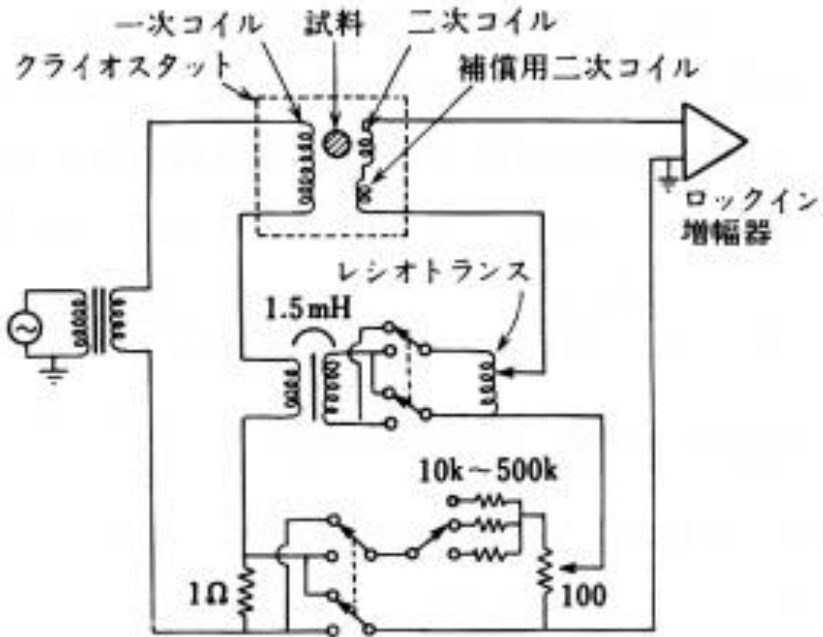
$$Z_x = R_x + \frac{1}{i\omega C_x}, \quad Z_2 = R_2, \quad Z_3 = \frac{1}{i\omega C_3}, \quad Y_1 = \frac{1}{R_1} + i\omega C_1$$

$$R_x + \frac{1}{i\omega C_x} = R_2 \frac{1}{i\omega C_3} \left( \frac{1}{R_1} + i\omega C_1 \right)$$

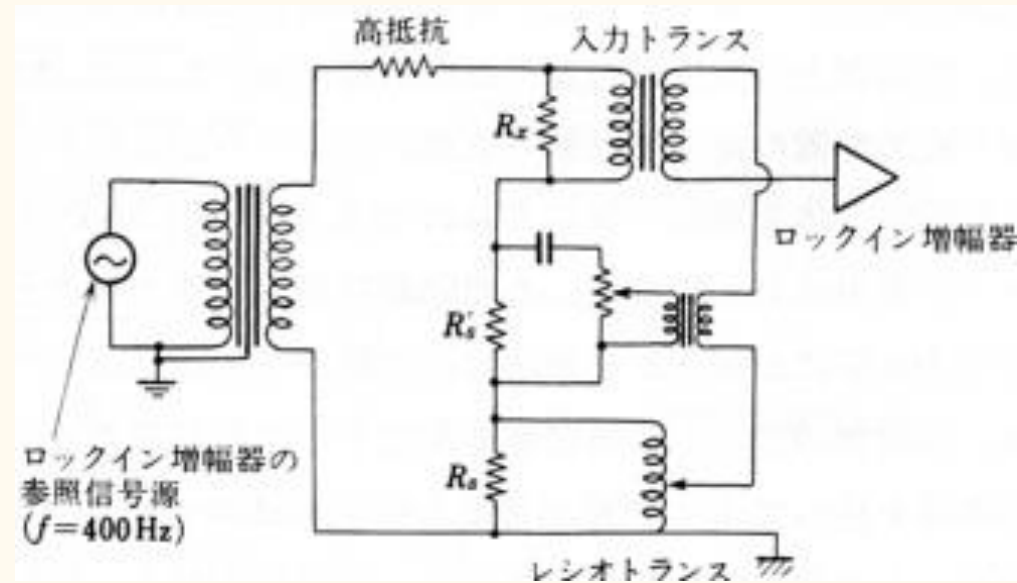
$$R_x = \frac{R_2 C_1}{C_3}, \quad C_x = \frac{R_1}{R_2} C_3$$

# Hartshorn bridge

## Magnetic moment measurement



## Resistance measurement





# Capacitance bridge キャパシタンスブリッジ



General Radio  
3-terminal  
Capacitance bridge

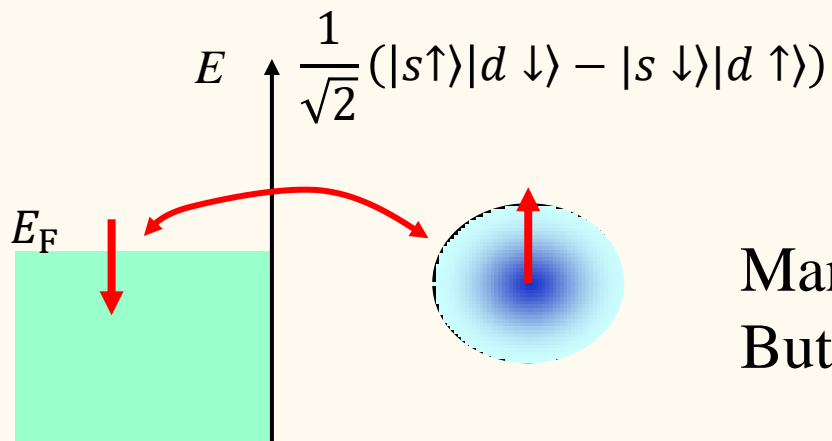
Agilent E4981A



# Kondo Resonance and Phase shift

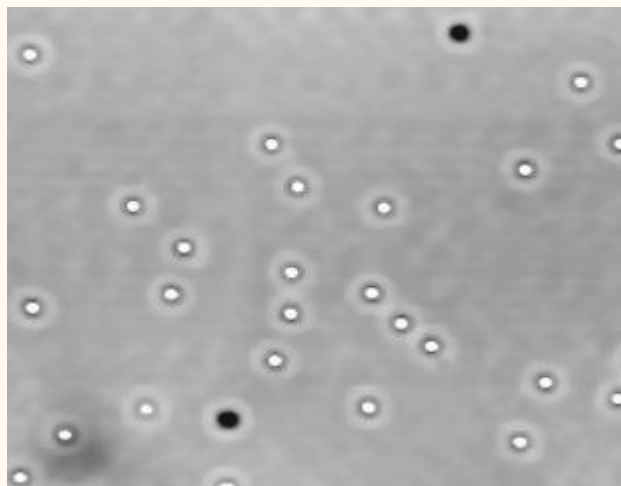


Jun Kondo

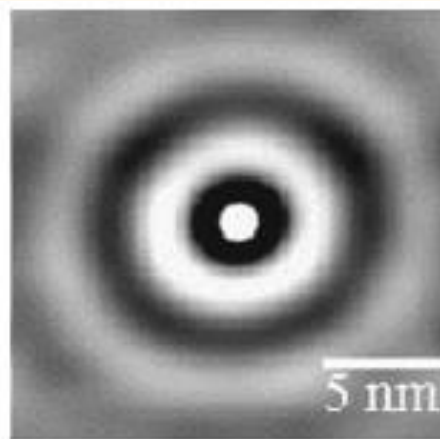


Many body resonance.  
But still has the phase shift of  $\pi/2$  !

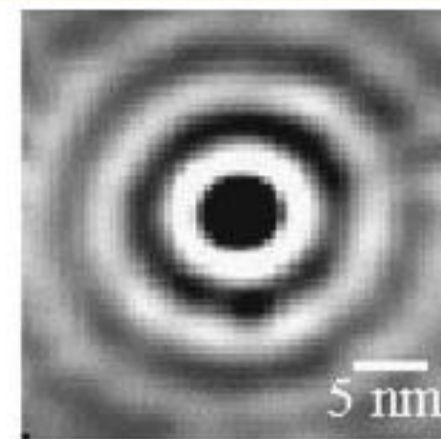
Co atoms on Ag (111) surface



Co (magnetic)



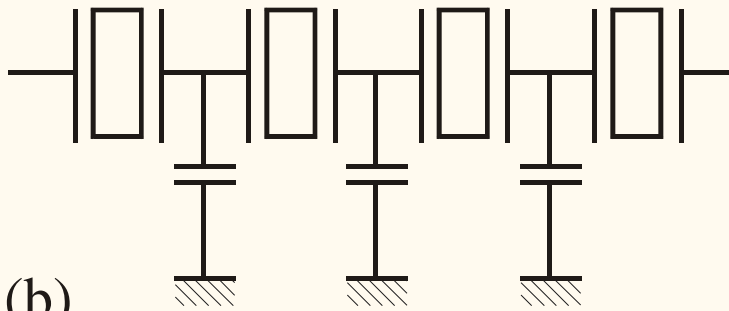
Defect (non-magnetic)



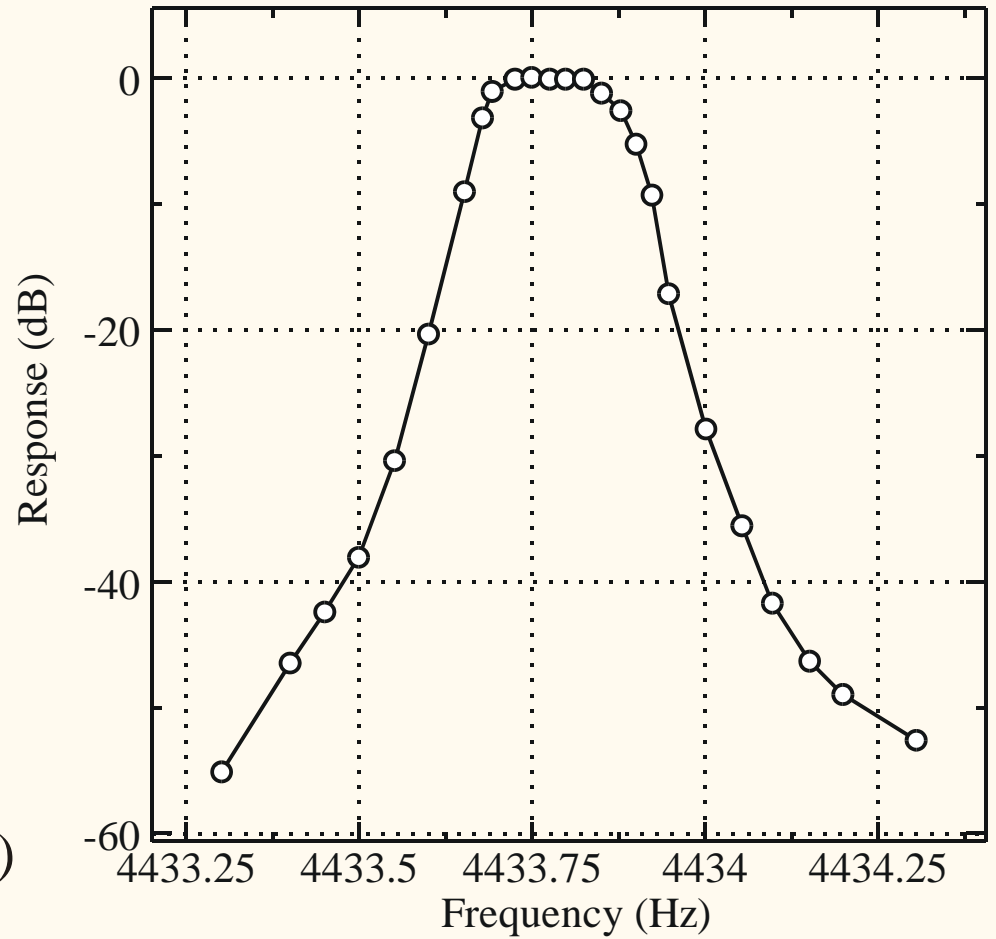
# Quartz crystal filter



(a)



(b)



(c)

Download LTSpice from the web site of Linear Technology



# What is Spice?

## SPICE: Simulation Program with Integrated Circuit Emphasis

A language which describes electronic circuits (corresponding to circuit diagrams).

ex) a CR circuit and a dc power source

```
* 0---R1---1---C1---2---V1---0
```

```
R1 0 1 10
```

```
C1 1 2 20
```

```
V1 2 0 5
```

```
.END
```

Graphical user interface: Circuit diagram

Linear Technology  
web site

The screenshot shows the Linear Technology website interface. At the top, there is a search bar and navigation links for "国内ニュースサイト", "ENGLISH", "中文网站", "品質", "採用", "問い合わせ", and "MyLinear". Below this is a main navigation bar with "製品", "ソリューション", "デザインサポート", "購入", and "会社概要". The main content area features a product highlight for the LTC6430, which includes a circuit diagram of an op-amp and a list of key features: "利得ブロック : 15dB", "OIP3 : +50dBm", and "3.3dB NF". To the right of the product highlight is a sidebar with "LTSPICE IV" resources, including "ダウンロード LTspice IV", "LTspiceデモ回路", and "LTspice資料". Below the product highlight is a "製品リリース" (Product Releases) section listing various LTspice models and their descriptions. At the bottom right, there is a "ビデオ" (Video) section with a thumbnail for "LT4321 PoE理想ダイオードブリッジコントローラ" and a link to "全てのビデオを見る".



Home > デザインサポート > ソフトウェア

## Design Simulation and Device Models

リアテクノロジーは高性能なスイッチング・レギュレータやアンプ、データ・コンバータ、フィルタなどを使用した回路を、初めての設計者でも短時間に容易に評価できるよう、**LTspice**・**LTpowerCAD**・**LTpowerPlay**のソフトウェアを提供しています。


- LTspice IV
- LTpowerCAD
- LTpowerPlay
- Amplifier Simulation & Design
- Filter Simulation & Design
- Timing Simulation & Design
- Data Converter Evaluation Software
- Dust Networks Starter Kits

### LTSPICE IV

#### LTspice IV

LTspice IVは高性能なSpice IIIシミュレータと回路図入力、波形ビューワに改善を加え、スイッチング・レギュレータのシミュレーションを容易にするためのモデルを搭載しています。Spiceの改善により、スイッチング・レギュレータのシミュレーションは、通常のSpiceシミュレータ使用時に比べて著しく高速化され、ほとんどのスイッチング・レギュレータにおいて波形表示をほんの数分でこなすことができます。Spiceとリアテクノロジーのスイッチング・レギュレータの80%に対応するMacro Model、200を超えるオペアンプ用モデルならびに抵抗、トランジスタ、MOSFETモデルをここからダウンロードできます。

- [LTspice IV \(Windows用\)をダウンロード \(2014年5月5日更新\)](#)
- [LTspice IV \(Mac OS X 10.7+用\)をダウンロード](#)
- [関連情報 & ショートカット](#)
- [Mac OS X用ショートカット](#)
- [スタート・ガイド](#)
- [ユーザ・ガイド\(ヘルプ・ファイル参照\)](#)
- [トランスの使用](#)
- [デモ回路集](#)
- [セミナーの開催予定を見る](#)

LTspiceのツイッターをフォロー 

LTspiceに関するビデオを見る 

### LTPOWERCAD

MYLINEAR ログイン



# Summary

Theorems for paired terminal circuits

Superposition, Ho-Tevenin, Reciprocity

Duality

Passive devices (elements) and active devices

**Transfer function and transient response**

Transfer function of single-pair terminal circuits

Resonance circuit

Bode plot

General properties



東京大学理学部・理学系研究科  
物性研究所  
勝本信吾  
Shingo Katsumoto

電子回路論第 4 回

Electric Circuits for Physicists



# Introduction of useful free software

## Circuit Simulator

### LTSpice (Linear Technology)



・ ・ とはならない  
By トランジスタ技術

# Circuit Simulator

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Graphical user interface: Circuit diagram

Linear Technology  
web site

Newest version  
LTSpice XVII !!



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# Operation example

## Design Simulation and Device Models

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### LTSPICE IV

#### LTspice IV

LTspice IVは高性能なSpice IIIシミュレータと回路図入力、波形ビューワに改善を加え、スイッチング・レギュレータのシミュレーションを容易にするためのモデルを搭載しています。Spiceの改善により、スイッチング・レギュレータのシミュレーションは、通常のSpiceシミュレータ使用時に比べて著しく高速化され、ほとんどのスイッチング・レギュレータにおいて波形表示をほんの数分で行なうことができます。Spiceとリニアテクノロジーのスイッチング・レギュレータの80%に対応するMacro Model、200を超えるオペアンプ用モデルならびに抵抗、トランジスタ、MOSFETモデルをここからダウンロードできます。

- [LTspice IV \(Windows用\)をダウンロード \(2014年5月5日更新\)](#)
- [LTspice IV \(Mac OS X 10.7+用\)をダウンロード](#)
- [関連情報 & ショートカット](#)
- [Mac OS X用ショートカット](#)
- [スタート・ガイド](#)
- [ユーザ・ガイド \(ヘルプ・ファイル参照\)](#)
- [トランスの使用](#)
- [デモ回路集](#)
- [セミナーの開催予定を見る](#)

LTspiceのツイッターをフォロー



LTspiceに関するビデオを見る



### LTPOWERCAD

[MYLINEAR ログイン](#)



# References

For circuit basics:

“Foundations of Analog and Digital Electronic Circuits”

by A. Agarwal and J. H. Lang (Elsevier, 2005)

1000 printed pages!

Ch.1 The Circuit Abstraction

“Teach Yourself Electricity and Electronics” 3<sup>rd</sup> Ed.

by Stan Gibilisco (McGraw-Hill, 2002) 748 printed pages

“Schaum’s outlines: Electric Circuits” 6<sup>th</sup> ed.

by M. Nahvi, J. A. Edminister (McGraw-Hill, 2014) 504pages

For measurement circuits:

“Electrical and Electronics Measurements”

by G. K. Banerjee (PHI Learning Private, 2012) 835 pages

# Outline today

3.2 Two terminal-pair passive circuits

3.2.1 Impedance matching (concept)

3.2.2 Poles and zeros of transfer function and Bode diagram

3.2.3 Image impedance

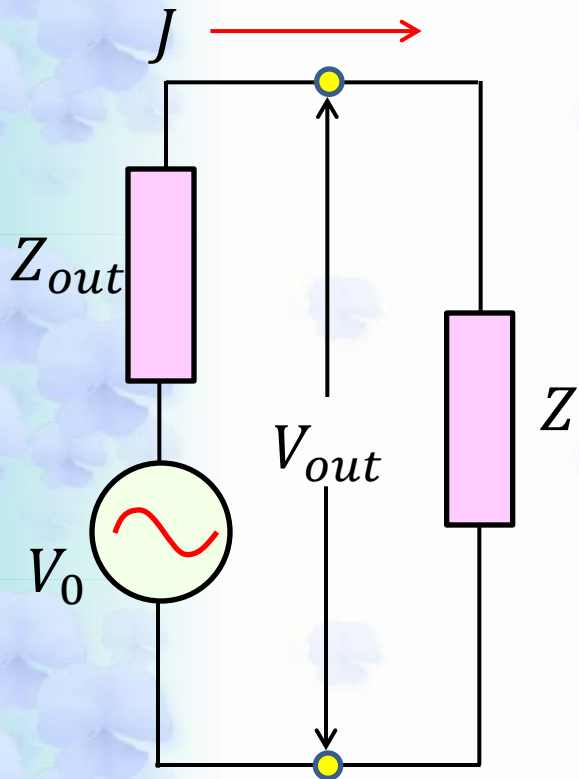
3.2.4 Impedance matching with terminal-pair circuits

3.2.5 Fidelity and distortion

3.2.6 Filter circuits



# Impedance matching



$$V_{out}(i\omega) = V_0(i\omega) - Z_{out}(i\omega)J(i\omega)$$

$$P = \text{Re}(V_{out}^* J) = \text{Re} \left( \frac{Z^* V_0^*}{Z^* + Z_{out}^*} \frac{V_0}{Z + Z_{out}} \right)$$
$$= \frac{|V_0|^2}{|Z + Z_{out}|^2} \text{Re}(Z)$$

$$\text{Maximum power: } P_{\max} = \frac{|V_0|^2}{4\text{Re}(Z_{out})^2}$$

Impedance matching condition:  $Z = Z_{out}^*$



# Zeros and Poles of Transfer Functions

$$W(s) = B \frac{(s - \beta_1) \cdots (s - \beta_m)}{(s - \alpha_1) \cdots (s - \alpha_n)}$$

$\{\alpha_j\}$ : Poles  
 $\{\beta_j\}$ : Zeros

Bode diagram

$$\log |W(i\omega)| = \log |B| + \sum_{j=1}^m \log |(i\omega - \beta_j)| - \sum_{j=1}^n \log |(i\omega - \alpha_j)|,$$

$$\arg(W(i\omega)) = \arg(B) + \sum_{j=1}^m \arg(i\omega - \beta_j) - \sum_{j=1}^n \arg(i\omega - \alpha_j)$$

$$W(s) = \frac{1}{s + 1}$$

$$\frac{d\theta}{d(\log \omega)} = -\frac{e^x}{e^{2x} + 1},$$

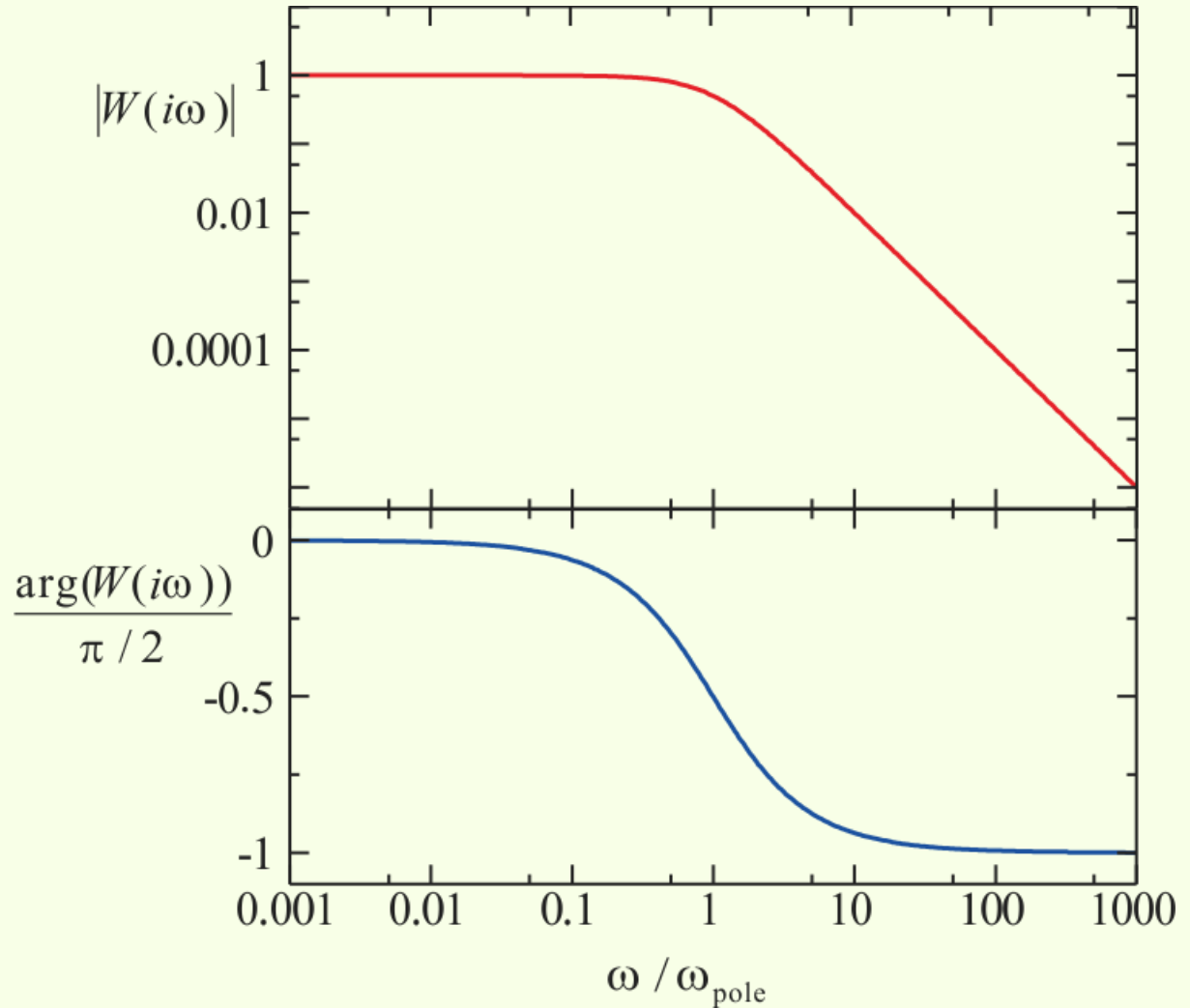
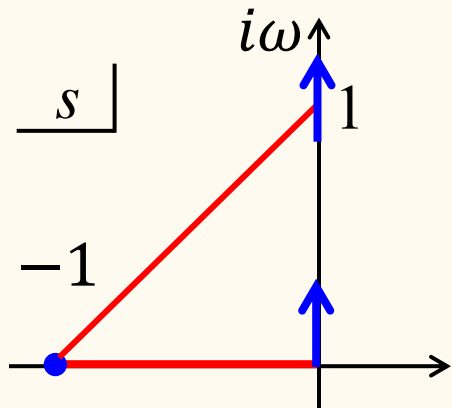
$$\frac{d^2\theta}{dx^2} = -\frac{e^x(1 - e^{2x})}{(e^{2x} + 1)^2}$$

$$\arg[W] = \theta$$

$$\log \omega = x \quad \frac{d(\log |W(i\omega)|)}{d(\log \omega)} = -\frac{e^{2x}}{1 + e^{2x}}, \quad \frac{d^2(\log |W|)}{dx^2} = -\frac{2e^{2x}}{(1 + e^{2x})^2}$$

# Effect of a Pole on the Real Axis for Bode Diagram

$$W(s) = \frac{1}{s+1}$$

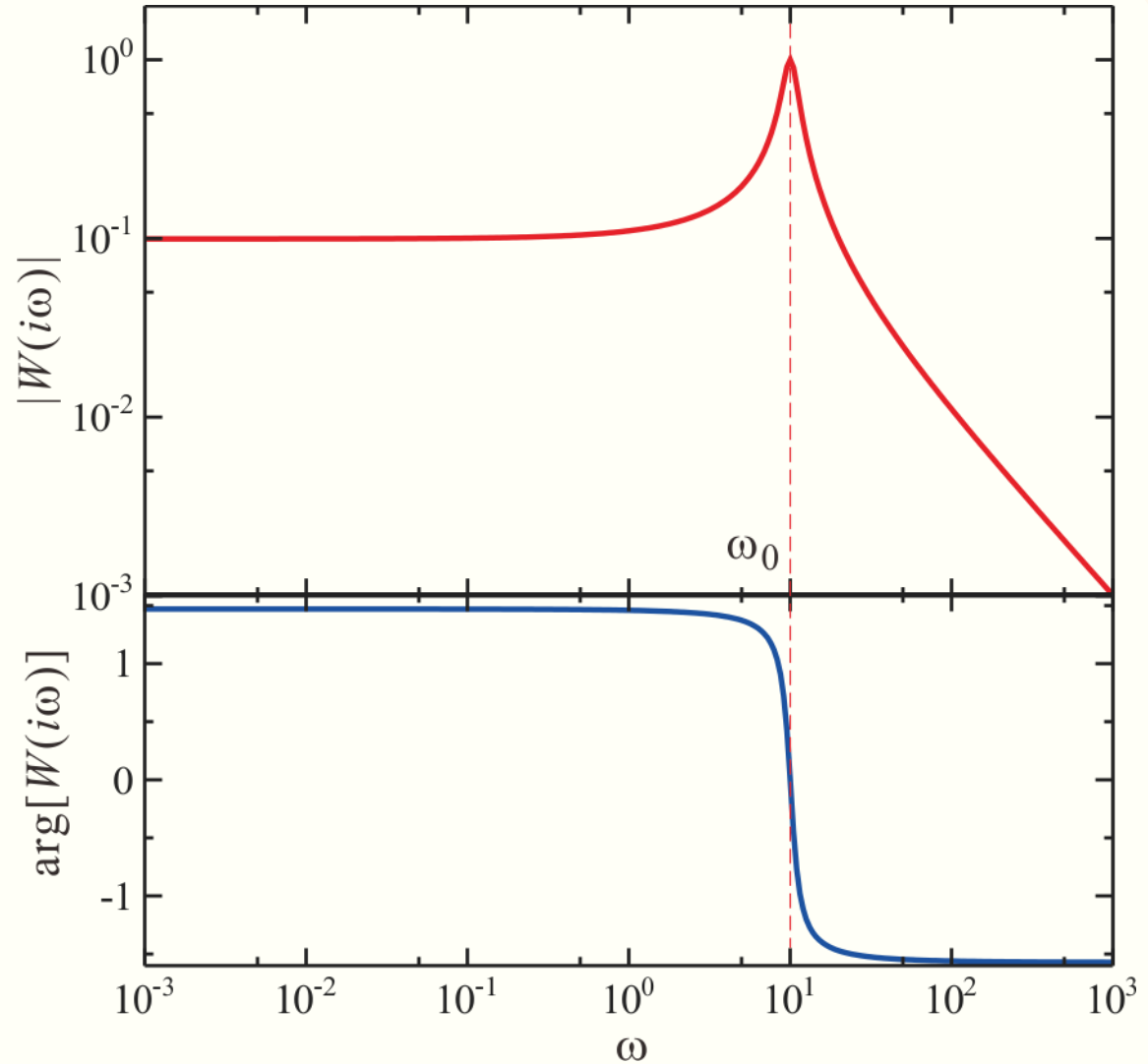
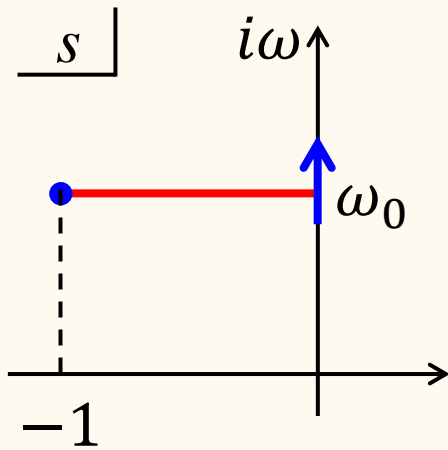


# Effect of a Resonance Pole (Finite Imaginary Part)

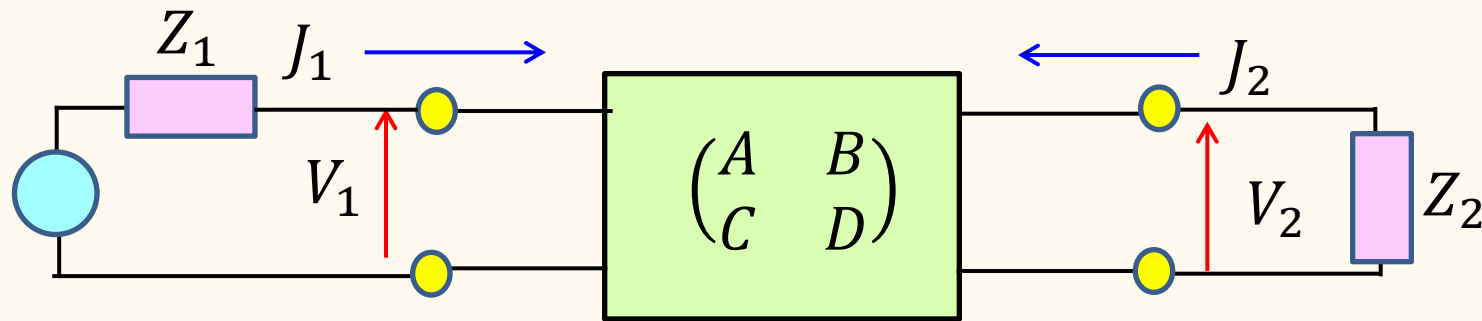
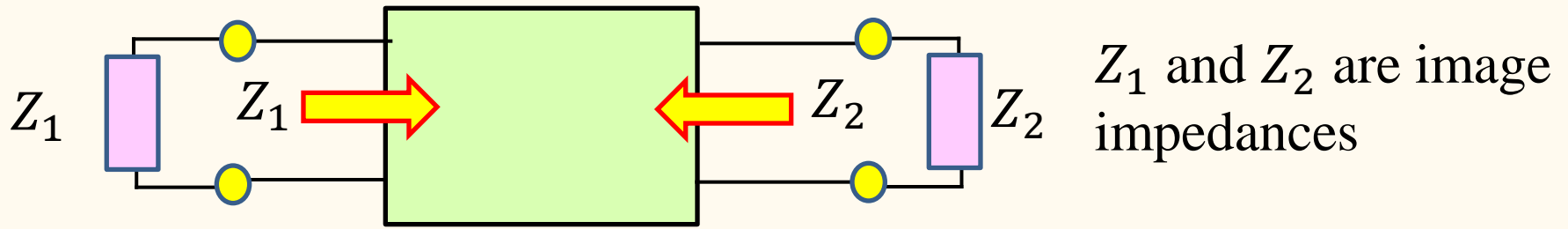
$$W(s) = \frac{1}{s + 1 - i\omega_0}$$

$$(\omega_0 > 0)$$

(fake example)



# Image parameters



$$\begin{cases} V_1 = AV_2 - BJ_2, \\ J_1 = CV_2 - DJ_2 \end{cases}$$

$$V_2 = -J_2 Z_2$$

$$\begin{cases} Z_1 = \frac{V_1}{J_1} = \frac{AZ_2 + B}{CZ_2 + D} \\ Z_2 = \frac{DZ_1 + B}{CZ_1 + A} \end{cases}$$

# Image parameters

$$Z_1 = \sqrt{\frac{AB}{CD}}, \quad Z_2 = \sqrt{\frac{DB}{CA}}$$

$$\frac{V_1}{V_2} = \sqrt{\frac{A}{D}}(\sqrt{AD} + \sqrt{BC}), \quad \frac{J_1}{-J_2} = \sqrt{\frac{D}{A}}(\sqrt{AD} + \sqrt{BC})$$

$$e^\theta \equiv \sqrt{\frac{V_1 J_1}{-V_2 J_2}} = \sqrt{\frac{Z_1}{Z_2} \frac{J_1}{-J_2}} = \sqrt{\frac{Z_2}{Z_1} \frac{V_1}{V_2}} = \sqrt{AD} + \sqrt{BC}$$

$\theta$ : Image propagation constant

$$\theta = \alpha + i\beta \quad (\alpha, \beta \in \mathbb{R})$$

$$\alpha = \frac{1}{2} \ln \left| \frac{V_1 J_1}{V_2 J_2} \right|, \quad \beta = \frac{1}{2} \arg \left[ \frac{V_1 J_1}{-V_2 J_2} \right]$$

Image attenuation constant

Image phase shift



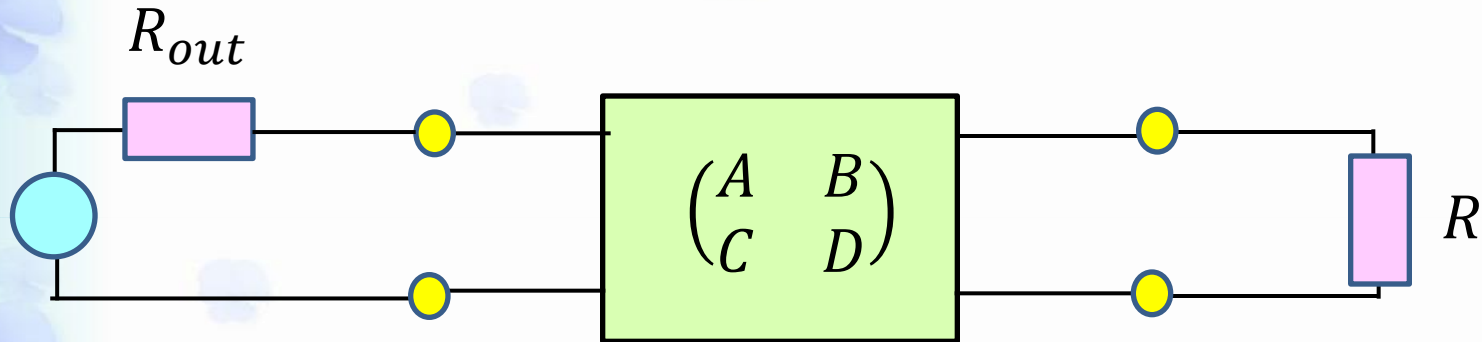
# Image parameters

$$A = \sqrt{\frac{Z_1}{Z_2}} \cosh \theta, \quad B = \sqrt{Z_1 Z_2} \sinh \theta,$$

$$C = \frac{1}{\sqrt{Z_1 Z_2}} \sinh \theta, \quad D = \sqrt{\frac{Z_2}{Z_1}} \cosh \theta$$

$Z_1, Z_2, \theta$ : Image parameters

# Impedance matching with two terminal-pair circuits



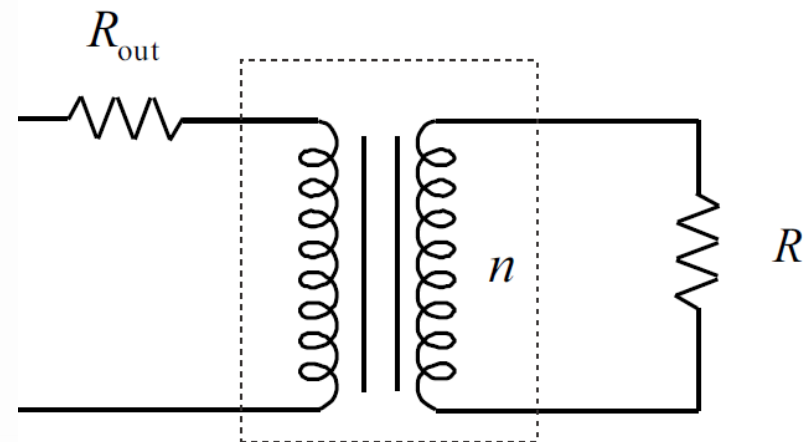
$$ABCD \neq 0 \quad R_{out} = \sqrt{\frac{AB}{CD}}, \quad R = \sqrt{\frac{BD}{AC}}$$

$$A = D = 0 \quad R_{out} = \frac{AR + B}{CR + D}, \quad R = \frac{DR_{out} + B}{CR_{out} + A} \rightarrow RR_{out} = B/C$$

$$B = C = 0 \quad R_{out}/R = A/D$$

Matching transformer

$$n = \sqrt{R/R_{out}}$$



# Fidelity and distortion in wave transformation

Linear response:  $w(t) = \mathcal{L}\{u(t)\}$

$$w(t) = A_0 u(t - \tau_0) \quad \therefore W(i\omega) = A_0 e^{-i\omega\tau_0} U(i\omega)$$

$$\Xi(i\omega) = A_0 e^{-i\omega\tau_0}$$

No distortion condition:

$$|\Xi(i\omega)| = A_0, \quad \arg[\Xi(i\omega)] = -\omega\tau_0$$

**(1) No filter effect**

$$\tau(\omega) = -\frac{d\phi(\omega)}{d\omega} \quad (\phi(\omega) = \arg[\Xi(i\omega)])$$

**(2) No dispersion in group delay**

Breaks (1): amplitude distortion, (2): delay distortion

# Effect of distortion

Sinusoidal amplitude distortion (amplitude modulation)

$$A(\omega) = a_1 \cos(\tau_1 \omega) + a_0, \quad \phi(\omega) = -\tau_0 \omega$$

$$\begin{aligned} w(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega) U(i\omega) e^{i(\omega t + \phi(\omega))} d\omega \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega U(i\omega) \{a_1 \cos(\tau_1 \omega) + a_0\} e^{i\omega(t - \tau_0)} \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega U(i\omega) \left[ a_0 + \frac{a_1}{2} (e^{i\tau_1 \omega} + e^{-i\tau_1 \omega}) \right] e^{i\omega(t - \tau_0)} \\ &= a_0 u(t - \tau_0) + \frac{a_1}{2} [u(t - \tau_0 + \tau_1) + u(t - \tau_0 - \tau_1)] \end{aligned}$$

Paired echo

# Effect of distortion

Sinusoidal group delay distortion

$$A(\omega) = A_0, \quad \phi(\omega) = -\tau_0\omega + b_1 \sin(\tau_1\omega)$$

$$\exp[ib_1 \sin(\tau_1\omega)] \approx 1 + \frac{ib_1}{2i} (e^{i\tau_1\omega} - e^{-i\tau_1\omega})$$

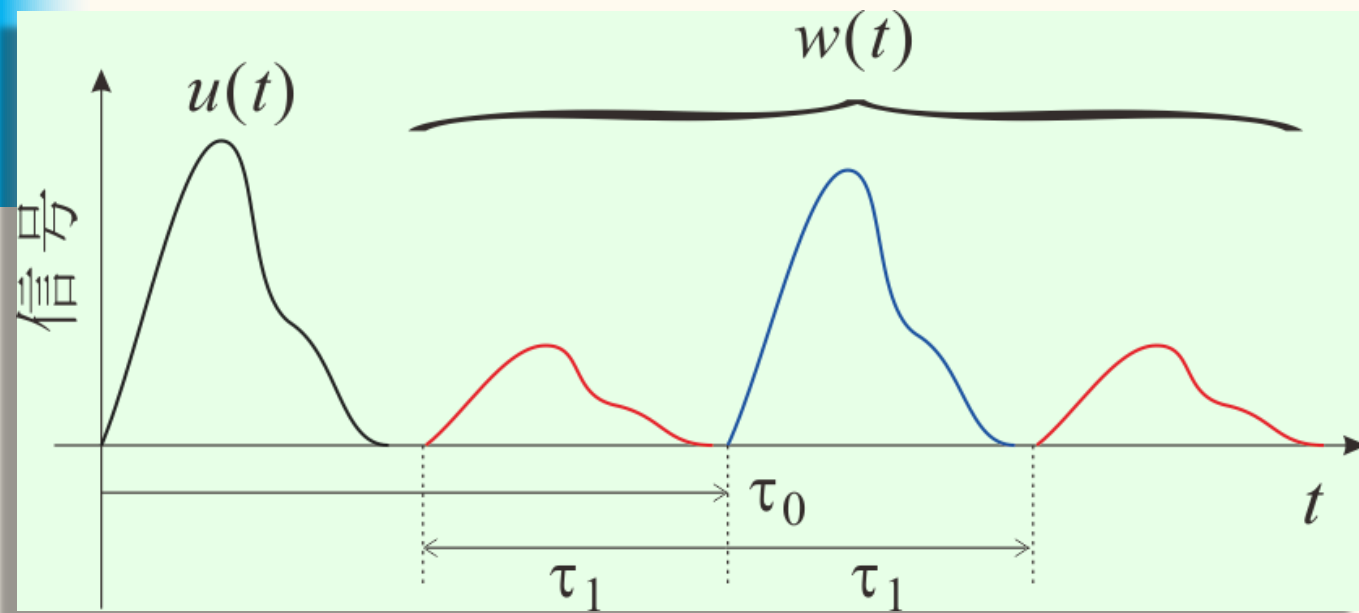
$$w(t) = A_0[u(t - \tau_0) + \frac{b_1}{2}\{u(t - \tau_0 + \tau_1) - u(t - \tau_0 - \tau_1)\}]$$

Paired echo

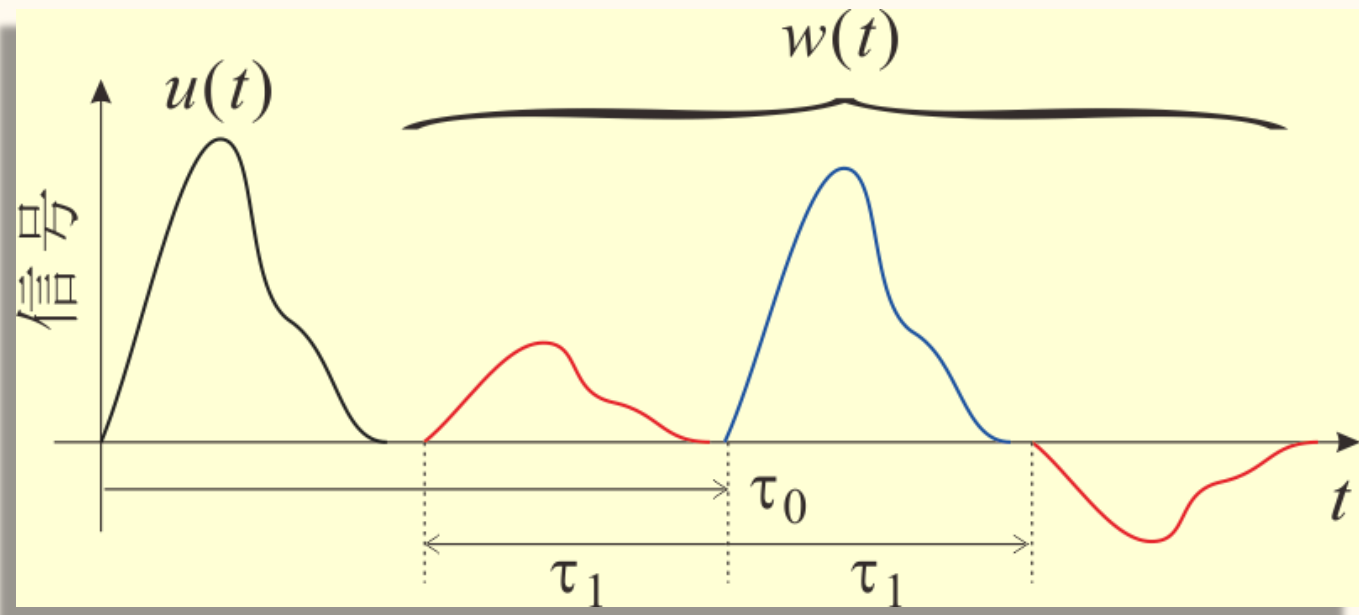


# Distortion (paired echo)

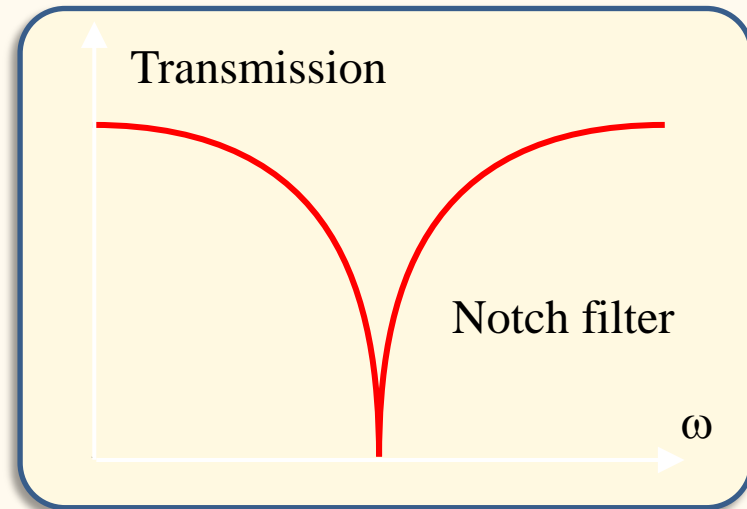
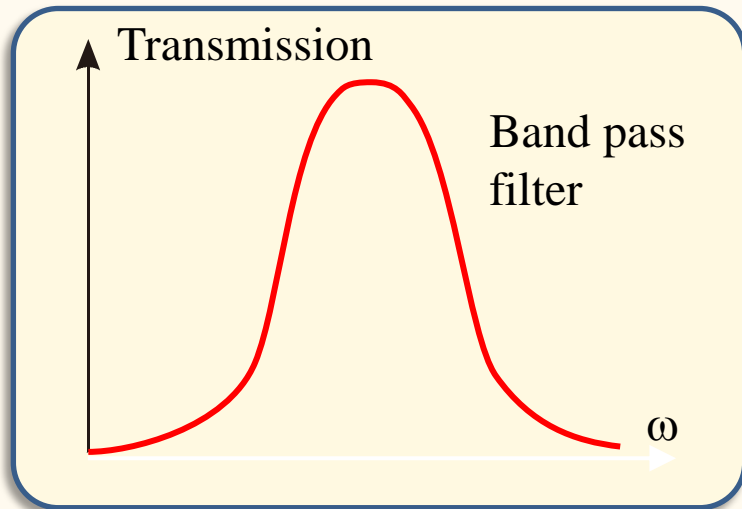
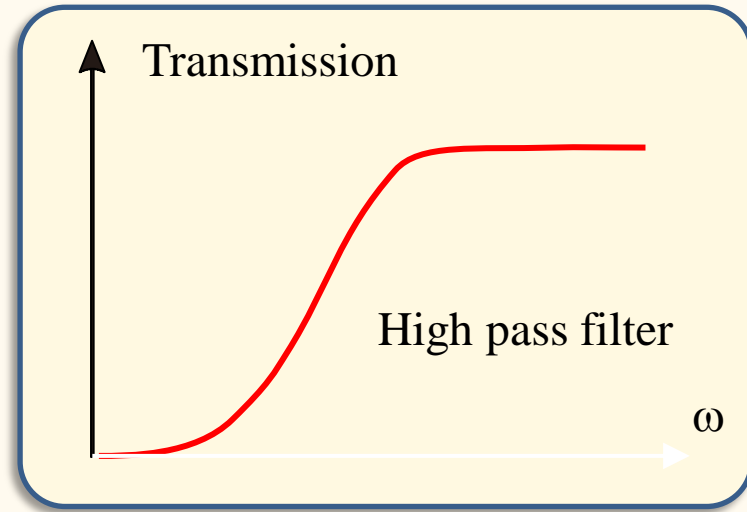
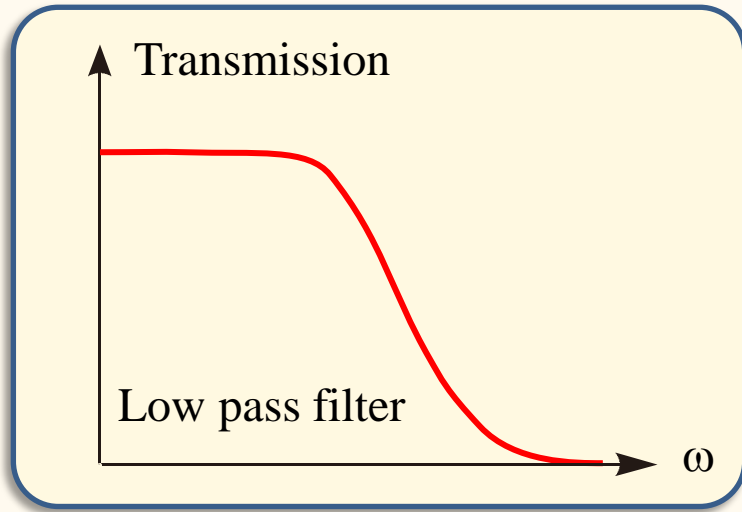
Cosine  
Amplitude  
Distortion



Sine  
Delay  
Distortion



# Filter Circuit

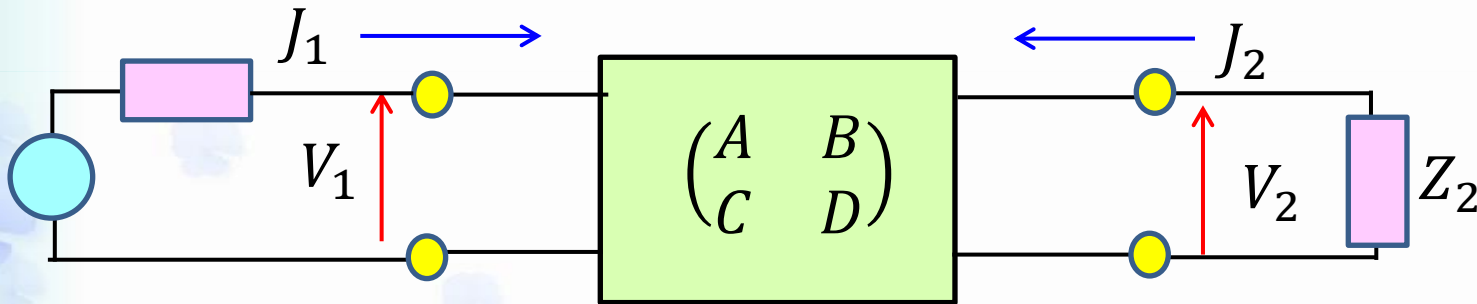


# Transmission

Voltage transmission coefficient:  $T(i\omega) \equiv \frac{V_2(i\omega)}{V_1(i\omega)}$

$$\log T = \log |T| + i \arg T = -\alpha - i\beta$$

attenuation                      Phase shift

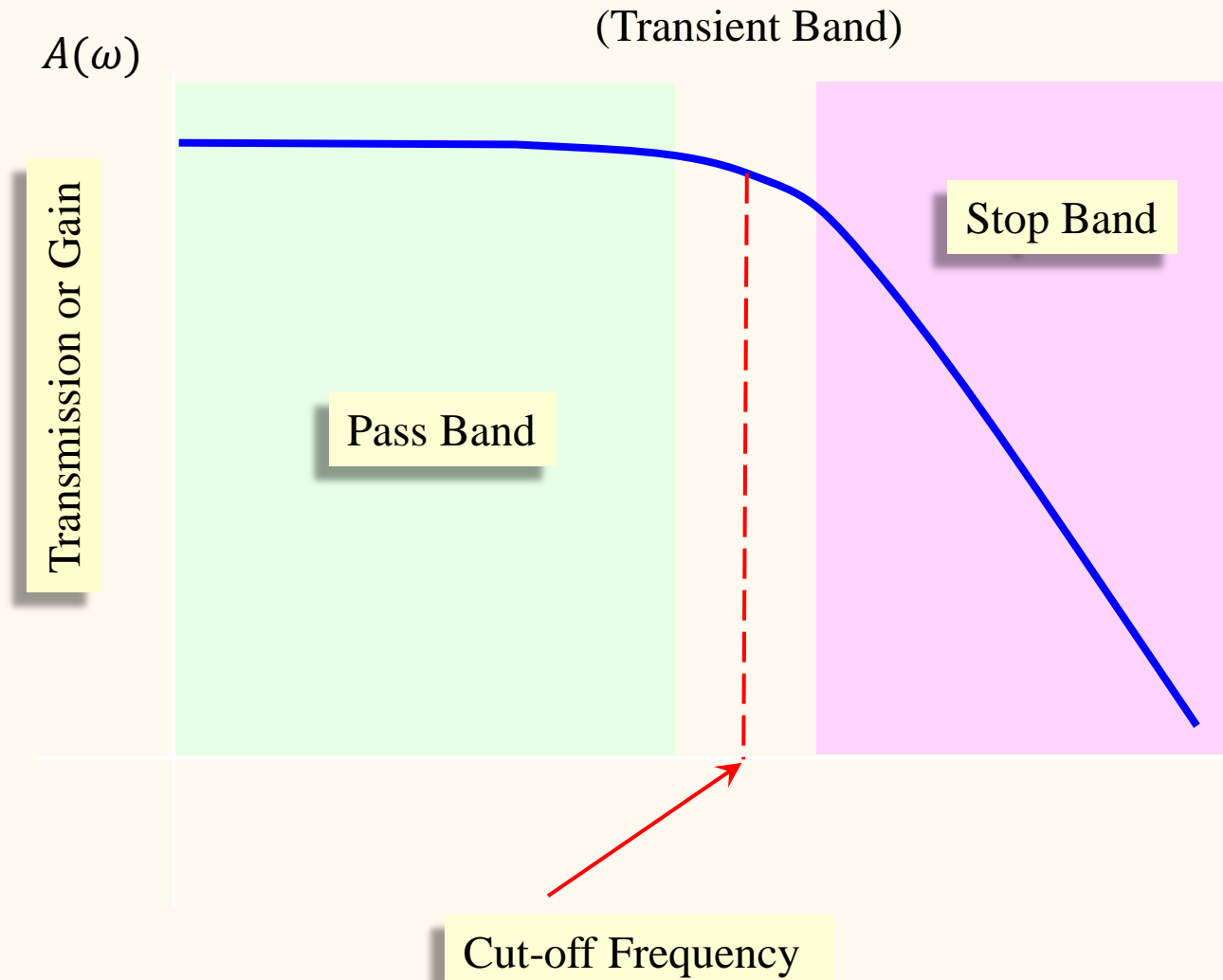


Square root power transmission coefficient

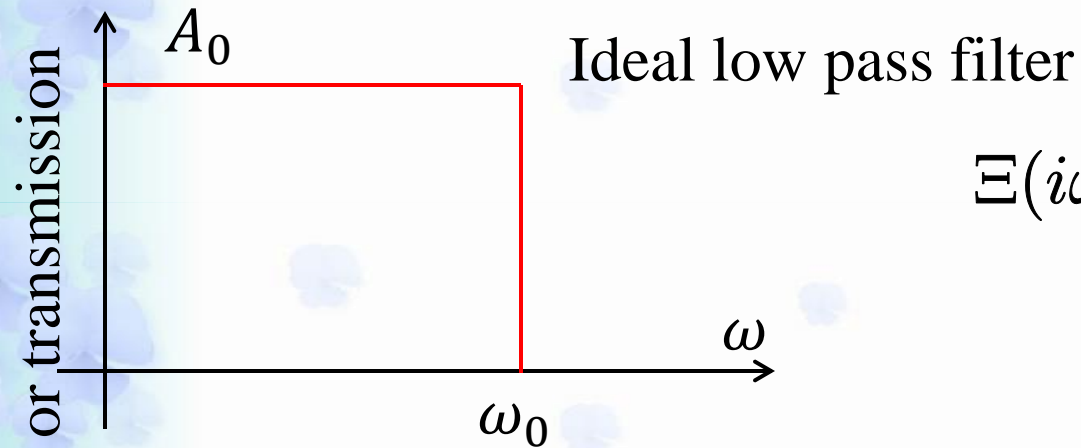
$$S_B \equiv \sqrt{\frac{P_0}{P_2}} = \frac{R_2 A + B + C R_1 R_2 + D R_1}{2\sqrt{R_1 R_2}}$$

# Terms for Filters

$$\mathbb{E}(i\omega) = A(\omega)e^{i\phi(\omega)}$$



# Ideal filter (not exist)



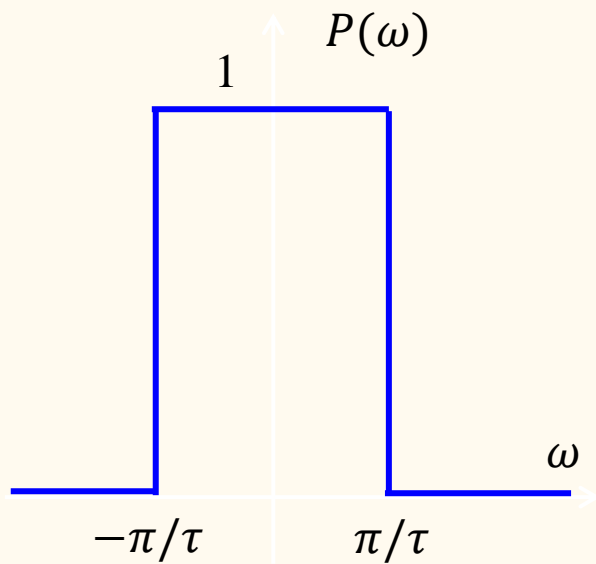
$$\Xi(i\omega) = A_0 H(\omega_0 - \omega)$$

Heaviside function

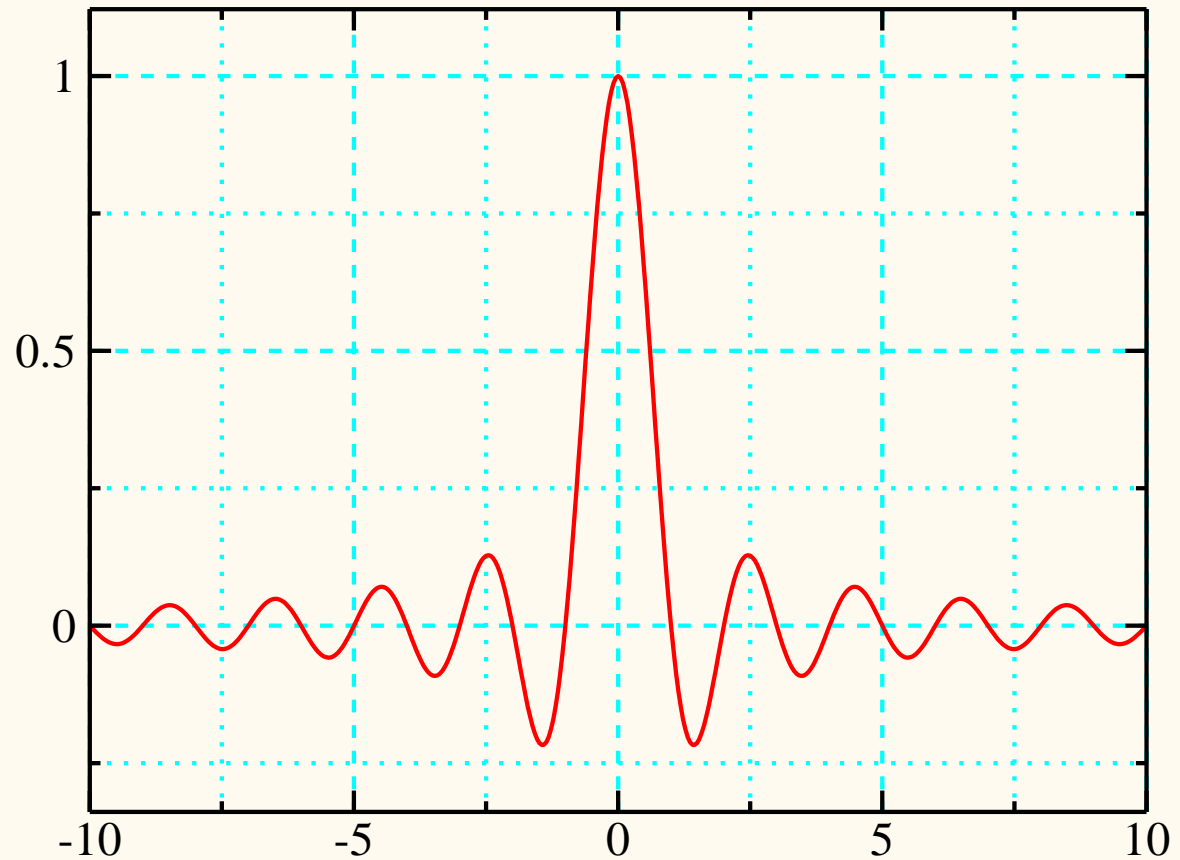
$$\begin{aligned} w(t) &= \int_{-\omega_0}^{\omega_0} A_0 e^{i\omega t} \frac{d\omega}{2\pi} \\ &= A_0 \int_{-\omega_0}^{\omega_0} \frac{d\omega}{2\pi} \cos \omega t \\ &= 2A_0 f_0 \frac{\sin \omega_0 t}{\omega_0 t} = 2A_0 f_0 \text{sinc}(2f_0 t) \end{aligned}$$



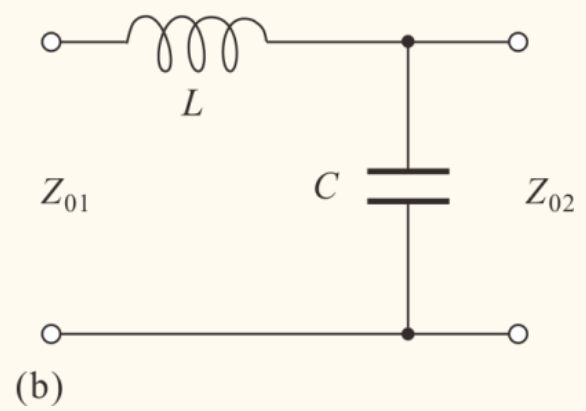
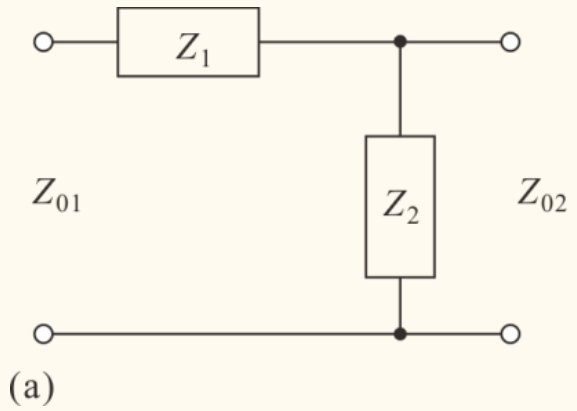
# Sinc function



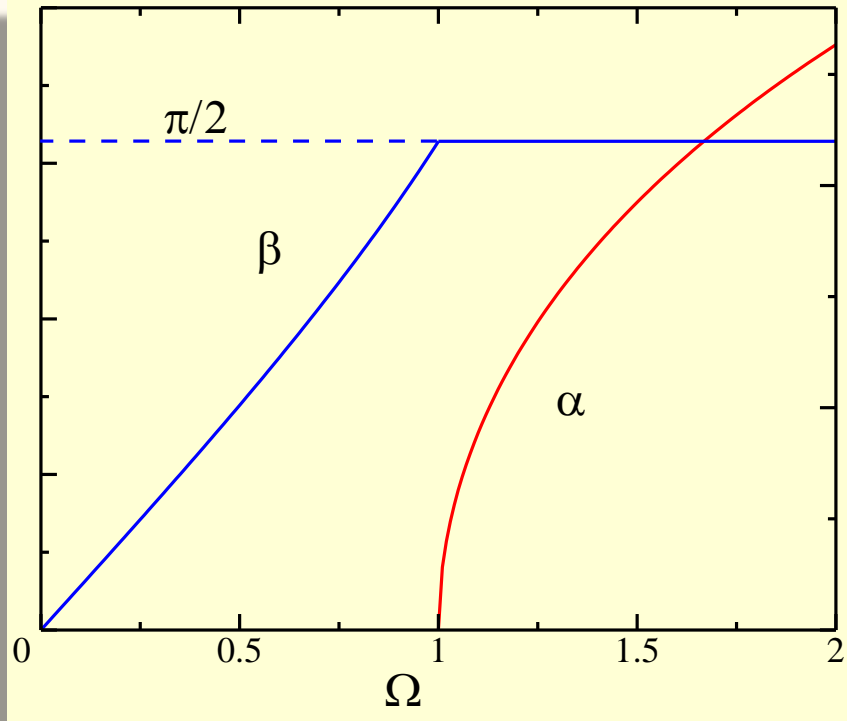
$$\text{sinc}(x) = \frac{\sin \pi x}{\pi x}$$



# Constant K type filter

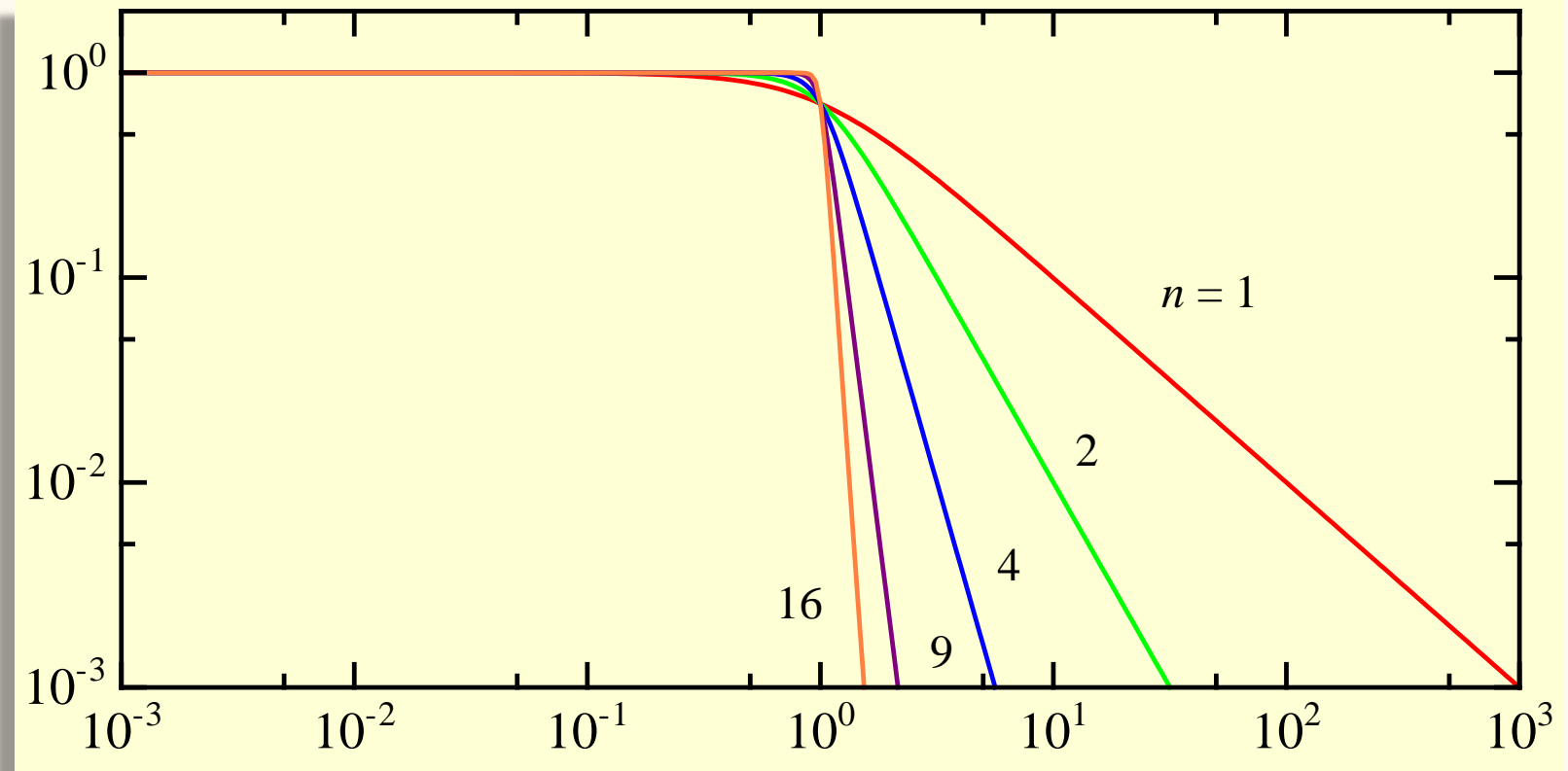


$$Z_1 Z_2 = R^2 (= K)$$



# Butterworth Filter

$$G^2(i\omega/\omega_0) = |H(i\omega)|^2 = \frac{1}{1 + (\omega/\omega_0)^{2n}}$$



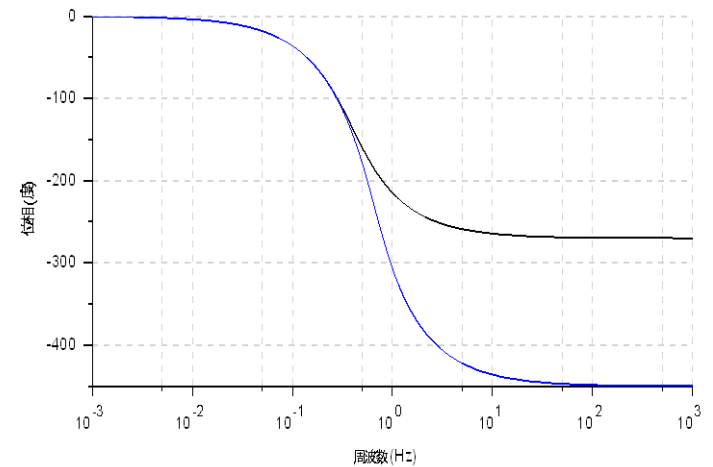
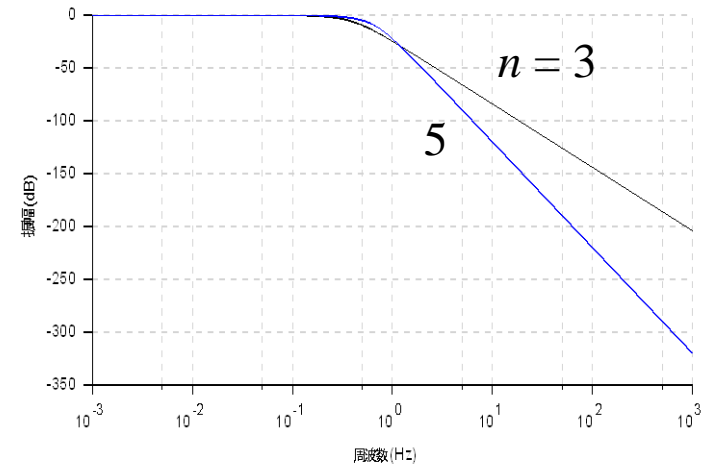
# Bessel Filter

## Inverse Bessel Polynomial

$$B_0 = 1, \quad B_1(s) = s + 1$$

$$B_n(s) = (2n - 1)B_{n-1}(s) + B_{n-2}(s)s^2$$

$$\Xi(s) = \frac{B_n(0)}{B_n(s)}$$

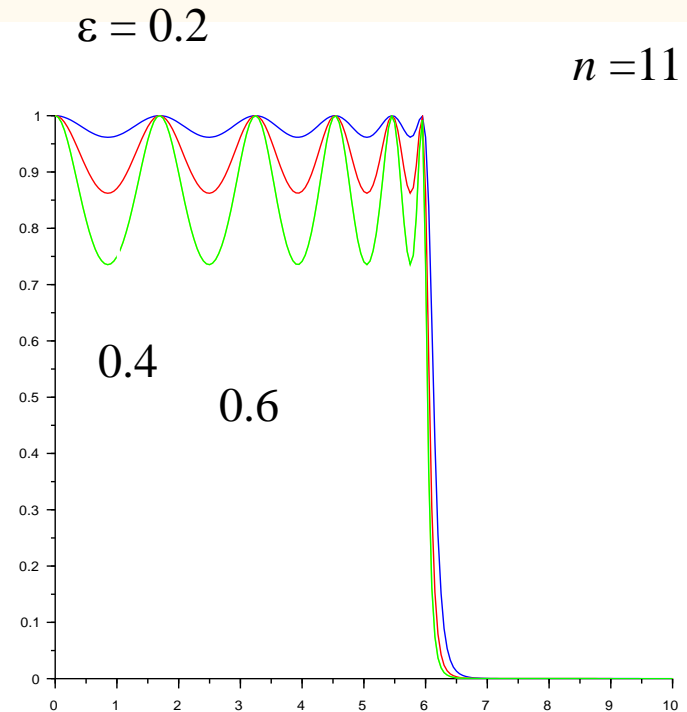
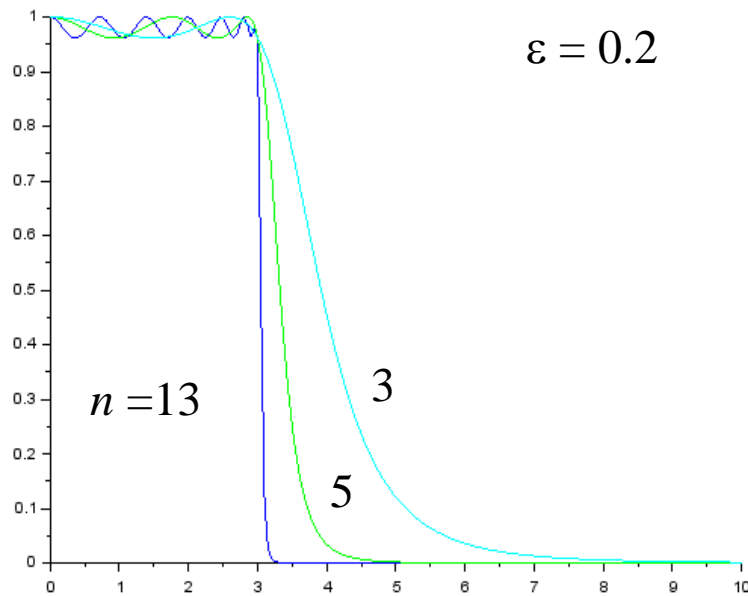


# Chebyshev Filter

$$G_n(i\Omega) = |H_n(i\Omega)| = \frac{1}{\sqrt{1 + \epsilon^2 T_n^2(\Omega)}}$$

$\epsilon$ : Ripple coefficient

$T_n$ :  $n$ -th order Chebyshev polynomial

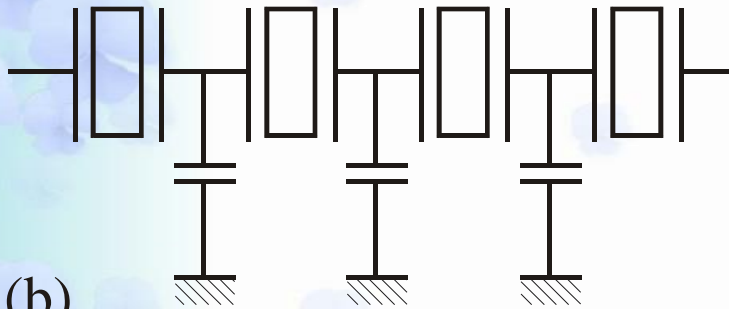




# Quartz crystal filter

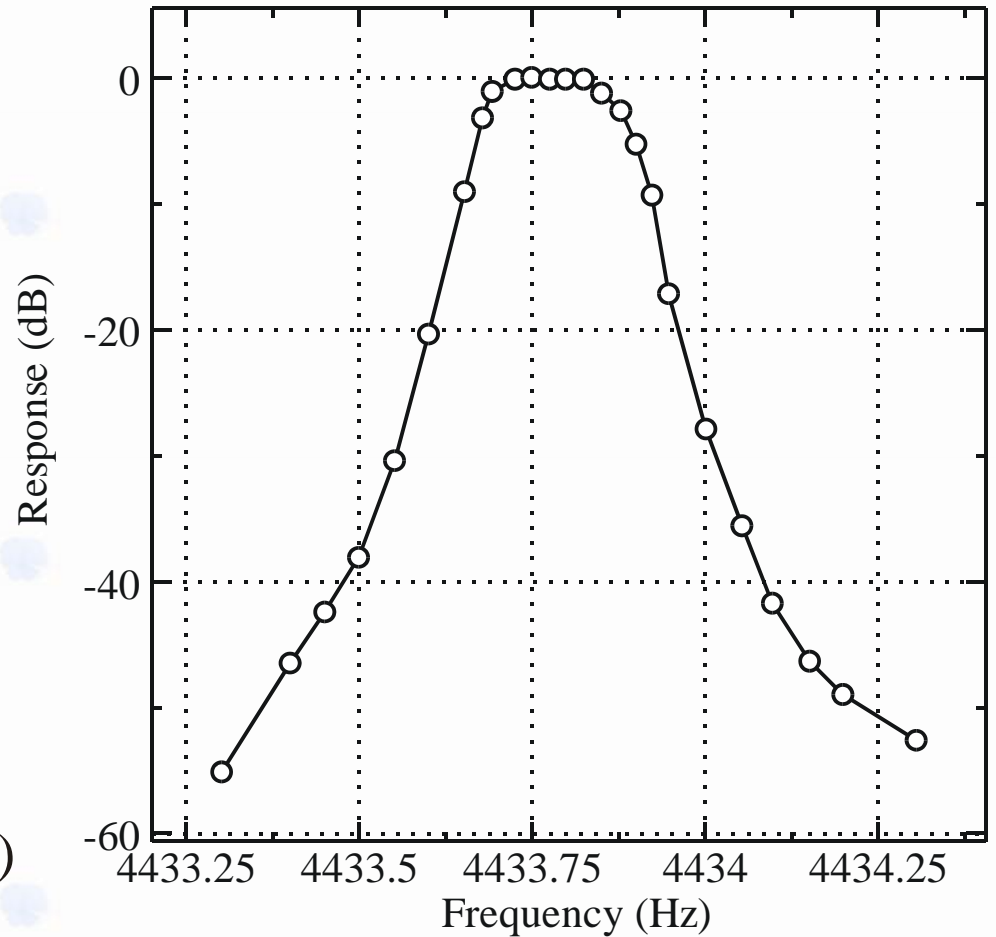


(a)



(b)

(c)



# Packaged filters



Web selection [page](#)

<http://www.minicircuits.com/products/Filters.shtml>

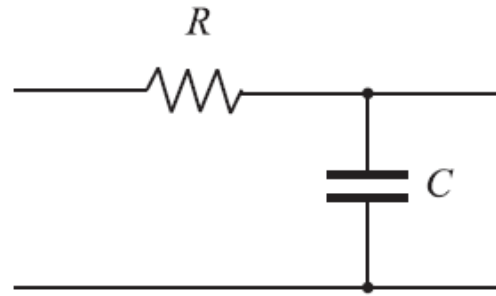


Mini-Circuits

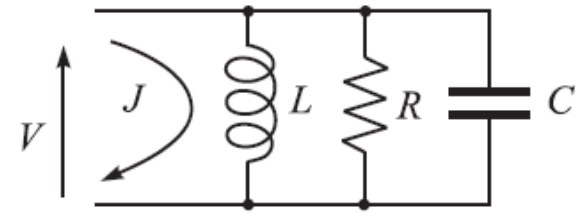
Band Pass

19.2 – 23.6MHz 50Ohm

# Classification with the number of energy storages



(a)



(b)

(a) Single energy storage

$$\Xi(s) = \frac{1}{1 + s/s_0}$$

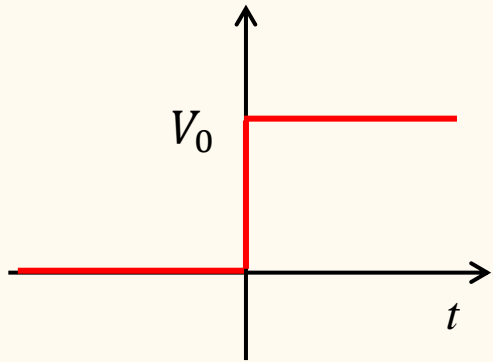
(b) Double energy storage

$$\Xi(s) = \frac{1}{b + s + as^{-1}}$$

# 過渡応答 (Transient Response)

$$w(t) = \int_{-\infty}^{\infty} \Xi(i\omega)U(i\omega)e^{i\omega t} \frac{d\omega}{2\pi}$$

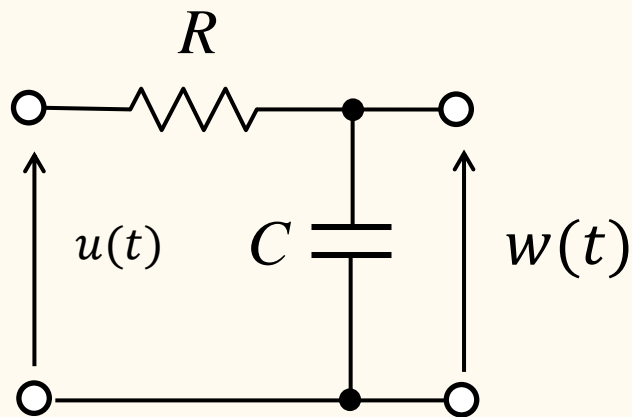
Heaviside



$$H(t) = \begin{cases} 0 & t < 0, \\ 1/2 & t = 0, \\ 1 & t > 0 \end{cases}$$

$$\mathcal{F}\{H(t)\} = \frac{1}{i\omega} + \pi\delta(\omega)$$

# Simple application

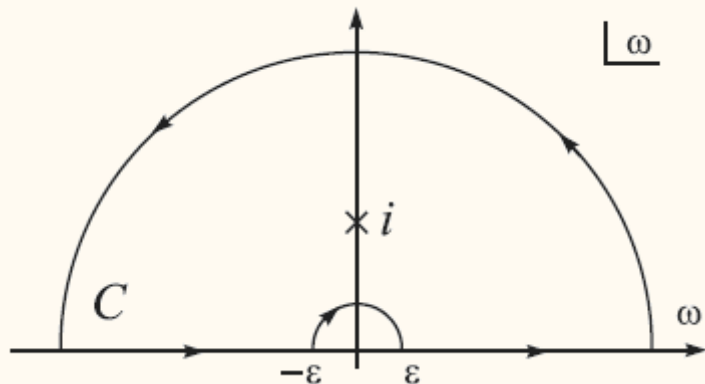


$$V = V_0 \left[ 1 - \exp \left( -\frac{t}{CR} \right) \right]$$

$$g(t) = \int_{-\infty}^{\infty} \frac{1}{1+i\omega} \left[ \frac{1}{i\omega} + \pi\delta(\omega) \right] e^{i\omega t} \frac{d\omega}{2\pi}$$

$$= \int_{-\infty}^{\infty} \frac{e^{i\omega t}}{(i-\omega)\omega} \frac{d\omega}{2\pi} + \frac{1}{2}$$

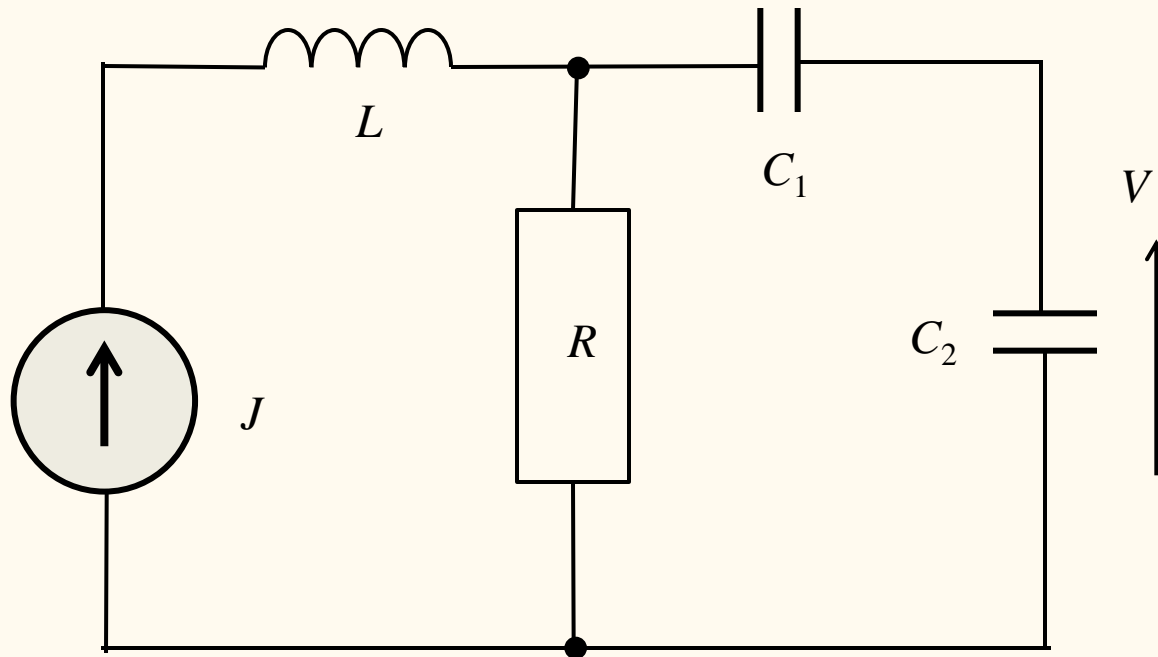
$$-2\pi i \frac{e^{-t}}{2\pi i} - \lim_{\epsilon \rightarrow 0} \left[ \int_{\pi}^0 \frac{e^{i\epsilon e^{i\theta} t}}{\epsilon e^{i\theta} (\epsilon e^{i\theta} - i)} \frac{i\epsilon e^{i\theta} d\theta}{2\pi} \right] = -e^{-t} - \frac{1}{2}$$



$$g(t) = -e^{-t}$$

# Exercise B-1

Calculate the voltage  $V$  over capacitor  $C_2$  by using Norton theorem.

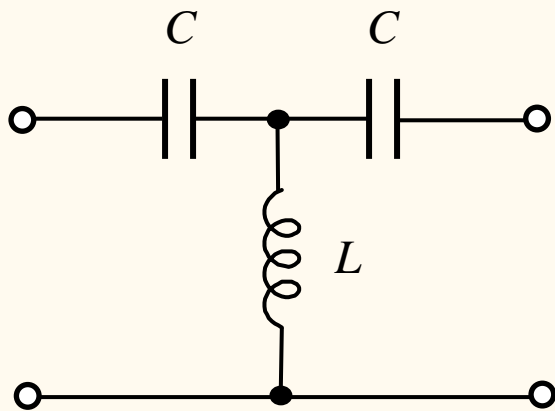




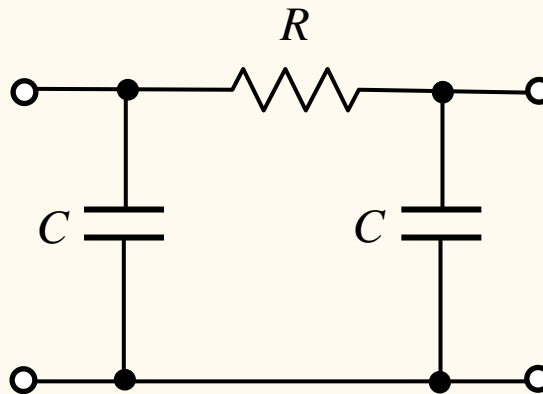
# Exercise B-2

Obtain F-matrices for the circuits below.

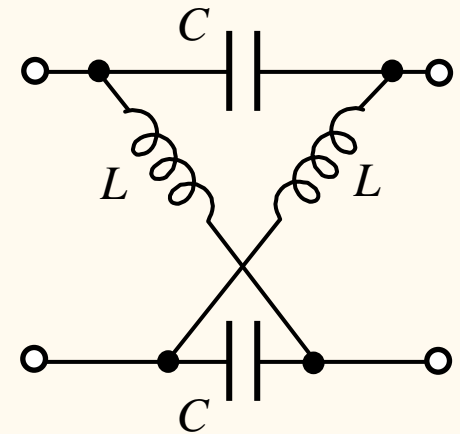
(a)



(b)

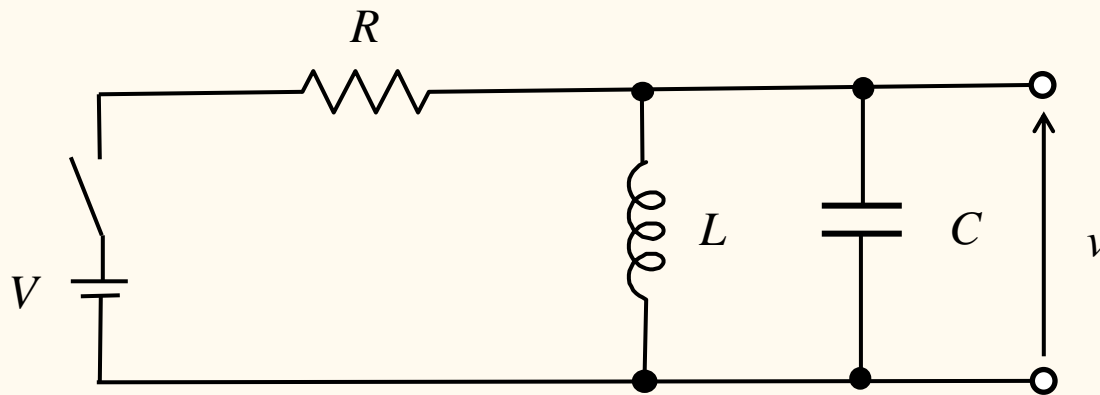


(c)



# Exercise B-3

The switch below is turned on at  $t = 0$ .  
Obtain the time evolution of voltage  $v$  henceforth.





電子回路論第5回

Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto



# Outline

Introduction of a freeware “Scilab”

## **Ch.4 Amplification circuit**

4.1 Amplification and system stability

4.1.1 What is amplifier?

4.1.2 Feedback

4.1.3 Stability of feedback

4.2 Operational amplifier (OP-amp)

4.2.1 Linear model of OP-amp

4.2.2 Package

4.2.3 Circuit examples

4.2.4 Datasheet

4.2.5 Stability

# A convenient freeware: Scilab

Home - Scilab

www.scilab.org

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**Download Scilab**  
Scilab 5.5.1 - 32-bit Windows • 127.92 MB  
Other Systems

Open source software for numerical computation

Scilab Console

File Edit Control Applications ?

File Browser C:\

Name

- Perflogs
- Program Files
- Users
- Windows
- autexec.bat
- config.sys

Startup execution:  
loading initial environment  
-->a=rand(4,4)  
a =  
  
column 1 to 2

Name	Dimen...	Type	Visib
a	4x4	Double	
ans	1x1	Boolean	
home	1x1	String	
WSCI	1x1	String	
PWD	1x1	String	
%k	1x1	Boolean	
%F	1x1	Boolean	
%T	1x1	Boolean	
%nan	1x1	Double	
%nanf	1x1	Double	

News : 10/16/2014 - Windows users, reinstall Scilab 5.5.1 10/6/2014 - Scilab at C.

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Education

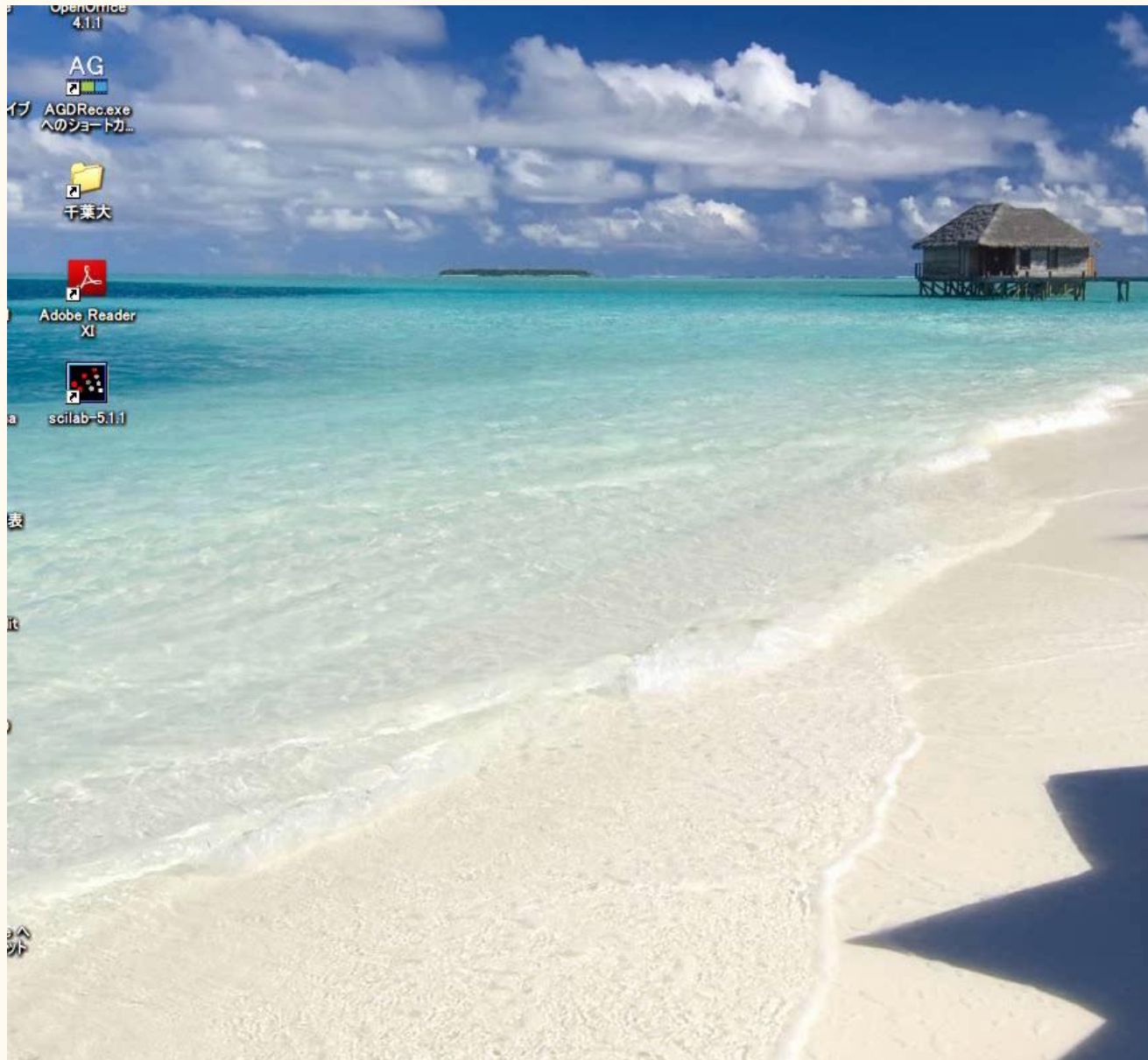
Scilab is widely used in secondary and higher education institutions for teaching [mathematics](#), [engineering sciences](#) and [automatic control engineering](#).

To donate

**Scilab**

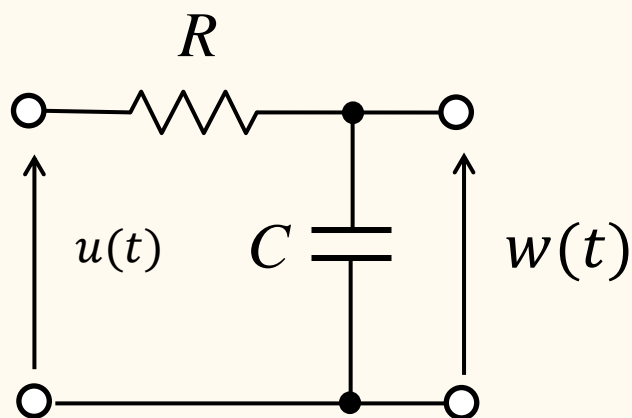
- Overview
- New in Scilab 5.5.0
- New in Scilab 5.5.1
- Xcos
- Features
- Gallery
- System requirements
- Quality

# Transfer function analysis with Scilab





# Simple application

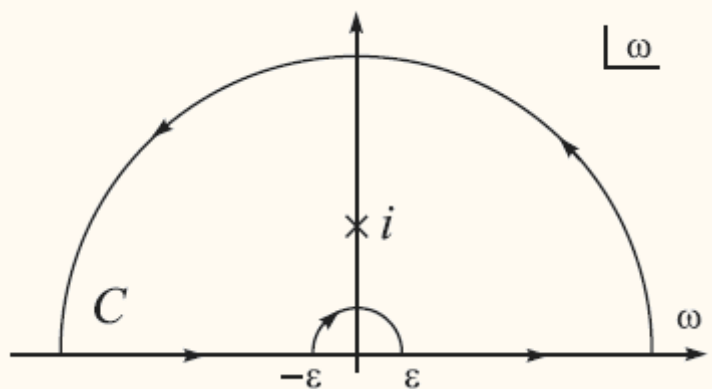


$$V = V_0 \left[ 1 - \exp \left( -\frac{t}{CR} \right) \right]$$

$$g(t) = \int_{-\infty}^{\infty} \frac{1}{1+i\omega} \left[ \frac{1}{i\omega} + \pi\delta(\omega) \right] e^{i\omega t} \frac{d\omega}{2\pi}$$

$$= \int_{-\infty}^{\infty} \frac{e^{i\omega t}}{(i-\omega)\omega} \frac{d\omega}{2\pi} + \frac{1}{2}$$

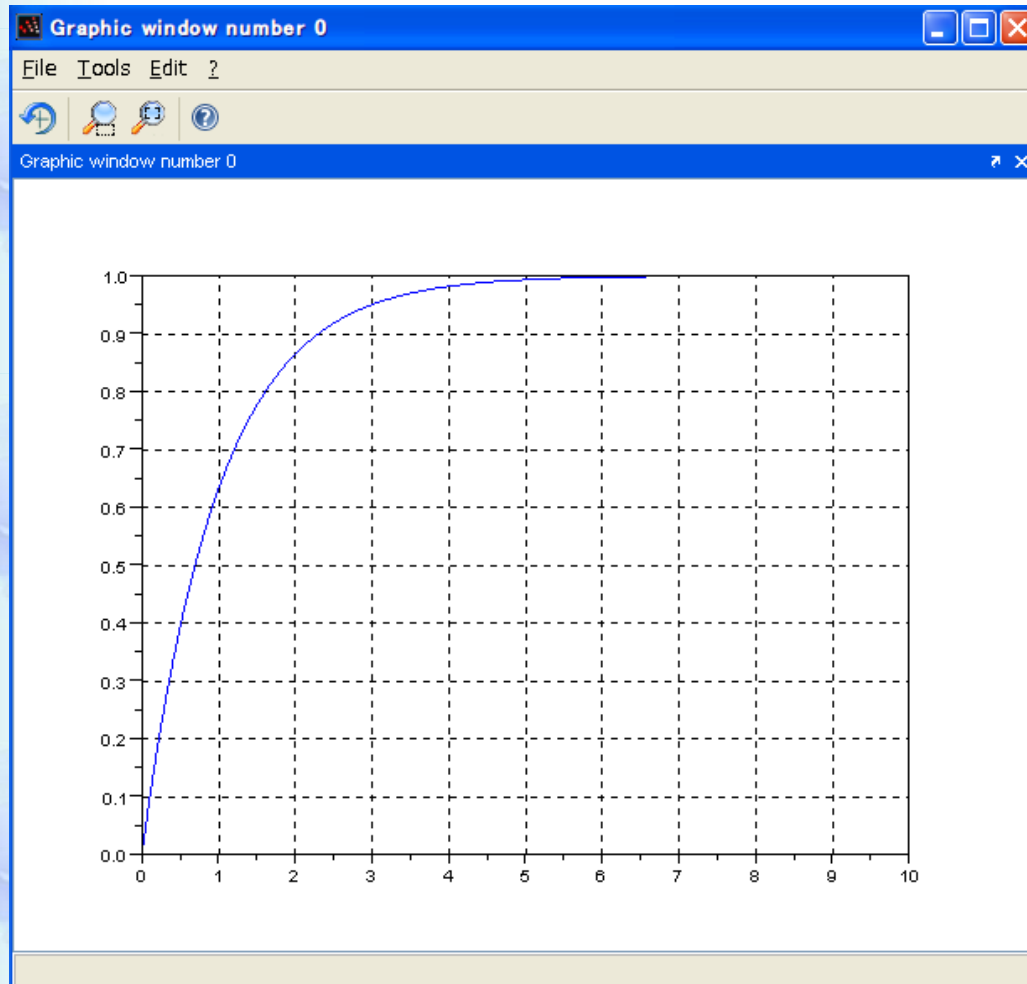
$$-2\pi i \frac{e^{-t}}{2\pi i} - \lim_{\epsilon \rightarrow 0} \left[ \int_{\pi}^0 \frac{e^{i\epsilon e^{i\theta} t}}{\epsilon e^{i\theta} (\epsilon e^{i\theta} - i)} \frac{i\epsilon e^{i\theta} d\theta}{2\pi} \right] = -e^{-t} - \frac{1}{2}$$



$$g(t) = -e^{-t}$$

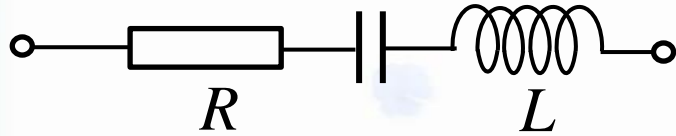
# Transient response: Use of Scilab

$$\Xi(s) = \frac{1}{1+s}$$

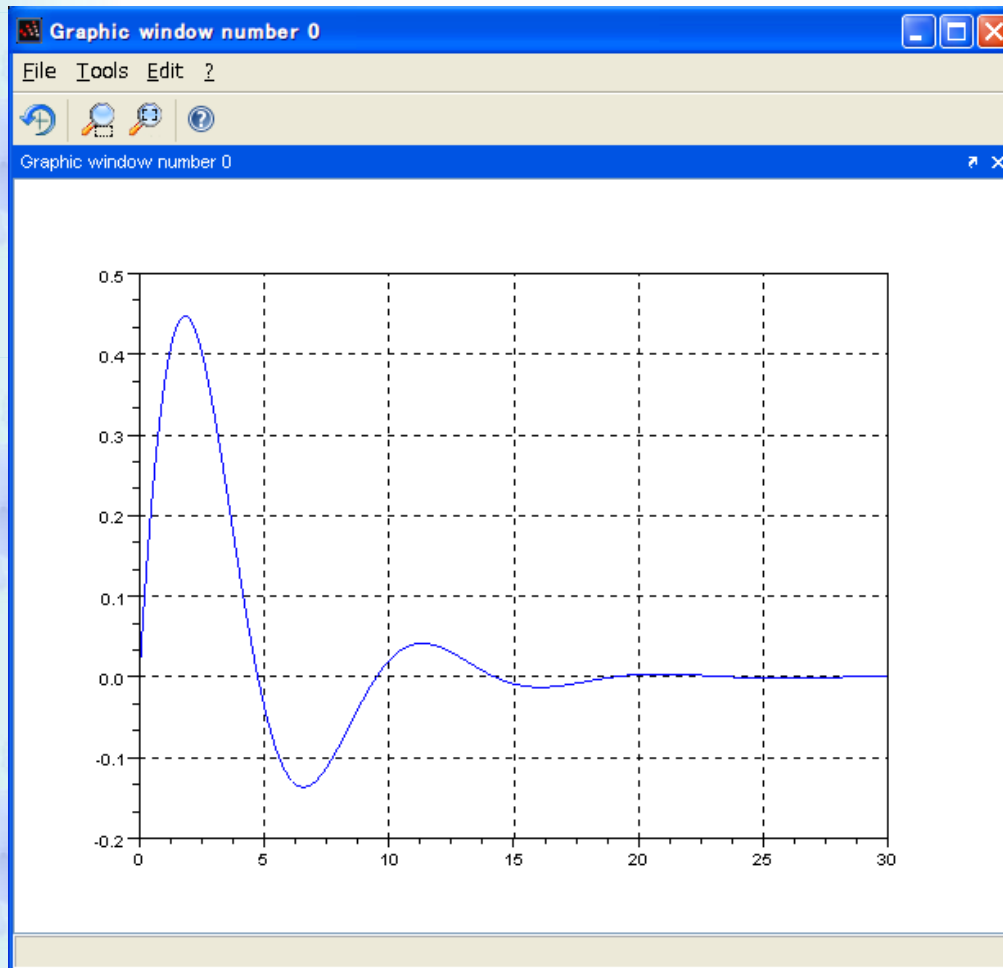


```
-->s=poly(0,'s');  
-->G=1/(1+s);  
-->sys=syslin('c',G);  
-->t=linspace(0,10,100);  
-->y=csim('step',t,sys);  
-->plot(t,y)  
-->xgrid()
```

# Transient response: Use of Scilab



$$Y(s) = \frac{Cs}{LCs^2 + CRs + 1}$$



```
-->G=s/(1+s+2*s*s);  
-->sys=syslin('c',G);  
-->y=csim('step',t,sys);  
-->plot(t,y)
```

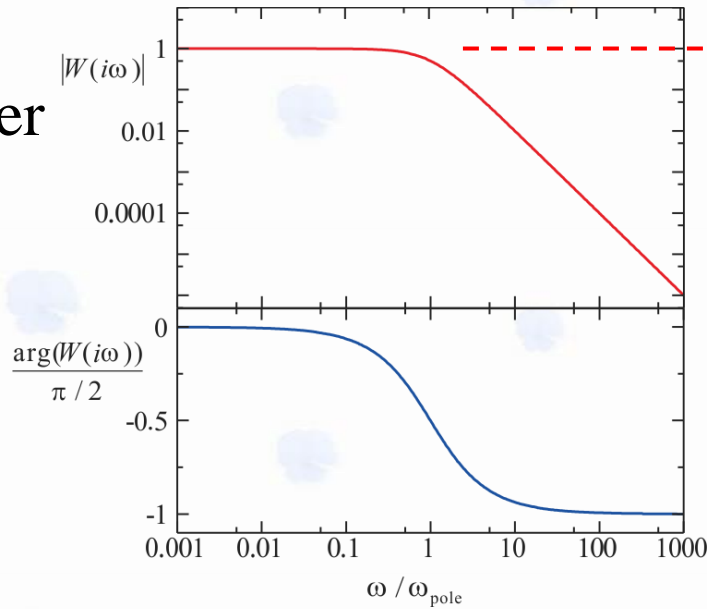


# Chapter 4

## Amplification circuits

# Linear amplifier

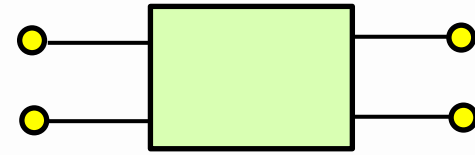
passive filter



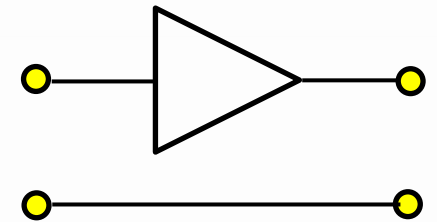
gain = 1

gain > 1 → amplifier

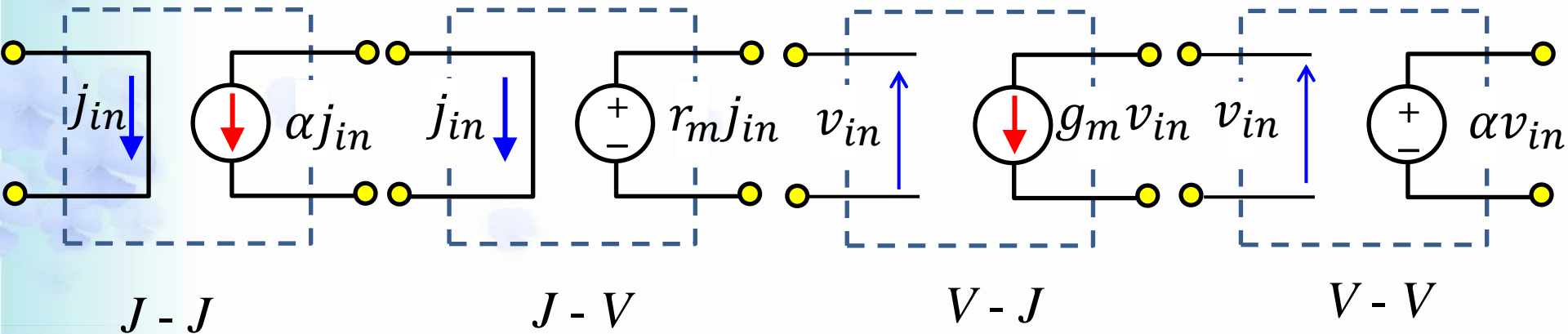
four terminal circuit model



Circuit symbol



Controlled power source models





# Gain, and “Unit” for gain

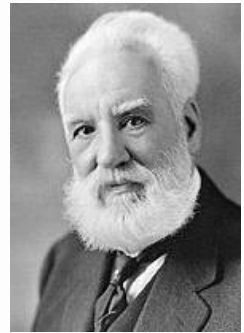
$$\text{Voltage gain: } \left| \frac{v_{out}}{v_{in}} \right| \quad \text{Current gain: } \left| \frac{j_{out}}{j_{in}} \right| \quad \text{Power gain: } \left| \frac{v_{out}j_{out}}{v_{in}j_{in}} \right|$$

When we say “the gain of the amplifier ...”, the gain means power gain.

$$\text{quantity } Q, \text{ unit } Q_0 : Q \text{ in log scale: } L = \log_{10} \frac{Q}{Q_0} \quad (\text{B, bel})$$

cf. deca- 10  
1/10 dB : (decibel)  
From: G. Bell

Alexander Graham Bell  
1847 - 1922



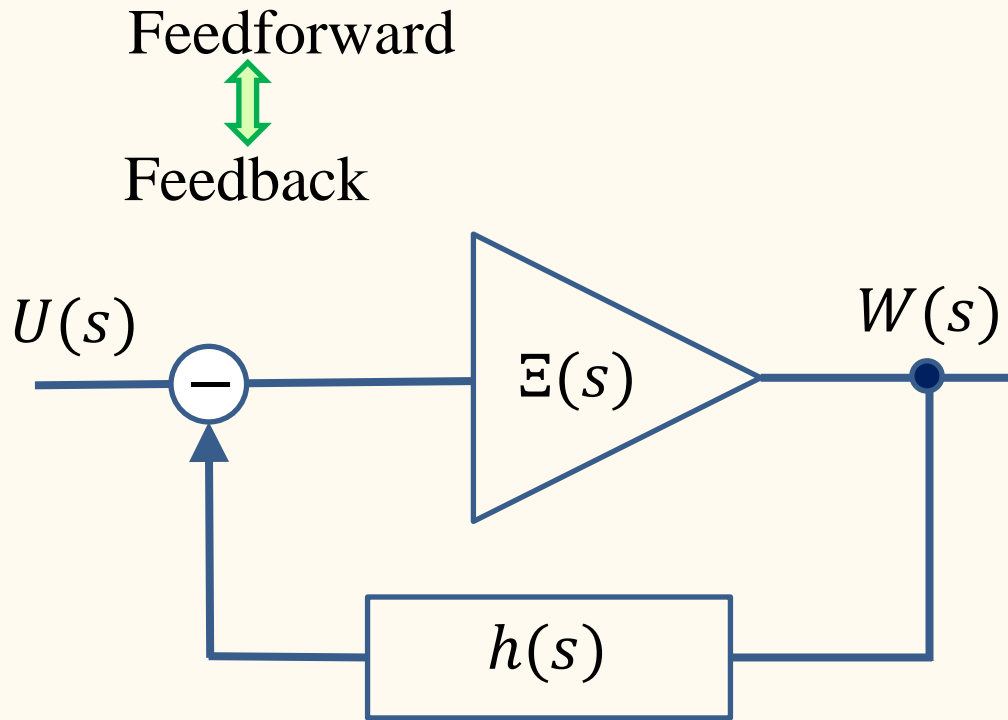
$$G = 10 \times \log_{10} \left( \frac{v_{out}}{v_{in}} \right)^2 = 20 \log_{10} \frac{v_{out}}{v_{in}}$$

---

dB units: dBm (1mW: 0dBm), dBv (1V: 0dBv), etc.



# Feedback circuit



$$W(s) = E(s)U(s)$$

$$W(s) = E(s)[U(s) - h(s)W(s)]$$

$$W(s) = \frac{E(s)}{1 + E(s)h(s)} U(s)$$

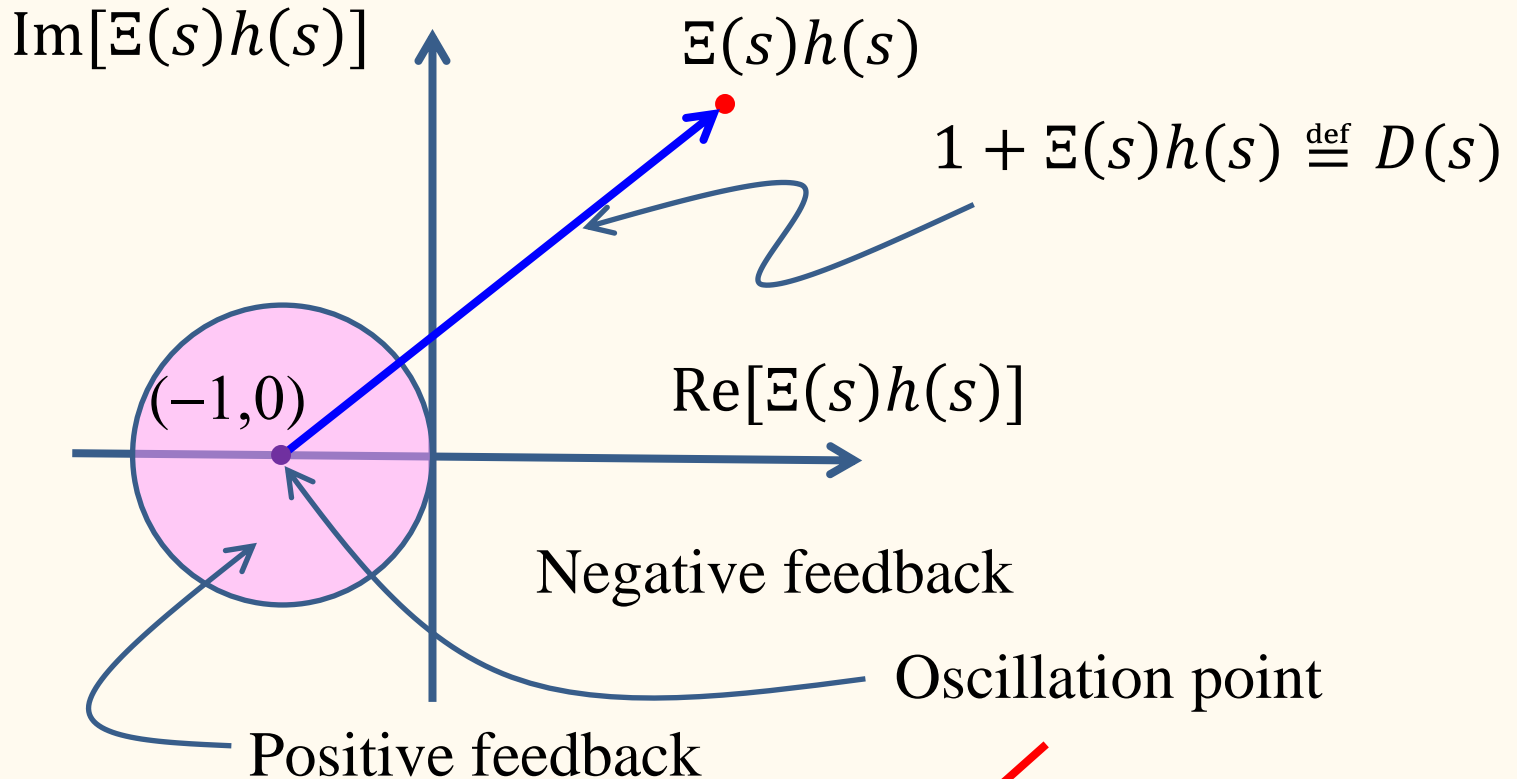
$$\stackrel{\text{def}}{=} G(s)U(s)$$

$|1 + E(s)h(s)| > 1$ : Negative feedback,  $< 1$ : Positive feedback

$$|E(s)| \gg 1 \rightarrow G(s) \approx \frac{1}{h(s)}$$

# Condition for negative feedback

$|1 + \Xi(s)h(s)| > 1$ : Negative feedback,  $< 1$ : Positive feedback



If  $\Xi(s)h(s) = -1$  has solutions, the circuit may be unstable.

How can we judge?



Criteria

(Routh-Hurwitz, **Nyquist**,  
Liapunov, ...)

# Zeros and poles of $D(s)$

Assumption 1:  $\Xi(s), \Xi(s)h(s)$  are stable

→ Poles are on the left half plane of  $s$ .

Assumption 2:  $\Xi(i\omega), \Xi(i\omega)h(i\omega) \rightarrow 0$  for  $|\omega| \rightarrow \infty$

$\Xi(s) = \frac{Q(s)}{P(s)}, h(s) = \frac{q(s)}{p(s)}$  :  $P(s), Q(s), p(s), q(s)$  polynomials

$\deg(P) > \deg(Q), \deg(p) \geq \deg(q)$

$$D(s) = 1 + \Xi(s)h(s) = \frac{P(s)p(s)}{P(s)p(s) + Q(s)q(s)}$$

$$D(s) = D_0 \frac{(s - \beta_1) \cdots (s - \beta_n)}{(s - \alpha_1) \cdots (s - \alpha_n)} \quad \begin{array}{l} \curvearrowright \\ \curvearrowleft \end{array} \text{The same order}$$

# Zeros and poles of $D(s)$

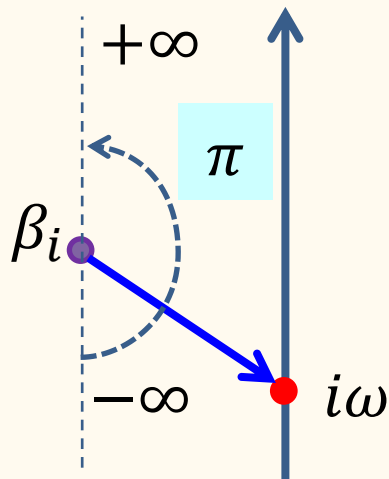
$$D(s) = D_0 \frac{(s - \beta_1) \cdots (s - \beta_n)}{(s - \alpha_1) \cdots (s - \alpha_n)}$$

$\{\beta_i\}$  : Zeros of  $D(s)$   $\rightarrow$  Poles of  $G(s)$

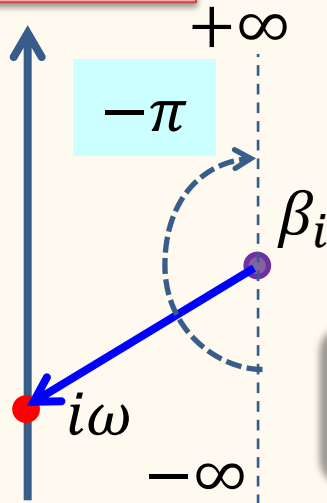
$\exists \beta_i \in$  right half plane of  $s \rightarrow$  The circuit is unstable.

$$\arg(D) = \sum_{i=1}^n \arg(s - \beta_i) - \sum_{i=1}^n \arg(s - \alpha_i)$$

Left half plane



Right half plane



$s = i\omega$  (on imaginary axis)

$\omega: -\infty \rightarrow +\infty$

Number of zeros on the right half plane:  $m$

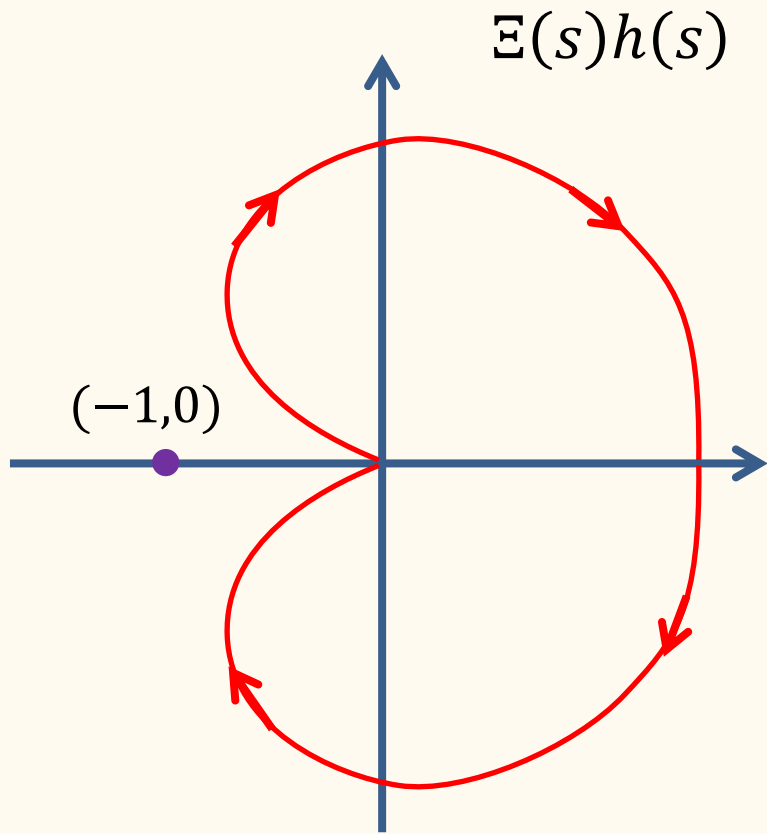
$$\Delta \arg(D) = (n - m)\pi - m\pi$$

$$-n\pi = -2m\pi$$

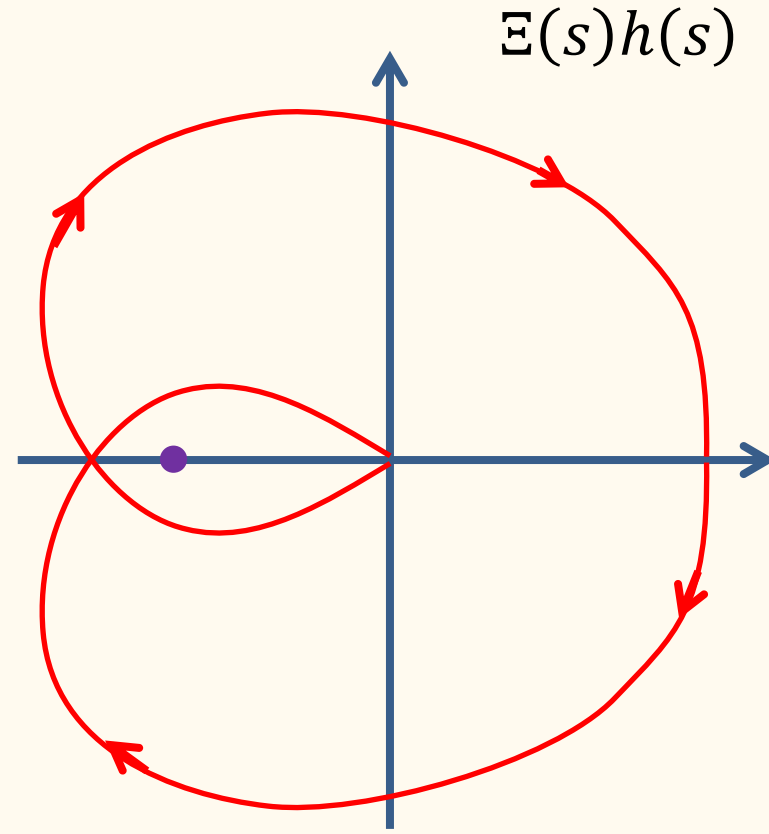
# Nyquist Plot and Criterion



Harry Nyquist  
(1889–1976)



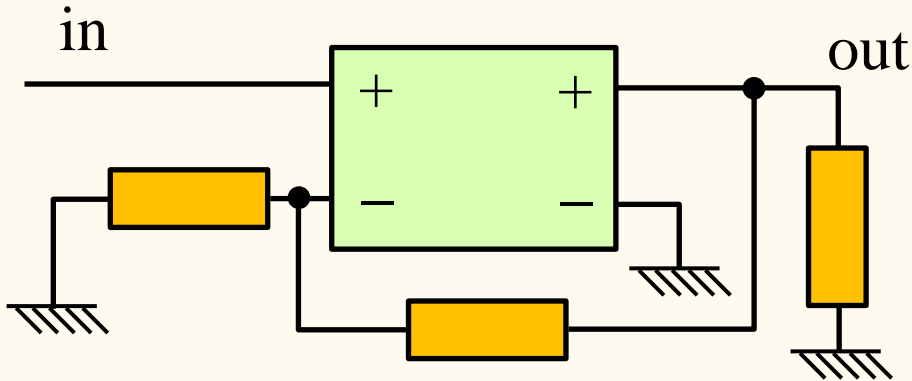
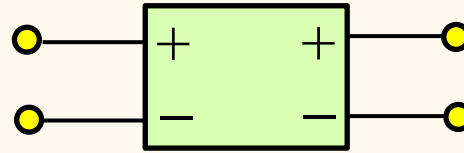
$\Delta \arg(D) = 0$   
Stable



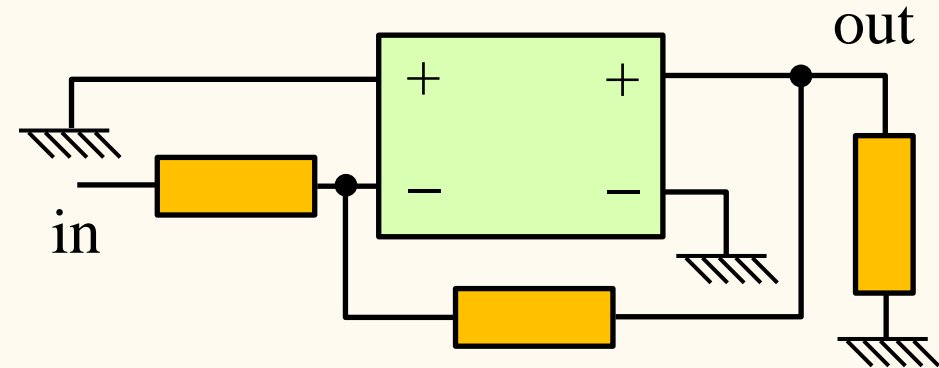
$\Delta \arg(D) = -4\pi$   
Unstable



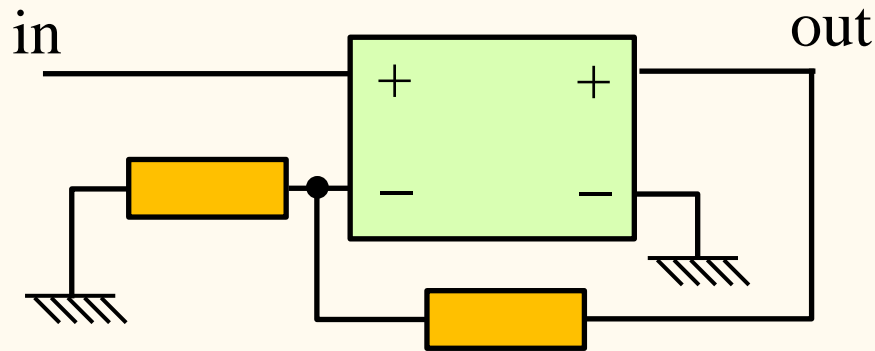
# Feedback in terminal-pair circuits with resistors



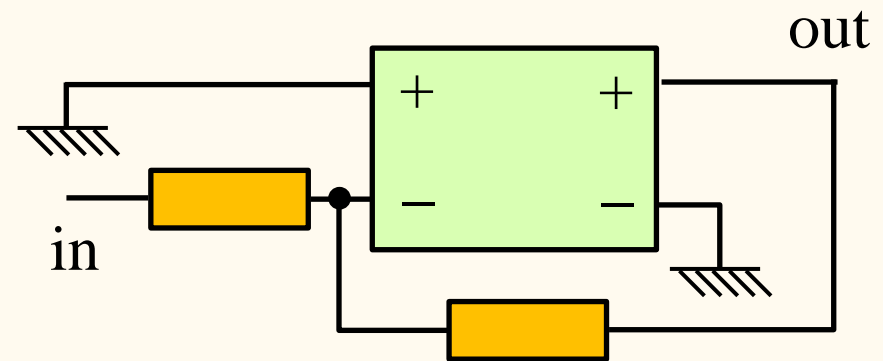
(i) input: parallel, output: parallel



(ii) input: series, output: parallel

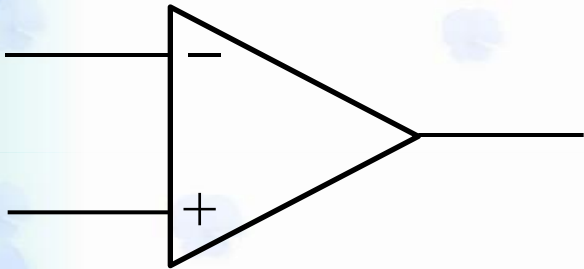


(iii) input: parallel, output: series



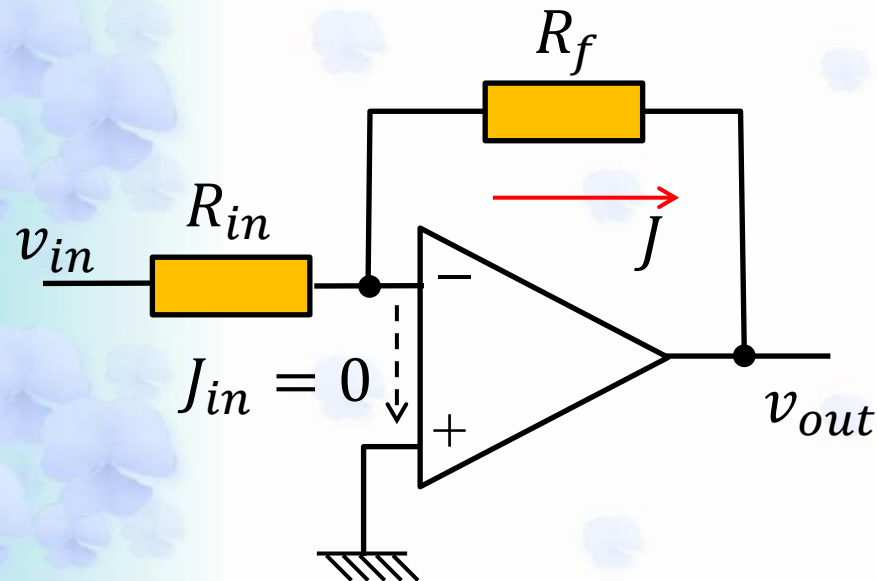
(iv) input: series, output: series

# Operational amplifier (OP amp.)



- Differential amplifier
- Input impedance  $\sim \infty$
- Open loop gain  $A_o \gg 1$
- Output resistance  $\approx 0$

Case (iv)



$$A_o \gg 1 \therefore \underline{V_- \approx V_+ = 0}$$

Virtual short circuit

$$J = -\frac{v_{out}}{R_f} = \frac{v_{in}}{R_{in}}$$

$$\therefore v_{out} = -\frac{R_f}{R_{in}} v_{in}$$

Inverting amplifier

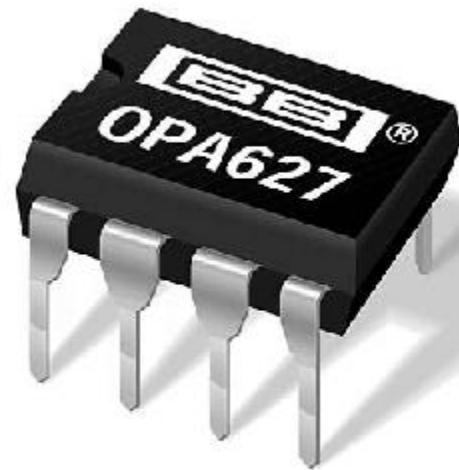
# Opamp packages



(a)



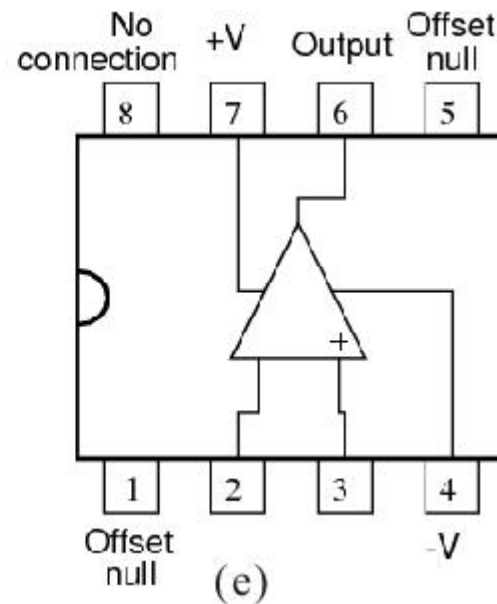
(b)



(c)

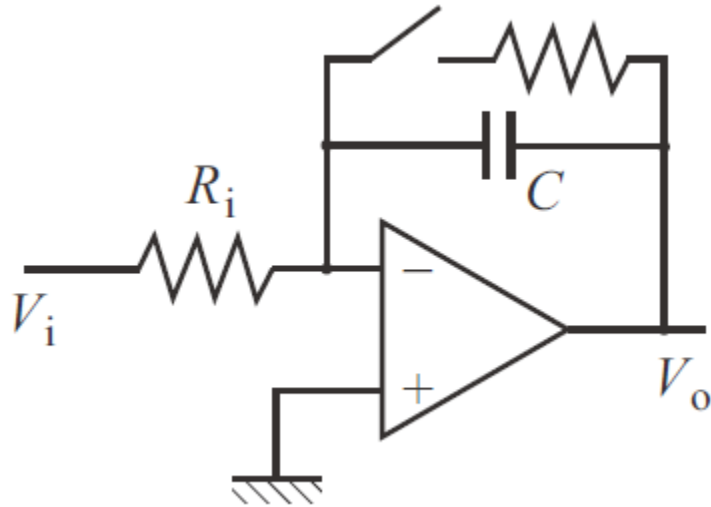


(d)



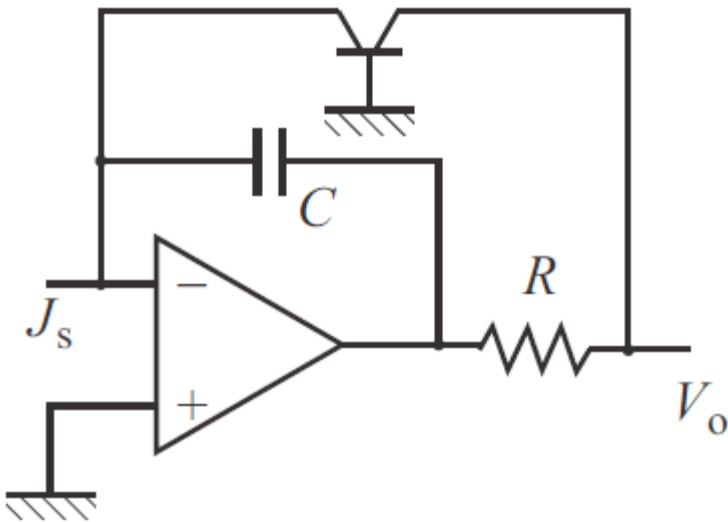
(e)

# Various applications of OP amps



$$V_{\text{out}}(t) = -\frac{Q}{C} = -\frac{1}{C} \int_0^t \frac{V_i(\tau)}{R_i} d\tau$$
$$= -\frac{1}{CR_i} \int_0^t V_i(\tau) d\tau$$

Integration circuit



$$V_{\text{out}} = -V_{\text{BE}} = -\frac{k_{\text{B}}T}{e} \ln \left( \frac{J_s}{J_0} + 1 \right)$$

Logarithmic amplifier

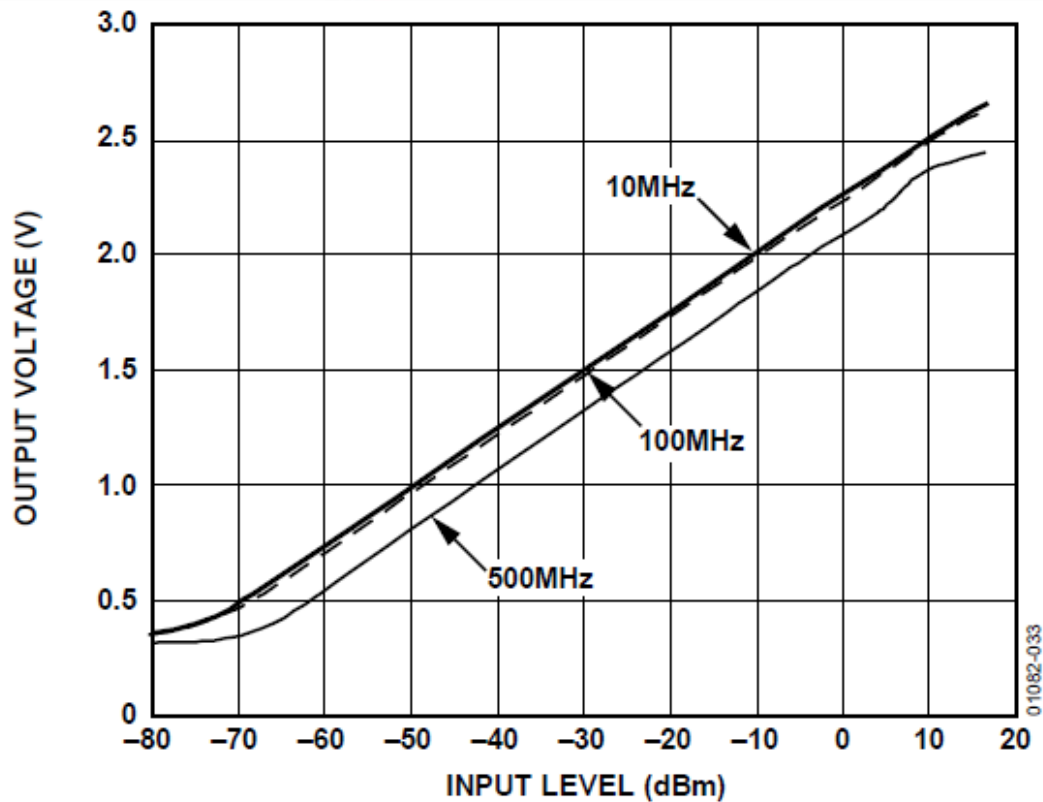
# Logarithmic Amplifier



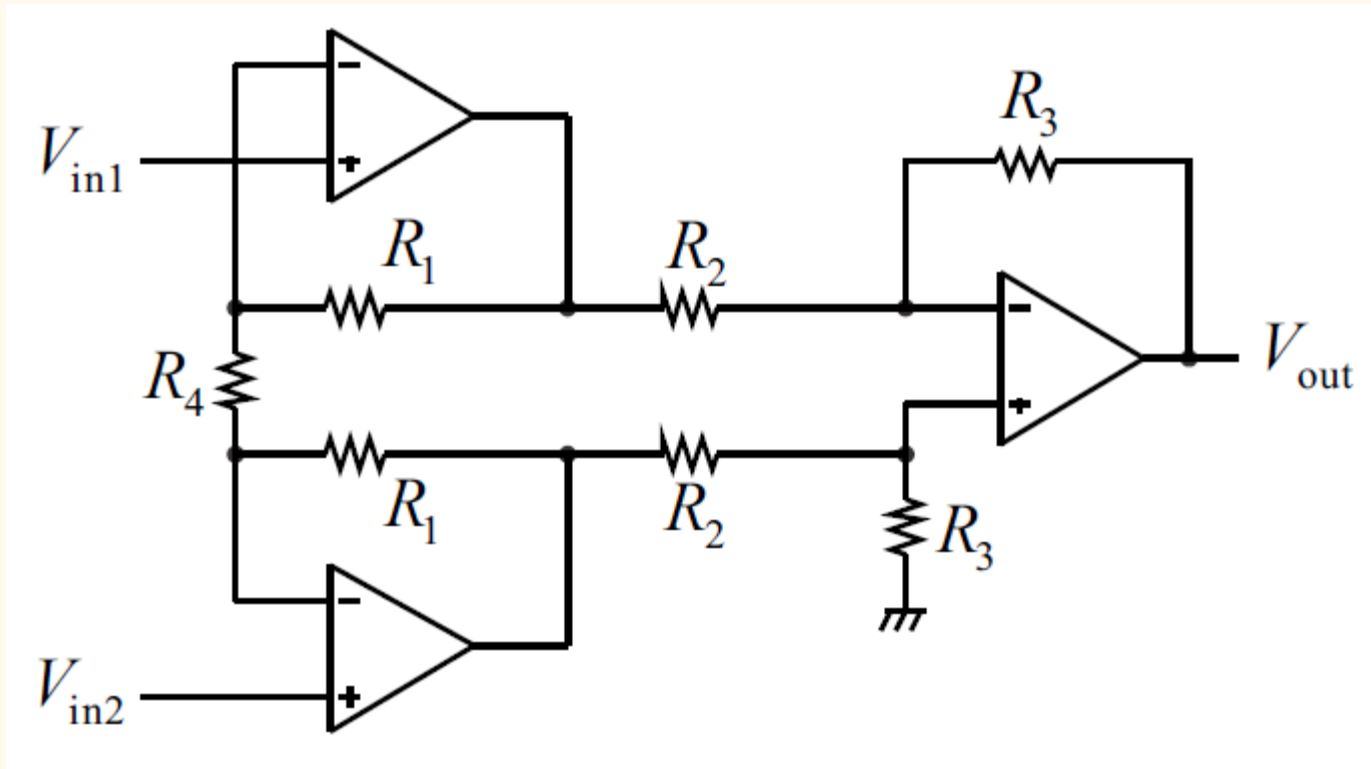
Low Cost, DC to 500 MHz, 92 dB  
Logarithmic Amplifier

Data Sheet

**AD8307**



# Instrumentation amplifier



$$V_{out} = -\frac{R_3}{R_2} \left( \frac{2R_1 + R_4}{R_4} \right) (V_{in1} - V_{in2})$$





# OP-amp data sheet



## Ultralow Offset Voltage Operational Amplifier

Data Sheet

OP07

### FEATURES

- Low  $V_{os}$ : 75  $\mu\text{V}$  maximum
- Low  $V_{os}$  drift: 1.3  $\mu\text{V}/^\circ\text{C}$  maximum
- Ultrastable vs. time: 1.5  $\mu\text{V}$  per month maximum
- Low noise: 0.6  $\mu\text{V}$  p-p maximum
- Wide input voltage range:  $\pm 14\text{ V}$  typical
- Wide supply voltage range:  $\pm 3\text{ V}$  to  $\pm 18\text{ V}$
- 125 $^\circ\text{C}$  temperature-tested dice

### PIN CONFIGURATION

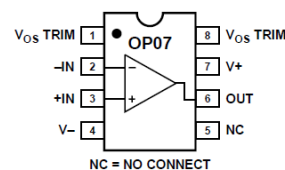
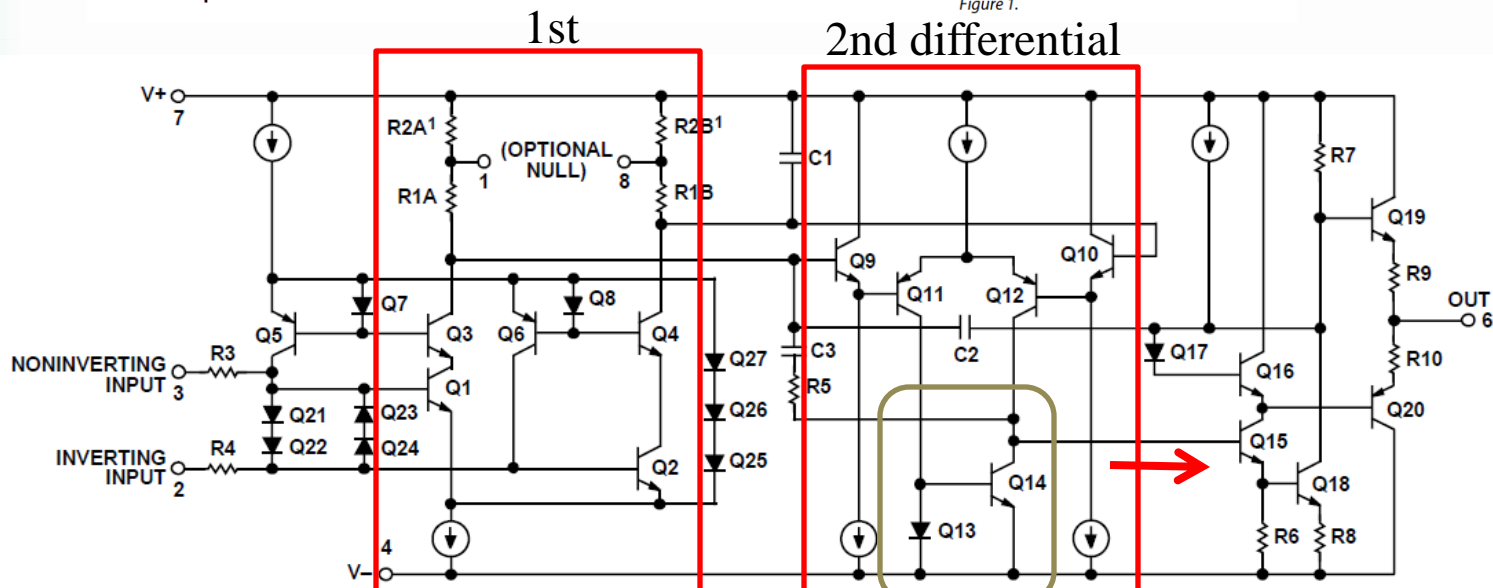


Figure 1.



<sup>1</sup>R2A AND R2B ARE ELECTRONICALLY ADJUSTED ON CHIP AT FACTORY FOR MINIMUM INPUT OFFSET VOLTAGE.

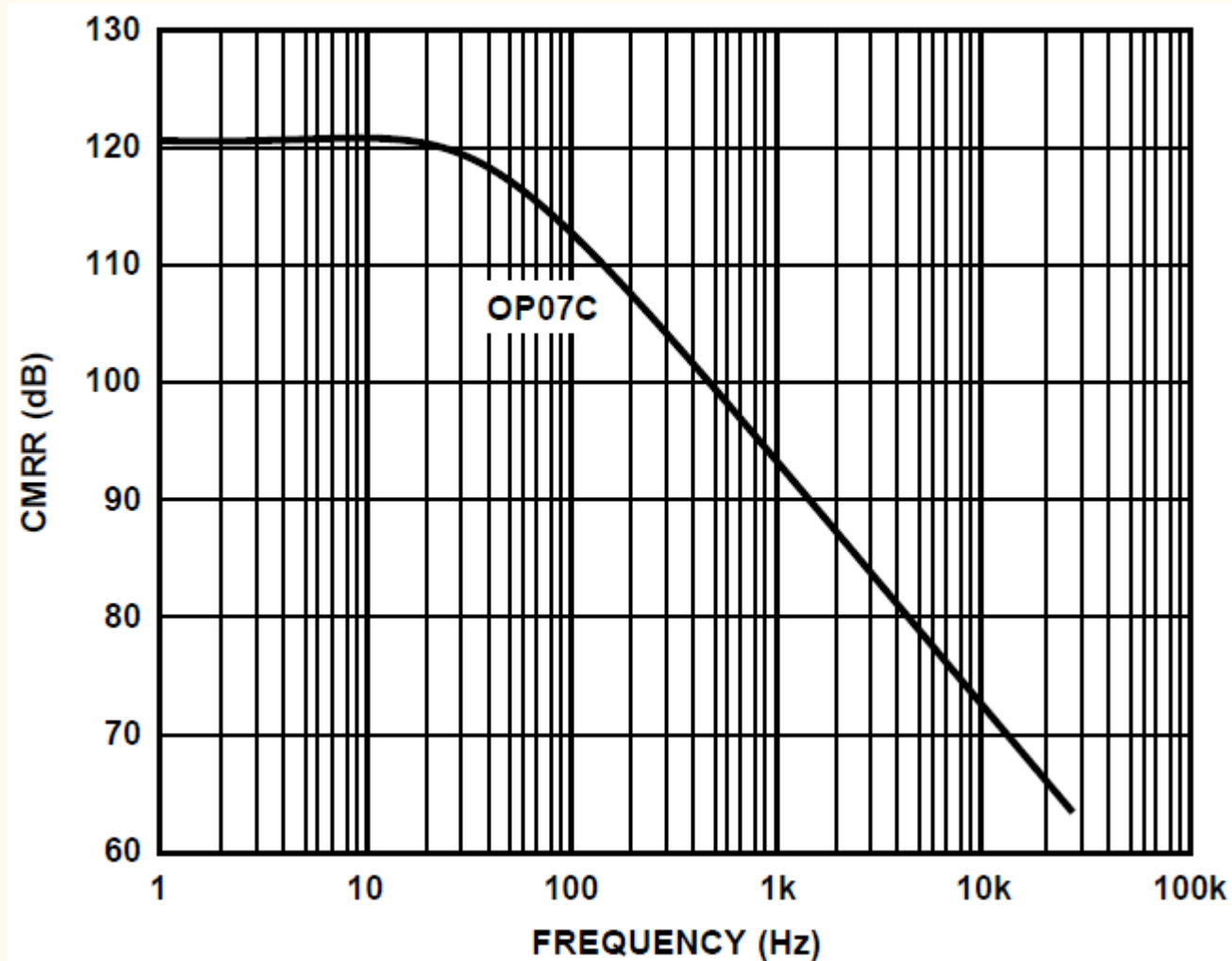
Figure 2. Simplified Schematic

# OP-amp data sheet

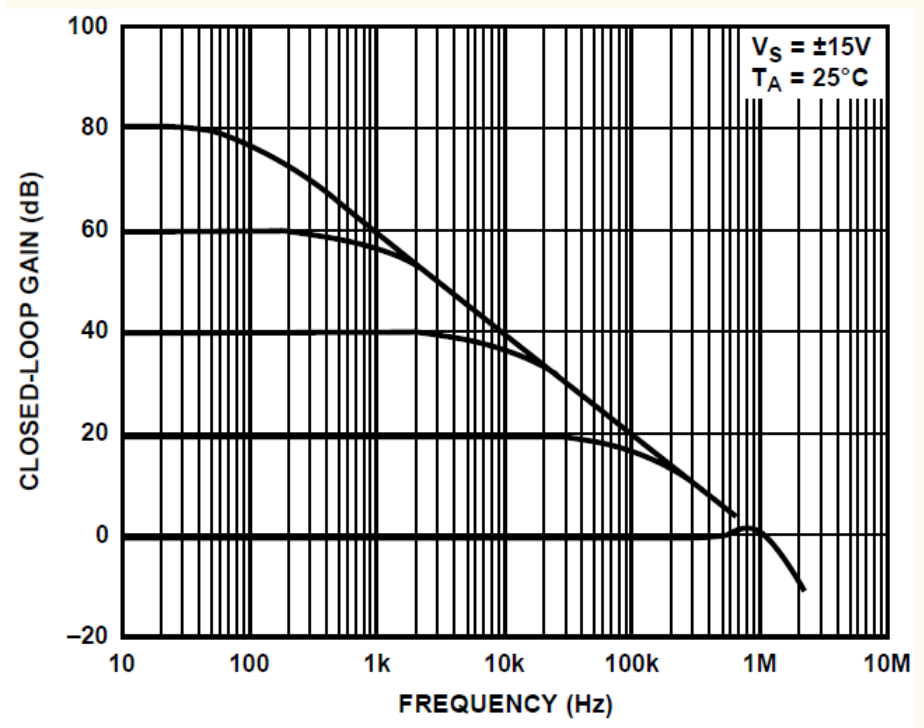
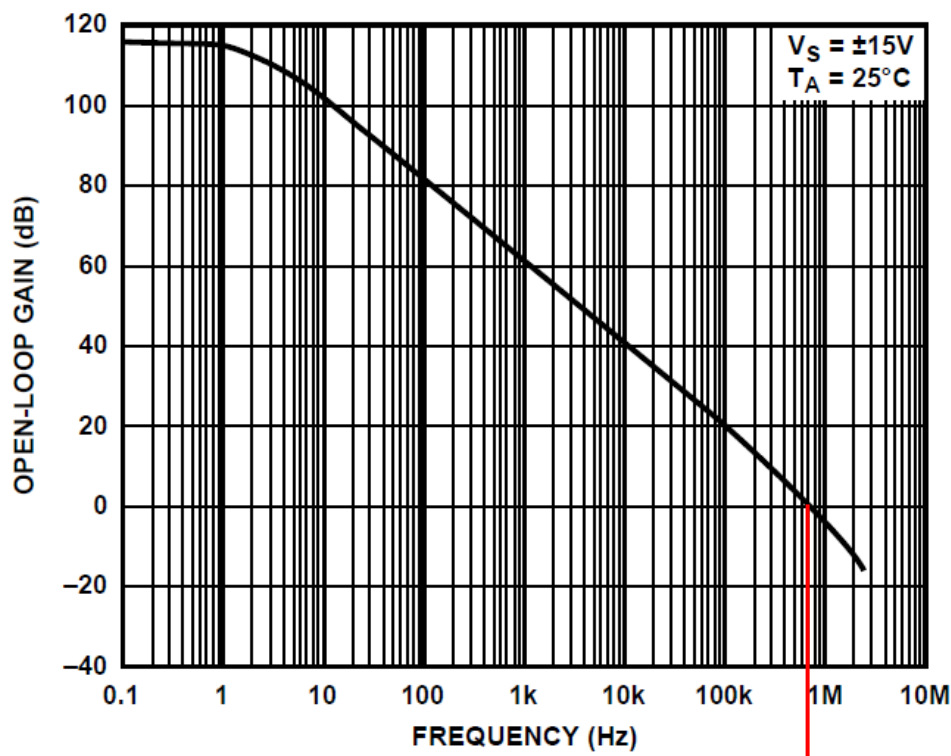
## Parameters

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
$T_A = 25^\circ\text{C}$						
Input Offset Voltage <sup>1</sup>	$V_{OS}$			60	150	$\mu\text{V}$
Long-Term $V_{OS}$ Stability <sup>2</sup>	$V_{OS}/\text{Time}$			0.4	2.0	$\mu\text{V}/\text{Month}$
Input Offset Current	$I_{OS}$			0.8	6.0	nA
Input Bias Current	$I_B$			$\pm 1.8$	$\pm 7.0$	nA
Input Noise Voltage	$e_n$ p-p	0.1 Hz to 10 Hz <sup>3</sup>		0.38	0.65	$\mu\text{V}$ p-p
Input Noise Voltage Density	$e_n$	$f_0 = 10$ Hz		10.5	20.0	$\text{nV}/\sqrt{\text{Hz}}$
		$f_0 = 100$ Hz <sup>3</sup>		10.2	13.5	$\text{nV}/\sqrt{\text{Hz}}$
		$f_0 = 1$ kHz		9.8	11.5	$\text{nV}/\sqrt{\text{Hz}}$
Input Noise Current	$I_n$ p-p			15	35	$\text{pA}$ p-p
Input Noise Current Density	$I_n$	$f_0 = 10$ Hz		0.35	0.90	$\text{pA}/\sqrt{\text{Hz}}$
		$f_0 = 100$ Hz <sup>3</sup>		0.15	0.27	$\text{pA}/\sqrt{\text{Hz}}$
		$f_0 = 1$ kHz		0.13	0.18	$\text{pA}/\sqrt{\text{Hz}}$
Input Resistance, Differential Mode <sup>4</sup>	$R_{IN}$		8	33		$\text{M}\Omega$
Input Resistance, Common Mode	$R_{INCM}$			120		$\text{G}\Omega$

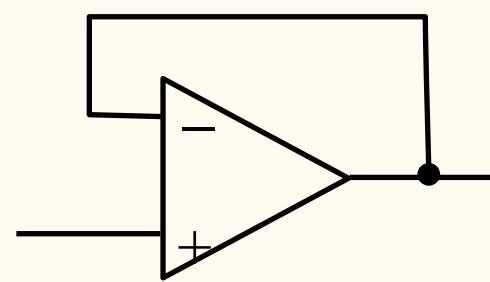
## Common mode rejection ratio (CMRR)



# OP-amp data sheet

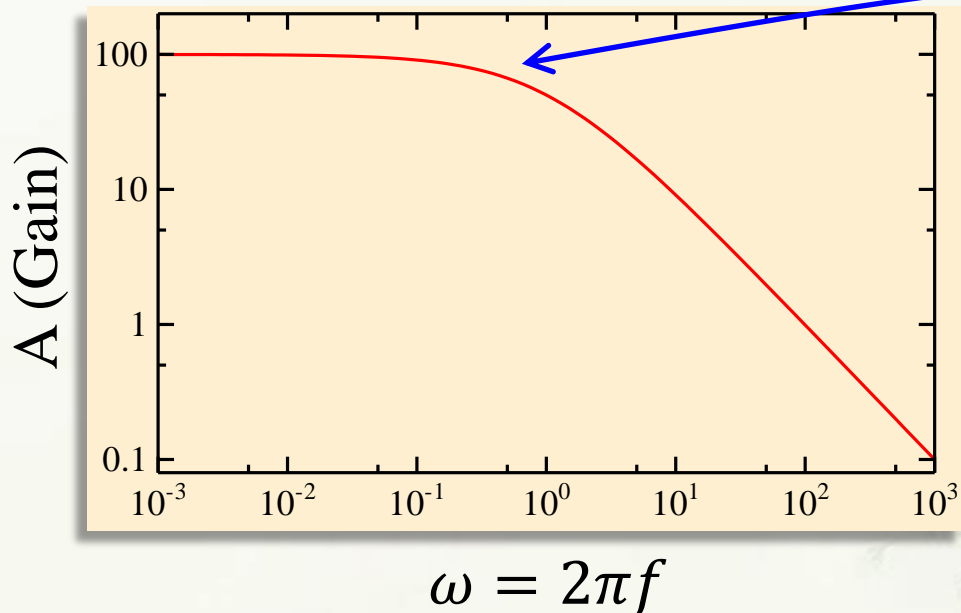


Unity gain frequency



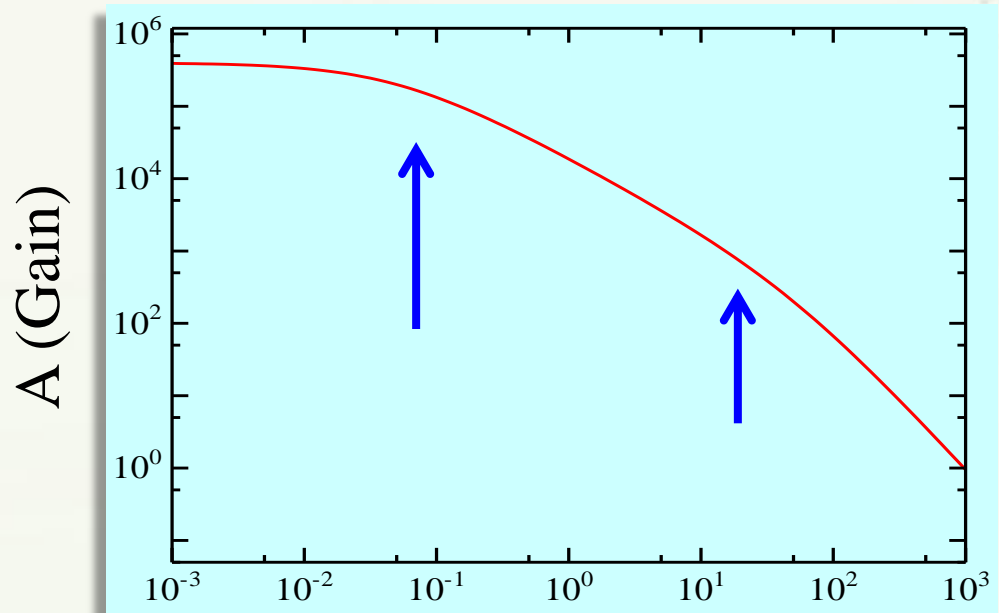
Voltage follower

# Frequency Dependent Characteristics of OP-Amps



Cut-off frequency  
 $\omega_T = 2\pi f_T$

Phase rotates by  $\pi/2$



Multiple cut-off frequency:  
Phase rotates more than  $\pi$

If gain is larger than 1 at  
phase shift  $\pi$  :

Dangerous!

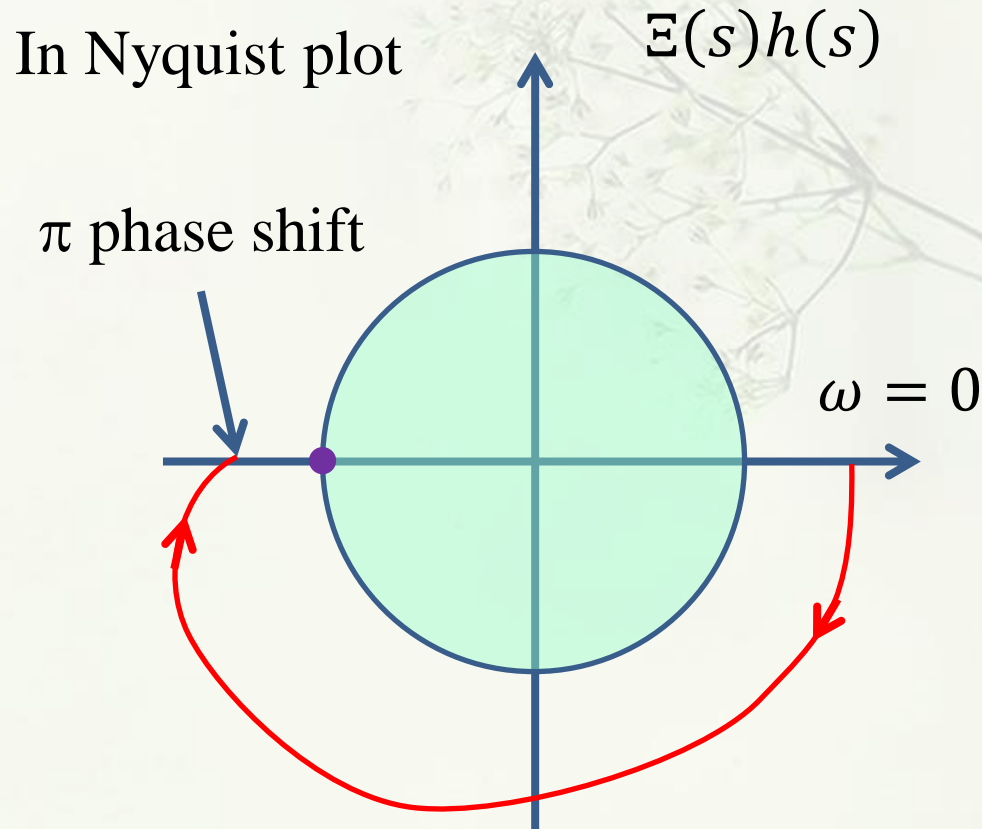


# Phase compensation

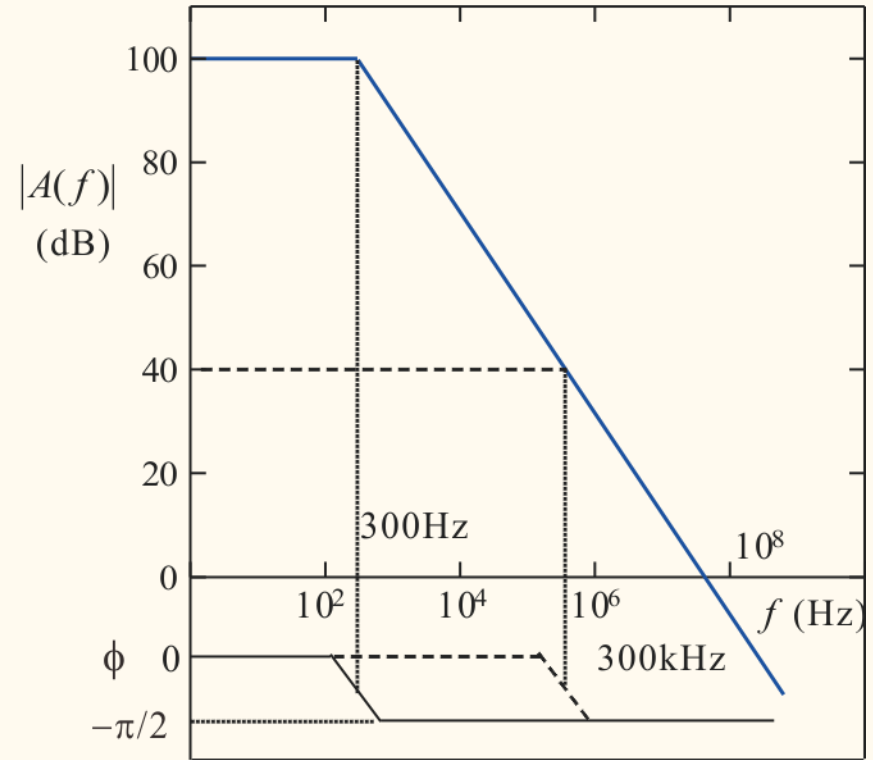
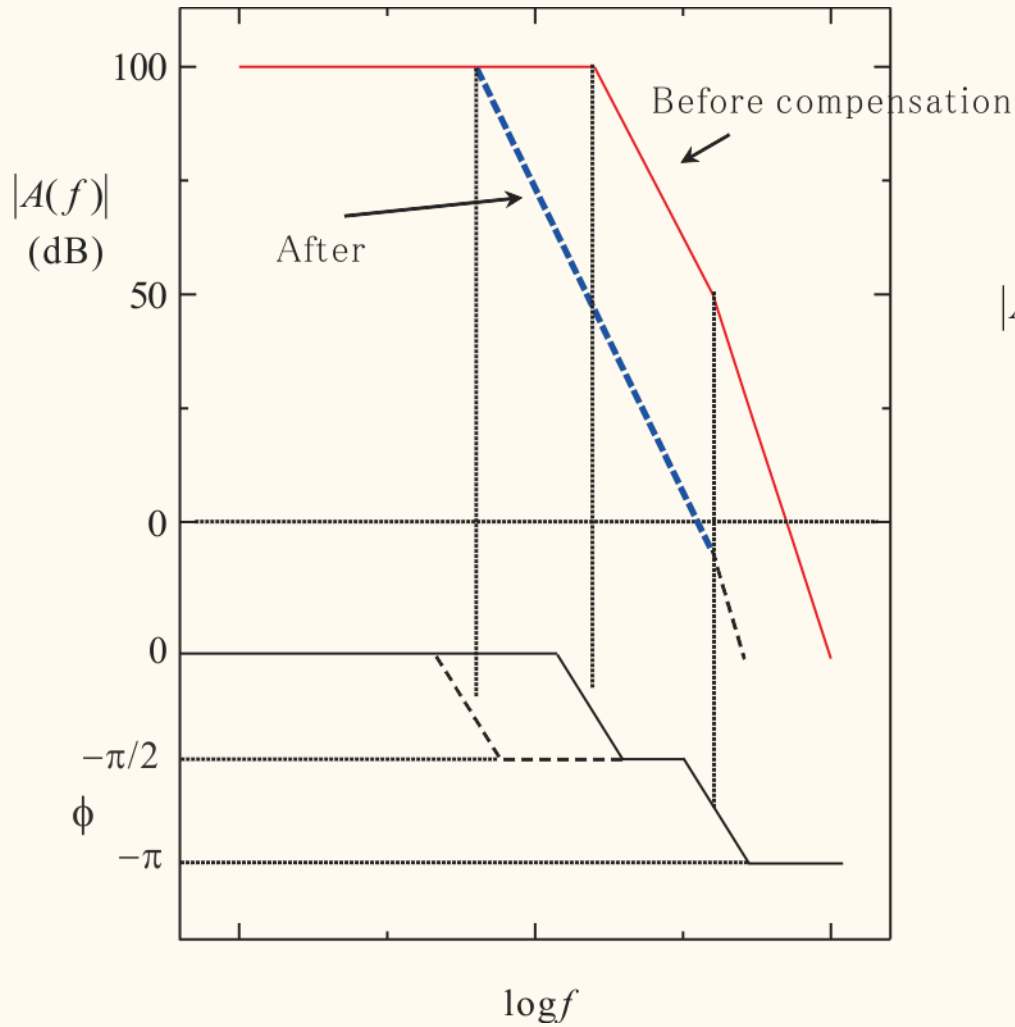
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Why dangerous?

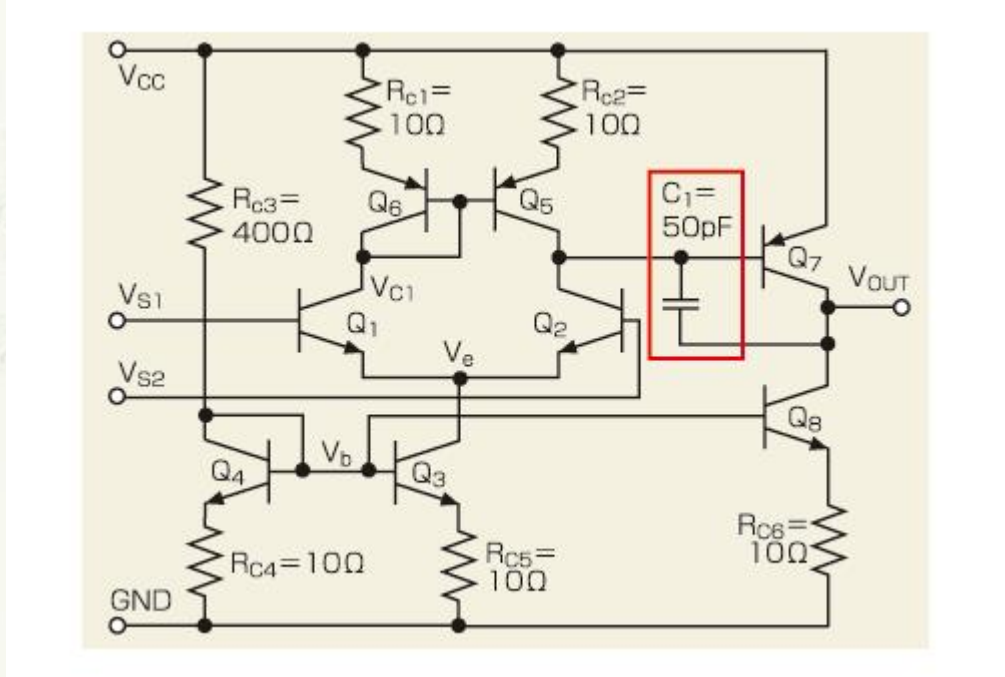
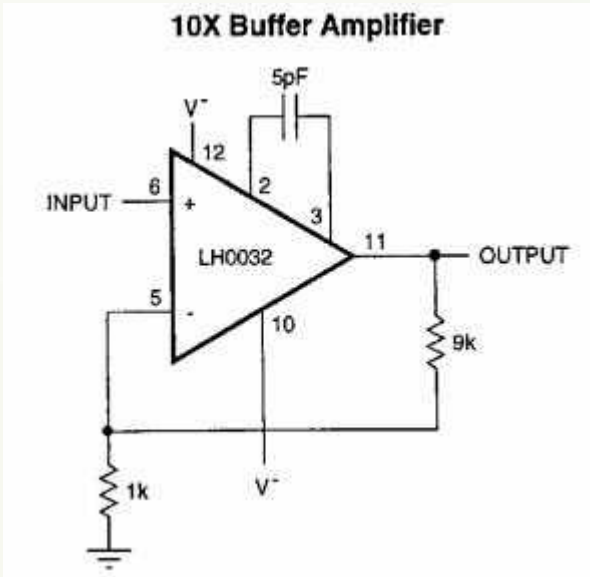
$\pi$  phase shift: negative feedback  $\rightarrow$  positive feedback



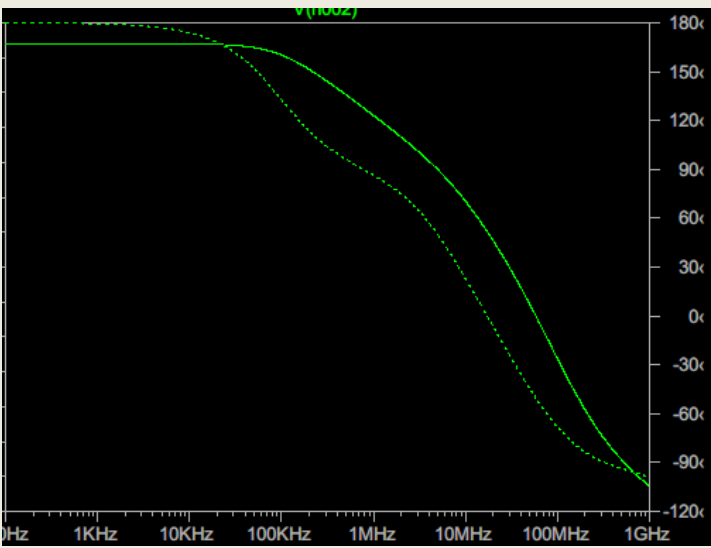
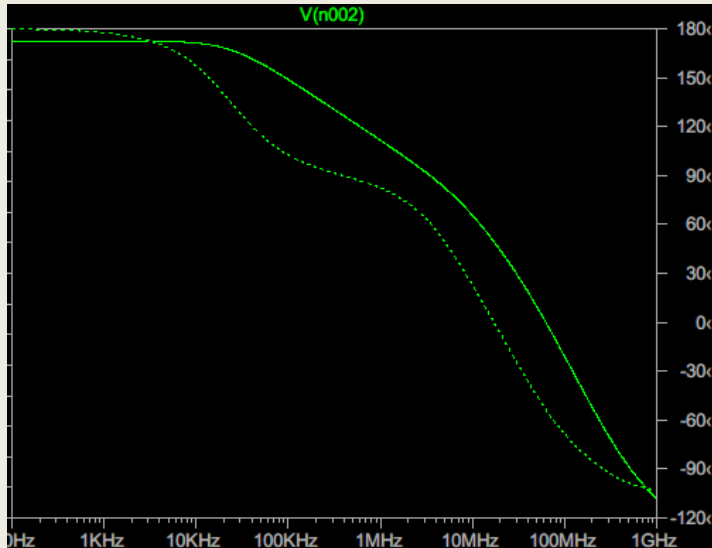
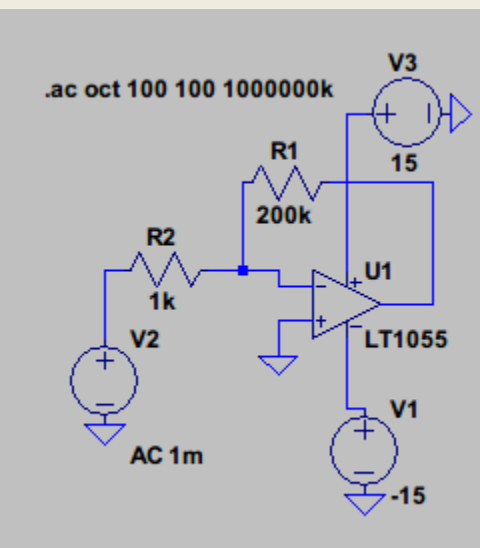
# Phase compensation



# Phase compensation

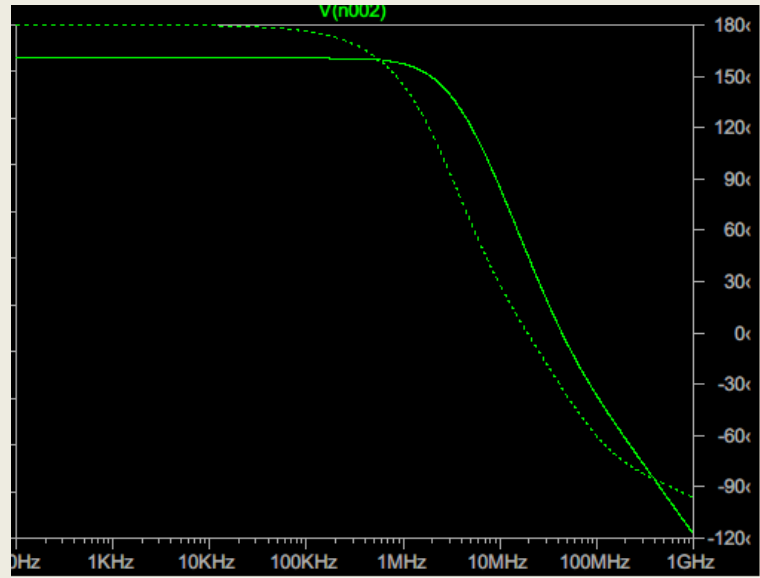
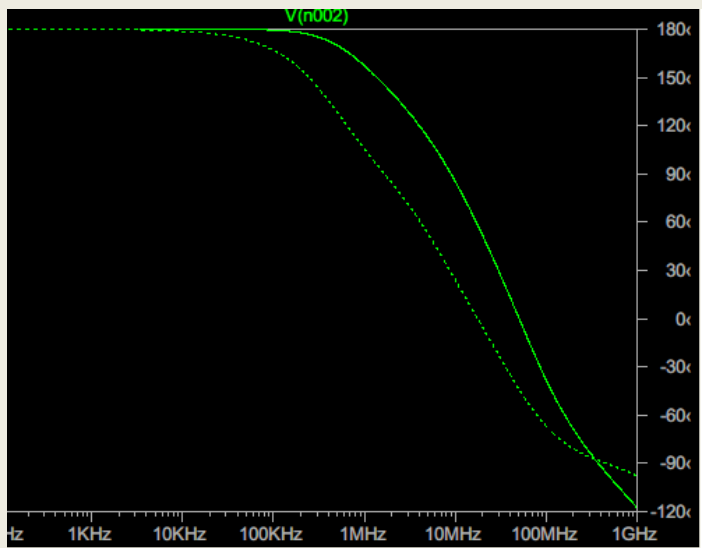


# Inverting amplifier and cut-off frequency



$$A = 200 f_T = 30\text{kHz}$$

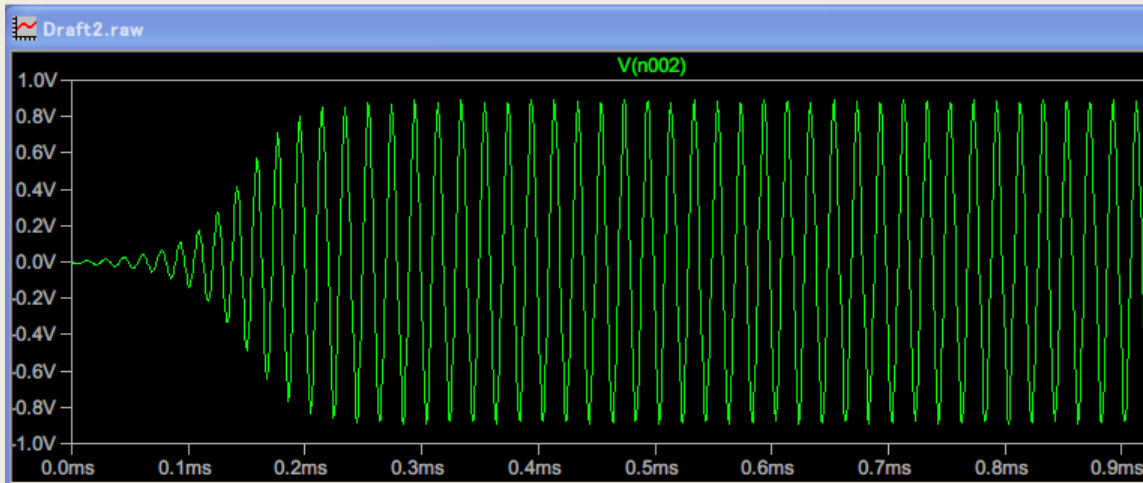
$$A = 50 f_T = 90\text{kHz}$$



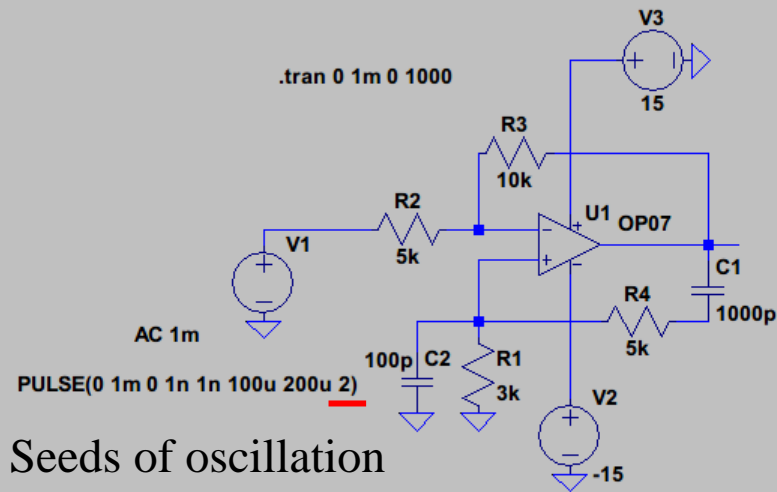
$$A = 10 f_T = 300\text{kHz}$$

$$A = 2 f_T = 2\text{MHz}$$

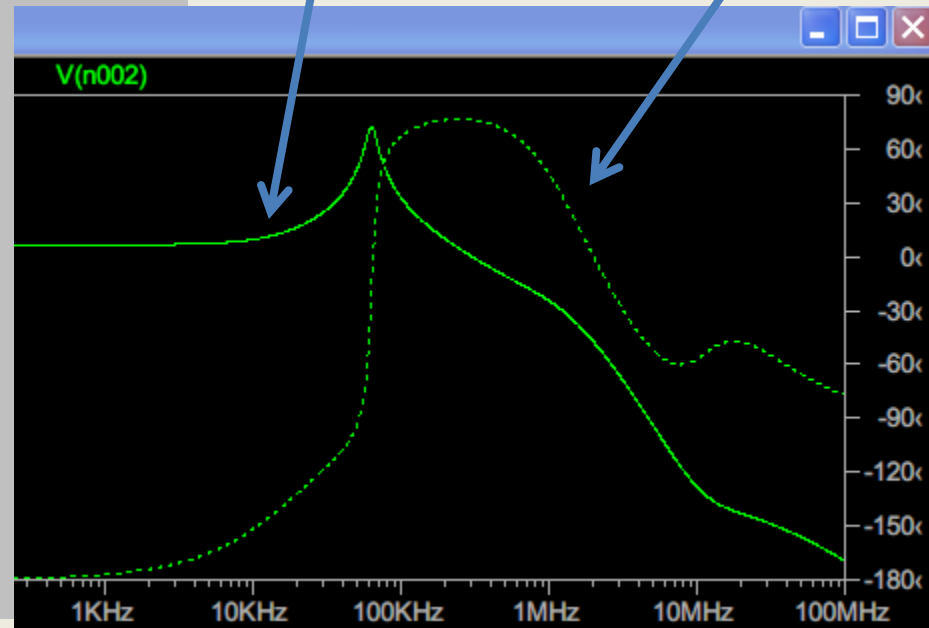
# Oscillation of OPamp



Draft2.asc



Seeds of oscillation







# 電子回路論第6回

# Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto



# Outline

## 4.3 Feedback control

### 4.3.1 Disturbance and noise

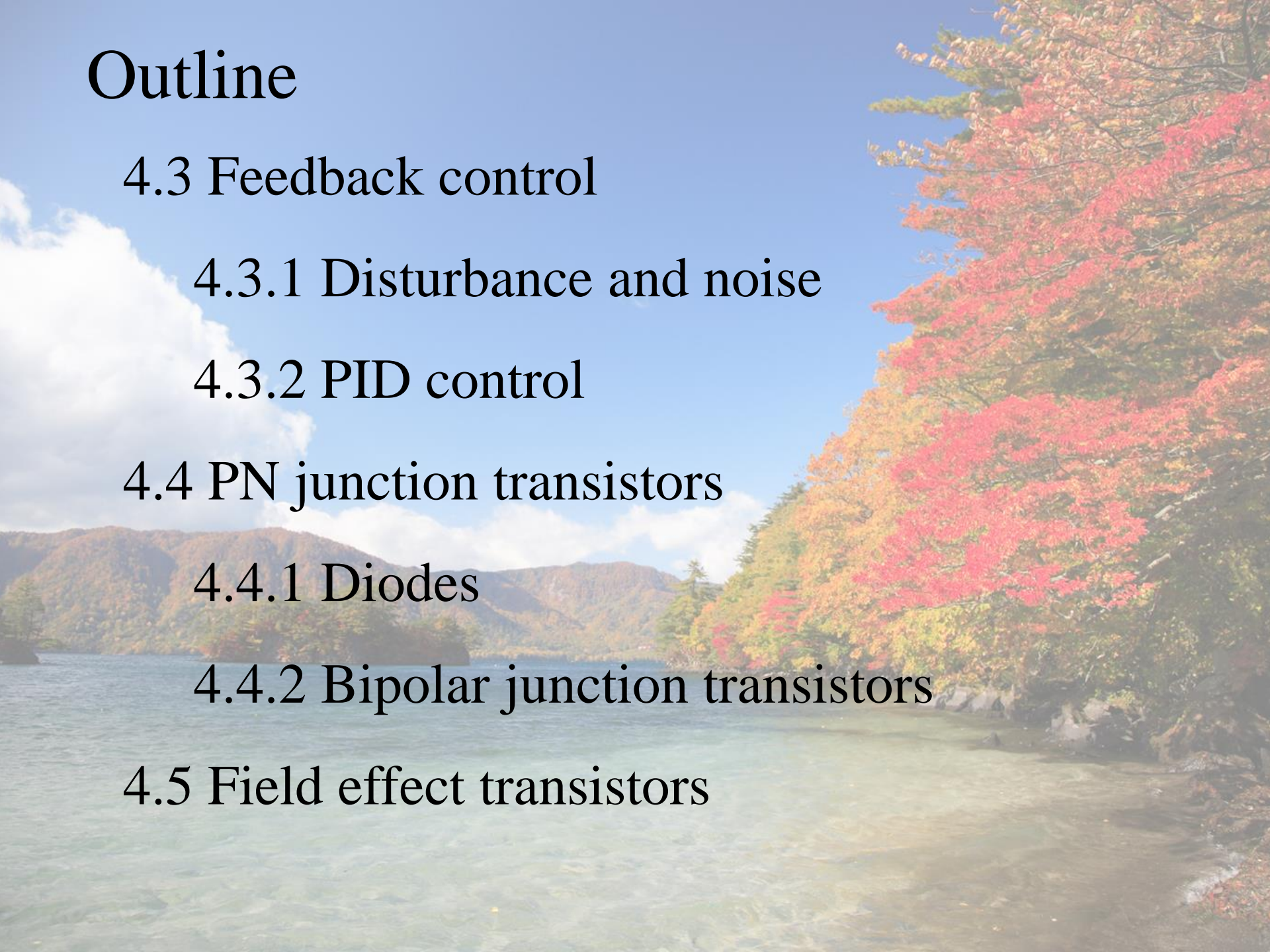
### 4.3.2 PID control

## 4.4 PN junction transistors

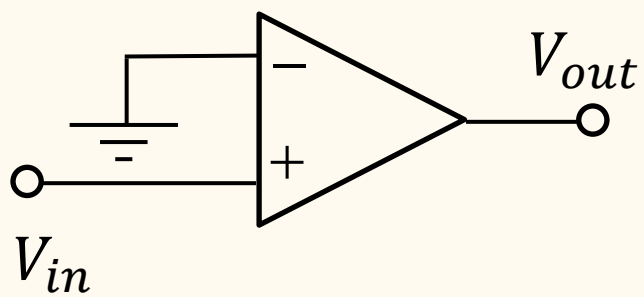
### 4.4.1 Diodes

### 4.4.2 Bipolar junction transistors

## 4.5 Field effect transistors

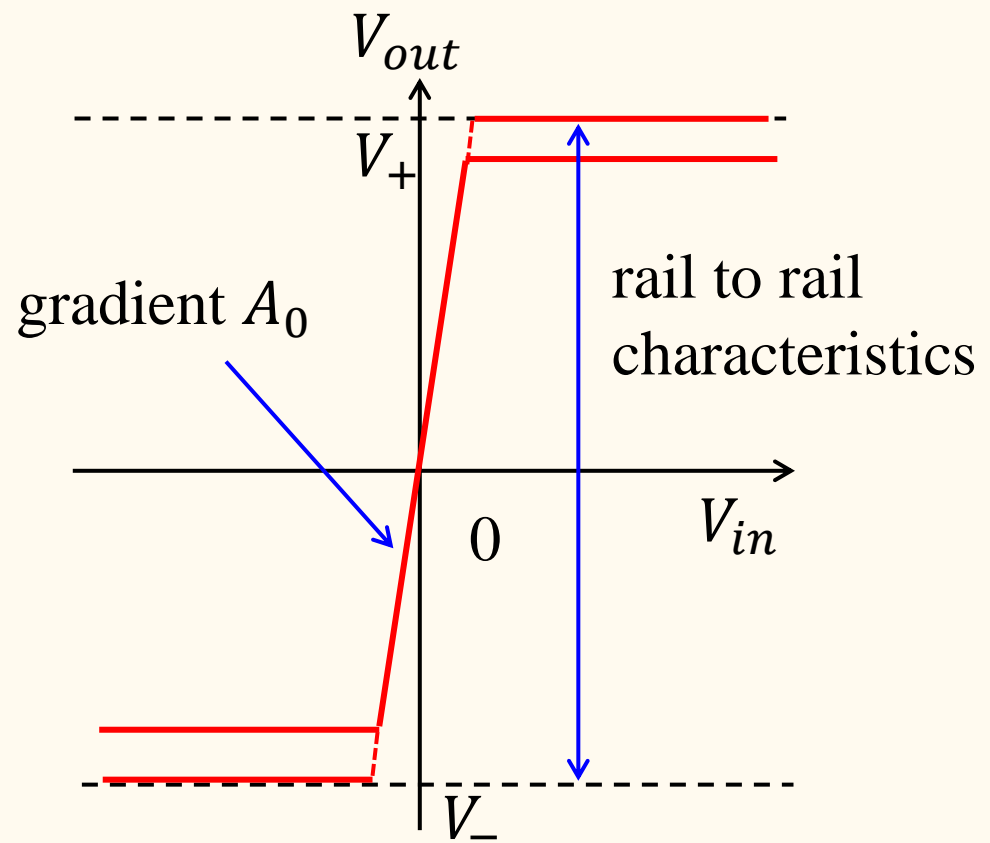
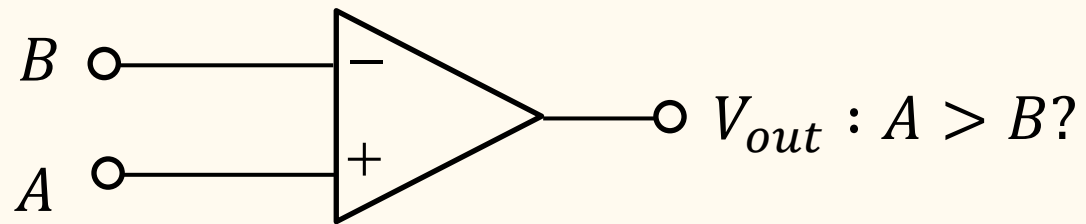


# Comment: Use of OP-amp at saturation voltages



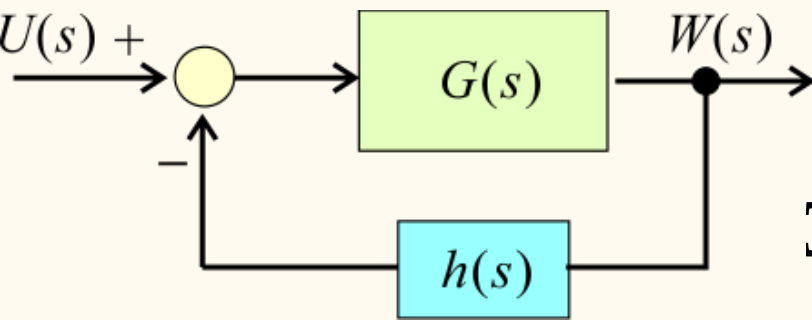
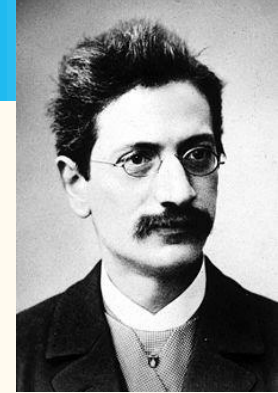
Compare  $V_{in}$  with 0

Comparator



# Hurwitz criterion

Adolf Hurwitz  
1859 - 1919



$$\Xi(s) = \frac{G(s)}{1 + h(s)G(s)}$$

Pole equation: (denominator)  $= a_n s^n + a_{n-1} s^{n-1} + \dots + a_0$   
 $= a_n (s - p_1) \dots (s - p_n) = 0$

$\forall j = 0, 1, \dots, n : a_j > 0$  (or  $< 0$ ) (Otherwise the system is unstable.)

Hurwitz matrix  
 $n \times n$

$$H = \begin{pmatrix} a_{n-1} & a_{n-3} & a_{n-5} & \dots & 0 \\ a_n & a_{n-2} & a_{n-4} & \dots & 0 \\ \hline 0 & a_{n-1} & a_{n-3} & \dots & 0 \\ 0 & a_n & a_{n-2} & \dots & 0 \\ \hline \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & a_0 \end{pmatrix}$$

# Hurwitz criterion

Hurwitz determinants  $H_j \equiv |H[1, \dots, j; 1, \dots, j]|$

$$H_1 = a_{n-1}, \quad H_2 = \begin{vmatrix} a_{n-1} & a_{n-3} \\ a_n & a_{n-2} \end{vmatrix}, \quad H_3 = \begin{vmatrix} a_{n-1} & a_{n-3} & a_{n-5} \\ a_n & a_{n-2} & a_{n-4} \\ 0 & a_{n-1} & a_{n-3} \end{vmatrix}, \dots$$

Hurwitz criterion

$$H_j > 0 \quad (j = 2, \dots, n = 1)$$

$H_1, H_n > 0$  is trivial from the assumption.

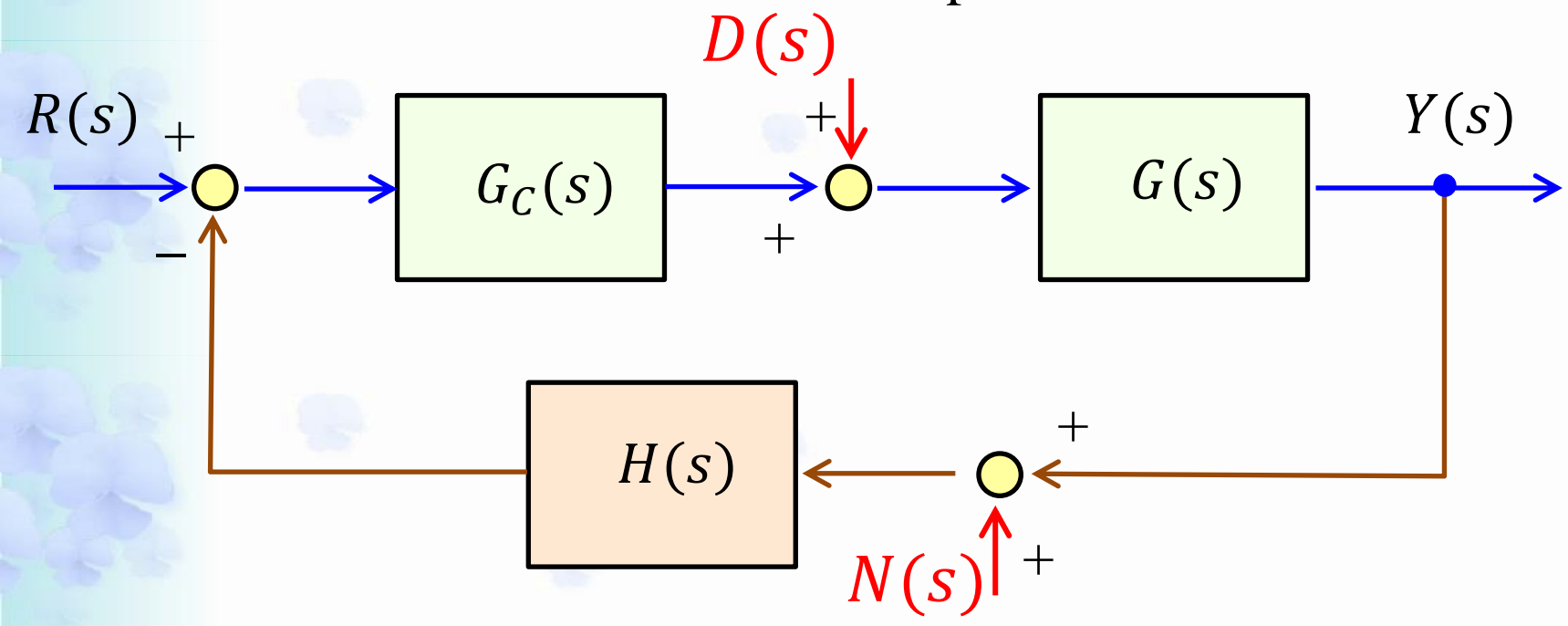
Another expression:

Divide the denominator to odd and even parts  $O(s)$  and  $E(s)$ .

If the zeros of  $O(s)$  and  $E(s)$  are aligned on the imaginary axis alternatively, the system is stable.

# Disturbance and noise on feedback control

- Circuit treatment of fluctuations:
- Prepare external power sources
  - Express them as transfer functions



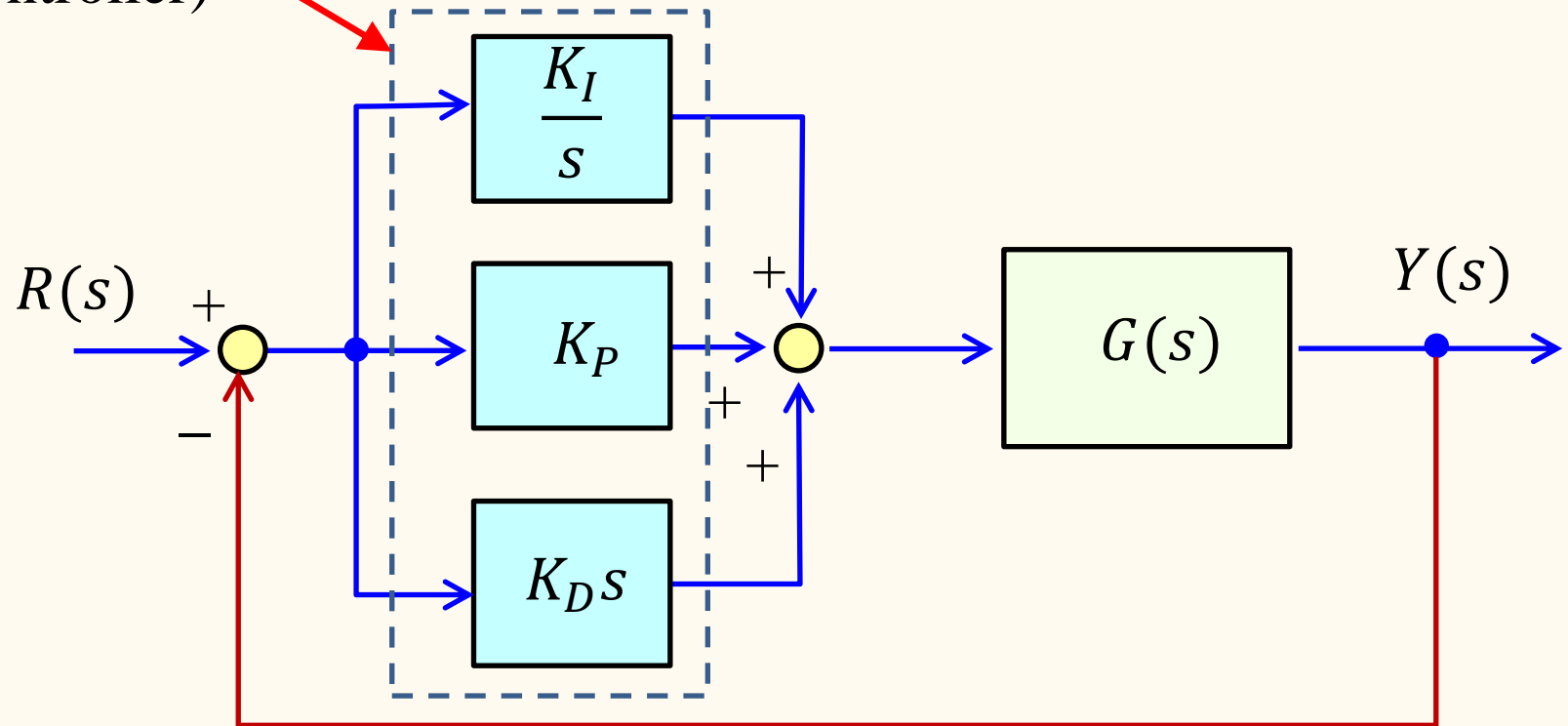
$$Y(s) = \frac{G(s)}{F(s)} [G_C(s)R(s) + D(s) + G_C(s)H(s)N(s)]$$

$$F(s) \equiv 1 + G_C(s)G(s)H(s)$$

# PID control

Compensator  
(controller)

P: proportional, I: integral, D: derivative



$$G_c(s) = K_P + \frac{K_I}{s} + K_D s$$

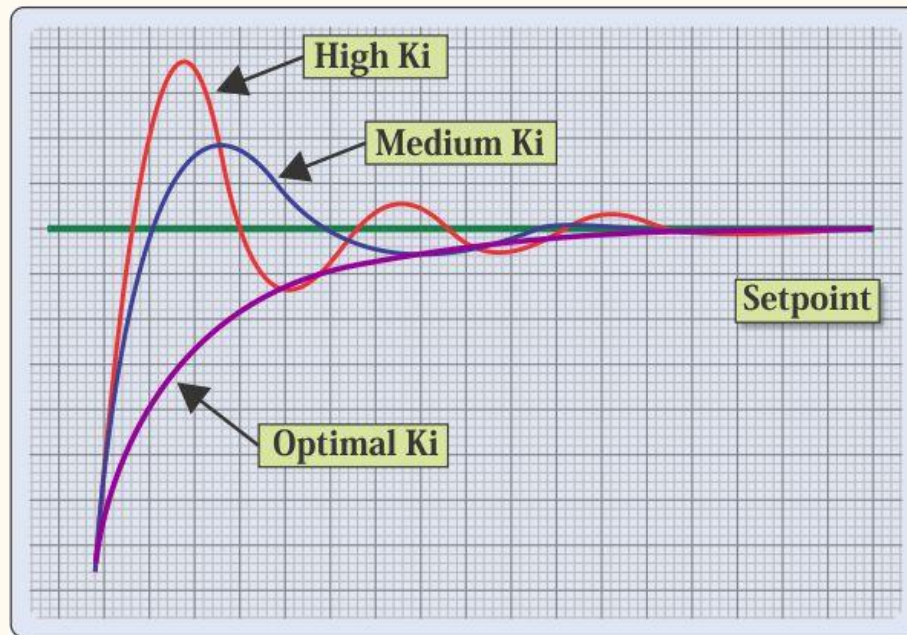


# PID controllers

OMRON

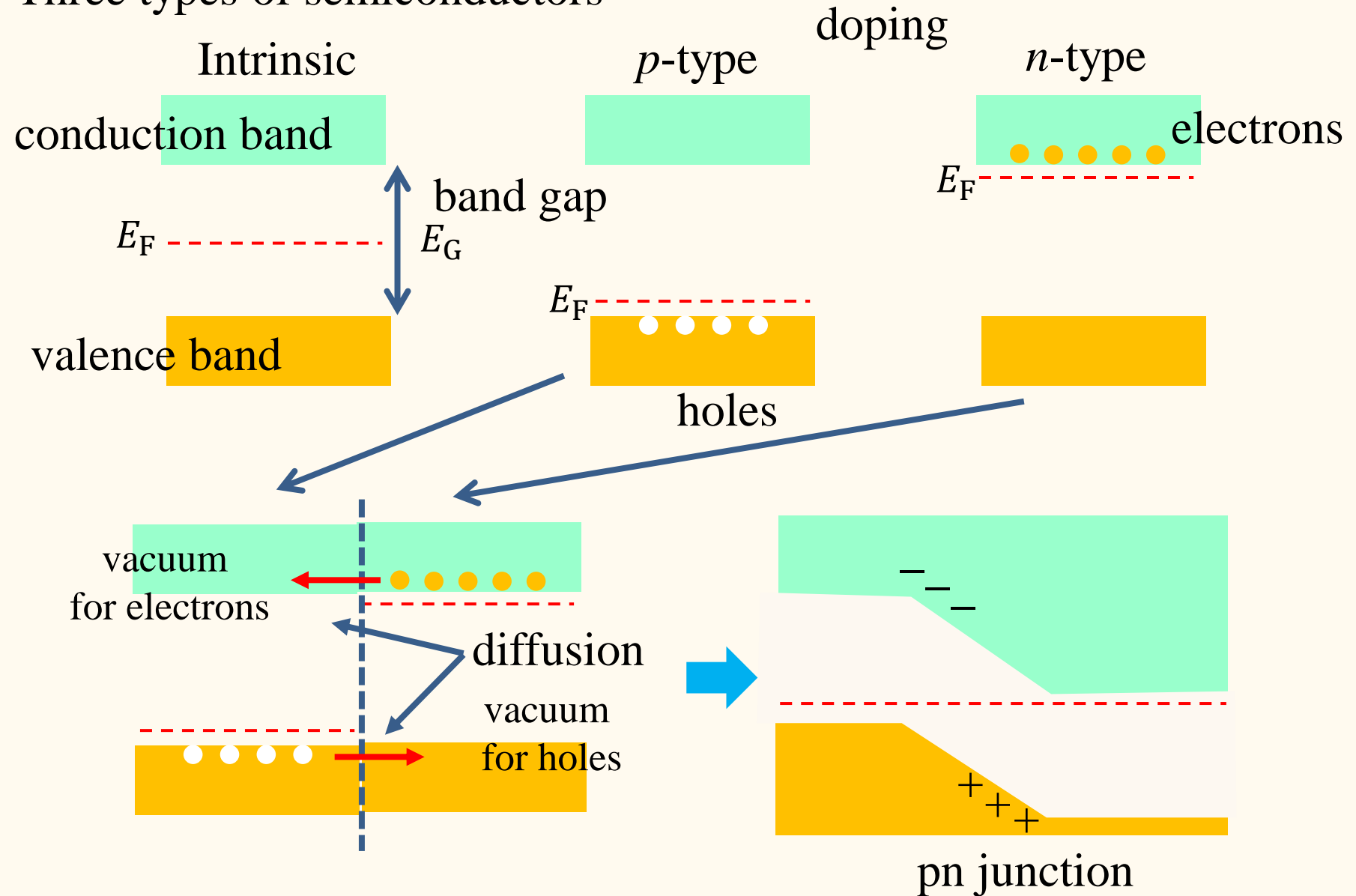


invensys  
**EUROTHERM**

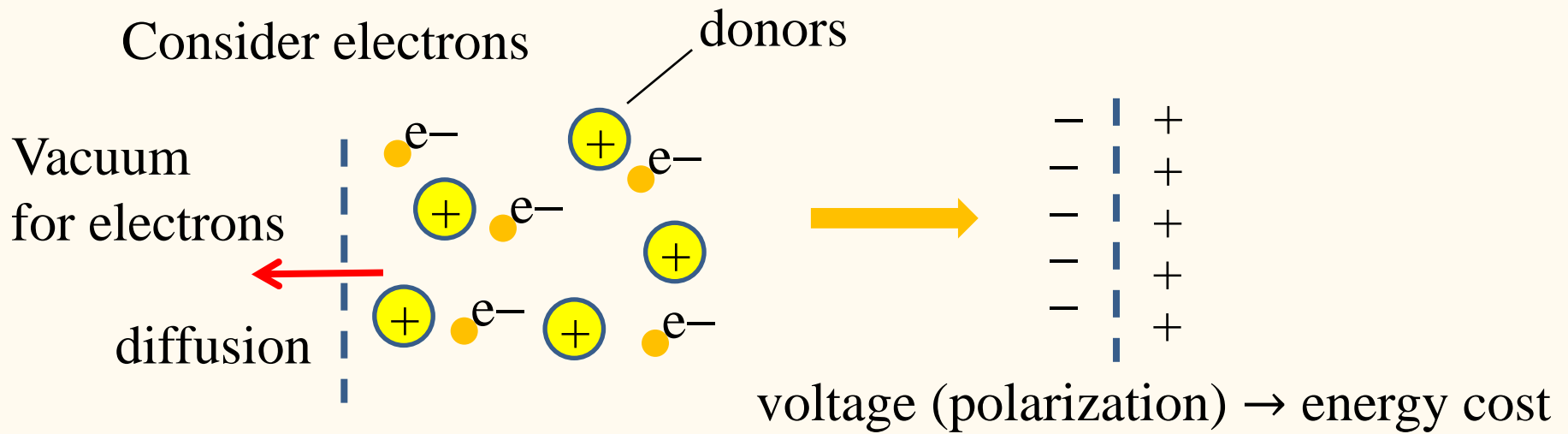


# 4.4 Example of active element: Transistors

Three types of semiconductors



# pn junction thermodynamics



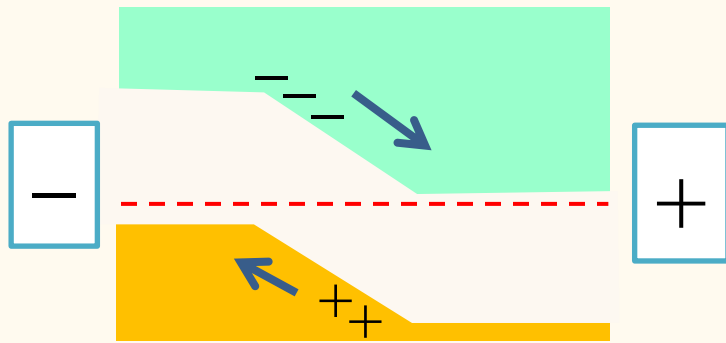
$$F = U - TS$$

Voltage (internal energy cost)

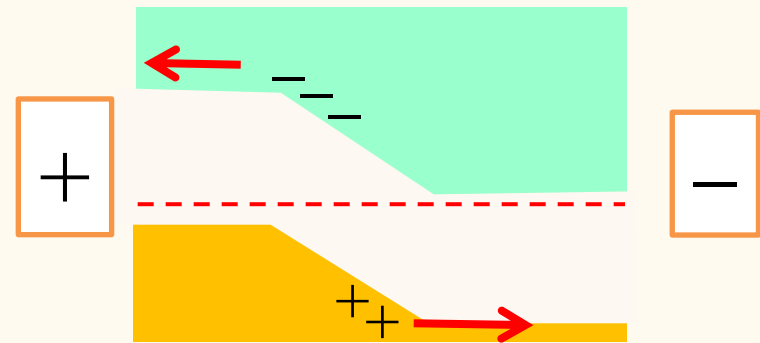
Diffusion (entropy)

Minimization of  $F$  → Built-in (diffusion) voltage  $V_{bi}$

# 4.4.1 I-V characteristics of pn junctions



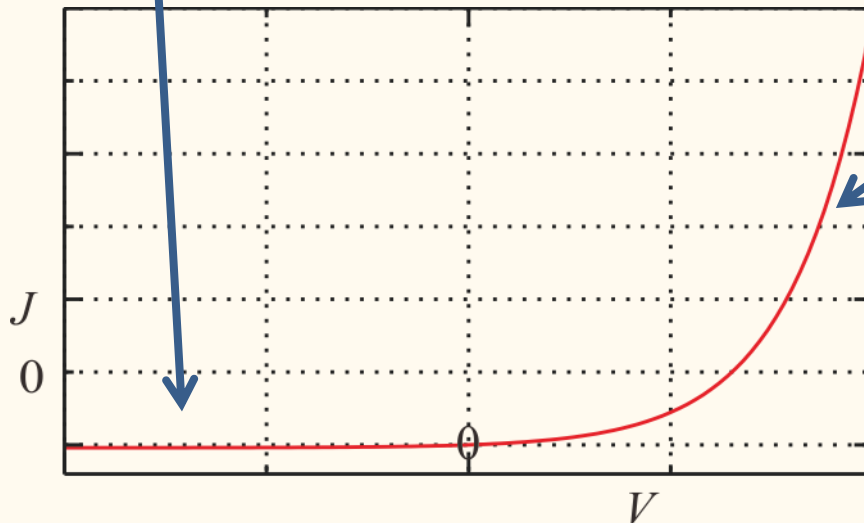
Reverse bias  
enhances  $V_{bi}$  : no go



Forward bias  
overcomes  $V_{bi}$  : go

Minority  
carrier injection

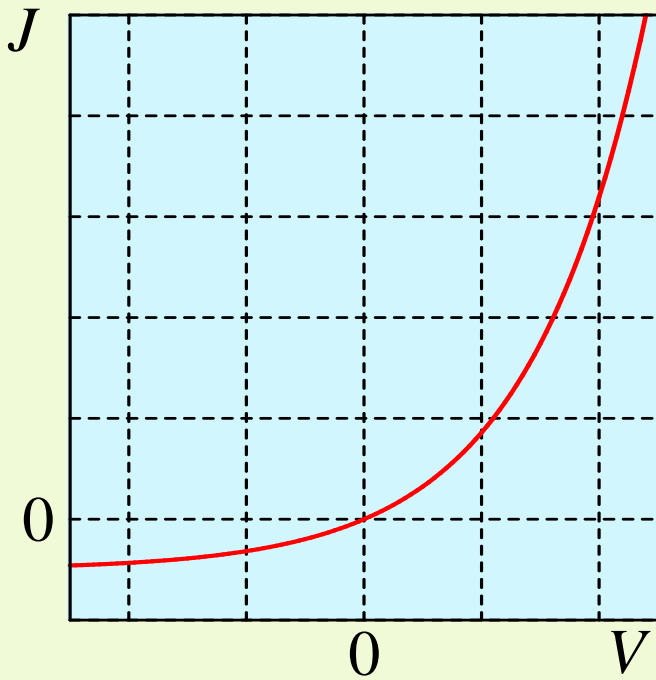
Rectification



$$J = J_0 \left[ \exp\left(\frac{eV}{k_B T}\right) - 1 \right]$$

Shockley theory

# Injection of minority carriers

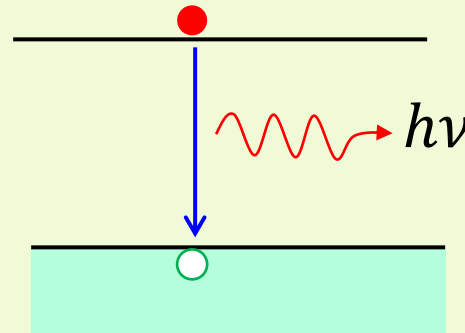


$$J = e(v_n n_p + v_p p_n) \left[ \exp \frac{eV}{k_B T} - 1 \right]$$

minority carrier  
current

Barrier overflow

light emitting  
diode



Fate of injected minority carriers:  
Radiative recombination

Nick Holonyak Jr.



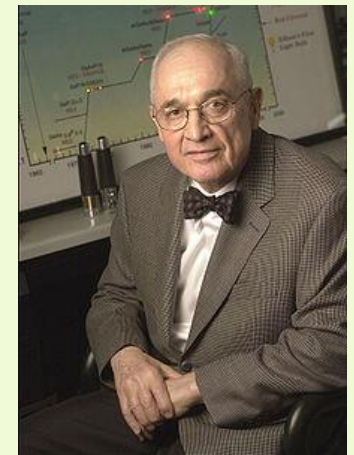
Photo: A. Mahmoud  
Isamu Akasaki



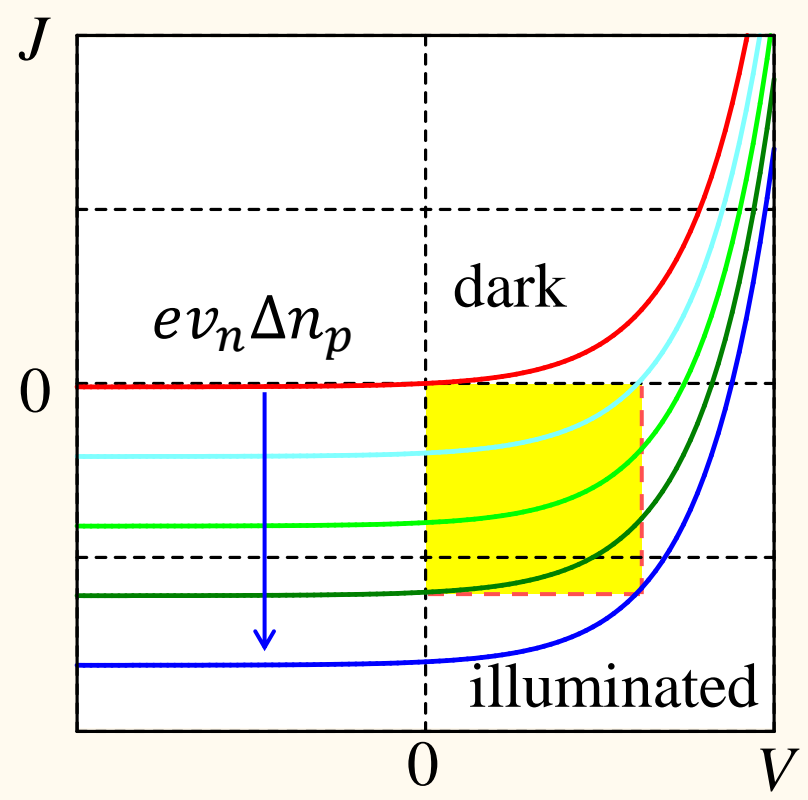
Photo: A. Mahmoud  
Hiroshi Amano



Photo: A. Mahmoud  
Shuji Nakamura



# Solar cell (injection of minority carriers with illumination)



$$J_{e0} = ev_n n_p \left[ \exp \frac{eV}{k_B T} - 1 \right]$$

$$J_e = ev_n n_p \exp \frac{eV}{k_B T} - ev_n (n_p + \Delta n_p)$$

$$= J_{n0} - \underline{ev_n \Delta n_p} \text{ External injection}$$

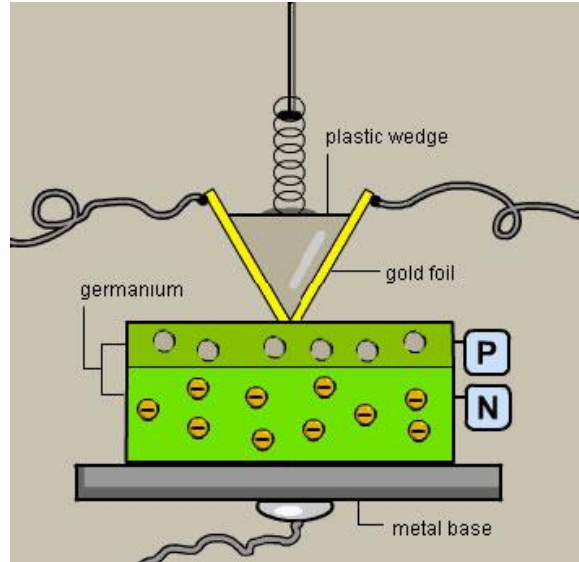


Gerald Pearson,  
Daryl Chapin  
and Calvin Fuller  
at Bell labs. 1954





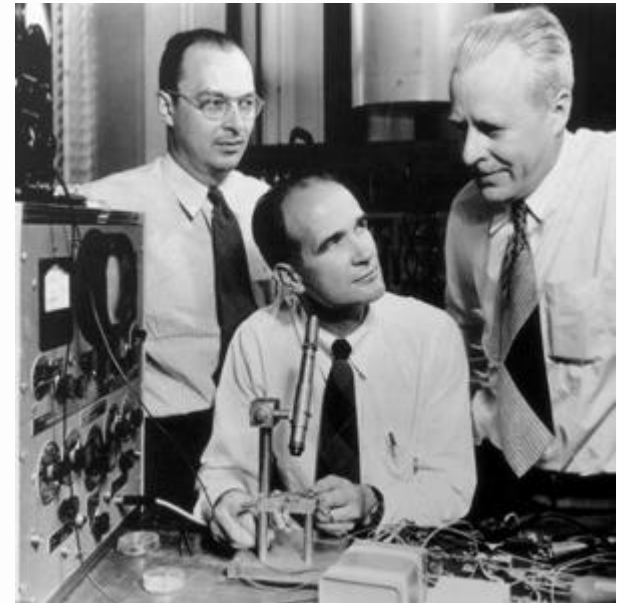
## 4.3.2 Discovery and invention of bi-polar transistors



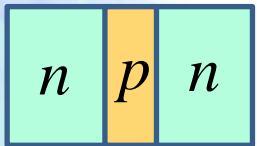
The first point contact transistor  
(Dec. 1947

The paper published in June 1948.)

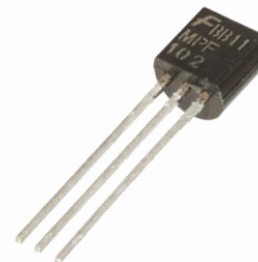
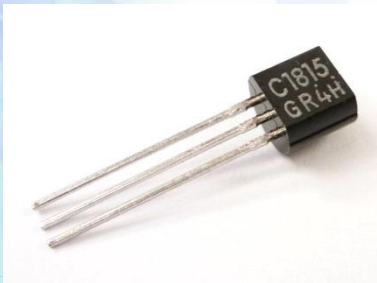
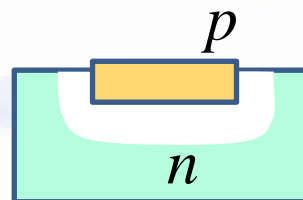
John Bardeen, William Shockley,  
Walter Brattain 1948 Bell Labs.



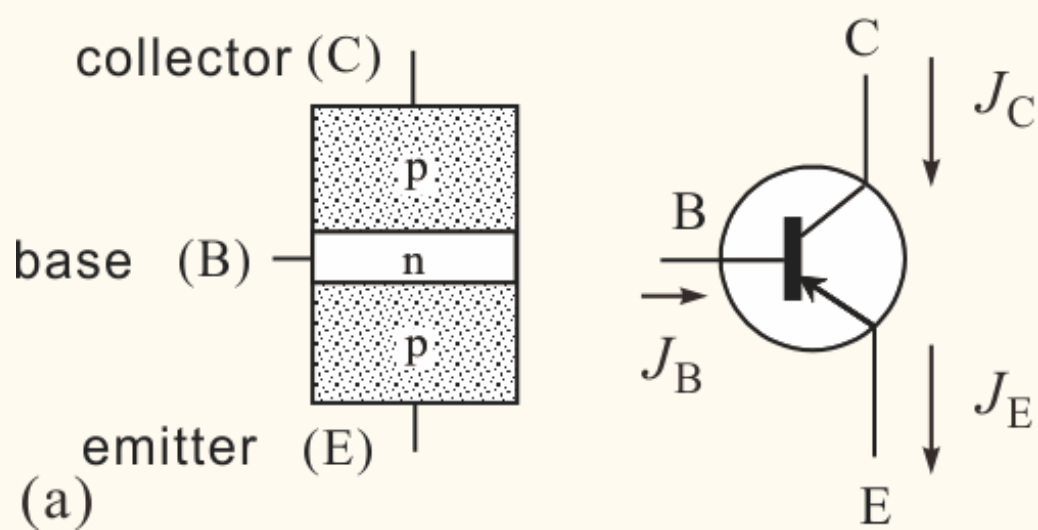
Bipolar junction transistor



Field effect transistor

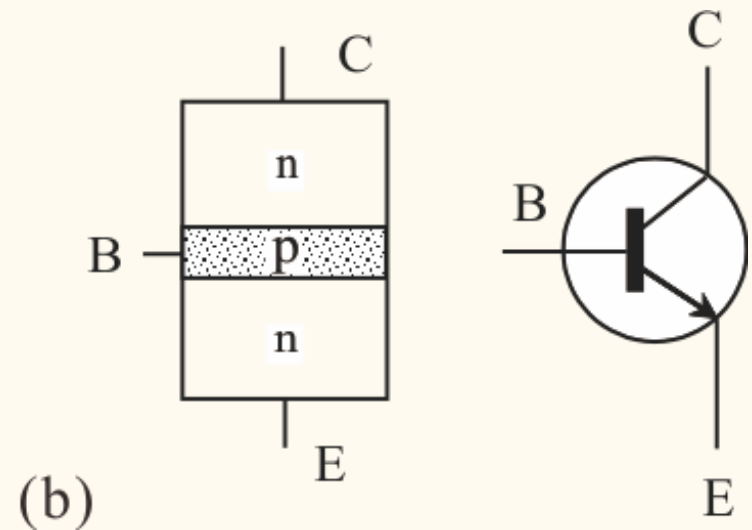


# Bipolar transistor structures and symbols



PNP type

$$L_B < L_h$$

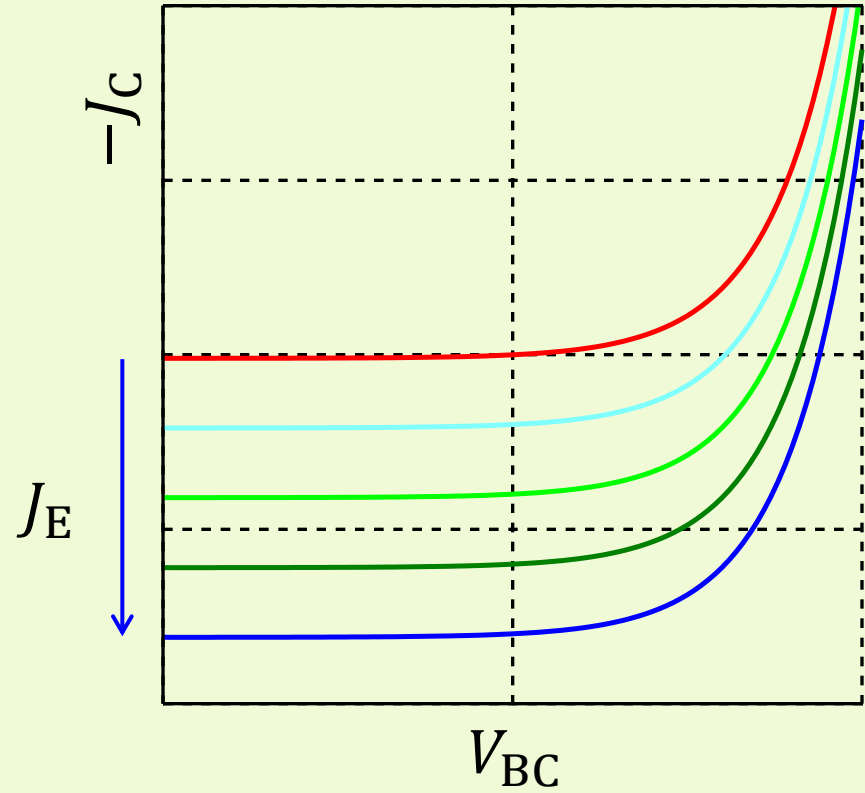
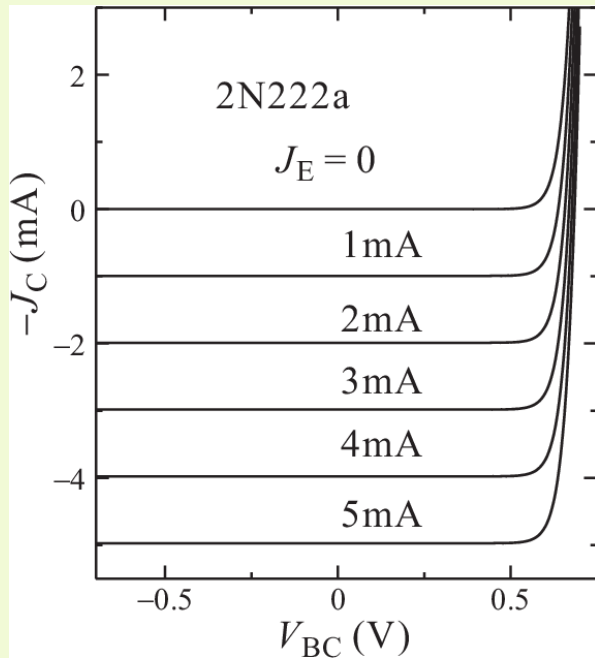
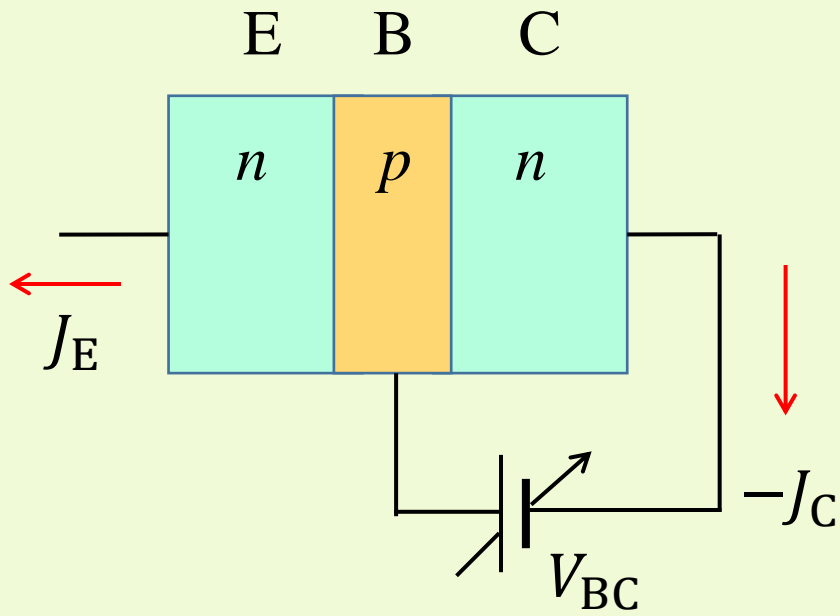


NPN type

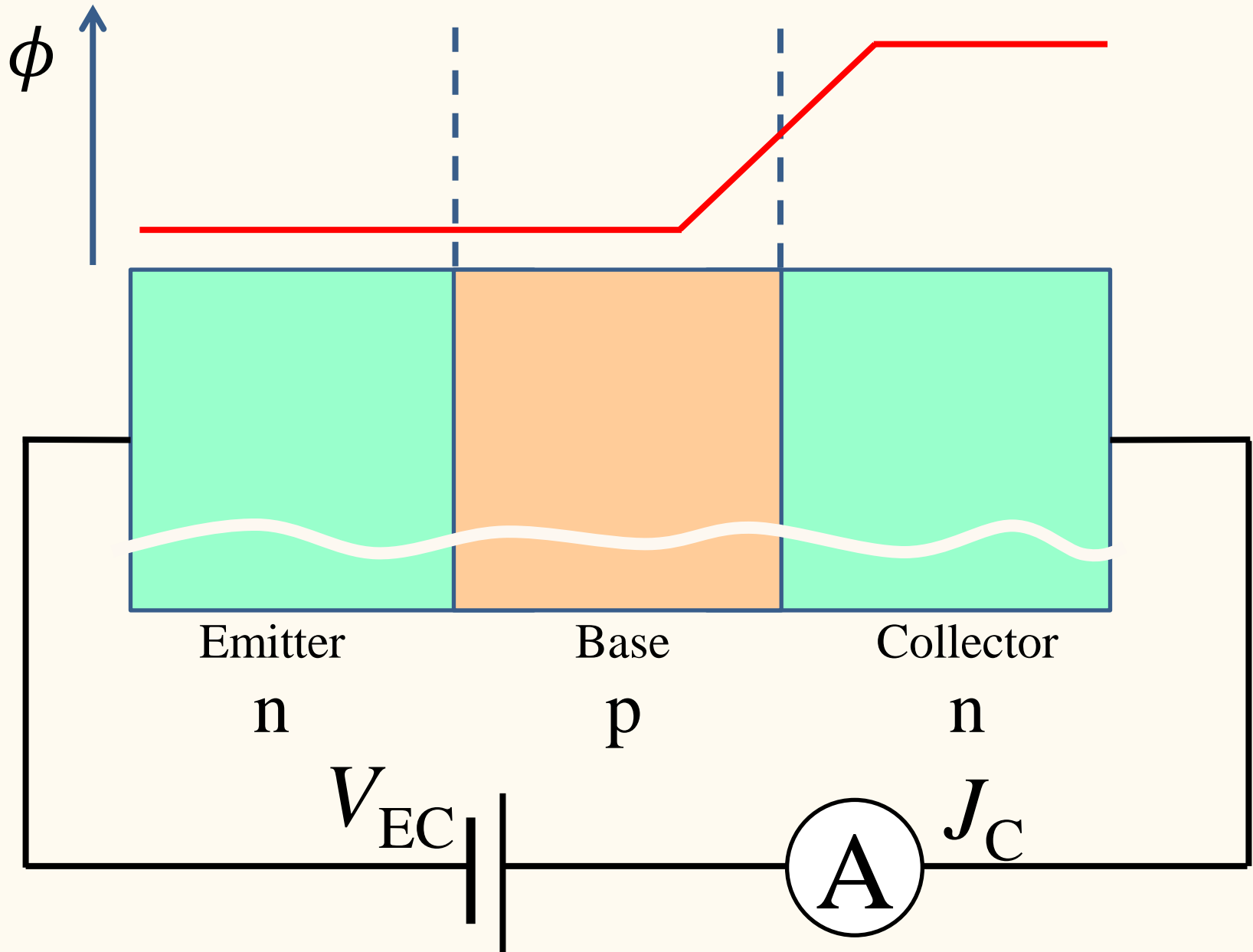
$$L_B < L_e$$

Similar characteristics PNP and NPN: complementary

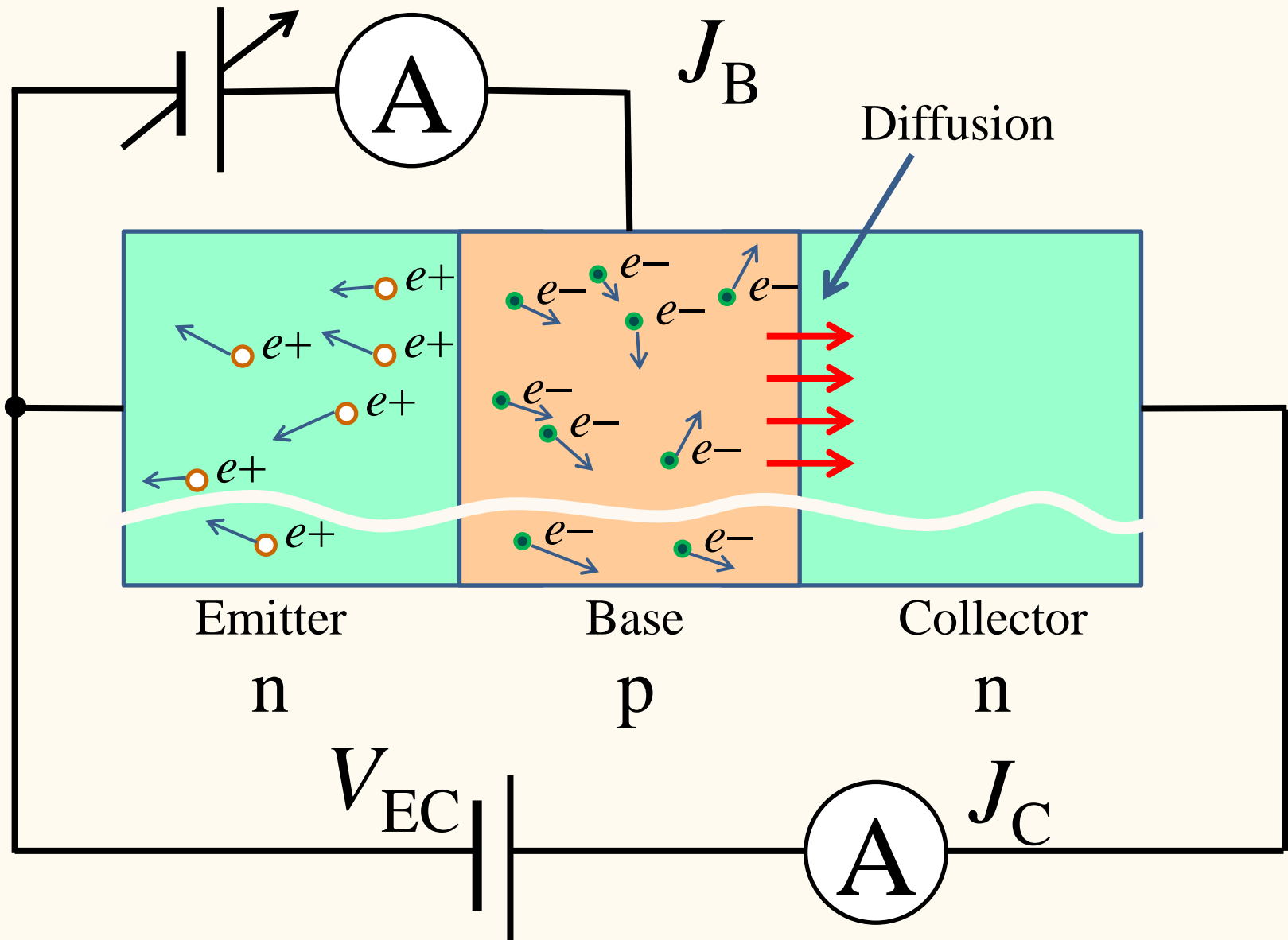
# Base-Collector characteristics



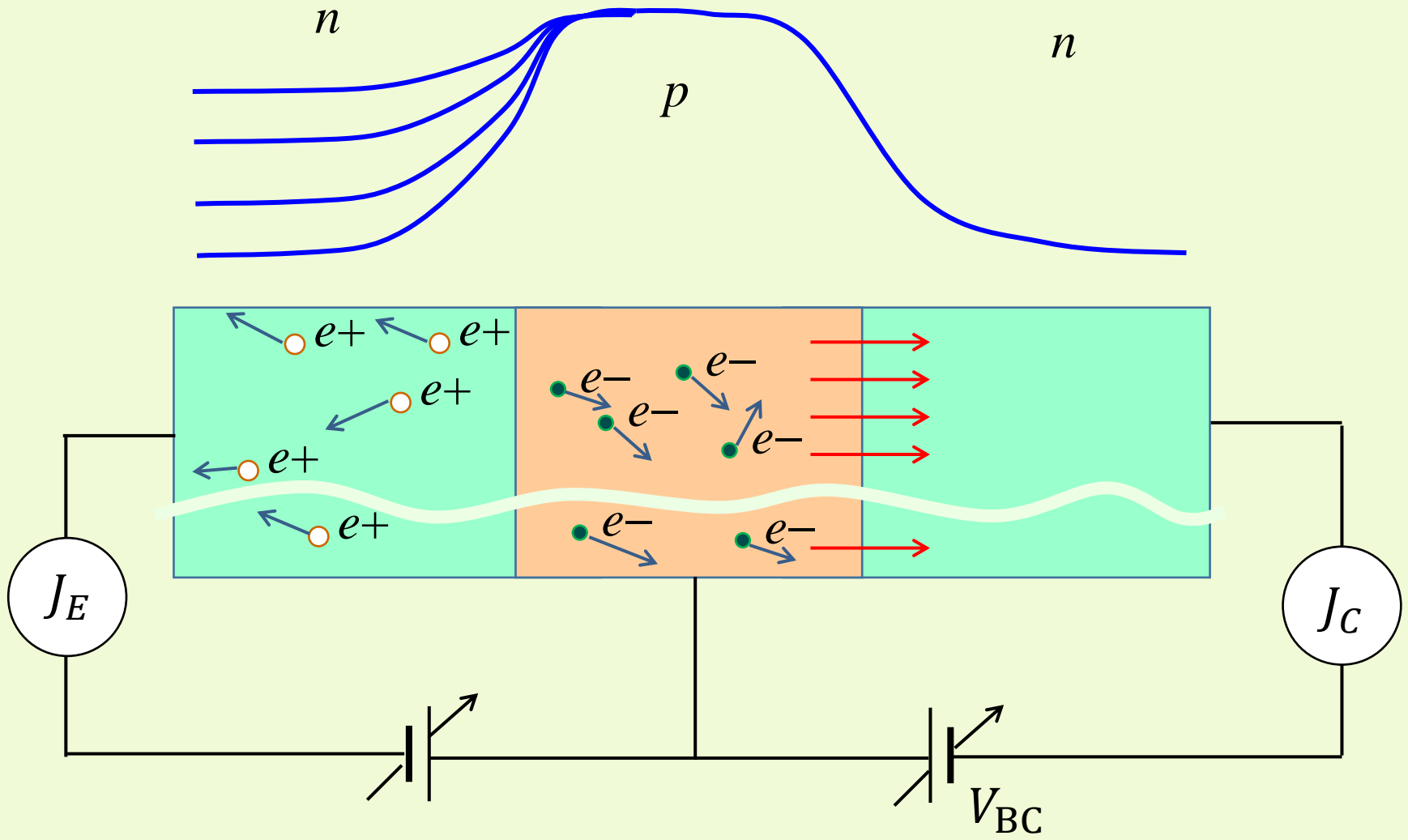
# How a bipolar transistor amplifies?



# How a bipolar transistor amplifies?

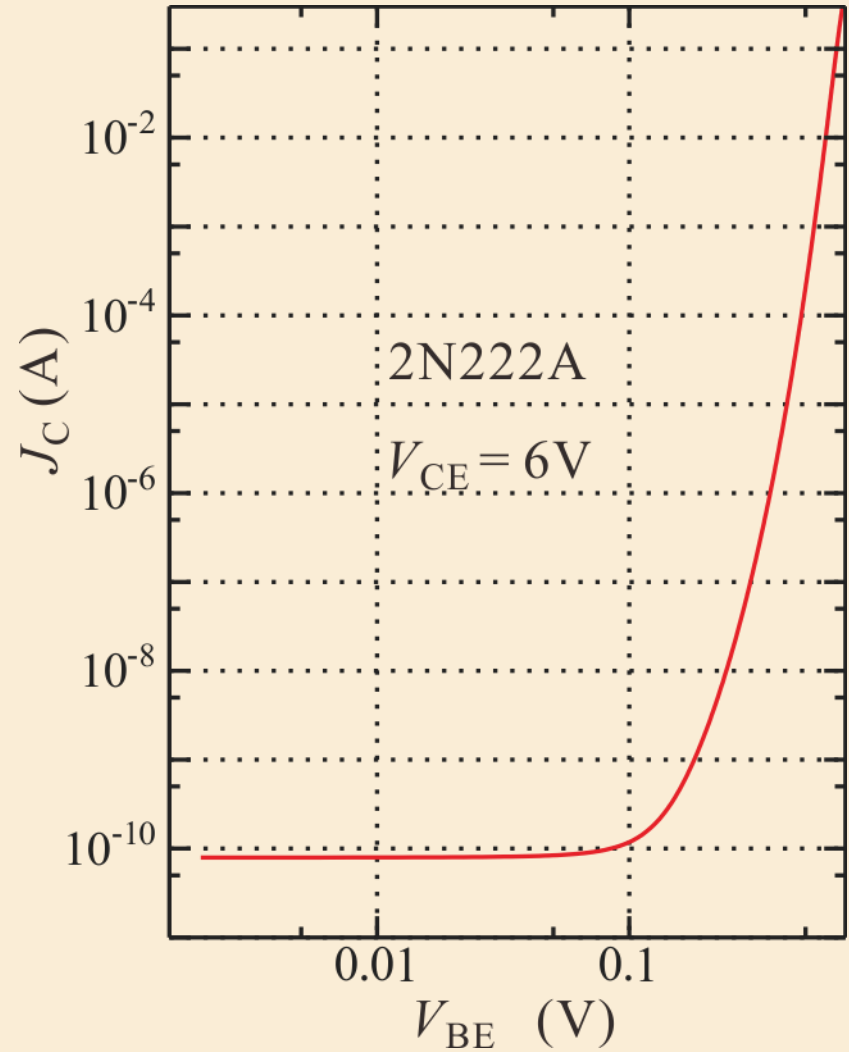
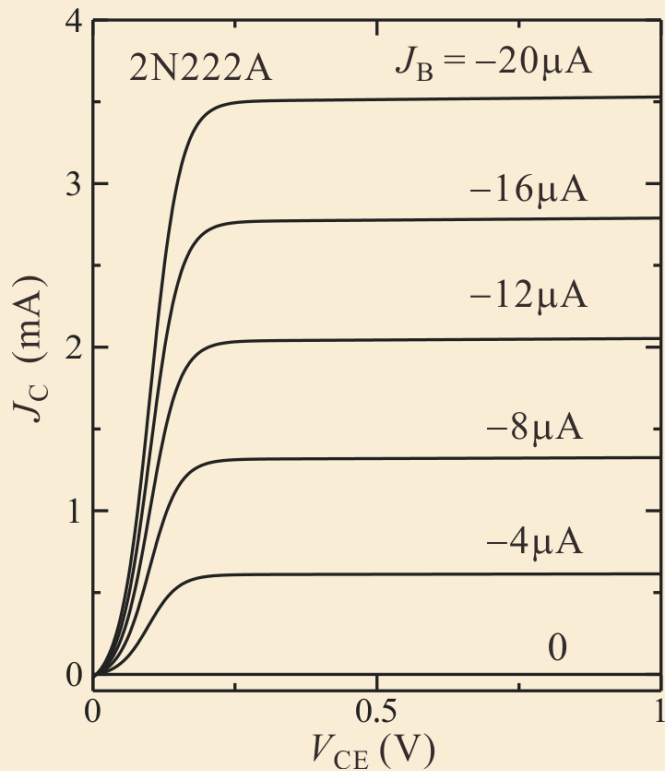
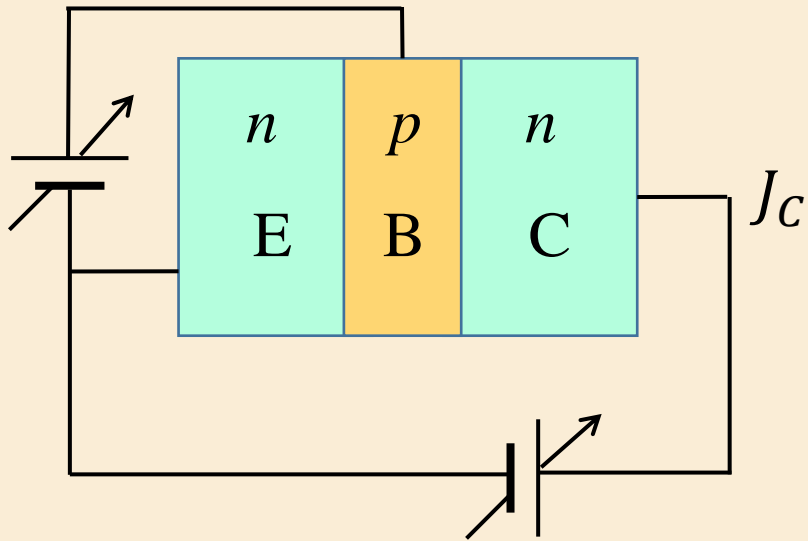


# Base-Collector characteristics

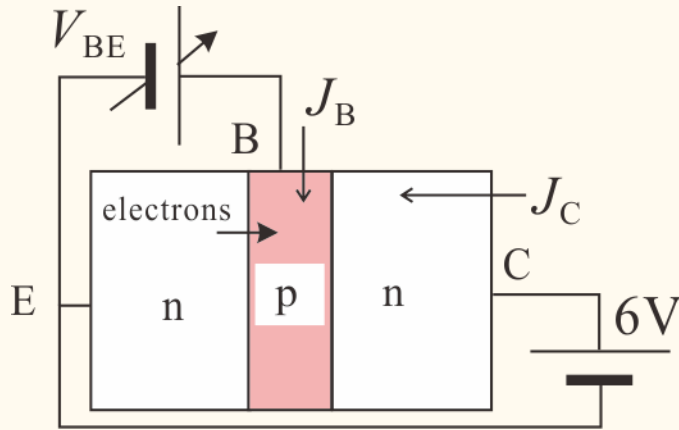




# Collector-Emitter characteristics

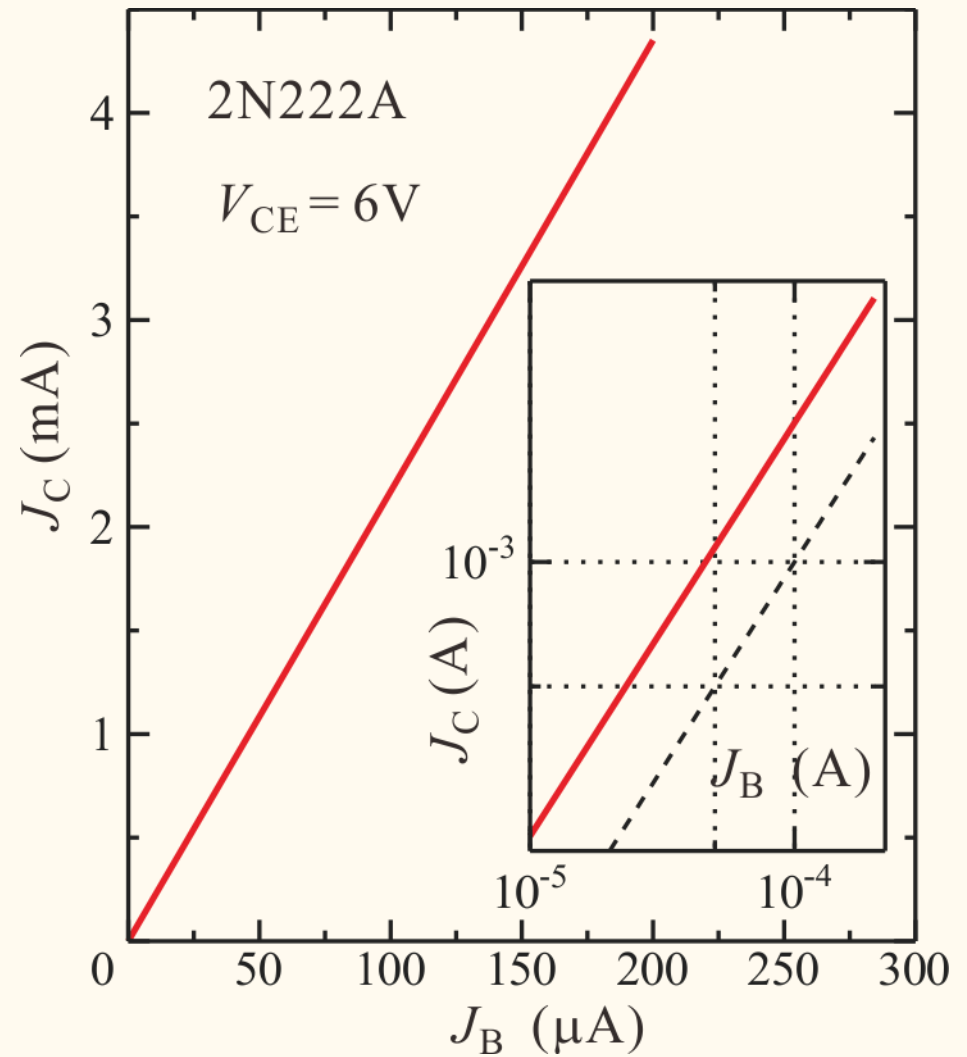


# Current amplification : Linearize with quantity selection



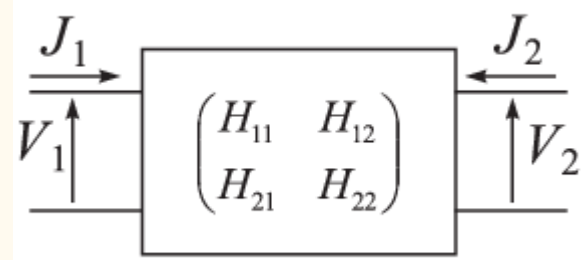
$$J_C = \underline{h_{FE}} J_B$$

Emitter-common current gain

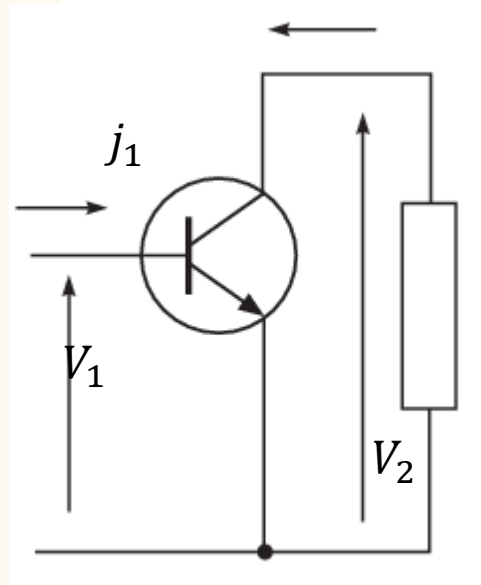


# Linear approximation of bipolar transistor

## Hybrid matrix



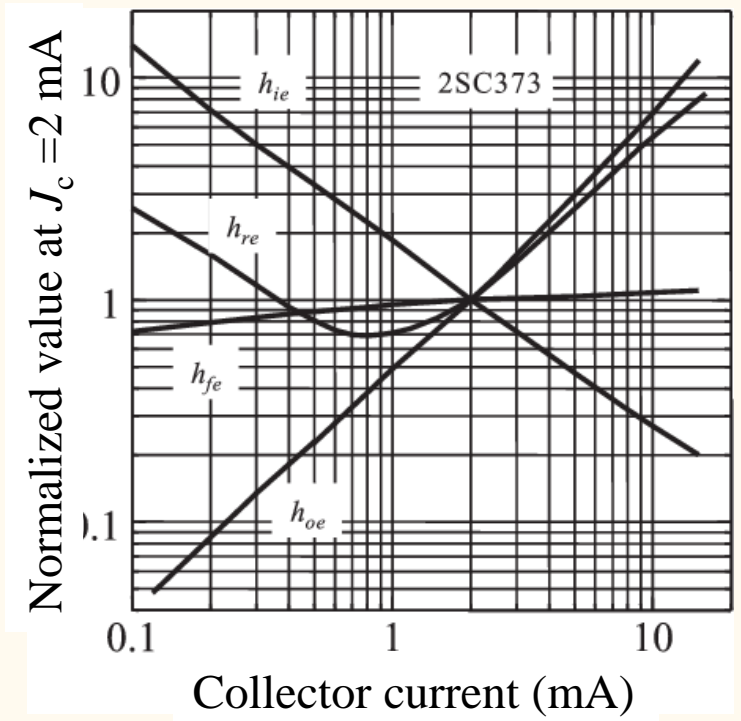
$$\begin{pmatrix} V_1 \\ J_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{21} & H_{22} \end{pmatrix} \begin{pmatrix} J_1 \\ V_2 \end{pmatrix}$$



$$j_2 \begin{pmatrix} v_1 \\ j_2 \end{pmatrix} = \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{pmatrix} \begin{pmatrix} j_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} h_i & h_r \\ h_f & h_o \end{pmatrix} \begin{pmatrix} j_1 \\ v_2 \end{pmatrix}$$

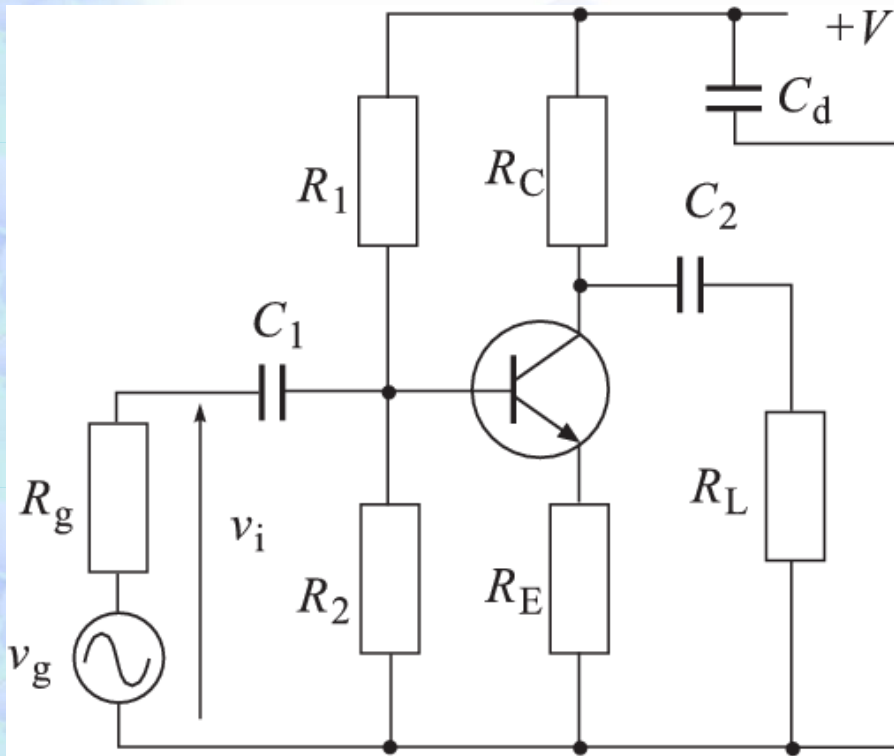
## h-parameters

(lower case:  
local linear approximation)



# Concept of bias circuits for non-linear devices

Common emitter amplifier

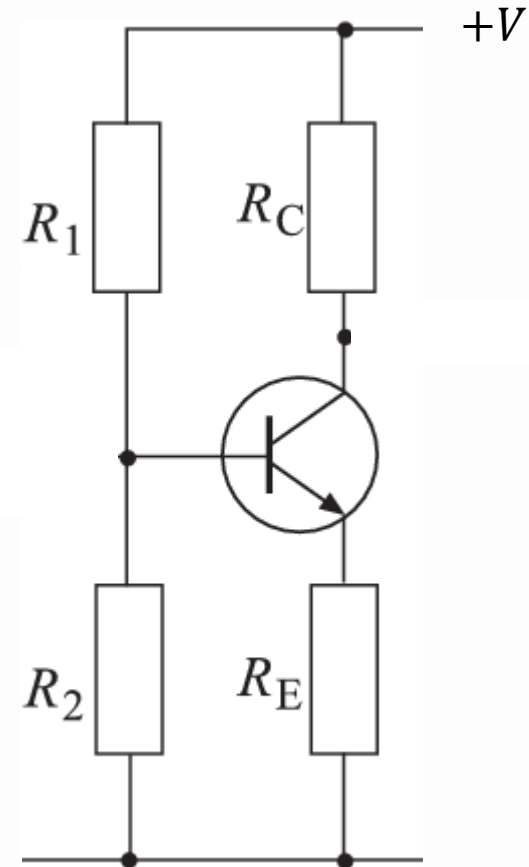


For small amplitude (high-frequency) circuits

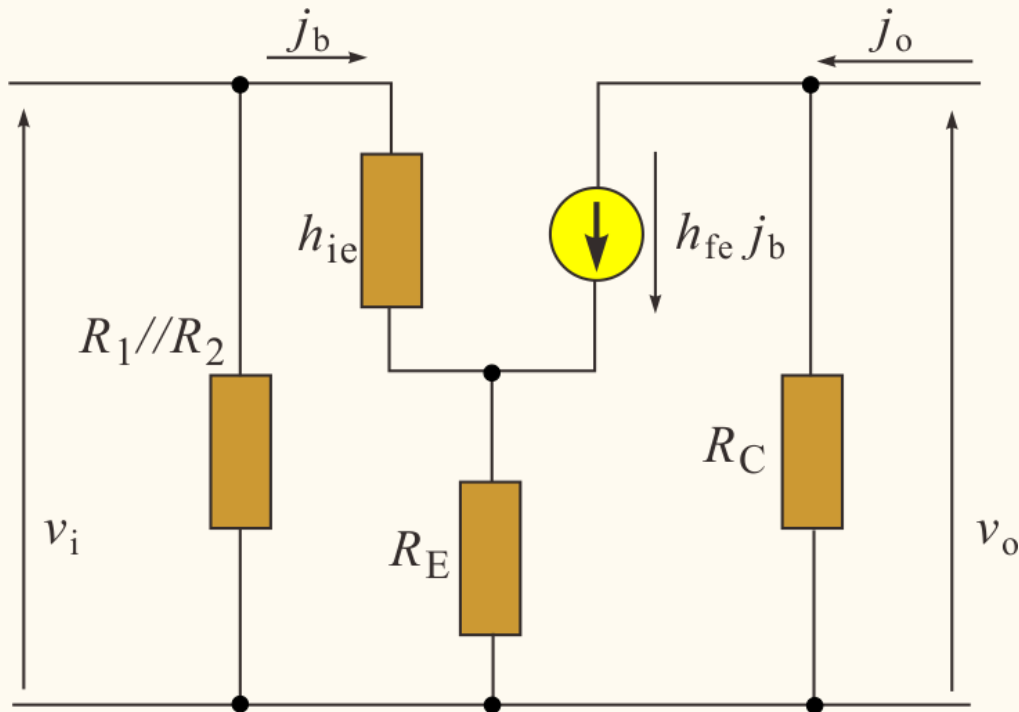
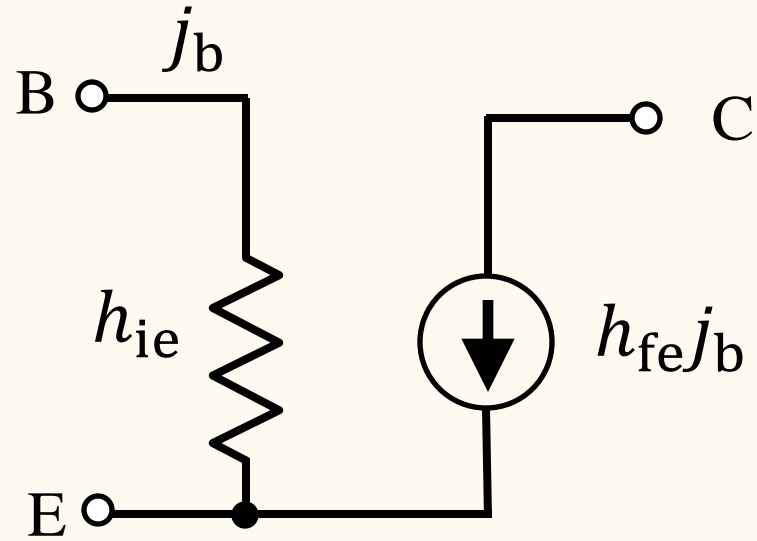
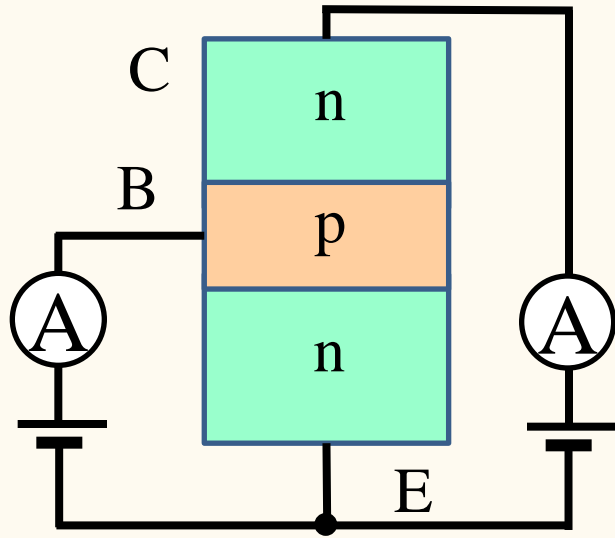
All the capacitors can be viewed as short circuits.

For bias (dc) circuits

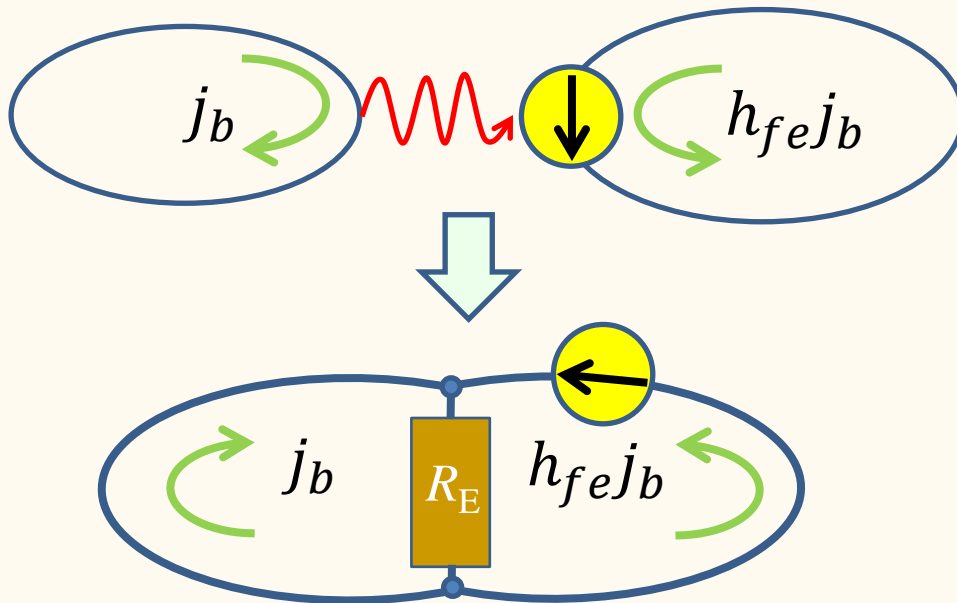
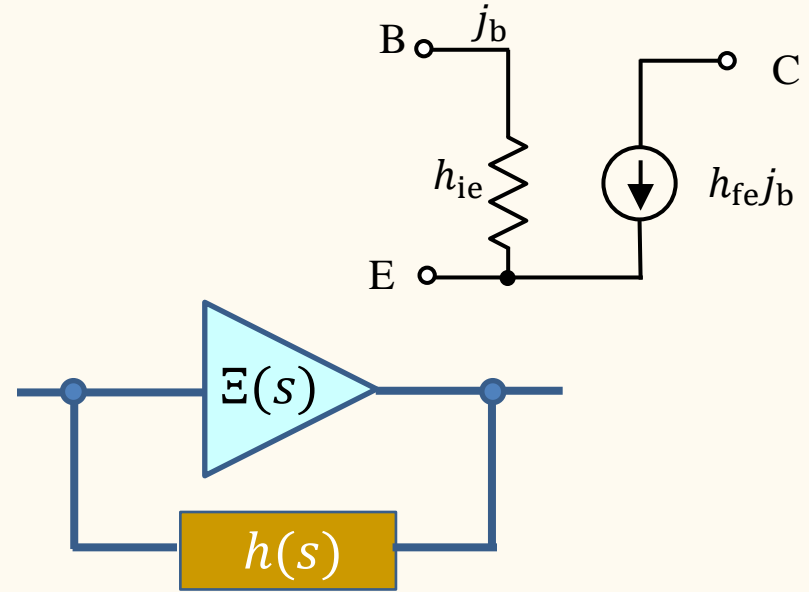
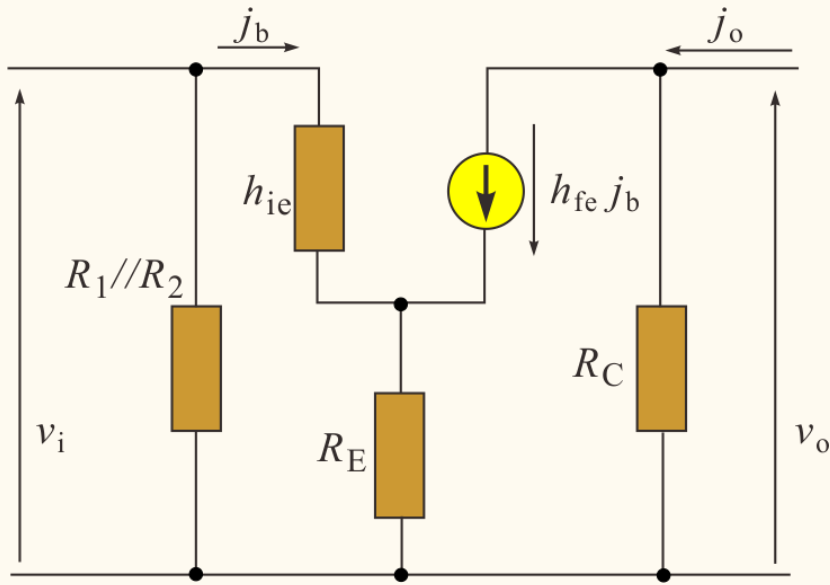
All the capacitors can be viewed as break line.



# Concept of equivalent circuit



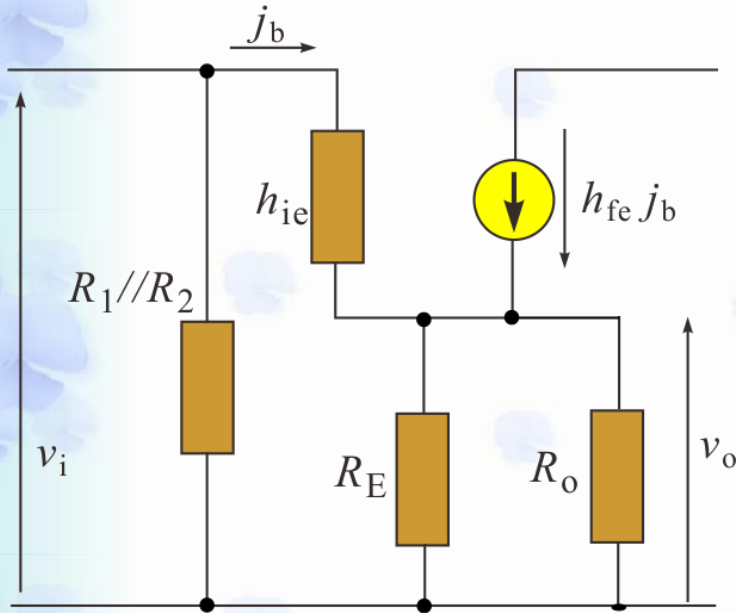
# Concept of equivalent circuit: Where is feedback?



$$\begin{aligned}
 A &= \frac{v_o}{v_i} \\
 &= \frac{h_{fe} R_C}{h_{ie} + R_E (1 + h_{fe})} \\
 &\approx \frac{R_C}{R_E} \quad h_{fe} \gg 1
 \end{aligned}$$



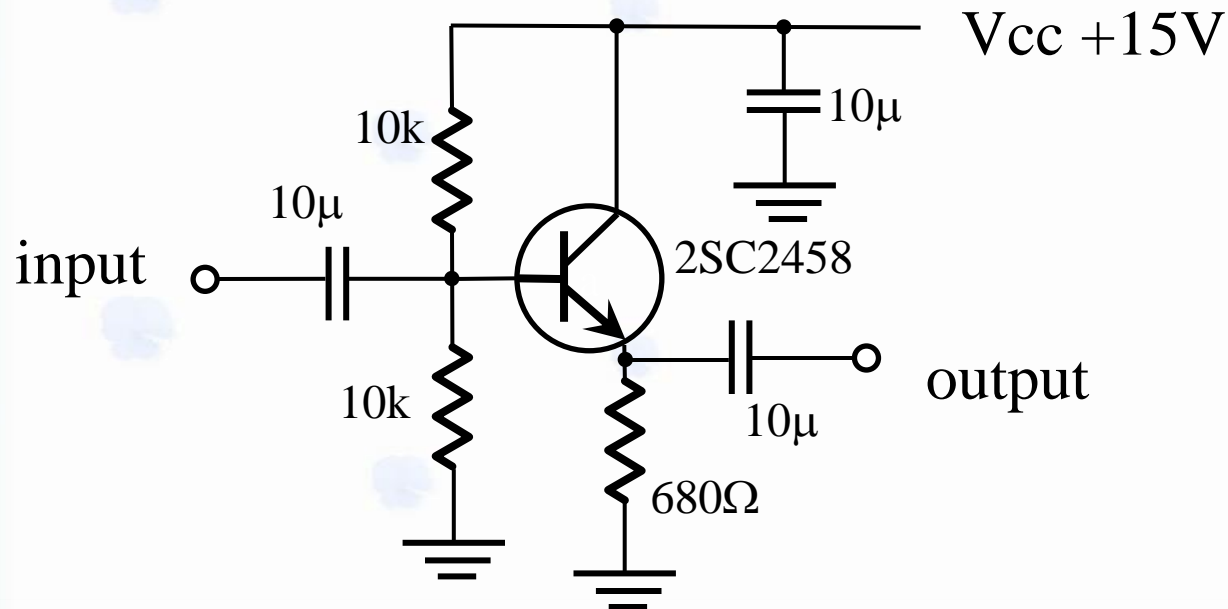
# Current amplification: Emitter follower



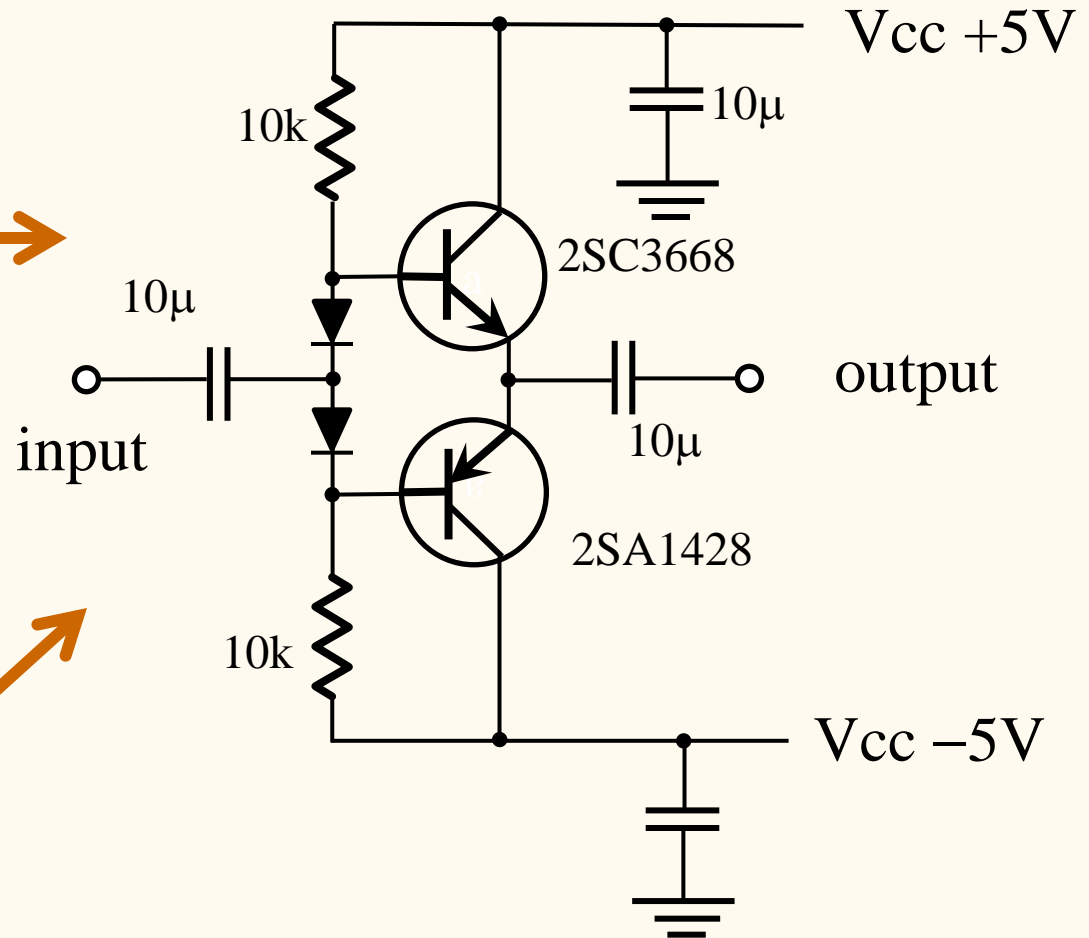
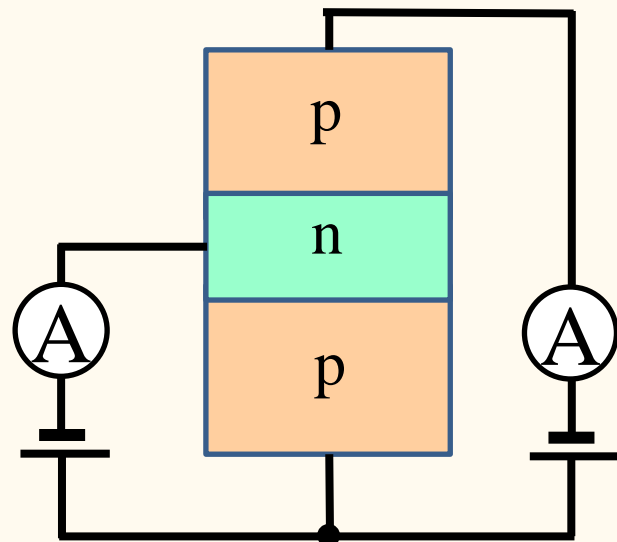
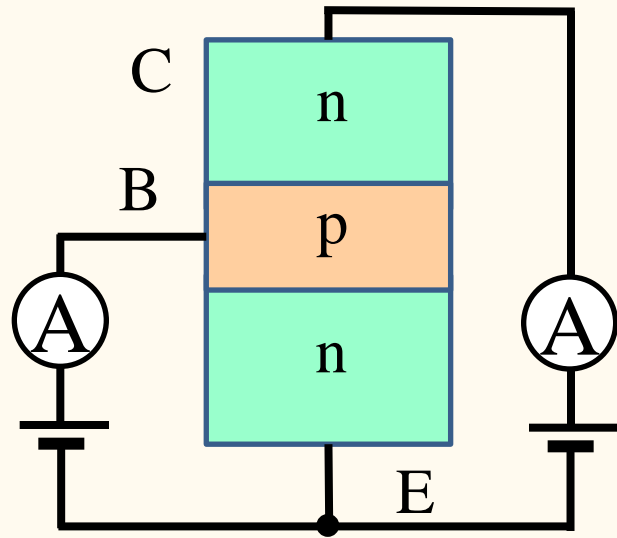
$$\frac{v_o}{v_i} = \frac{j_b(1 + h_{fe})(R_E \parallel R_o)}{j_b[h_{ie} + (1 + h_{fe})(R_E \parallel R_o)]}$$
$$\approx 1 \quad (h_{fe} \gg 1)$$

$v_o$  does not depend on load resistance

$\Rightarrow$  Very low output resistance



# Complementary transistors



Symmetric characteristics: Complementary

Symmetric: Small collector current  
(idling current) for zero input.

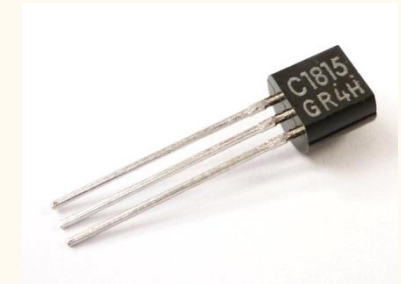
# Example of transistor datasheet

**TOSHIBA**

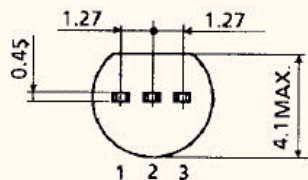
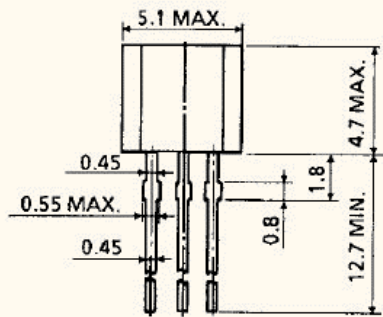
2SC1815(L)

TOSHIBA Transistor Silicon NPN Epitaxial Type (PCT process)

## 2SC1815(L)



Unit: mm



1. EMITTER
2. COLLECTOR
3. BASE

Audio Frequency Voltage Amplifier Applications  
Low Noise Amplifier Applications

- High breakdown voltage, high current capability  
:  $V_{CEO} = 50 \text{ V (min)}$ ,  $I_C = 150 \text{ mA (max)}$
- Excellent linearity of  $h_{FE}$   
:  $h_{FE} (2) = 100 \text{ (typ.)}$  at  $V_{CE} = 6 \text{ V}$ ,  $I_C = 150 \text{ mA}$   
:  $h_{FE} (I_C = 0.1 \text{ mA})/h_{FE} (I_C = 2 \text{ mA}) = 0.95 \text{ (typ.)}$
- Low noise:  $NF = 0.2\text{dB (typ.)}$  ( $f = 1 \text{ kHz}$ ).
- Complementary to 2SA1015 (L). (O, Y, GR class).

JEDEC	TO-92
JEITA	SC-43
TOSHIBA	2-5F1B

# Example of transistor datasheet

**TOSHIBA**

2SC1815(L)

TOSHIBA Transistor Silicon NPN Epitaxial Type (PCT process)

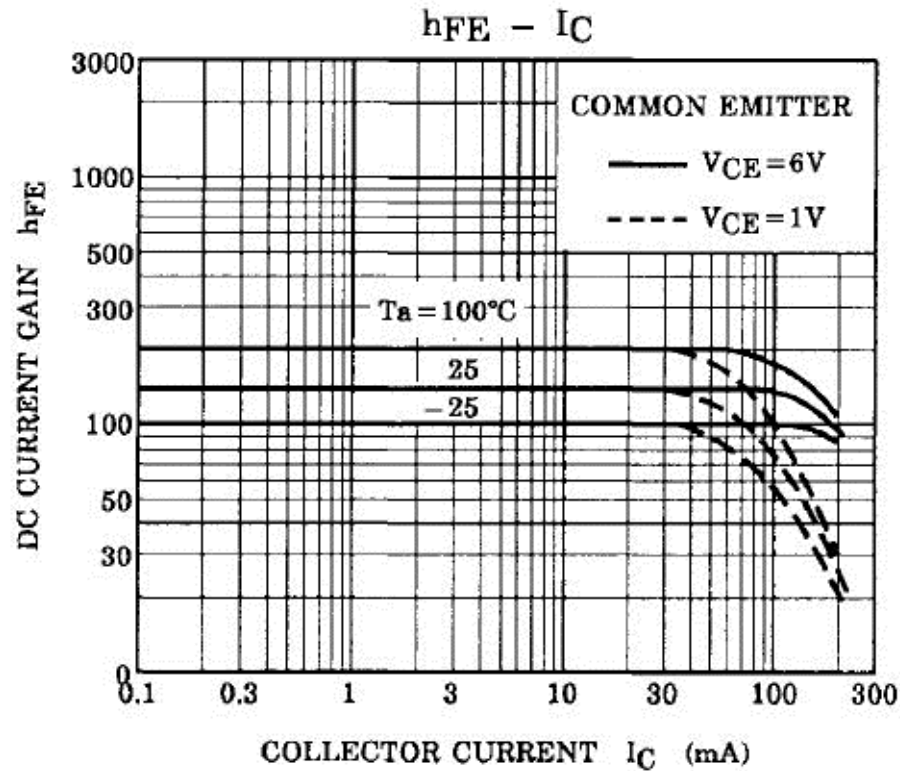
## 2SC1815(L)

### Electrical Characteristics (Ta = 25°C)

Characteristics		Symbol	Test Condition	Min	Typ.	Max	Unit
Collector cut-off current		$I_{CBO}$	$V_{CB} = 60 \text{ V}, I_E = 0$	—	—	0.1	$\mu\text{A}$
Emitter cut-off current		$I_{EBO}$	$V_{EB} = 5 \text{ V}, I_C = 0$	—	—	0.1	$\mu\text{A}$
DC current gain		$h_{FE} (1)$ (Note)	$V_{CE} = 6 \text{ V}, I_C = 2 \text{ mA}$	70	—	700	
		$h_{FE} (2)$	$V_{CE} = 6 \text{ V}, I_C = 150 \text{ mA}$	25	100	—	
Saturation voltage	Collector-emitter	$V_{CE} (\text{sat})$	$I_C = 100 \text{ mA}, I_B = 10 \text{ mA}$	—	0.1	0.25	V
	Base-emitter	$V_{BE} (\text{sat})$	$I_C = 100 \text{ mA}, I_B = 10 \text{ mA}$	—	—	1.0	
Transition frequency		$f_T$	$V_{CE} = 10 \text{ V}, I_C = 1 \text{ mA}$	80	—	—	MHz
Collector output capacitance		$C_{ob}$	$V_{CB} = 10 \text{ V}, I_E = 0, f = 1 \text{ MHz}$	—	2.0	3.5	pF
Base intrinsic resistance		$r_{bb'}$	$V_{CE} = 10 \text{ V}, I_E = -1 \text{ mA}, f = 30 \text{ MHz}$	—	50	—	$\Omega$
Noise figure		NF (1)	$V_{CE} = 6 \text{ V}, I_C = 0.1 \text{ mA}$ $R_G = 10 \text{ k}\Omega, f = 100 \text{ Hz}$	—	0.5	6	dB
		NF (2)	$V_{CE} = 6 \text{ V}, I_C = 0.1 \text{ mA}$ $R_G = 10 \text{ k}\Omega, f = 1 \text{ kHz}$	—	0.2	3	

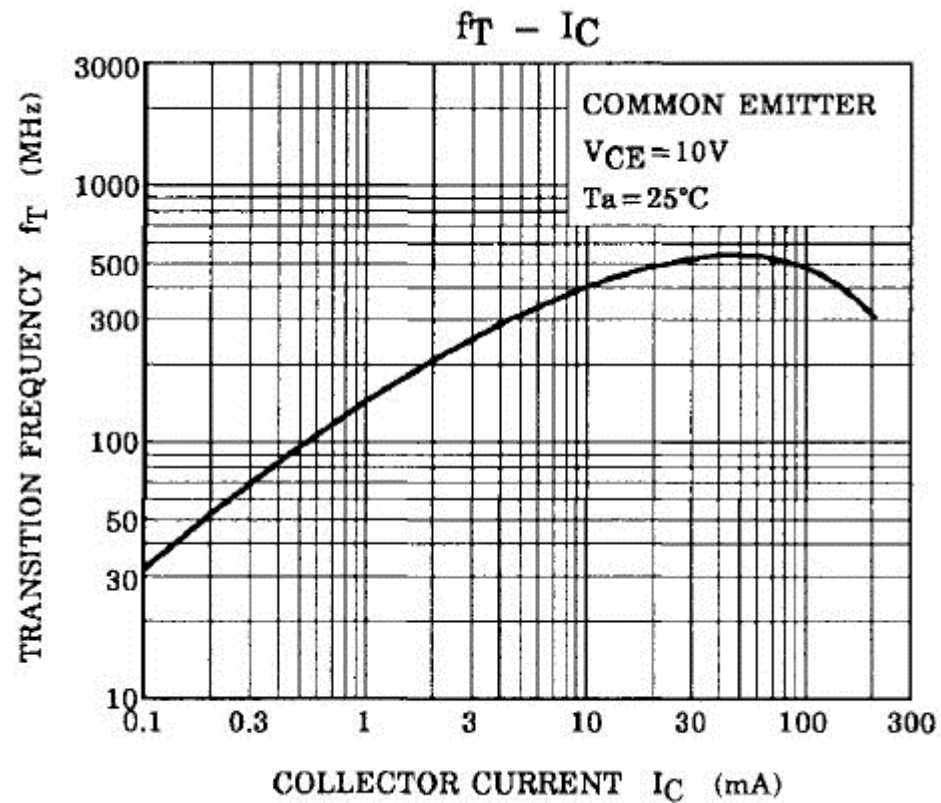
Note:  $h_{FE} (1)$  classification O: 70~140, Y: 120~240, GR: 200~400, BL: 350~700

# Example of transistor datasheet

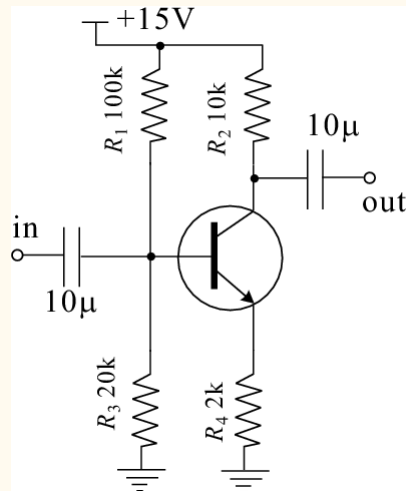


Cut-off frequency as a function of  $I_C$

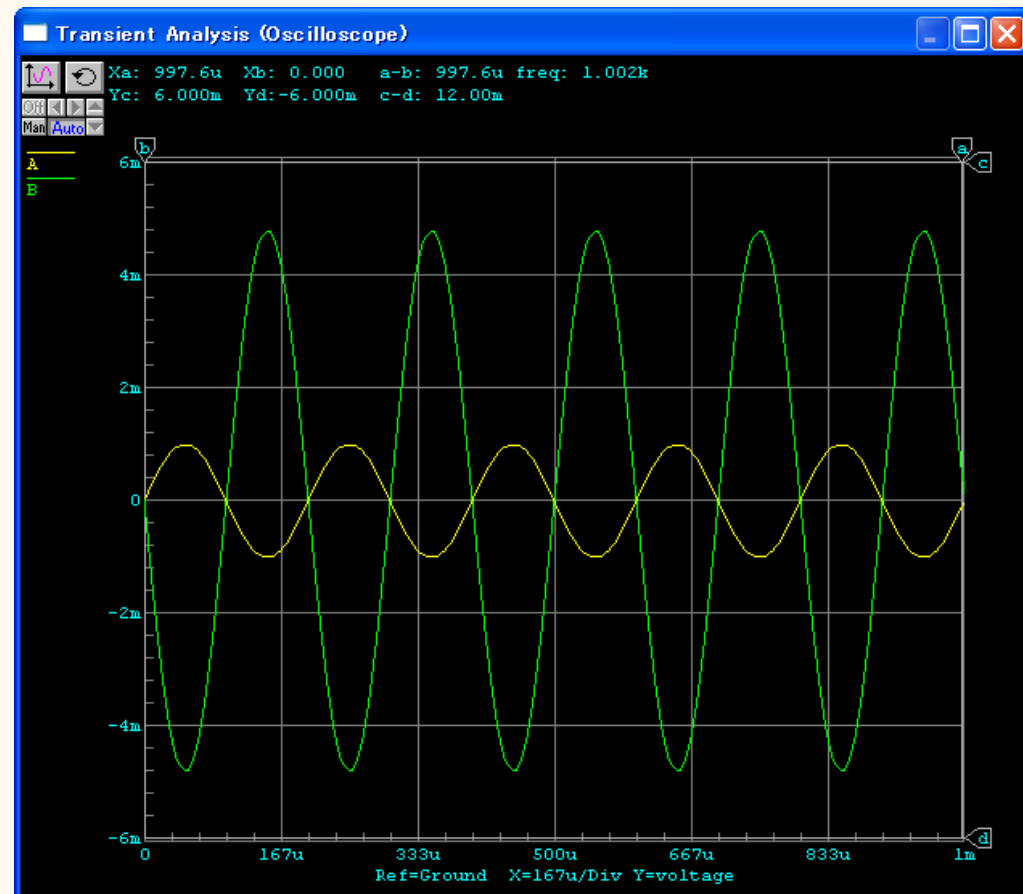
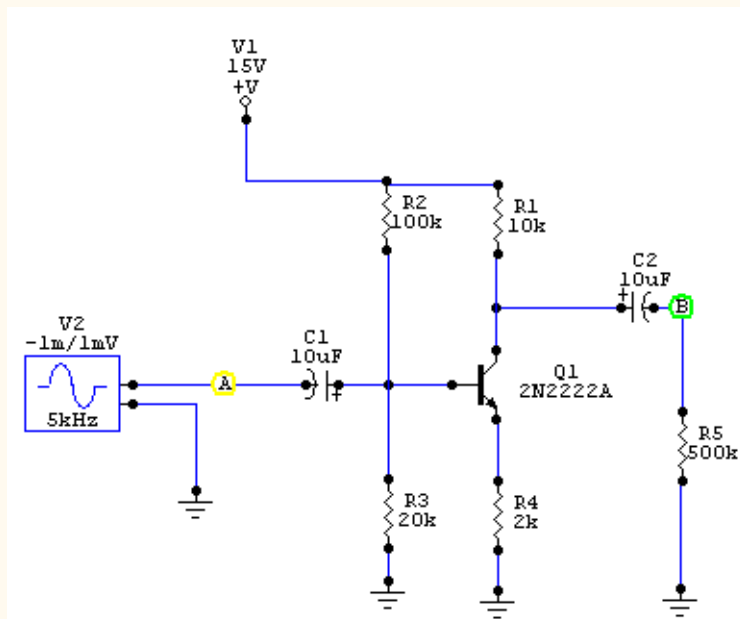
$h_{fe}$  linear model availability  
in the range of  $I_C$ .



# Common emitter (grounded emitter) amplifier circuit



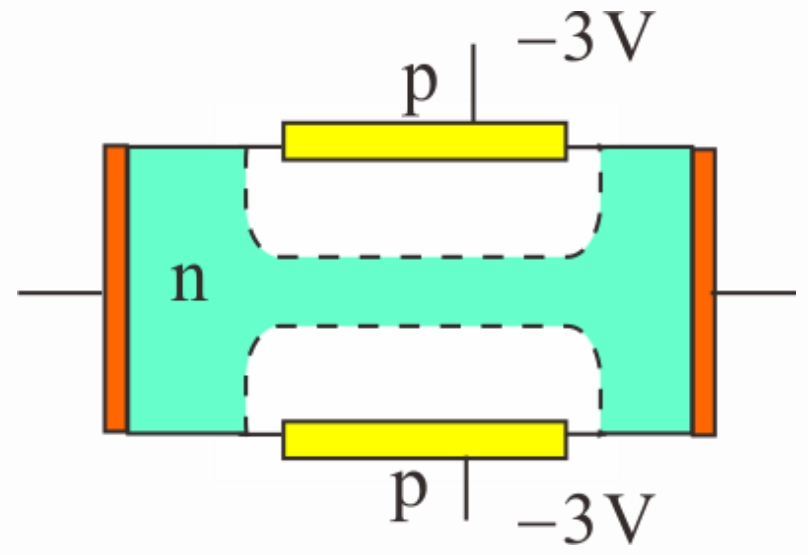
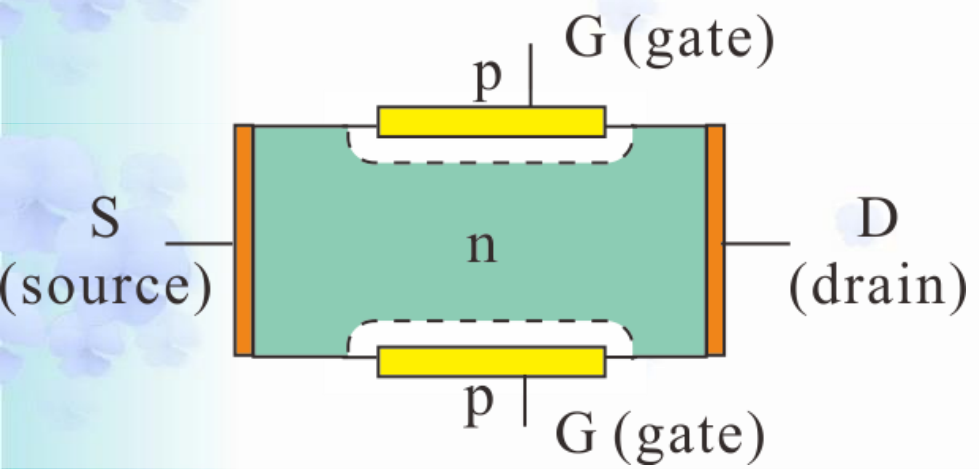
$$\Delta V_C = R_2 \Delta J_C \approx R_2 \Delta J_E = R_2 \frac{\Delta V_E}{R_4} = \frac{R_2}{R_4} \Delta V$$



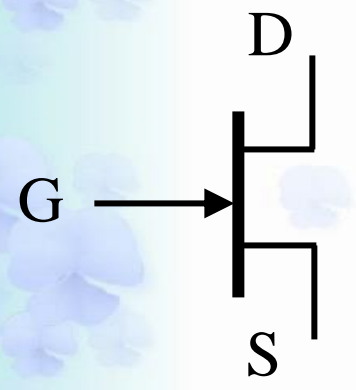


# 4.4 Field effect transistor (FET)

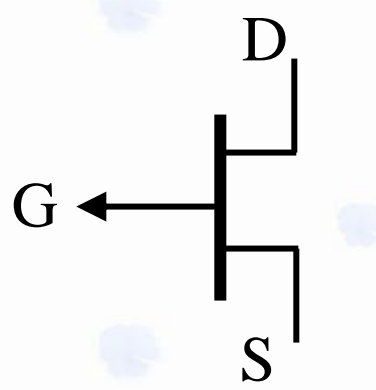
## Junction FET (JFET)



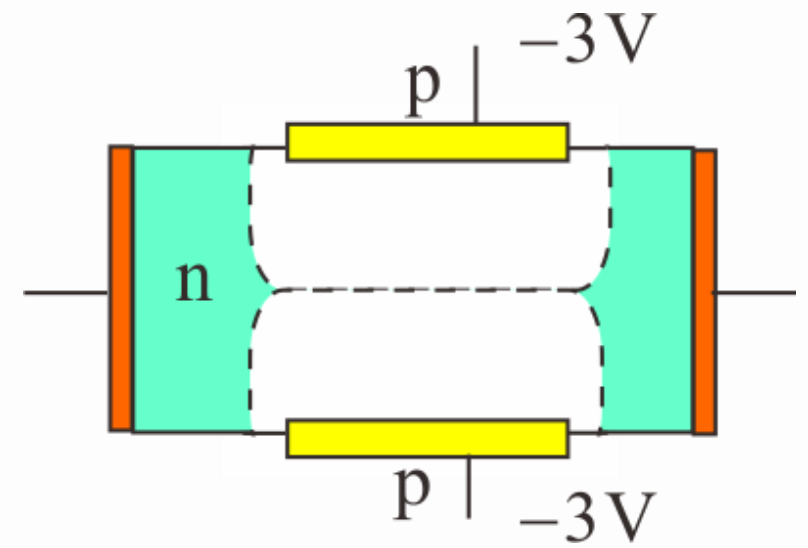
## Circuit symbols



*n*-channel

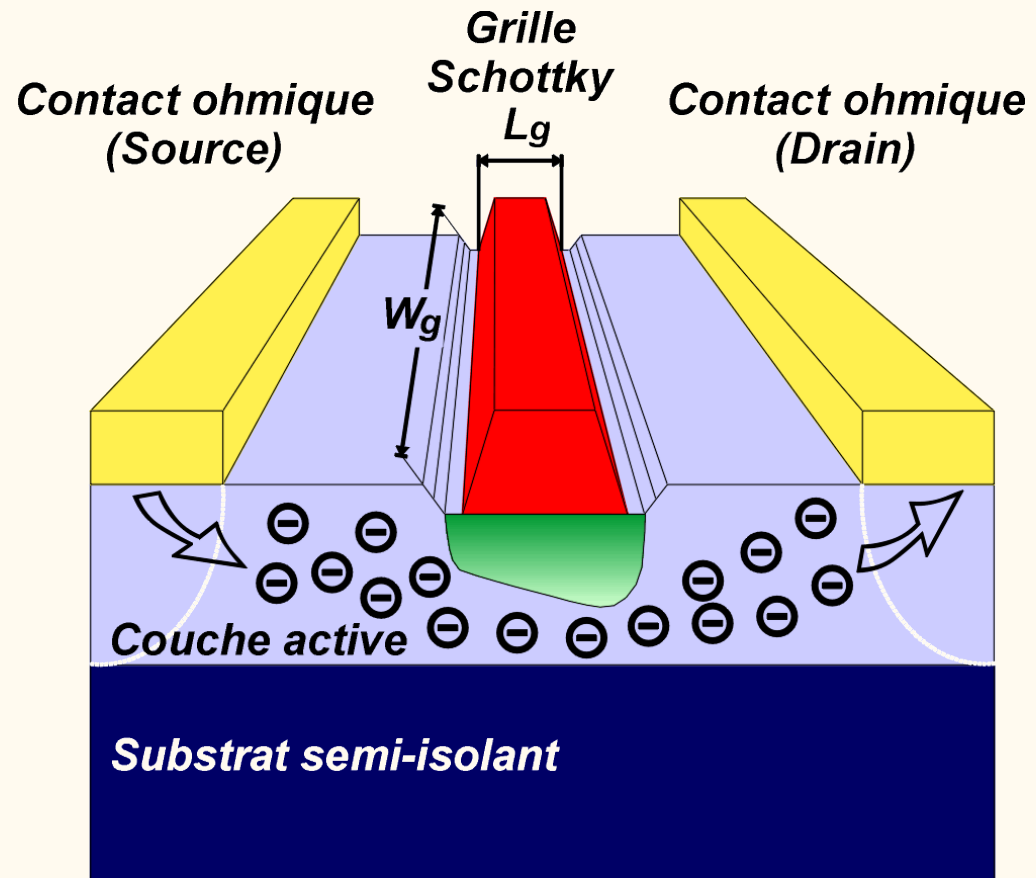
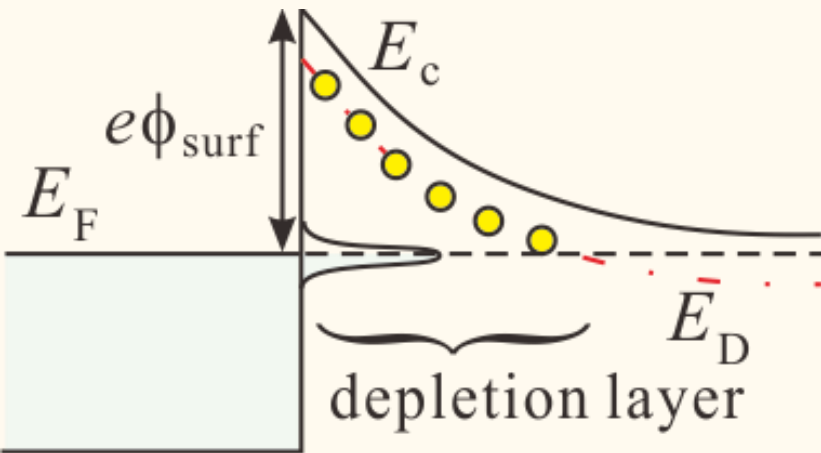


*p*-channel

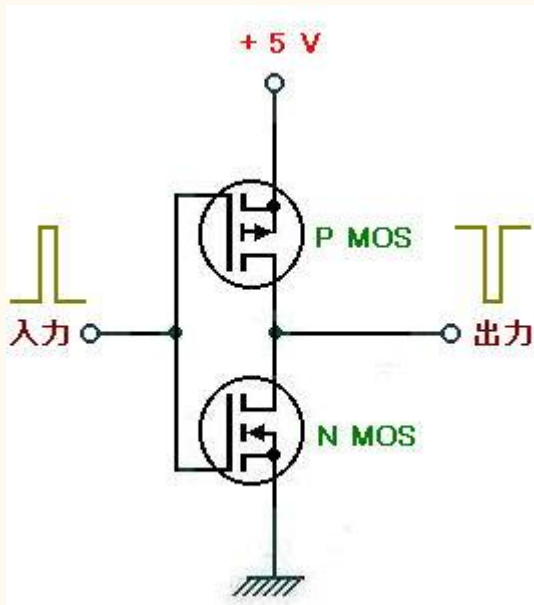
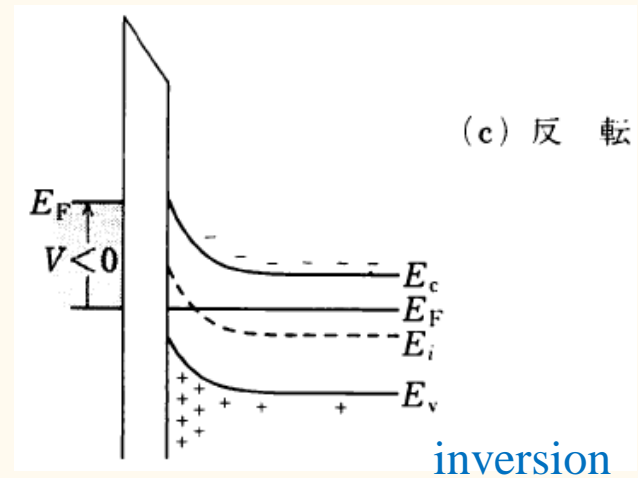
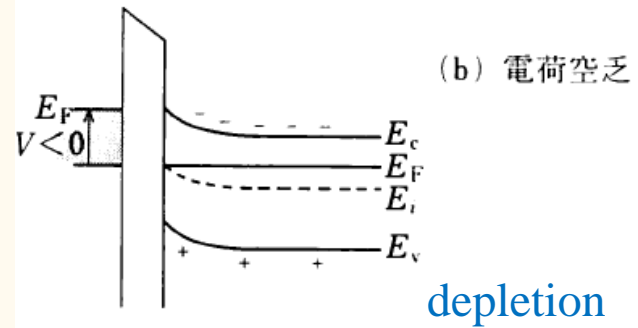
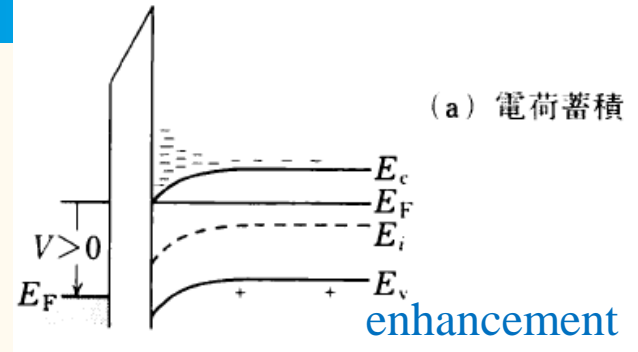
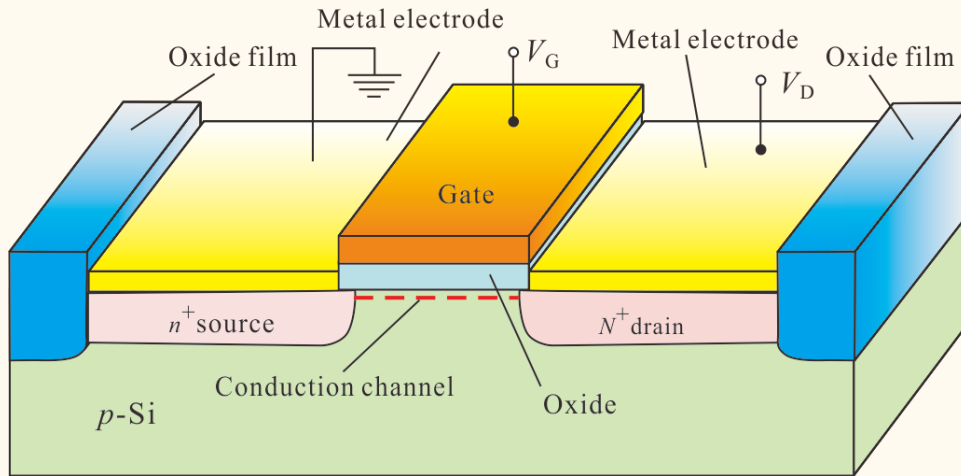


Pinch-off

# MES-FET



# MOS-FET

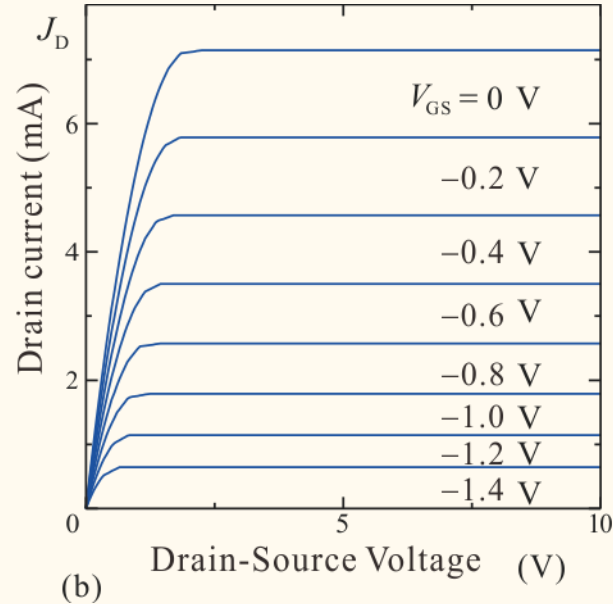
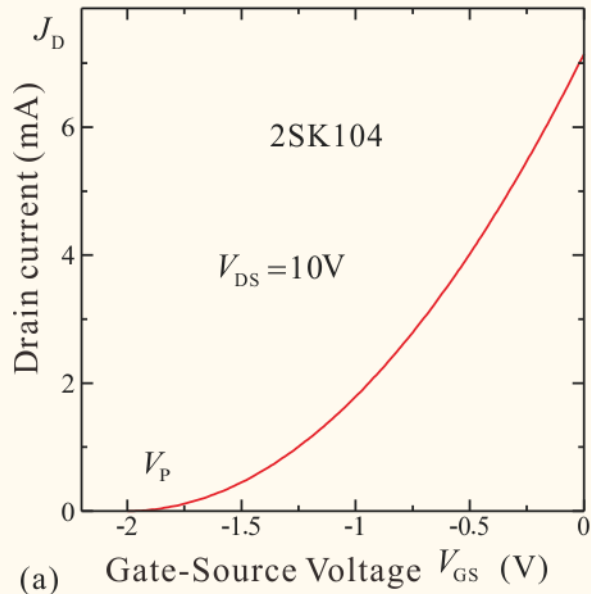


Simplified  
CMOS inverter  
circuit

Low leakage  
current

Single gate input  
both on/off switch

# Static characteristics of FET



$$J_G \simeq 0, \quad g_m \equiv \left( \frac{\partial J_D}{\partial V_{GS}} \right)_{V_D = \text{const.}}, \quad \text{transconductance}$$

$$J_D = f(V_G, V_D)$$

$$r_d \equiv \left( \frac{\partial V_D}{\partial J_D} \right)_{V_{GS} = \text{const.}} \quad \text{Drain resistance}$$

Locally linear approximation 
$$\dot{j}_d = g_m v_{gs} + \frac{v_d}{r_d}$$

# References

## Feedback

- 土谷武士, 江上正 「現代制御工学」 (産業図書, 2000)
- J. J. Distefano, et al. “Schaum’s outline of theory and problems of feedback and control systems” 2<sup>nd</sup> ed. (McGraw-Hill, 1990)

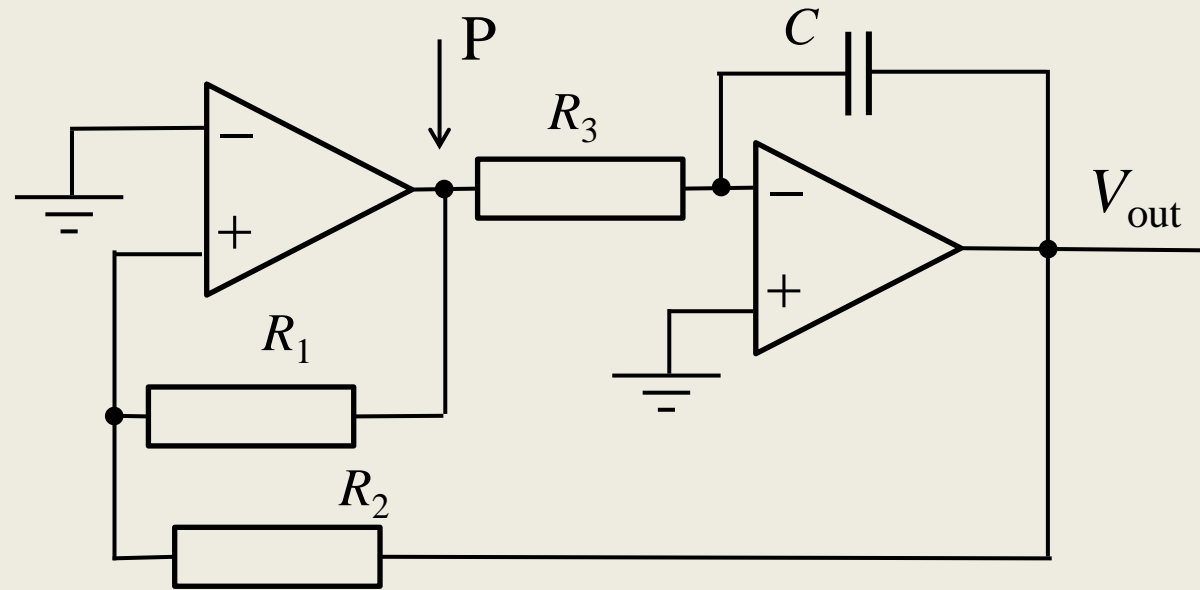
## OP amp. circuit design

- 岡村迪夫 「OPアンプ回路の設計」 CQ出版社
- J. K. Roberge, K. H. Lundberg, “Operational Amplifiers: Theory and Practice” (MIT, 2007).  
<http://web.mit.edu/klund/www/books/opamps181.pdf>

## BJT, FET circuits

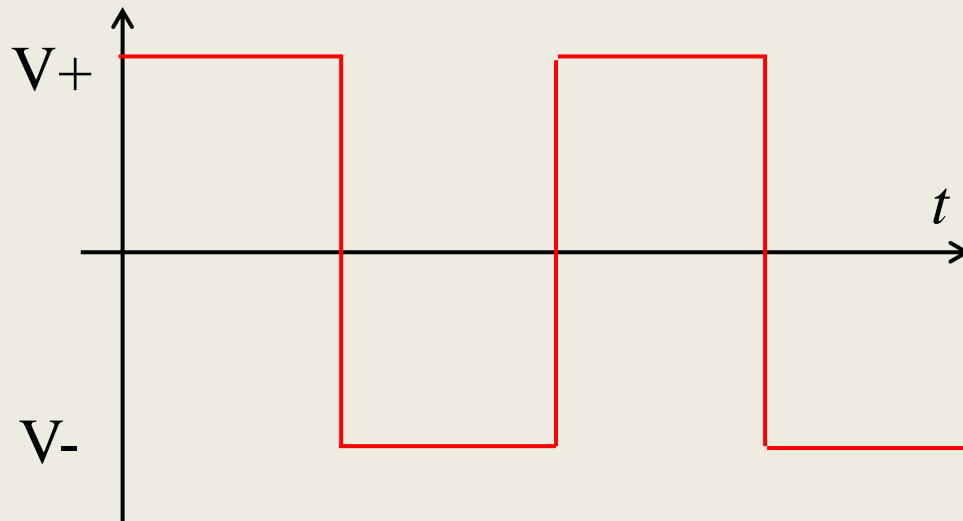
- 松澤昭 「基礎電子回路工学」 (電気学会, 2009).
- S. M. Sze, K. K. Ng, “Physics of Semiconductor Devices” (Wiley, 2007).

# Exercise C-1



In the circuit shown in the left, at point P, a waveform in the lower panel was observed. Here  $V_+$  and  $V_-$  are power source voltages for + and - respectively.

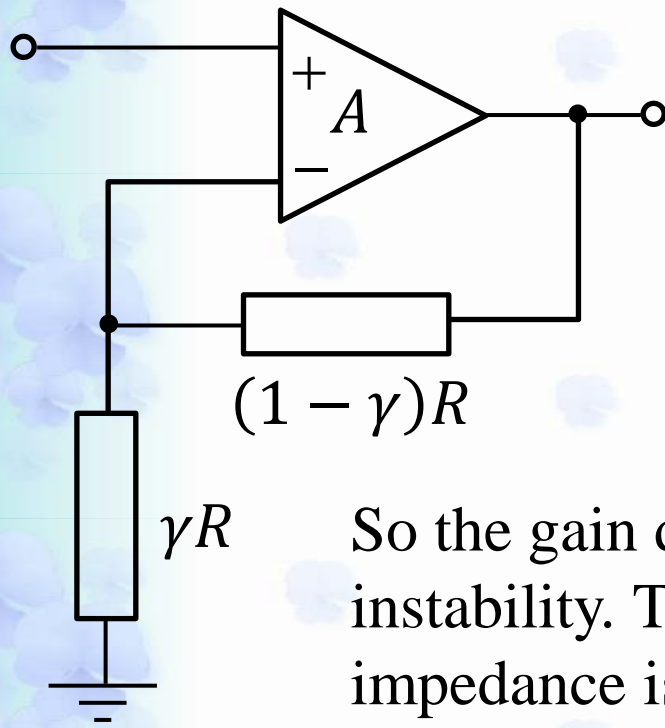
Draw a rough sketch of the waveform for  $V_{out}$ .



“Rough sketch” should contain the levels and the timing of folding points. Write a short comment why  $V_{out}$  should be in such a form.



## Exercise C-2



Consider a differential amplifier with the open loop gain

$$A(s) = \frac{A_0\omega_1\omega_2}{s(s + \omega_1)(s + \omega_2)}.$$

So the gain diverges with  $s \rightarrow 0$  but here we ignore this instability. The input impedance is  $\infty$ , and the output impedance is 0.

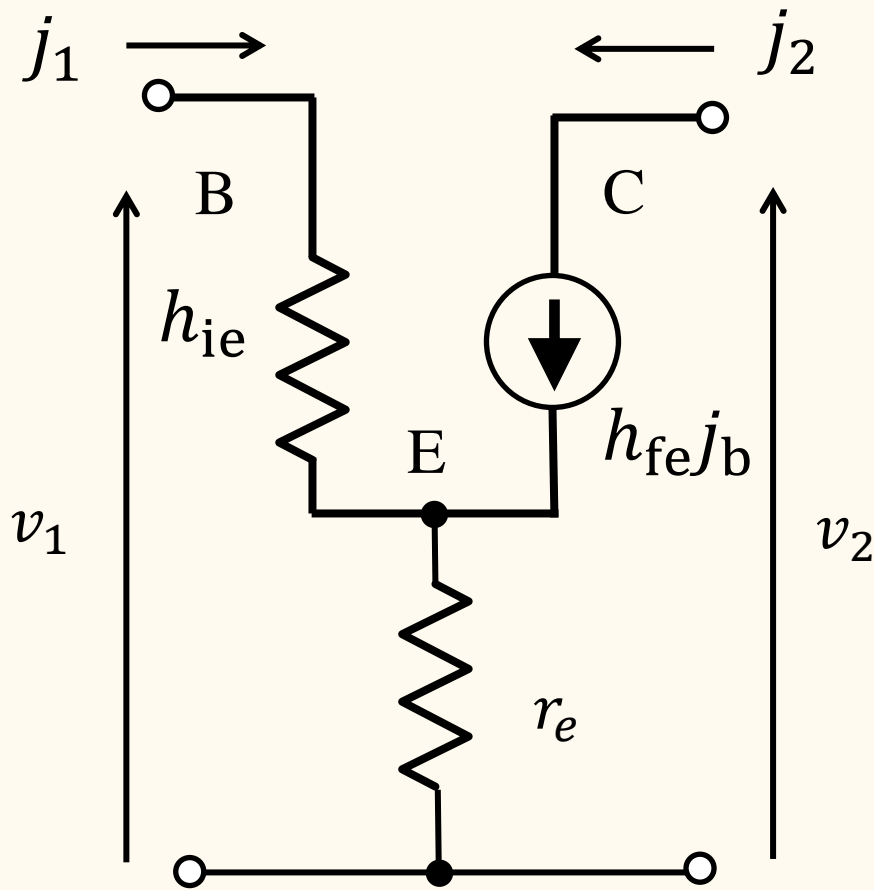
It is now placed in a circuit with a feedback shown in the left.

Obtain the stability condition for  $\gamma$ .

(hint) Apply the Hurwitz criterion for zeros of even and odd parts of the denominator.

Or just calculate  $H_2$ .

# Exercise C-3



Let us view a bipolar transistor plus an emitter resistance as a four terminal circuit as shown in the left figure.

Obtain the Y (admittance) matrix defined below for this circuit.

Calculate each element in the Y matrix for  $r_e = 25\Omega$ ,  $h_{ie} = 500\Omega$ ,  $h_{fe} = 200$

$$\begin{pmatrix} j_1 \\ j_2 \end{pmatrix} = \begin{pmatrix} Y_{11} & Y_{12} \\ Y_{21} & Y_{22} \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

# 電子回路論第7回

## Electric Circuits for Physicists



東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto



# Outline

## 4.5 Field Effect Transistors (FETs)

## **Ch.5 Distributed constant circuits**

### 5.1 Transmission lines

#### 5.1.1 Coaxial cables

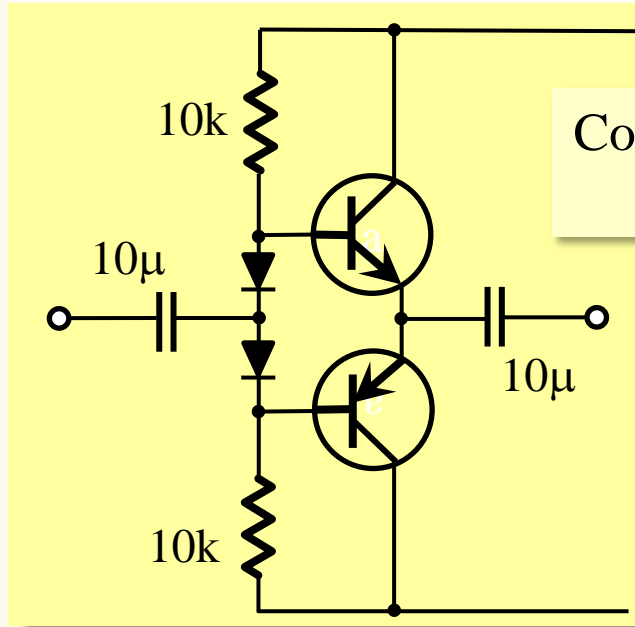
#### 5.1.2 Lecher lines

#### 5.1.3 Micro-strip lines

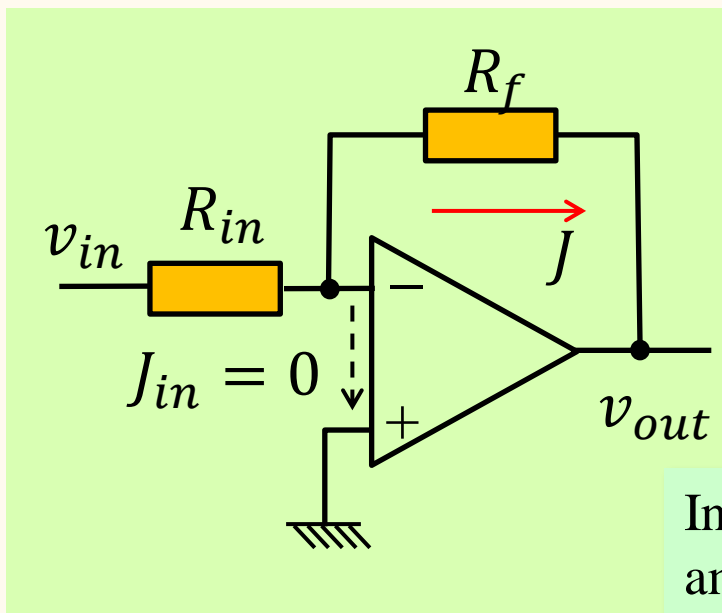
### 5.2 Wave propagation through transmission lines

#### 5.2.2 Connection and termination of transmission lines

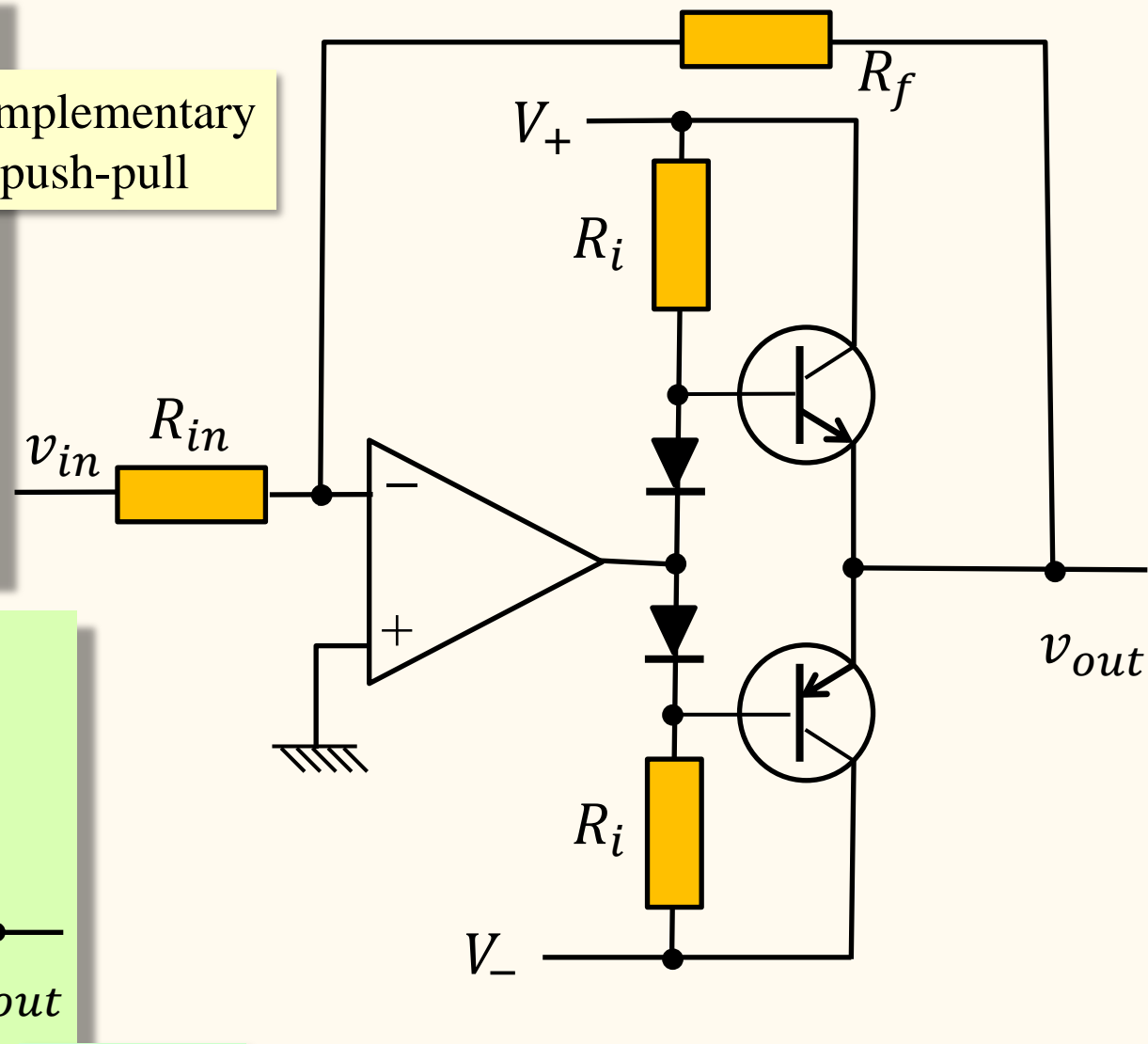
# Combination of an OP-amp and discrete transistors



Complementary push-pull

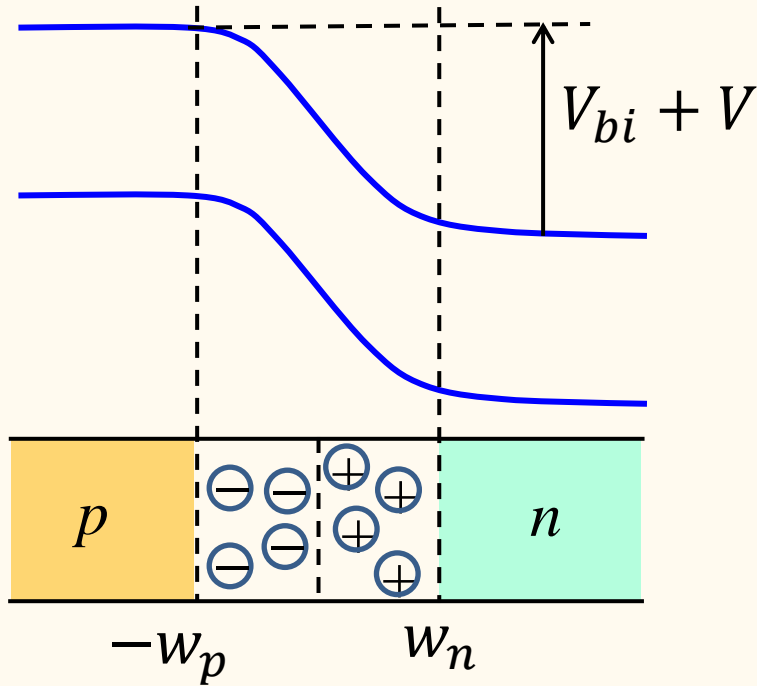


Inversion amplifier



Voltage, current booster

# Depletion layer width with reverse bias voltage



Poisson equation

$$\frac{d^2\phi}{dx^2} = -aq(x) \quad (a \equiv (\epsilon\epsilon_0)^{-1})$$

$$\begin{cases} q = -eN_A & (-w_p \leq x \leq 0), \\ q = eN_D & (0 \leq x \leq w_n) \end{cases}$$

$$\phi(-\infty) = 0$$

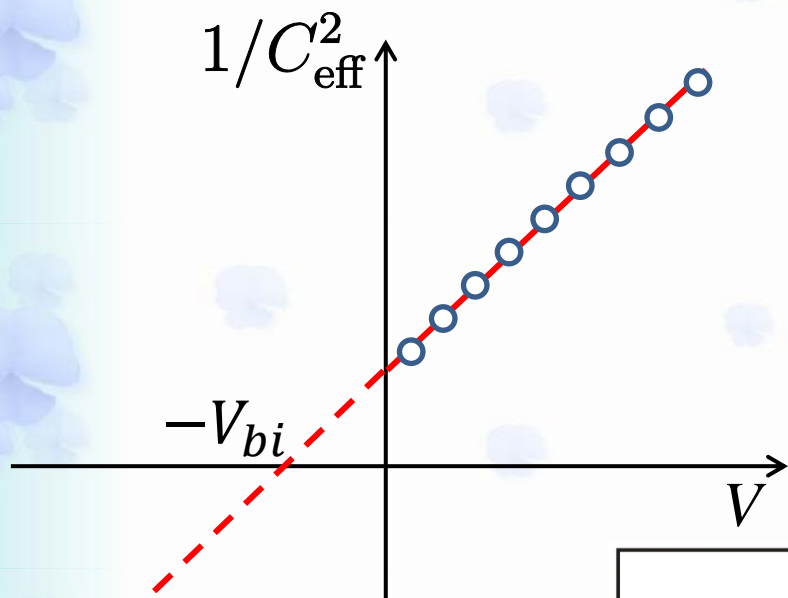
$$\phi(-w_p) = 0, \quad \left. \frac{d\phi}{dx} \right|_{-w_p} = 0,$$

$$\phi(w_n) = V + V_{bi}, \quad \left. \frac{d\phi}{dx} \right|_{w_n} = 0$$

$$\phi(x) = \begin{cases} (aeN_A/2)(x + w_p)^2 & (-w_p \leq x \leq 0), \\ V + V_{bi} - (aeN_D/2)(x - w_n)^2 & (0 \leq x \leq w_n) \end{cases}$$



# Effective capacitance and reverse bias voltage



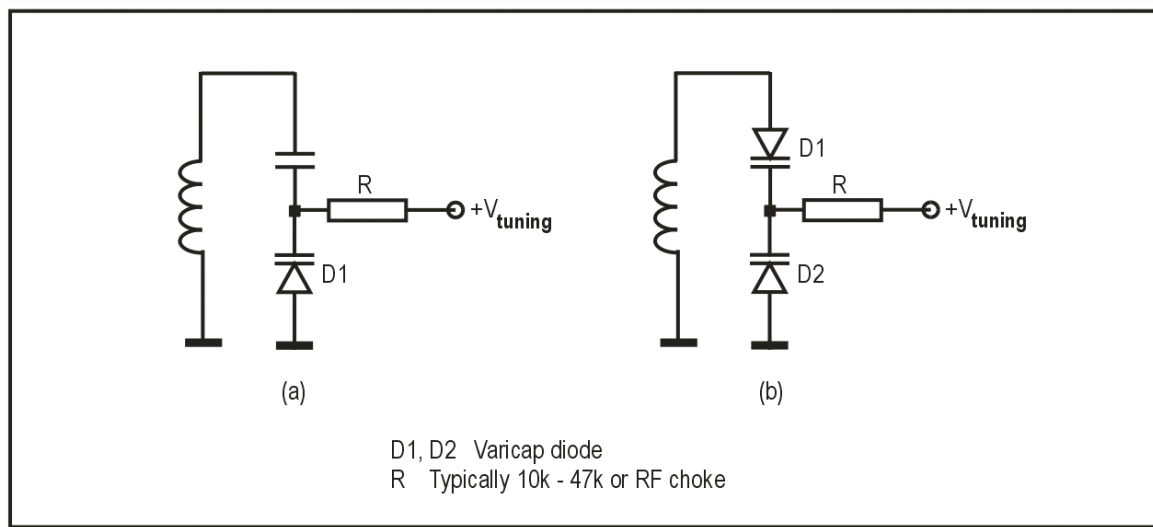
$$\frac{1}{C_{\text{eff}}^2} = \frac{2}{\epsilon\epsilon_0 e N_D} (V + V_{bi})$$

Doping profiler

Varicap diode



KB505

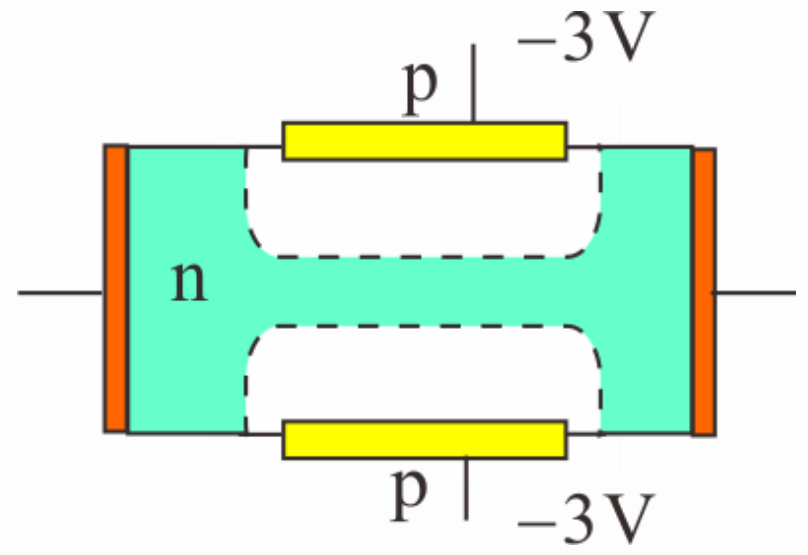
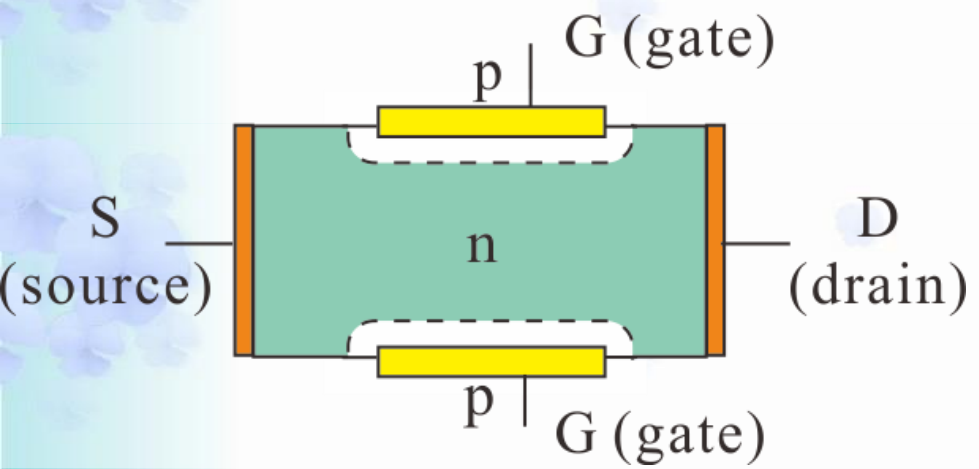


D1, D2 Varicap diode  
R Typically 10k - 47k or RF choke

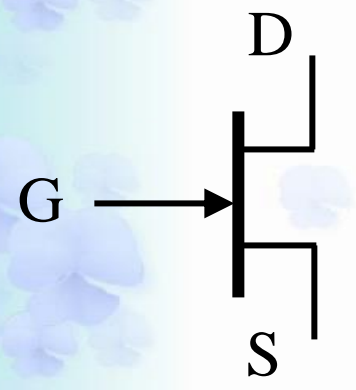
Frequency modulation  
Phase lock loop

# 4.4 Field effect transistor (FET)

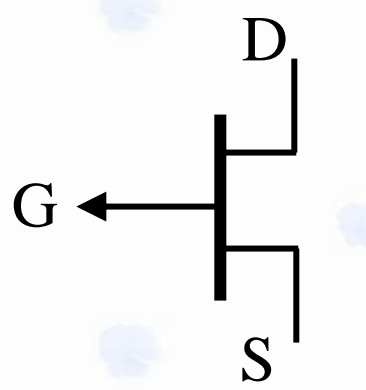
## Junction FET (JFET)



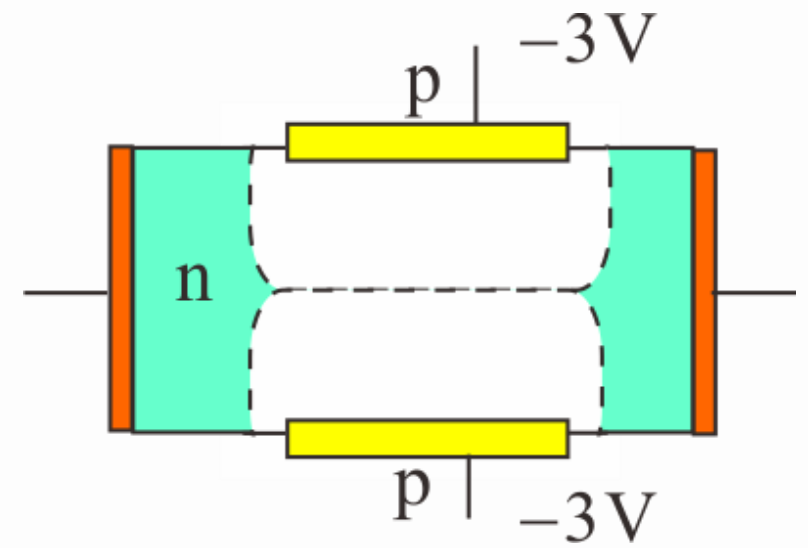
## Circuit symbols



*n*-channel

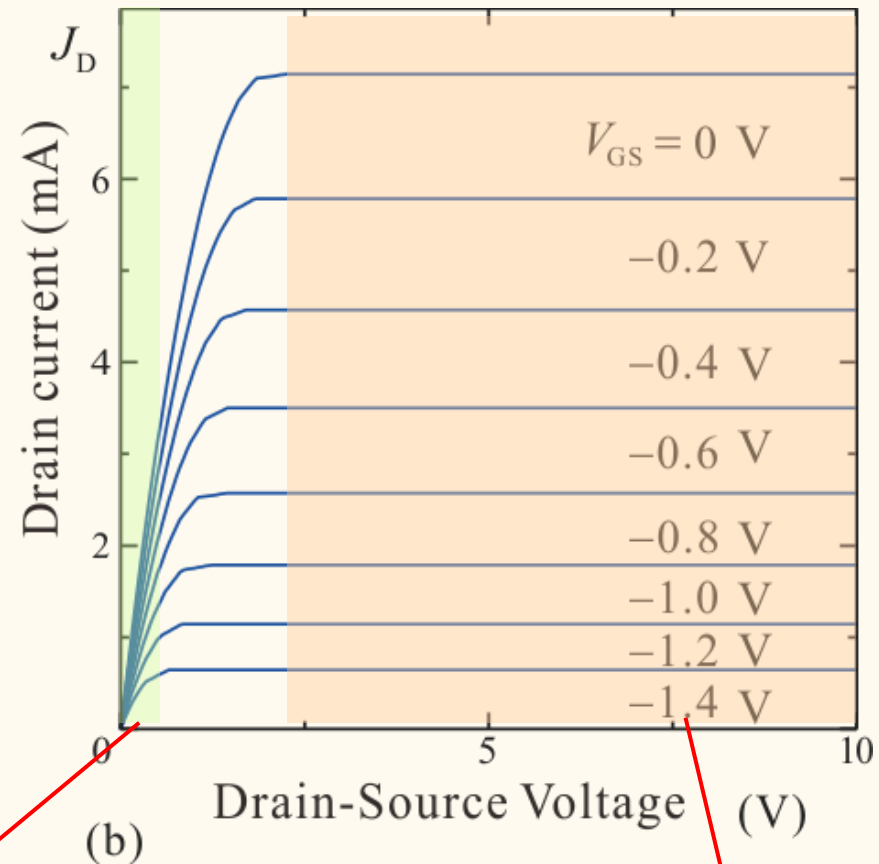
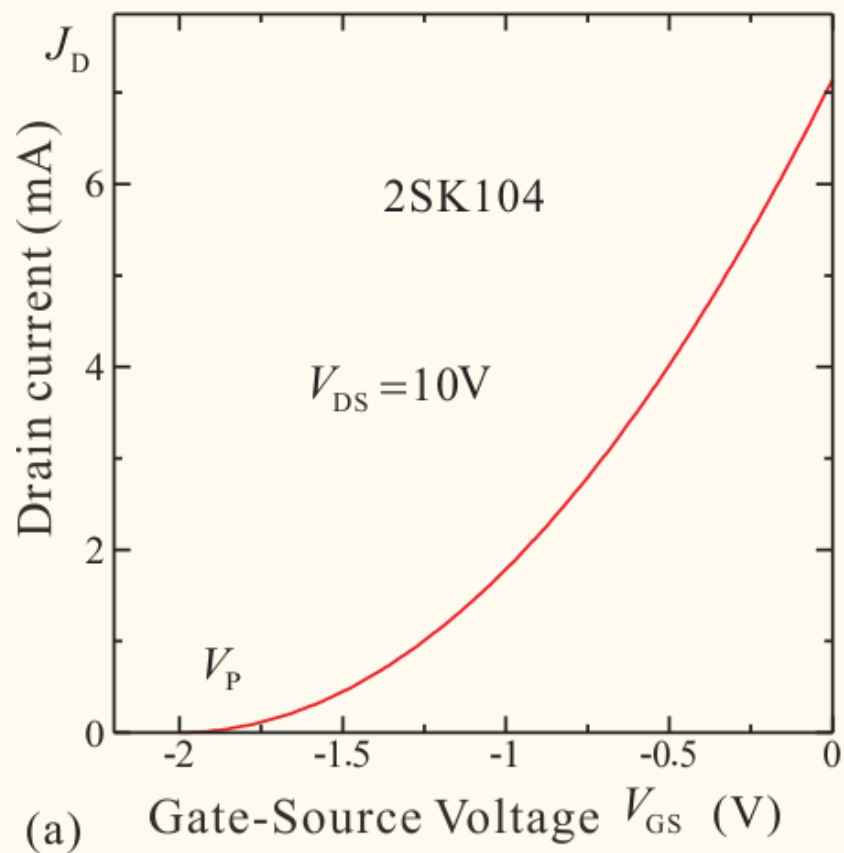


*p*-channel



Pinch-off

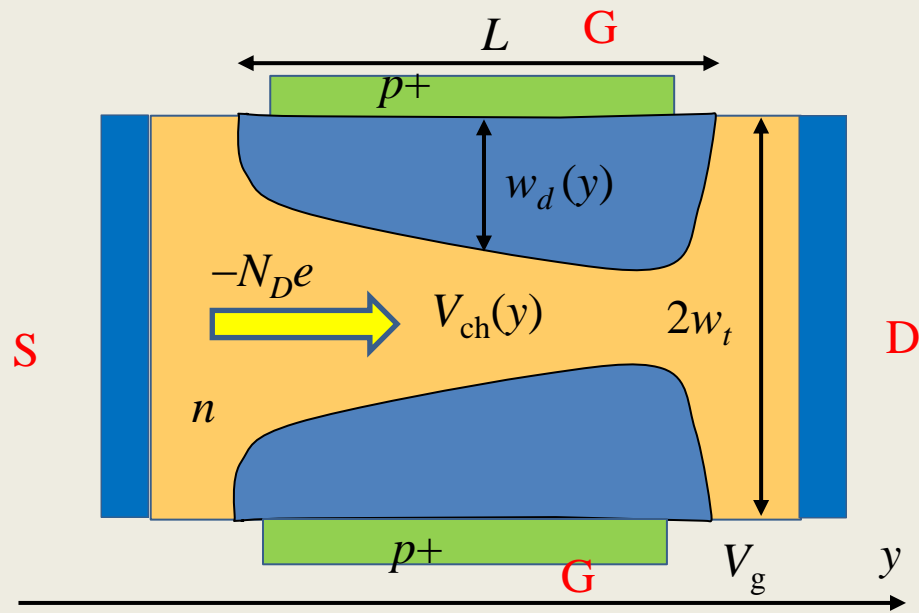
# Static characteristics of FET



Ohmic area

Space charge limited area

# Space-charge limitation of source-drain current



$$V(y) = V_g + V_{vi} - V_{ch}(y)$$

$$w_d(y) = \sqrt{\frac{2\epsilon\epsilon_0 V(y)}{eN_D}}$$

$$J_{ch} = \underbrace{eN_D\mu_n}_{\text{conductivity}} \underbrace{\frac{dV_{ch}}{dy}}_{\text{electric field}} \cdot \underbrace{2[w_t - w_d(y)]W}_{\text{channel width}}$$

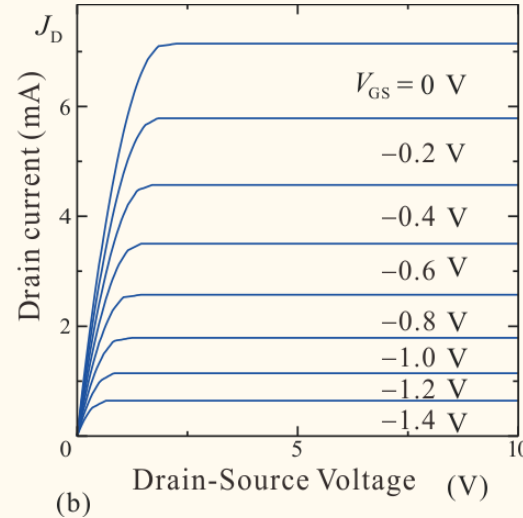
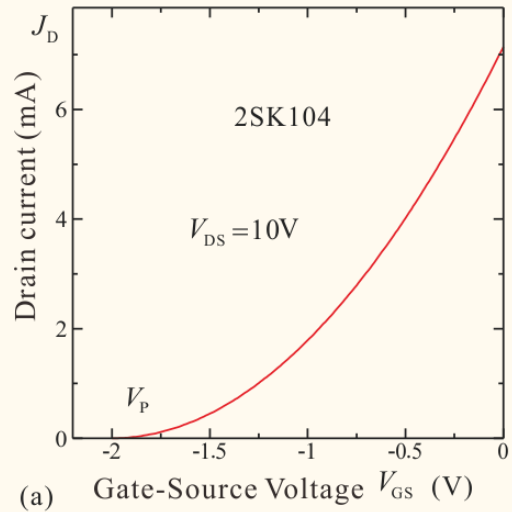
$$J_{ch}L = \int_0^L J_{ch} dy = 2eN_D\mu_n W \int_0^L (w_t - w_d) \frac{dV}{dy} dy = 2w_t eN_D\mu_n W \int_{V_0}^{V_L} \left(1 - \frac{w_d}{w_t}\right) dV$$

pinch off (internal) voltage:  $w_d(V_c) = w_t$   $V_c = \frac{eN_D w_t^2}{2\epsilon\epsilon_0}$

$$J_{ch} = \frac{2N_D e \mu_n W w_t}{L} \left[ V_L - V_0 + \frac{2}{3\sqrt{V_c}} (V(V_0)^{3/2} - V(V_L)^{3/2}) \right]$$

Only valid for  $w_d < w_t/2$ .

# Static characteristics of FET



$J_G \simeq 0,$   
 $J_D = f(V_G, V_D)$

$$g_m \equiv \left( \frac{\partial J_D}{\partial V_{GS}} \right)_{V_D = \text{const.}}$$

transconductance

Low bias current:  
small power consumption

$$r_d \equiv \left( \frac{\partial V_D}{\partial J_D} \right)_{V_{GS} = \text{const.}}$$

Drain resistance

Locally linear approximation

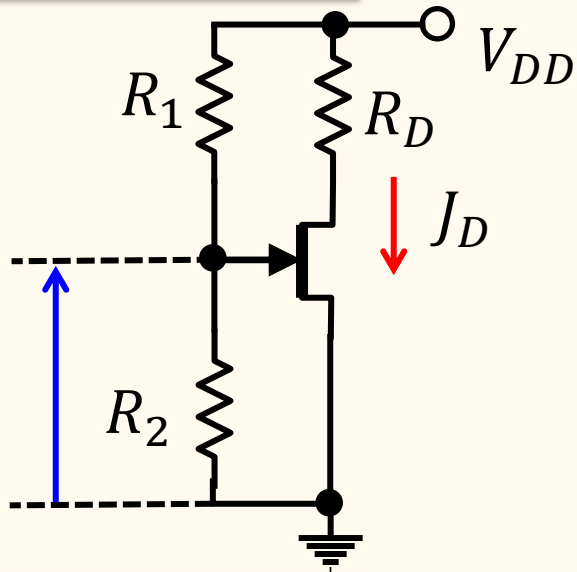
$$\dot{j}_d = g_m v_{gs} + \frac{v_d}{r_d}$$

$$v_d = -\underbrace{r_d g_m}_{\text{Amplification factor}} v_{gs} + r_d \dot{j}_d$$

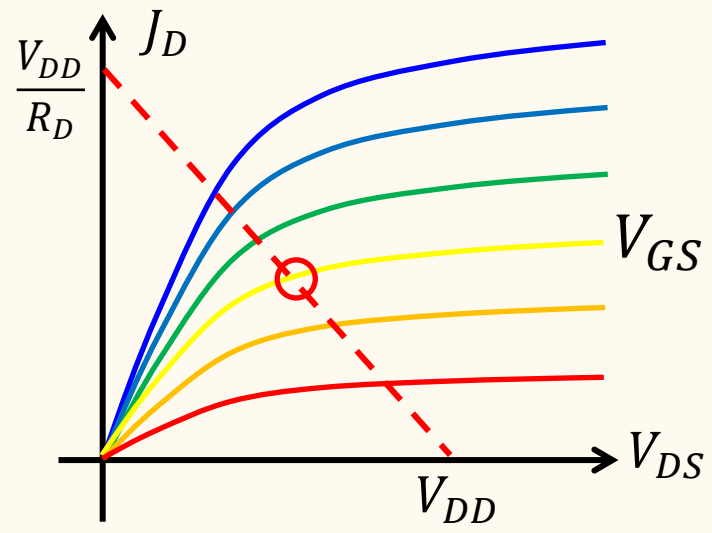
Amplification factor (voltage gain)  $\equiv \mu$

# Biasing circuits for FETs

Fixed bias circuit

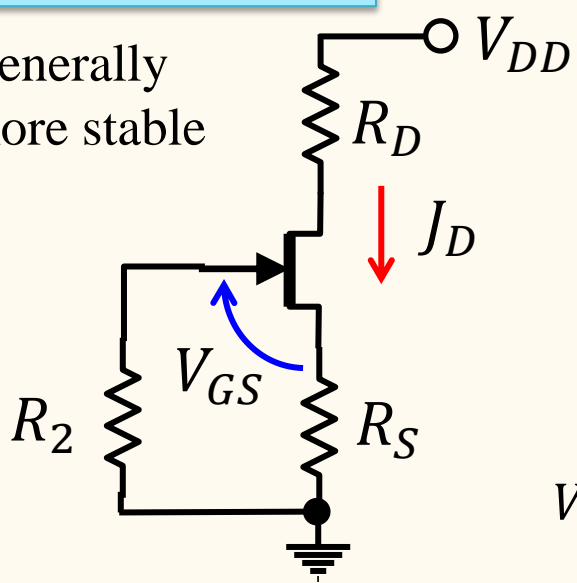


$$V_{GS} = \frac{R_2}{R_1 + R_2} V_{DD}, \quad V_{DS} = V_{DD} - R_D J_D$$

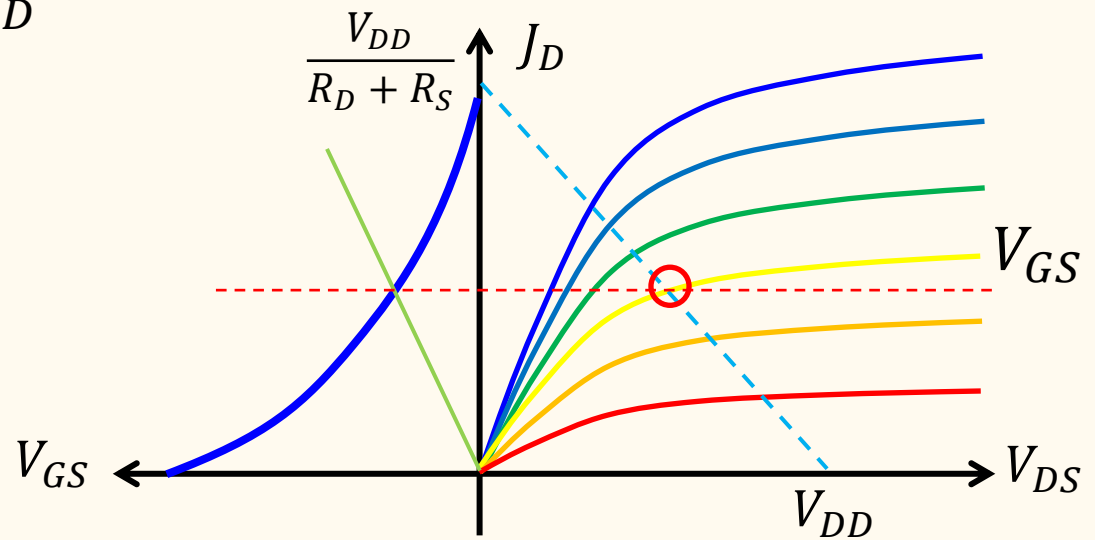


Self-biasing circuit

Generally more stable

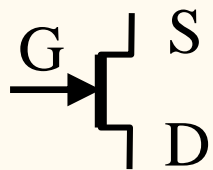


$$V_{GS} = -R_S J_D, \quad V_{DS} = V_{DD} - (R_D + R_S) J_D$$

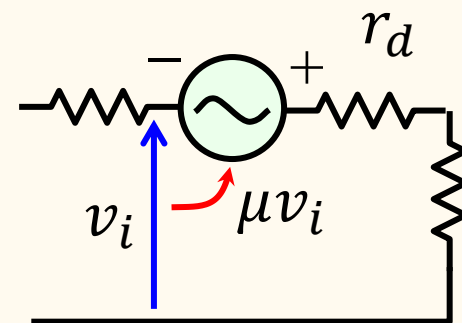
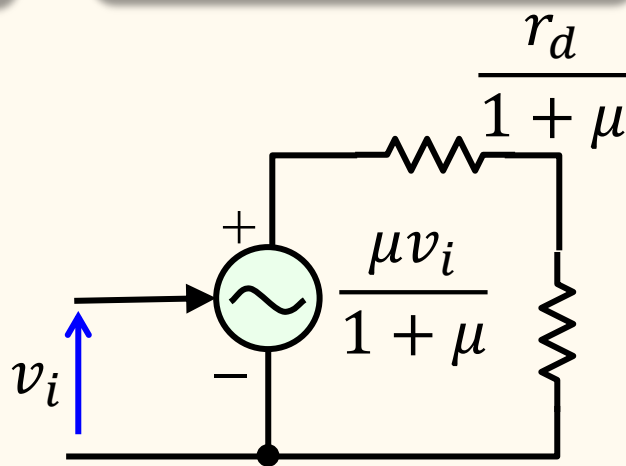
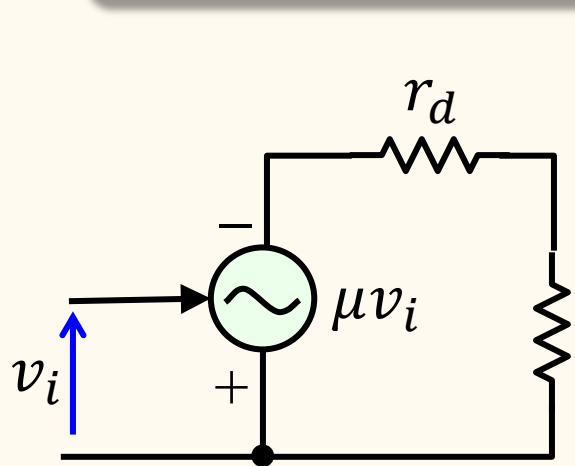
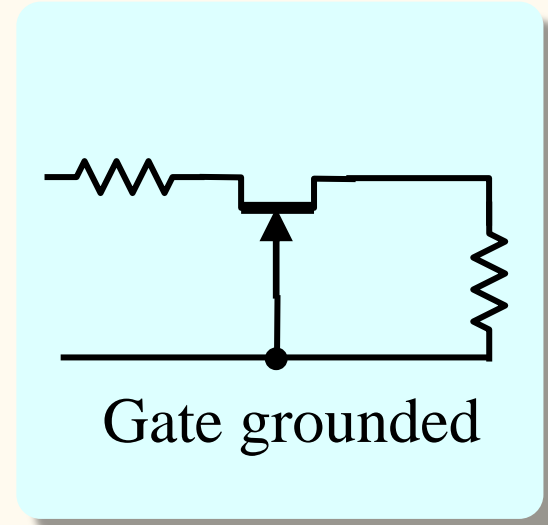
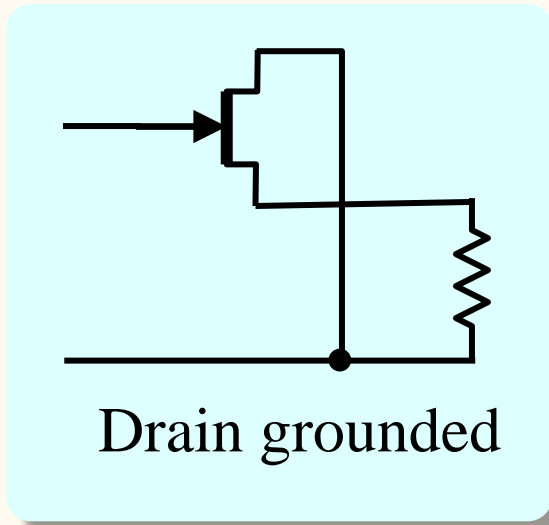
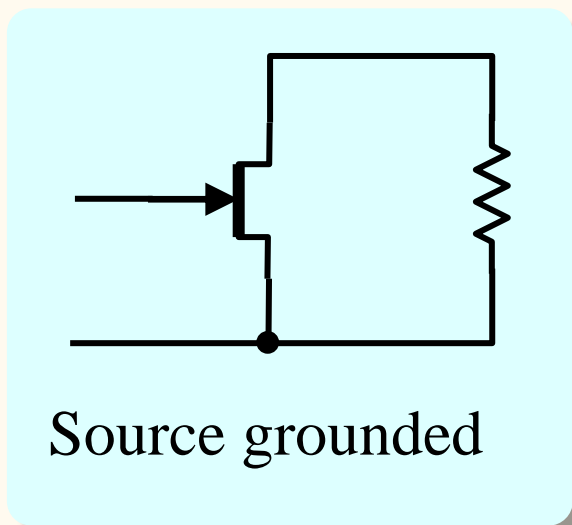




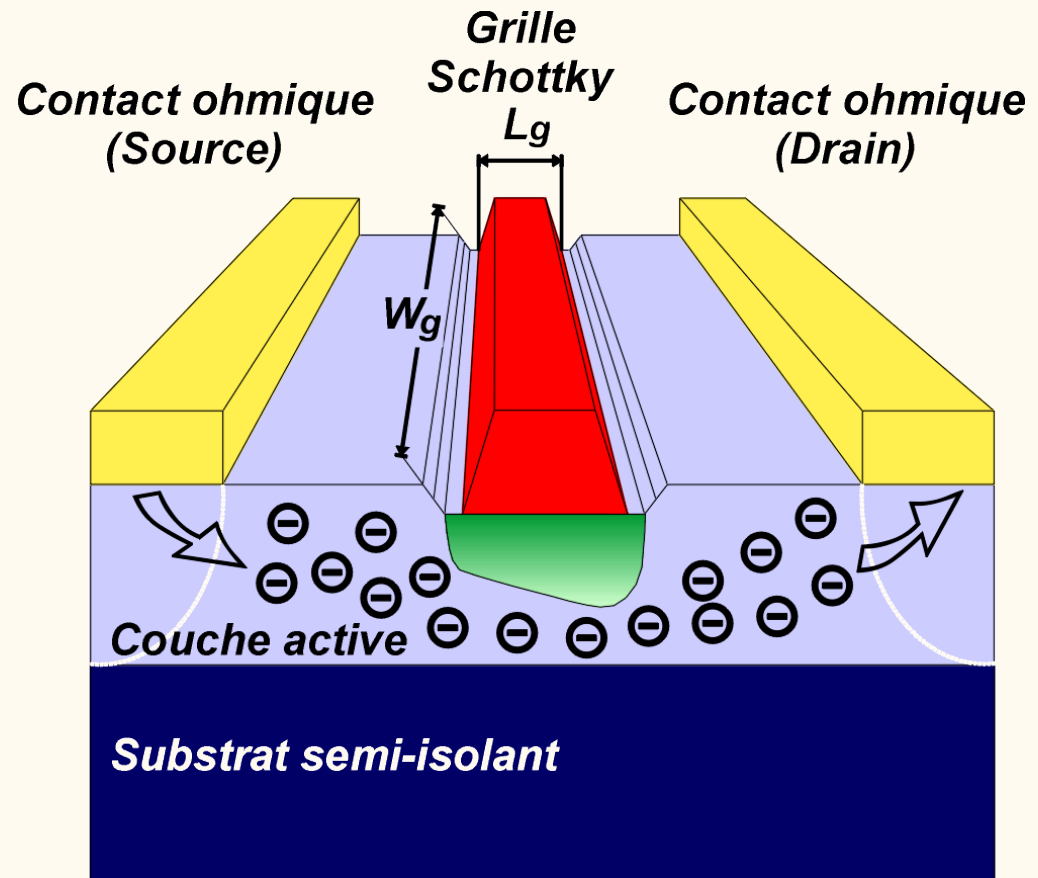
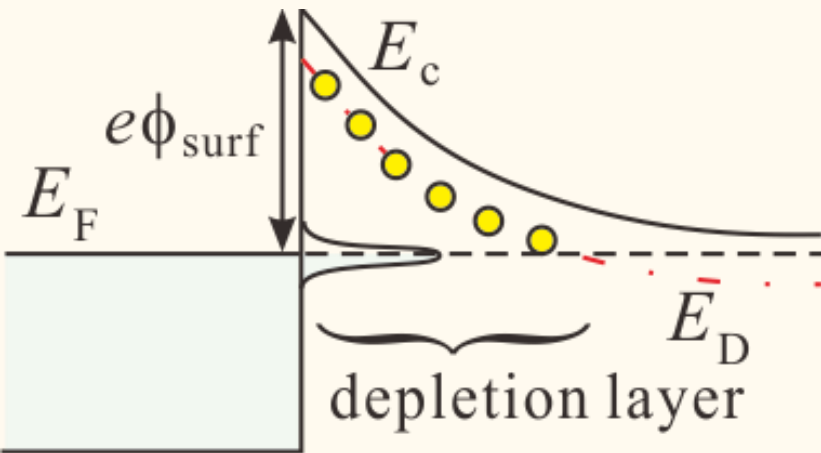
# Equivalent signal circuits for FET



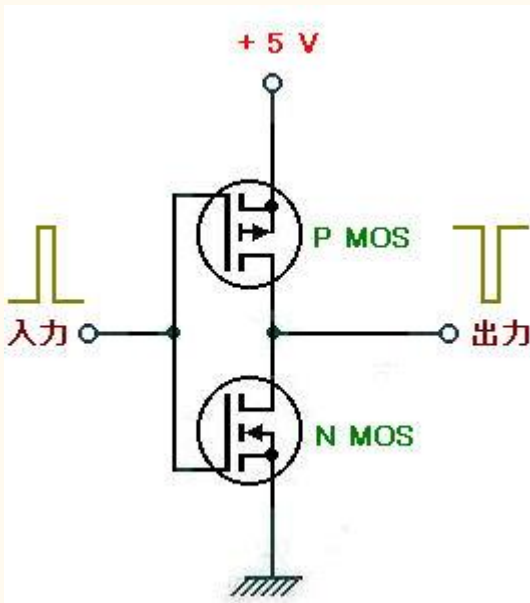
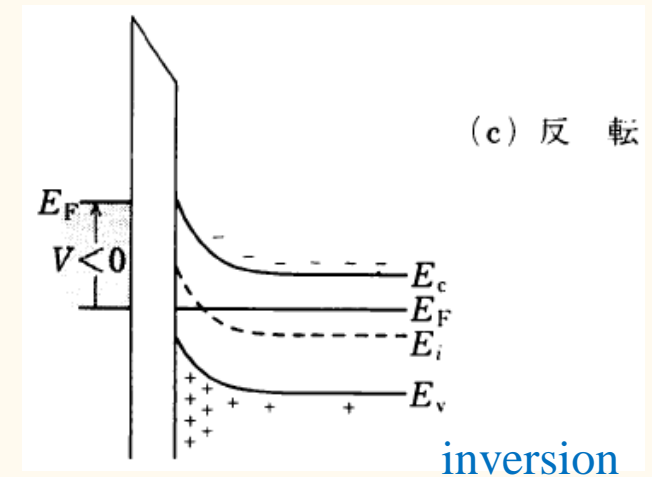
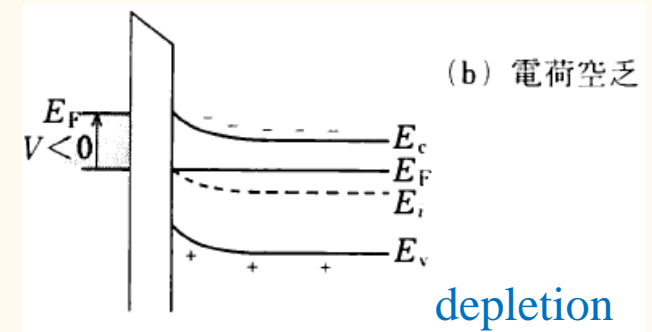
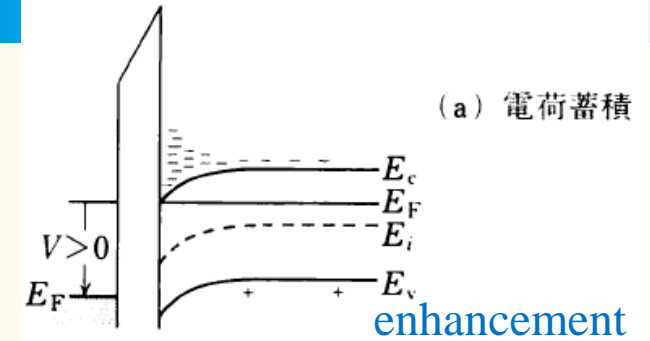
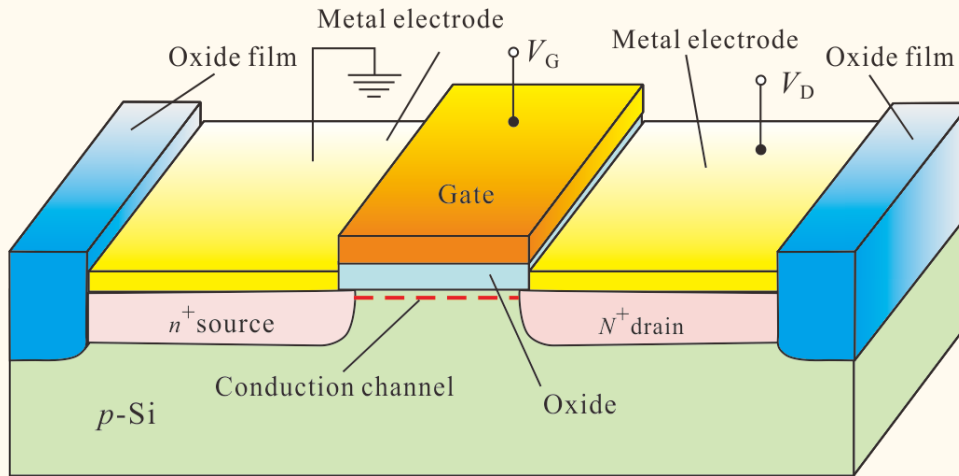
$$\mu = r_d g_m$$



# MES-FET



# MOS-FET



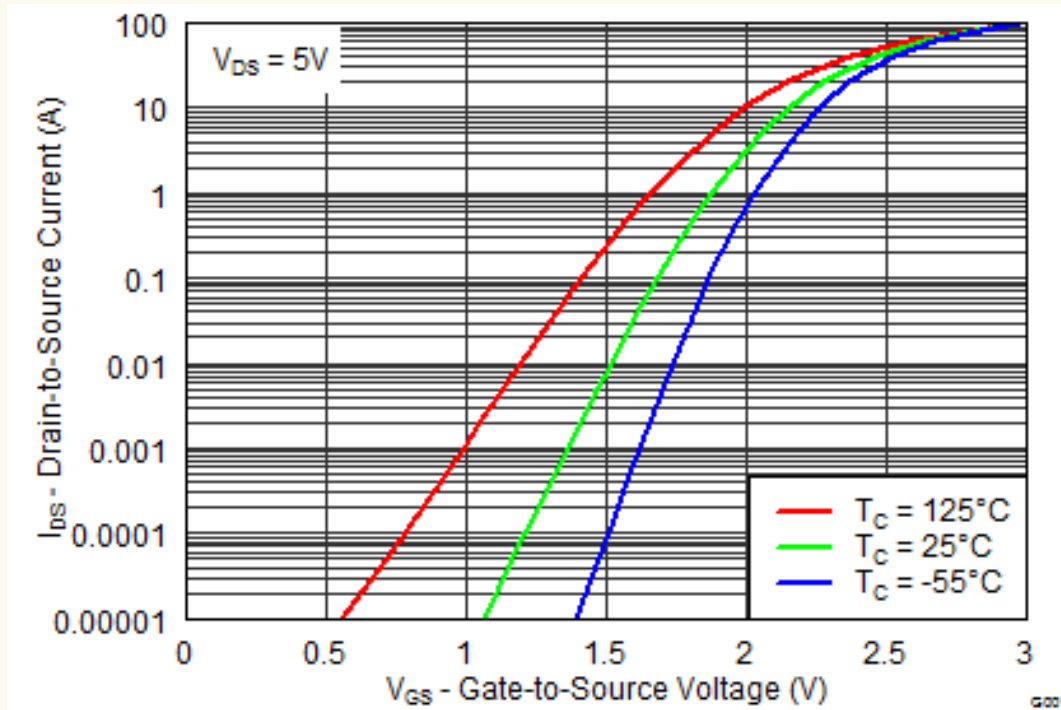
Simplified  
CMOS inverter  
circuit

Low leakage  
current

Single gate input  
both on/off switch

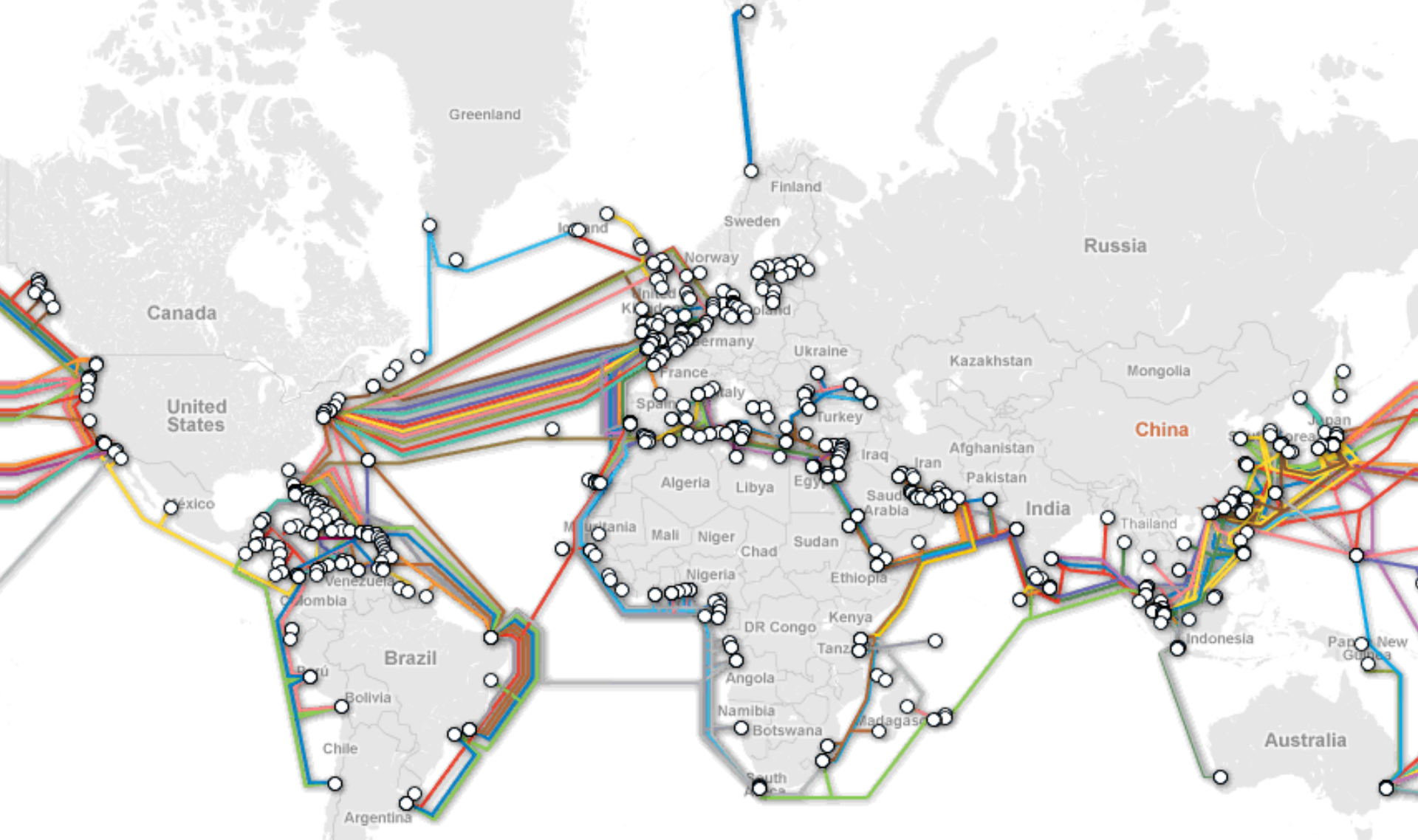
# MOSFET switching characteristics

From datasheet CSD87381P power MOSFET (Texas instr.).



More than 7 orders change in  $I_D$  within 3 V change of  $V_{GS}$ .

# Ch.5 Distributed constant circuits



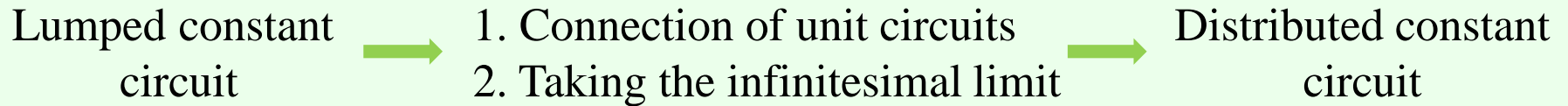
Submarine cable map

# Distributed constant circuit concept

1. In what case we need to consider distributed constant circuits?

Characteristic sizes of devices  $\gtrsim$  wavelength of electromagnetic signal

2. A typical scheme to make the shift for distributed circuit

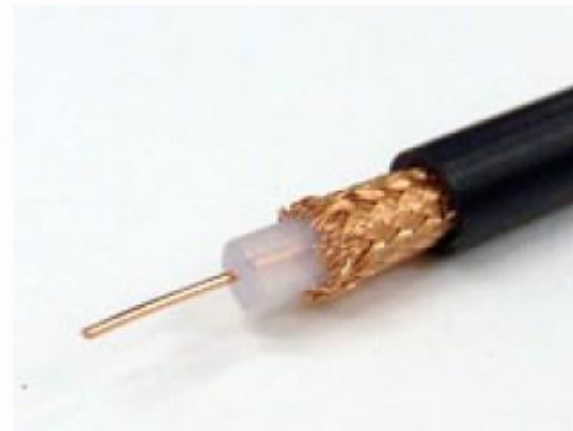
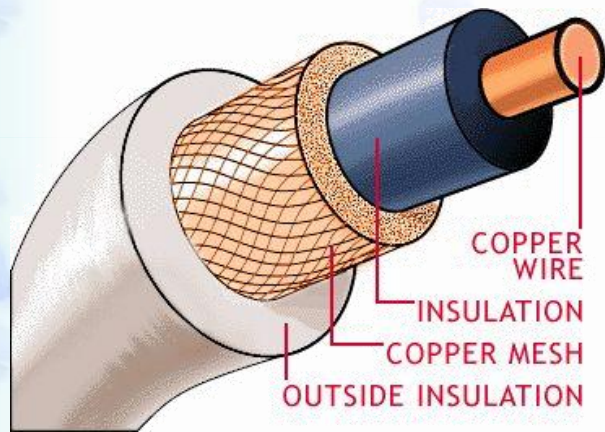


3. Distributed constant circuits : transmission lines

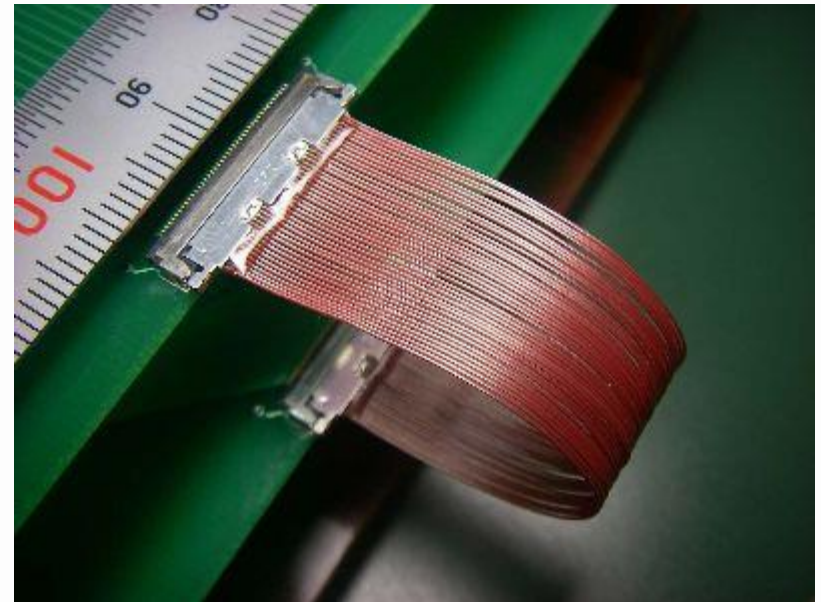
Coaxial cables, Lecher lines, micro-strip lines, waveguides, optical fibers



# 5.1.1 Coaxial cable

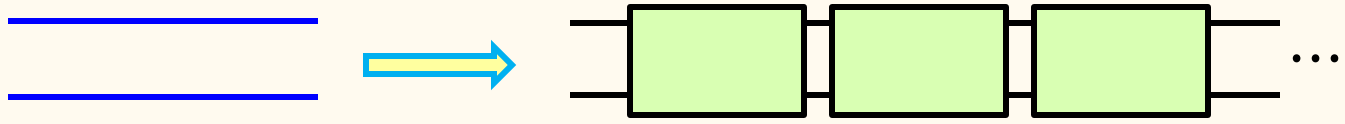


Thin coaxial cable AWG50 ( $\phi 25\mu\text{m}$ )

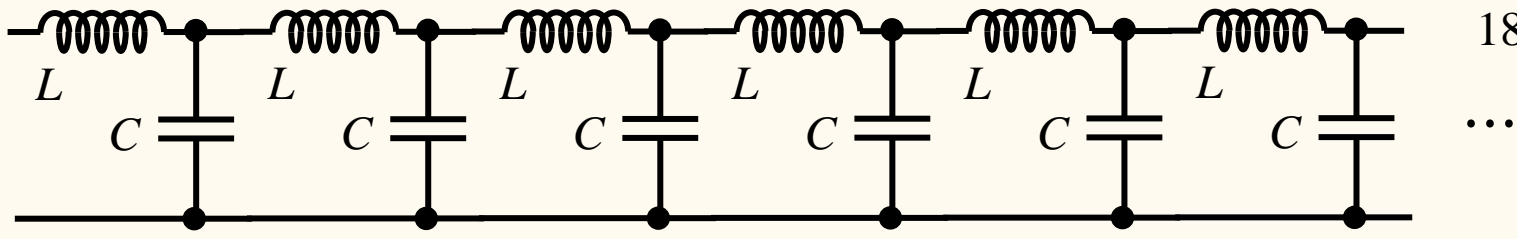


# Transmission line as a series of infinitesimal terminal-pairs

Transmission line → divide into four terminal circuits

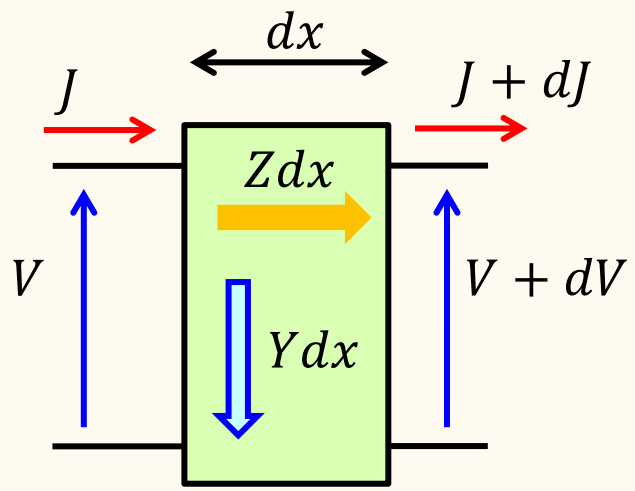


Each unit should have delay. Ignore energy dissipation.



Oliver Heaviside  
1850- 1925

Then take the infinitesimal limit



Width → 0, Number → ∞

$$dV = -JZdx, \quad dJ = -VYdx$$

$$\begin{cases} \frac{d^2 J}{dx^2} = YZJ, \\ \frac{d^2 V}{dx^2} = YZV \end{cases}$$

Telegraphic equation

# Characteristic impedance

$$\kappa \equiv \sqrt{YZ} \quad (\text{dimension: } L^{-1})$$

$$J(x, t) = J(0, t) \exp(\pm \kappa x), \quad V(x, t) = V(0, t) \exp(\pm \kappa x)$$

–: Progressive, +: Retrograde

$$\frac{V}{J} = \mp \frac{Z}{\kappa} = \mp \sqrt{\frac{Z}{Y}}$$

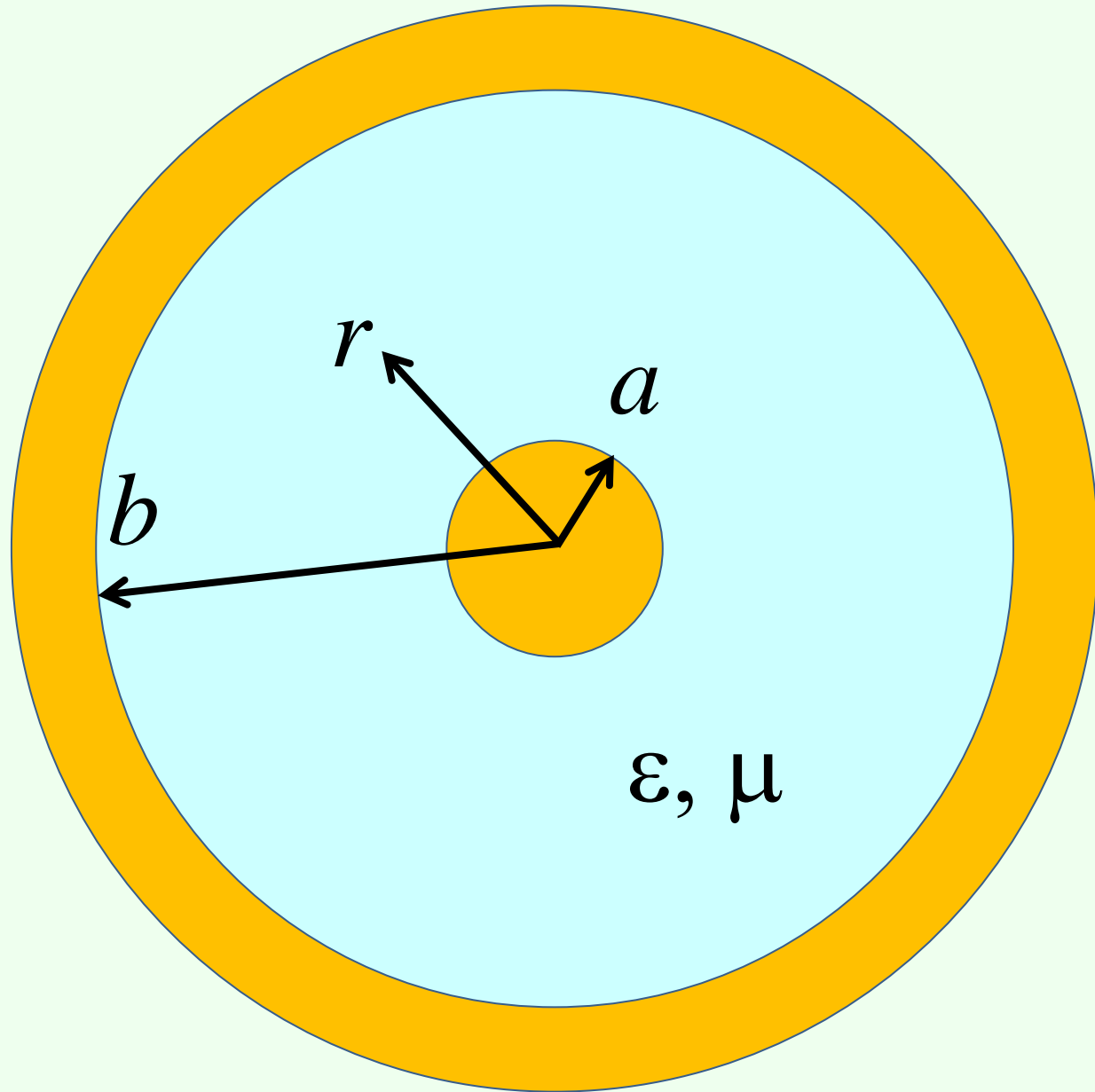
Characteristic impedance

Pure reactance  $Y = i\omega C$ ,  $Z = i\omega L$  For  $L$  and  $C$  model

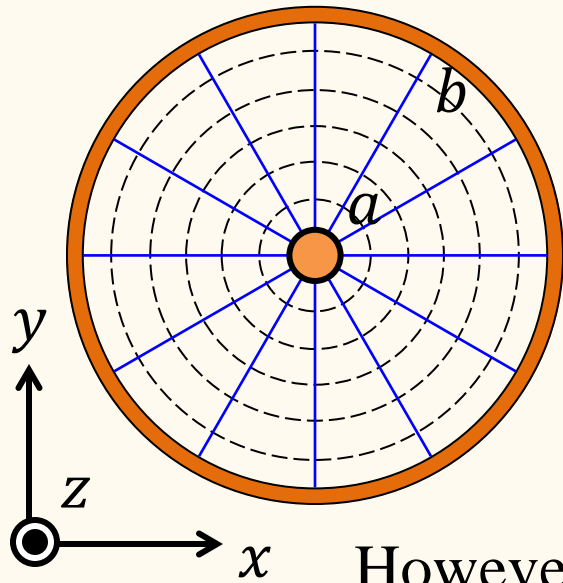
$$\kappa = \sqrt{-\omega^2 LC} = i \frac{\omega}{\omega_0}, \quad \omega_0 \equiv \frac{1}{\sqrt{LC}} \quad (\text{dimension: velocity})$$

$$Z_0 = \sqrt{\frac{L}{C}}$$

# Coaxial cable setup



# Maxwell theory



$$E = E_0(x, y)e^{i\omega t - \gamma z}, \quad H = H_0(x, y)e^{i\omega t - \gamma z}$$

From Maxwell equations

$$(\omega^2 \epsilon \mu + \gamma^2) \begin{pmatrix} E_x \\ E_y \end{pmatrix} = \begin{pmatrix} -\gamma \partial_x & -i\omega \mu \partial_y \\ -\gamma \partial_y & i\omega \mu \partial_x \end{pmatrix} \begin{pmatrix} E_z \\ H_z \end{pmatrix},$$

$$(\omega^2 \epsilon \mu + \gamma^2) \begin{pmatrix} H_x \\ H_y \end{pmatrix} = \begin{pmatrix} i\omega \mu \partial_y & -\gamma \partial_x \\ -i\omega \mu \partial_x & -\gamma \partial_y \end{pmatrix} \begin{pmatrix} E_z \\ H_z \end{pmatrix}.$$

However in TEM (transverse electric and magnetic) mode:

$$E_z = H_z = 0 \quad \text{i.e., the RHSs are zero.}$$

For the fields along  $x$  and  $y$  to survive,  $\omega^2 \epsilon \mu + \gamma^2 = 0 \quad \therefore \gamma = \pm i\omega \sqrt{\epsilon \mu}$

Propagation velocity 
$$v = \frac{\omega}{\omega \sqrt{\epsilon \mu}} = \frac{1}{\sqrt{\epsilon \mu}}$$

In such a case, from Maxwell equations:  $\text{rot}_{xy} \mathbf{H} = 0, \quad \text{rot}_{xy} \mathbf{E} = 0$

→ Potentials are conceivable for  $\mathbf{H}$  and  $\mathbf{E}$ .

# Maxwell theory

$$\mathbf{E} = \nabla_{xy}\mathcal{U}/\sqrt{\epsilon}, \quad \mathbf{H} = \nabla_{xy}\mathcal{V}/\sqrt{\mu}$$

$$\frac{\partial\mathcal{U}}{\partial x} = \frac{\partial\mathcal{V}}{\partial y}, \quad \frac{\partial\mathcal{U}}{\partial y} = -\frac{\partial\mathcal{V}}{\partial x} \quad \text{Cauchy-Riemann theorem}$$

$$\text{Characteristic impedance: } Z_0 = \frac{\mathcal{U}_a - \mathcal{U}_b}{J\sqrt{\epsilon}}$$

If we can express  $V$  and  $J$  in the form of distributed constant circuit model ( $L$  and  $C$  model), the equivalence is certified.

Capacitance part

$$V = \frac{q}{\epsilon} \int_a^b \frac{dr}{2\pi r} = \frac{q}{2\pi\epsilon} \log \frac{b}{a} = \frac{q}{C}$$
$$\therefore C = \frac{2\pi\epsilon}{\log(b/a)}$$



# Maxwell theory

Inductance part

Core current  $J$ , shield current  $-J$

$$H(r) = \frac{J}{2\pi r}, \quad B(r) = \frac{\mu J}{2\pi r}$$

Flux per length:  $\Phi = \int_a^b dr B(r) = \frac{\mu J}{2\pi} \log \frac{b}{a}$

Self inductance per length:  $L = \frac{\mu}{2\pi} \log(b/a)$

$$Z_0 = \sqrt{\frac{L}{C}} = \frac{1}{2\pi} \sqrt{\frac{\mu}{\epsilon}} \log\left(\frac{b}{a}\right)$$

cf. Characteristic impedance of vacuum  $Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} \approx 376\Omega$

# Coaxial cable 2

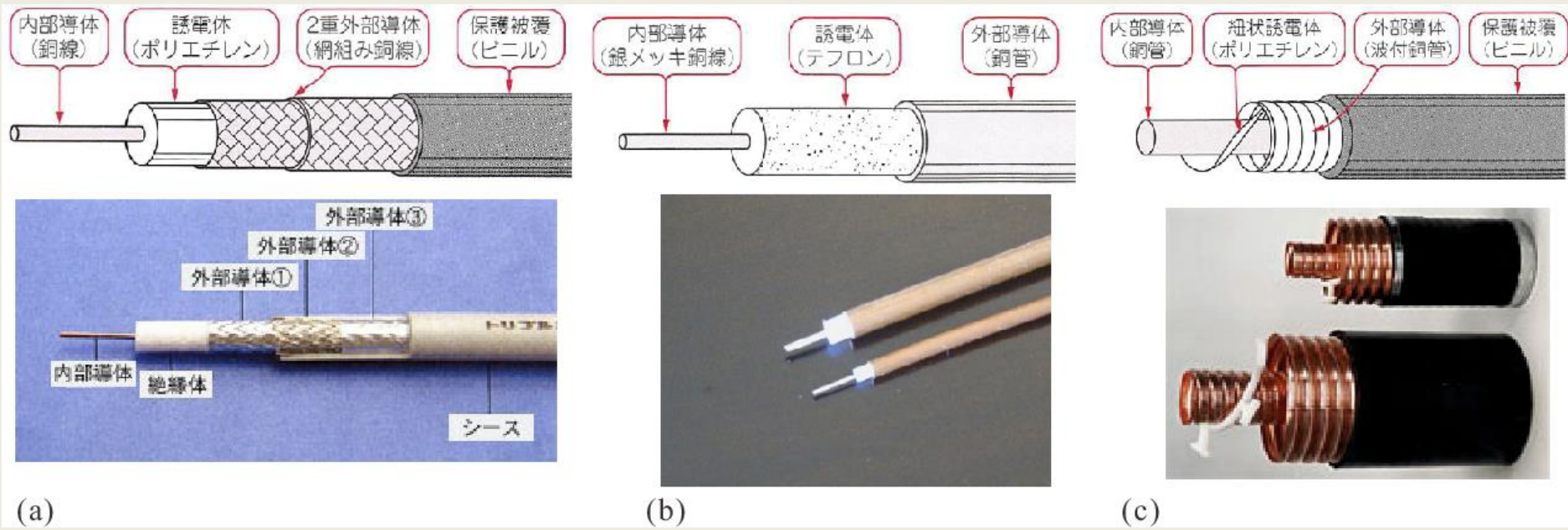


図12 同軸ケーブルの型名 (JIS C3501)

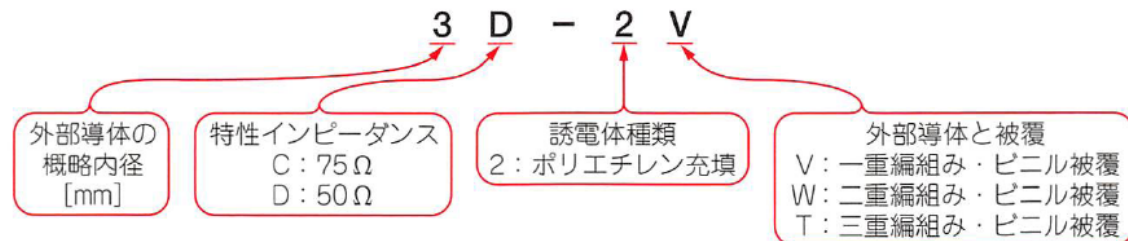
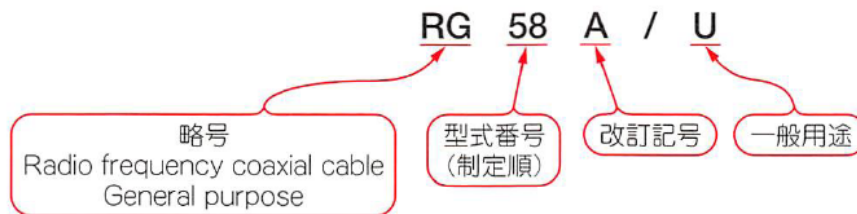
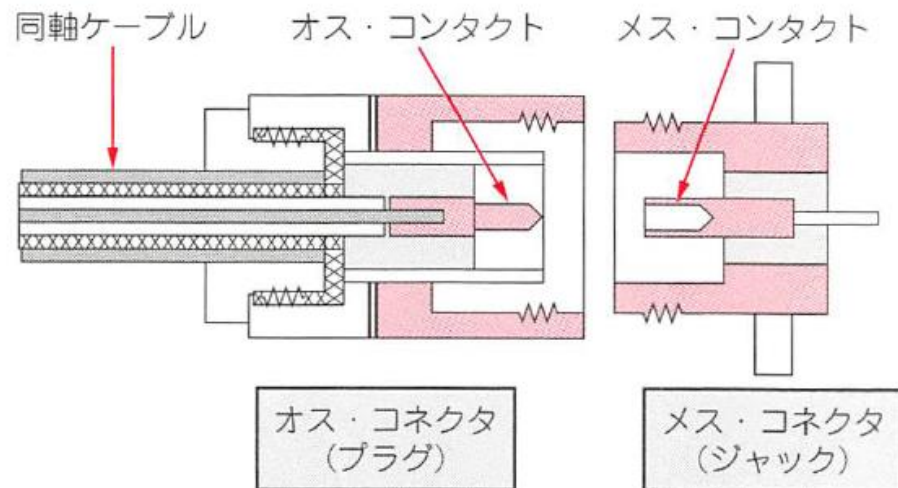


図13 MIL規格での同軸ケーブル型名の例



# Coaxial connectors

図22 同軸コネクタの構造(概念図)



代表的な同軸コネクタの最高使用周波数例

形式	外部導体内径	最高使用周波数
BNC	約 7 mm	2 ~ 4 GHz
N	約 7 mm	10 ~ 18 GHz
7 mm	7 mm	~ 18 GHz
SMA	4.15 mm	18 GHz
3.5 mm	3.5 mm	26.5 GHz
K	2.92 mm	40 GHz
2.4 mm	2.4 mm	50 GHz
V	1.85 mm	65 GHz
W	1.1 mm	110 GHz
1.0 mm	1.0 mm	110 GHz

# Coaxial connectors

写真2 N型コネクタ



(a) フランジ付きジャック

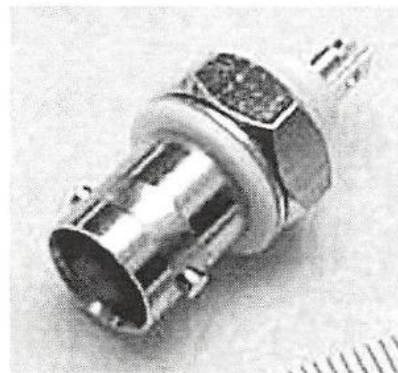


(b) プラグ

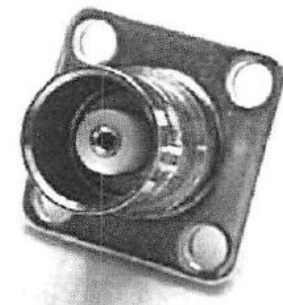


(c) プラグ [(b)を分解]

写真3 BNC型コネクタ



(a) 絶縁型ジャック  
(高周波に向かない)



(b) フランジ付きジャック

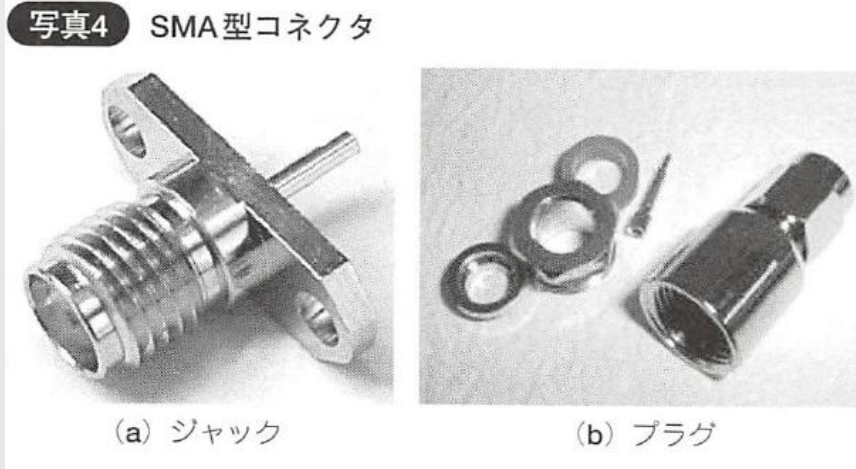


(c) プラグ



# Coaxial connectors 2

## SMA-type

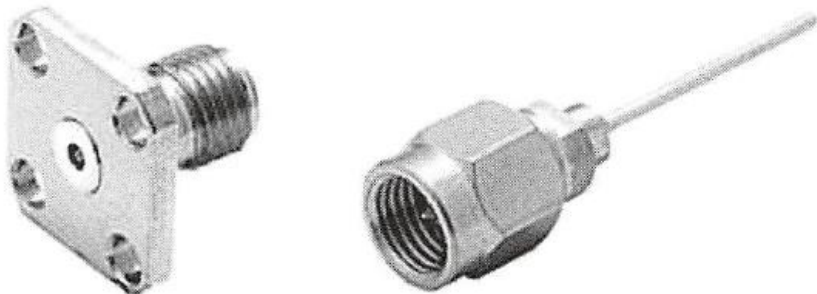


jack

plug

## K-type

写真6 K型コネクタ

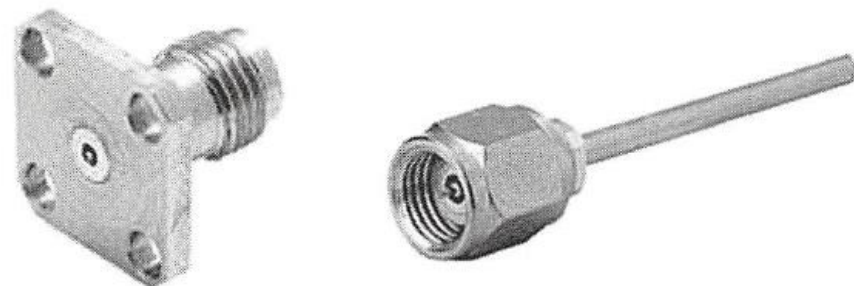


(a) ジャック

(b) プラグ

## V-type

写真7 V型コネクタ



(a) ジャック

(b) プラグ

# LEMO cables and connectors

MFBモデル



MSBモデル



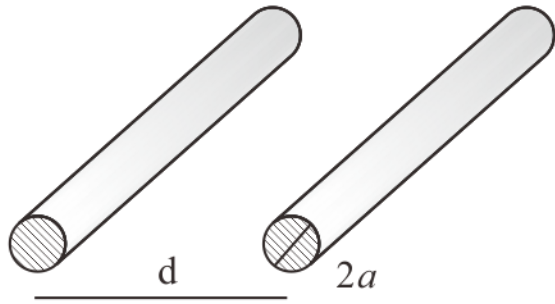
<http://www.lemo.com/>

High-energy physics experiment,  
etc.

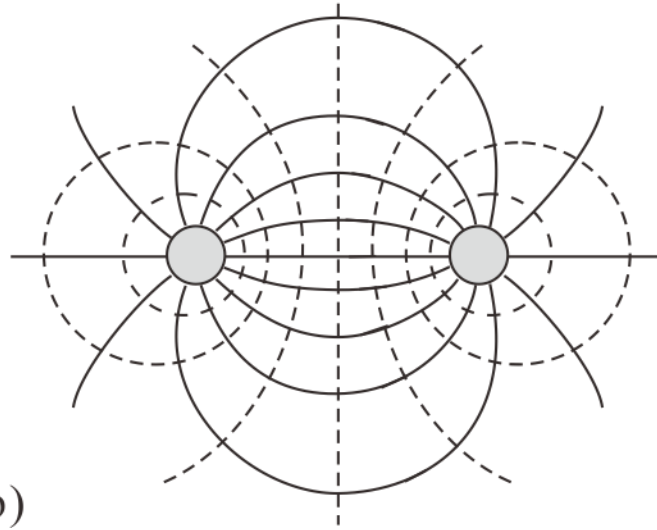




# Lecher line



(a)



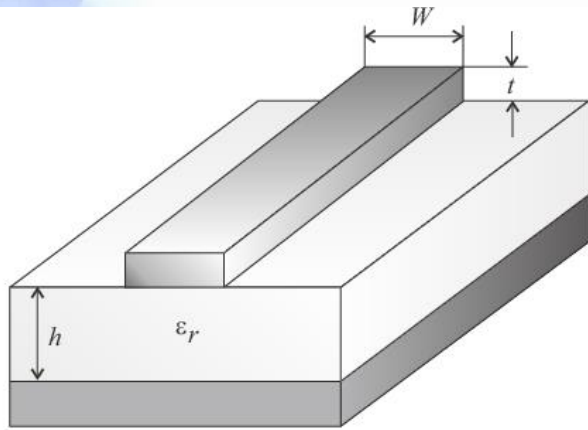
(b)



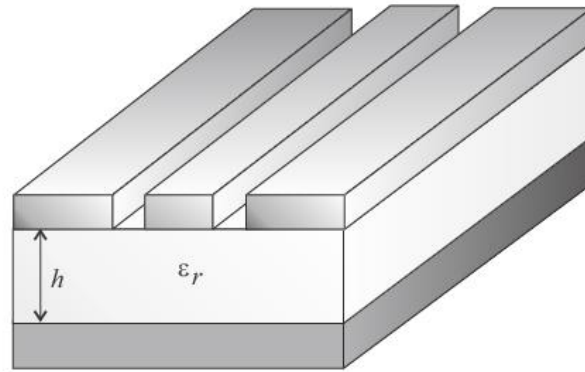
(c)

$$\phi_1 = -\phi_2 = \frac{J\sqrt{\mu}}{2\pi} \log \frac{d}{a} \quad Z_0 = \sqrt{\frac{\mu}{\epsilon}} \frac{1}{\pi} \log \frac{d}{a}$$

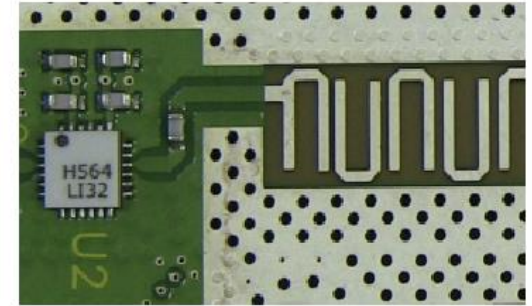
# Micro strip line



(a)



(b)



(c)

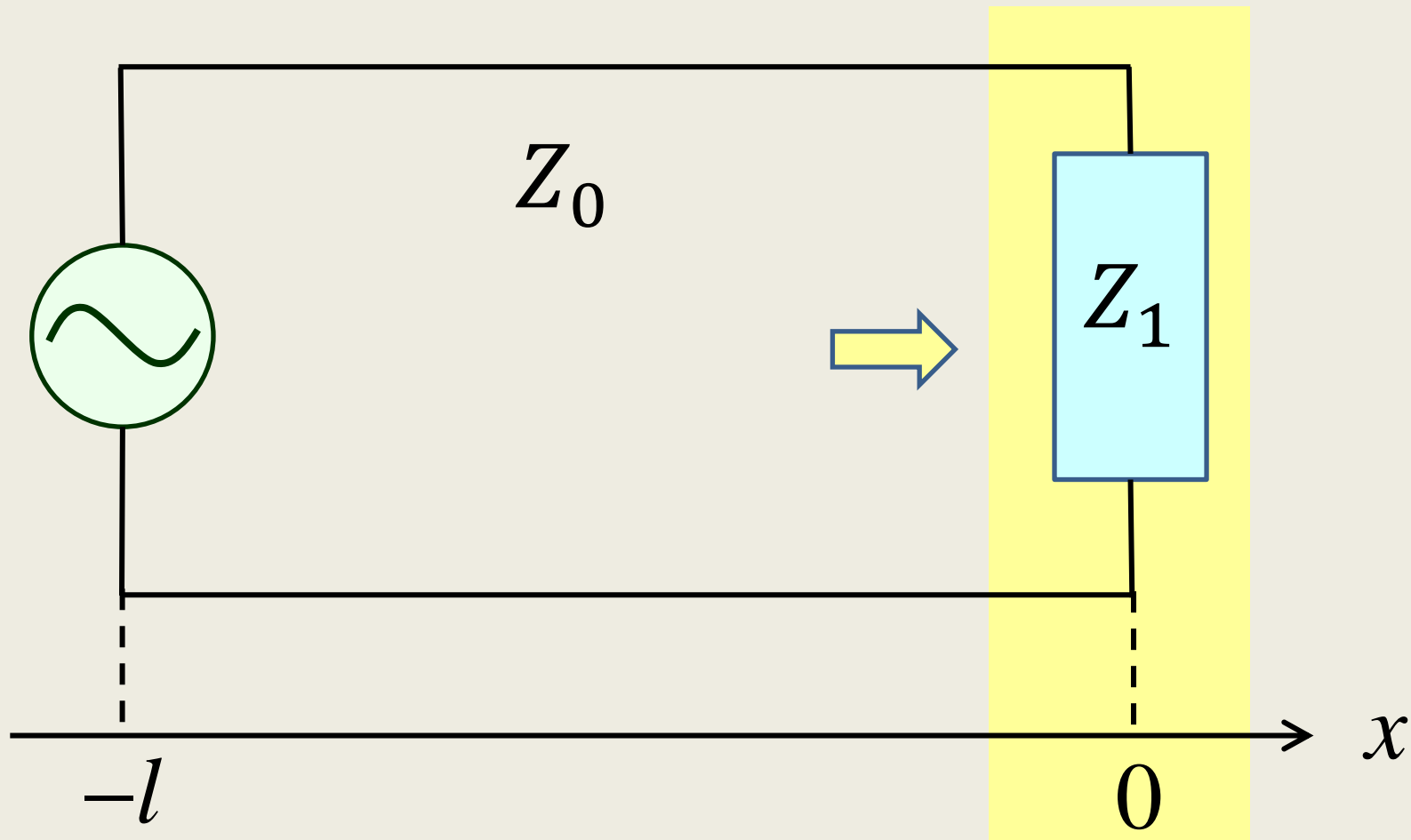
Wide ( $W/h > 3.3$ ) strip

$$Z(W, h, \epsilon_r) = \frac{Z_{F0}}{2\sqrt{\epsilon_r}} \left\{ \frac{W}{2h} + \frac{1}{\pi} \log 4 + \frac{\epsilon_r + 1}{2\pi\epsilon_r} \log \left[ \frac{\pi e}{2} \left( \frac{W}{2h} + 0.94 \right) \right] \frac{\epsilon_r - 1}{2\pi\epsilon_r^2} \log \frac{e\pi^2}{16} \right\}^{-1}$$

Narrow ( $W/h < 3.3$ ) strip

$$Z(W, h, \epsilon_r) = \frac{Z_{F0}}{\pi\sqrt{2(\epsilon_r + 1)}} \left\{ \log \left[ \frac{4h}{W} + \sqrt{\left( \frac{4h}{W} \right)^2 + 2} \right] - \frac{1}{2} \frac{\epsilon_r - 1}{\epsilon_r + 1} \left( \log \frac{\pi}{2} + \frac{1}{\epsilon_r} \log \frac{4}{\pi} \right) \right\}$$

# Connection and termination



# Connection and termination

$$\text{At } x = 0: \begin{cases} J = J_+ + J_- & \text{(definition right positive)} \\ \text{progressive} & \text{retrograde} \\ V = V_+ + V_- = Z_0(J_+ - J_-) \end{cases}$$

$$Z_1 = \frac{V}{J} = \frac{J_+ - J_-}{J_+ + J_-} Z_0$$

$$\text{Reflection coefficient: } r = \frac{V_-}{V_+} = -\frac{J_-}{J_+} = \frac{Z_1 - Z_0}{Z_1 + Z_0}$$

$Z_1 = Z_0$  : no reflection, i.e., **impedance matching**

$Z_1 = +\infty$  (open circuit end) :  $r = 1$ , i.e., **free end**

$Z_1 = 0$  (short circuit end) :  $r = -1$ , i.e., **fixed end**

# Connection and termination

Finite reflection  $\rightarrow$  Standing wave

$$\text{Voltage-Standing Wave Ratio (VSWR):} = \frac{1 + |r|}{1 - |r|}$$

---

At  $x = -l$

$$\left. \begin{aligned} V &= V_{+0} \exp(\kappa l) + V_{-0} \exp(-\kappa l) = [J_{+0} \exp(\kappa l) - J_{-0} \exp(-\kappa l)] Z_0 \\ J &= J_{+0} \exp(\kappa l) + J_{-0} \exp(-\kappa l) \end{aligned} \right\}$$

$$Z_l = \frac{V}{J} = \frac{J_{+0} e^{\kappa l} - J_{-0} e^{-\kappa l}}{J_{+0} e^{\kappa l} + J_{-0} e^{-\kappa l}} Z_0$$

Reflection coefficient:

$$r_l = \frac{V_-}{V_+} = \frac{V_{-0} e^{-\kappa l}}{V_{+0} e^{\kappa l}} = r \exp(-2\kappa l)$$

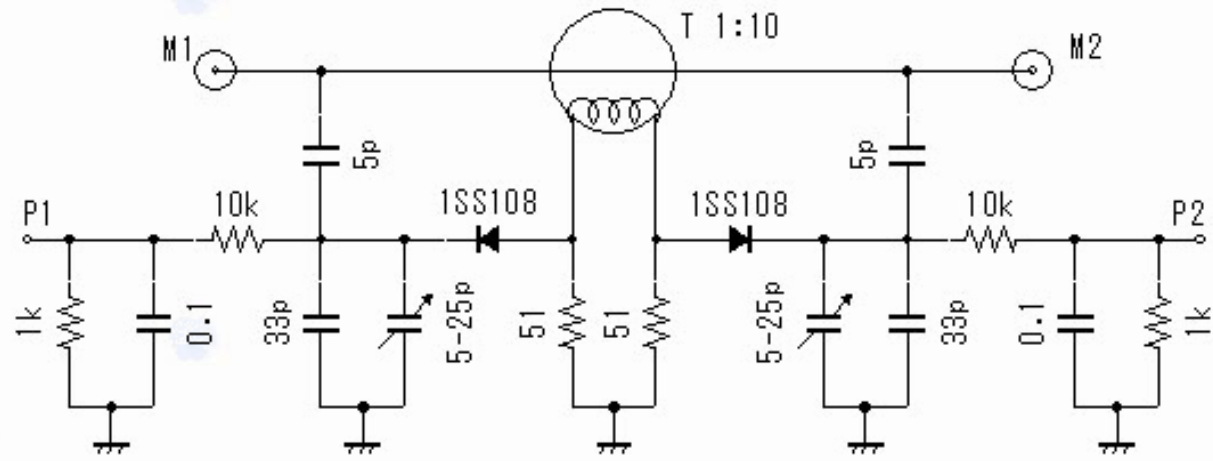
# SWR measurement

## SWR Meters:

Desktop types



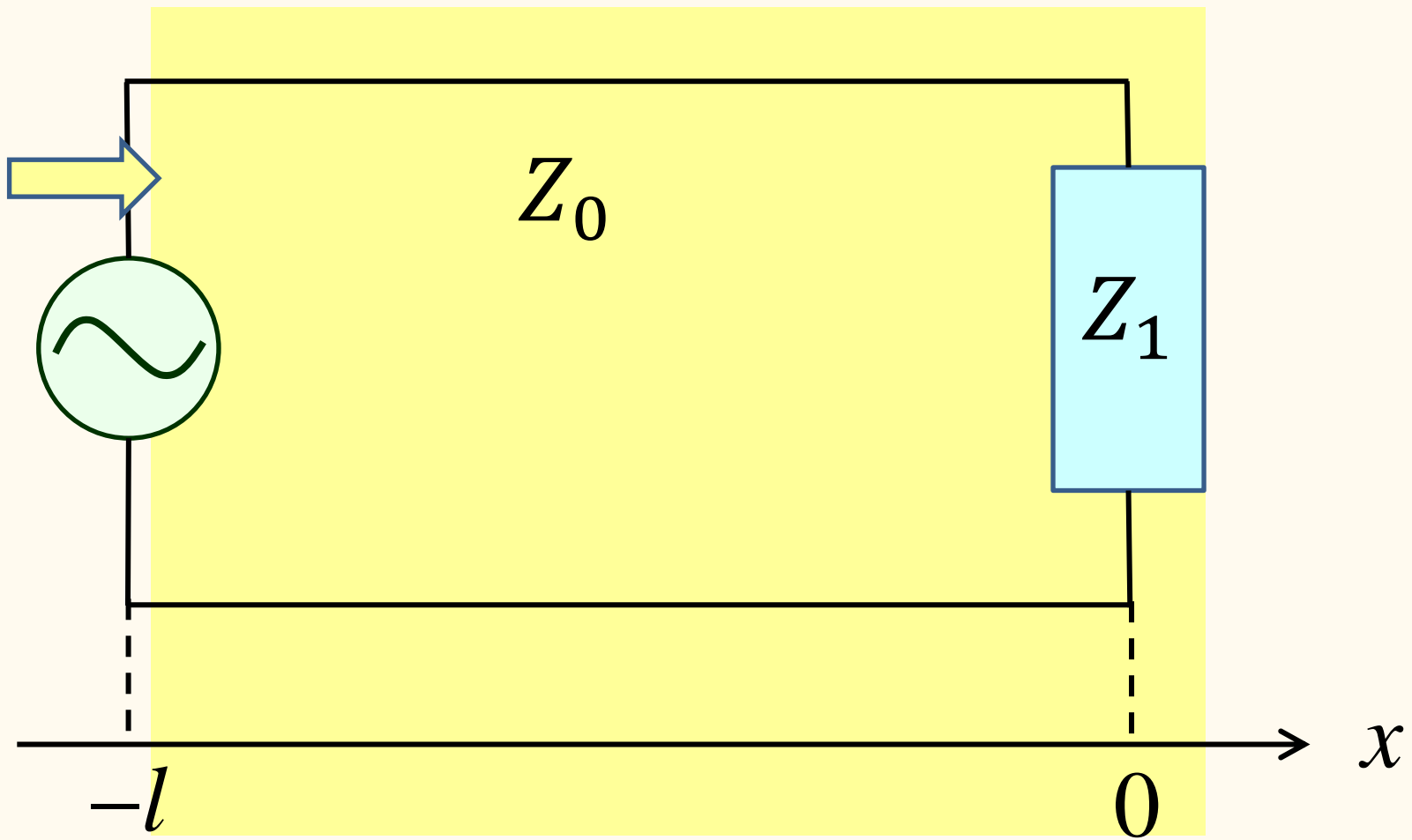
Cross-meter



Handy type



# Connection and termination



# Connection and termination

Transmission line connection.

Characteristic impedance  $Z_0, Z_0'$

At the connection point, only the local relation between  $V$  and  $J$  affects the reflection coefficient.

The local impedance from the left hand side is  $Z_0'$ .

$$r = \frac{Z_0' - Z_0}{Z_0' + Z_0}$$

# 電子回路論第 8 回

## Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto



# Outline

## 5.1 Transmission lines

TEM mode Lecher line

Micro-strip line

TE, TM mode Waveguide

Optical fiber

## 5.2 Propagation in transmission lines

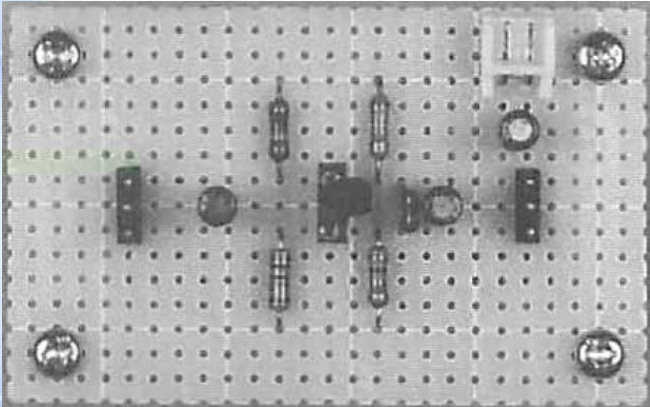
Termination and connection

Smith chart

Scattering matrix

Impedance matching

# Comment: bias + signal superposition

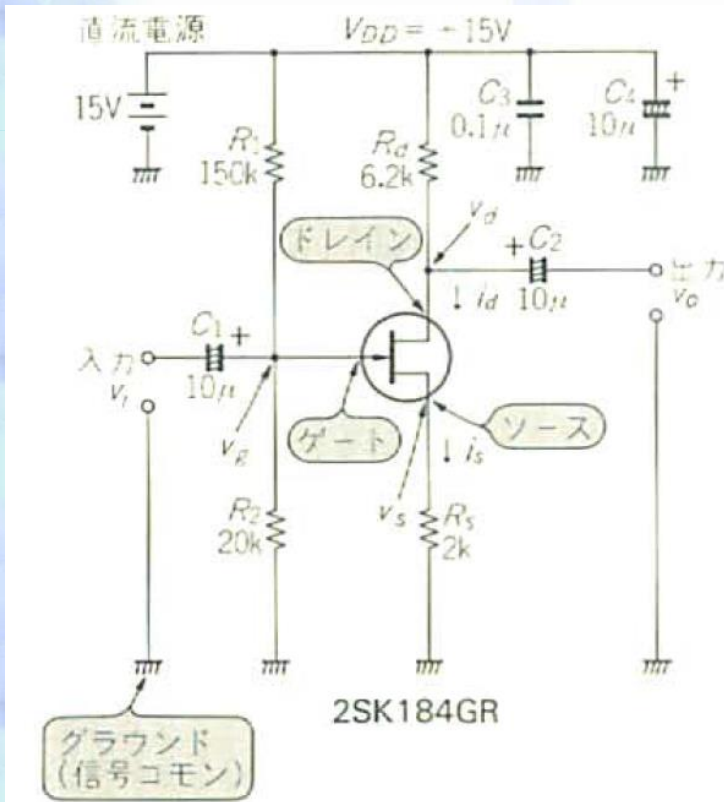


For bias (dc) circuits

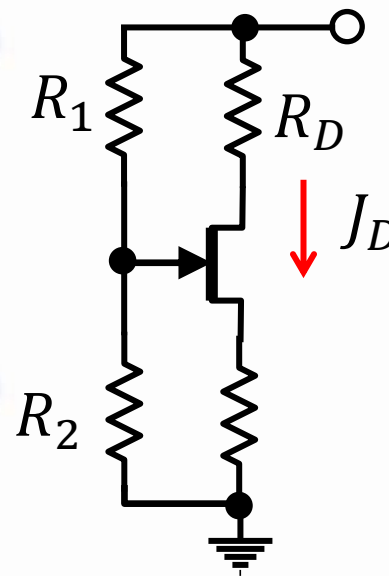
All the capacitors can be viewed as break line.

For small amplitude (high-frequency) circuits

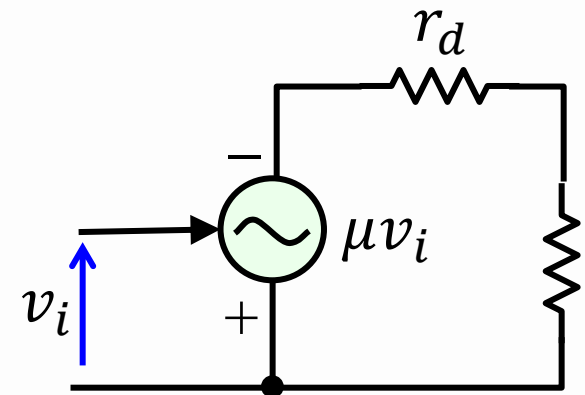
All the capacitors can be viewed as short circuits.



Self-bias



Source-grounded





# Coaxial cable 2

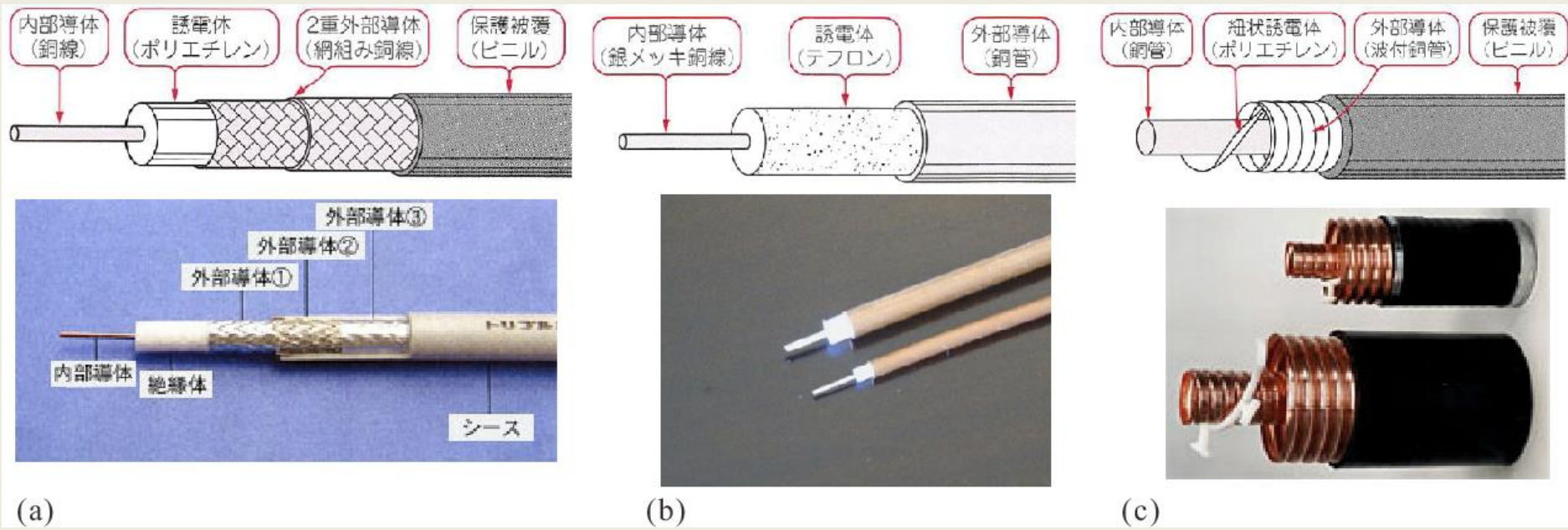


図12 同軸ケーブルの型名 (JIS C3501)

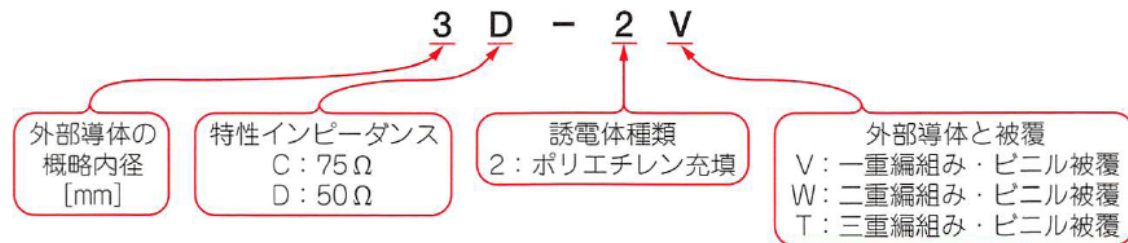
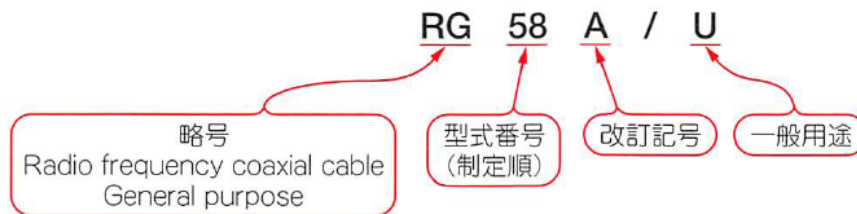


図13 MIL規格での同軸ケーブル型名の例

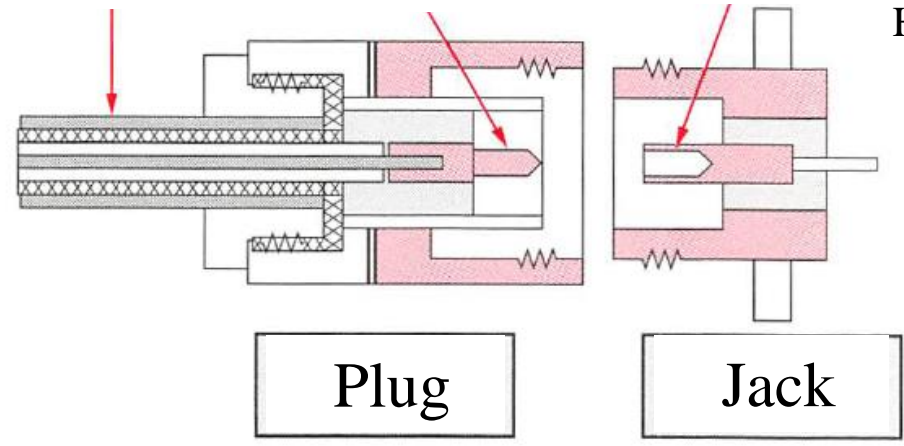




# Coaxial connectors

図22 coaxial connector (schematic)

coaxial cable    male contact    female contact

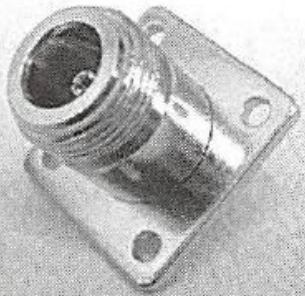


Highest available frequencies for coaxial connectors

type	outer diam.	highest freq.
BNC	約 7 mm	2 ~ 4 GHz
N	約 7 mm	10 ~ 18 GHz
7 mm	7 mm	~ 18 GHz
SMA	4.15 mm	18 GHz
3.5 mm	3.5 mm	26.5 GHz
K	2.92 mm	40 GHz
2.4 mm	2.4 mm	50 GHz
V	1.85 mm	65 GHz
W	1.1 mm	110 GHz
1.0 mm	1.0 mm	110 GHz

# Coaxial connectors

## N-type connectors



(a) jack with flange

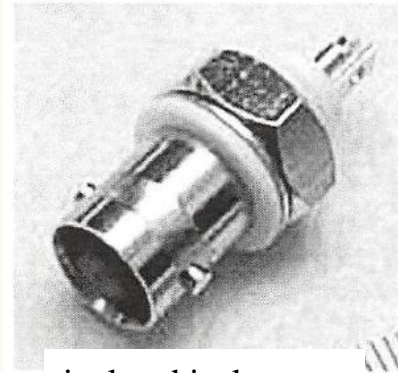


(b) plug

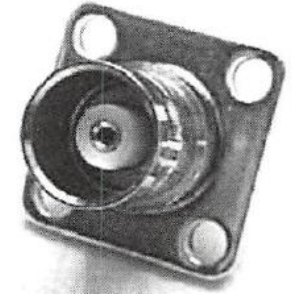


(c) plug [disassembled (b) ]

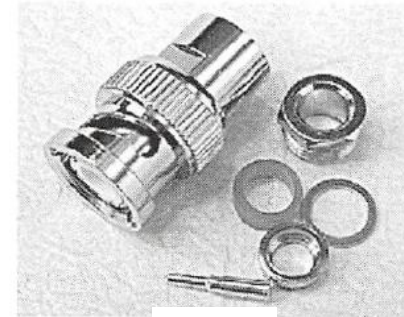
## BNC-type connectors



isolated jack  
(not for high freq.)



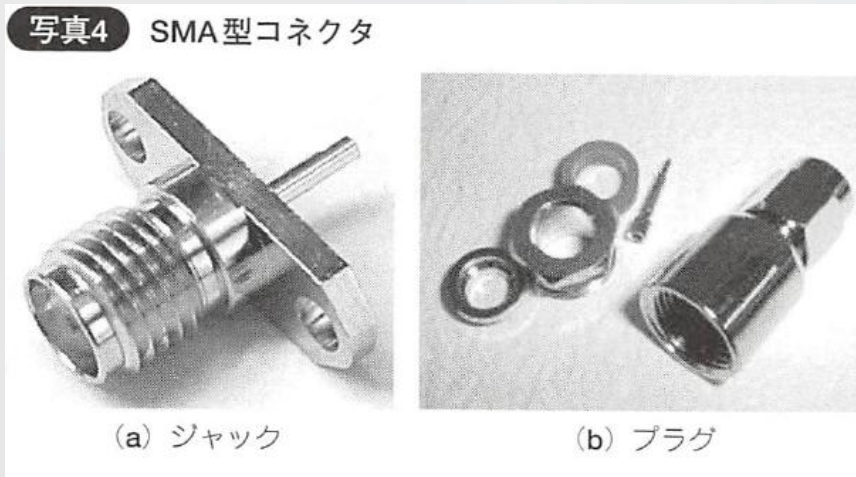
jack with flange



plug

# Coaxial connectors 2

## SMA-type

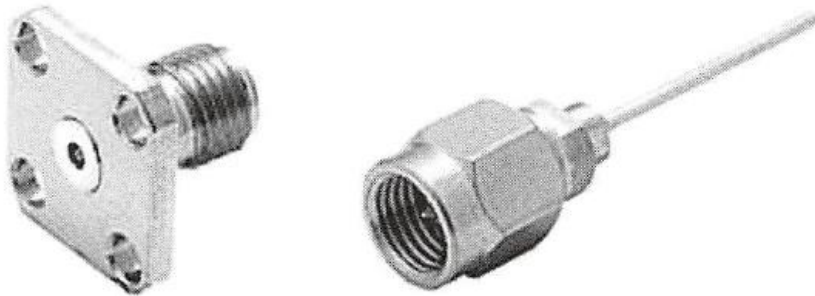


jack

plug

## K-type

写真6 K型コネクタ

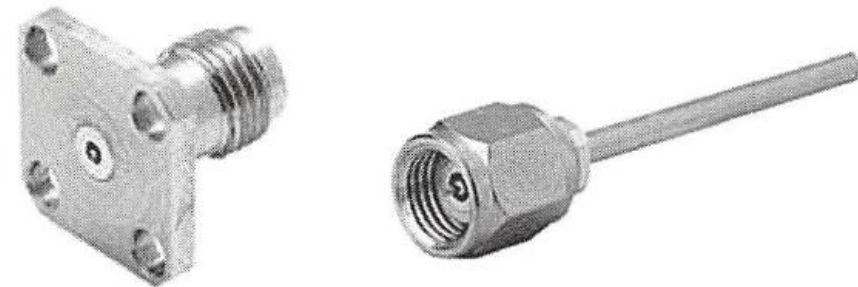


jack

plug

## V-type

写真7 V型コネクタ



jack

plug

# LEMO cables and connectors

MFBモデル



MSBモデル



<http://www.lemo.com/>

High-energy physics experiment,  
etc.

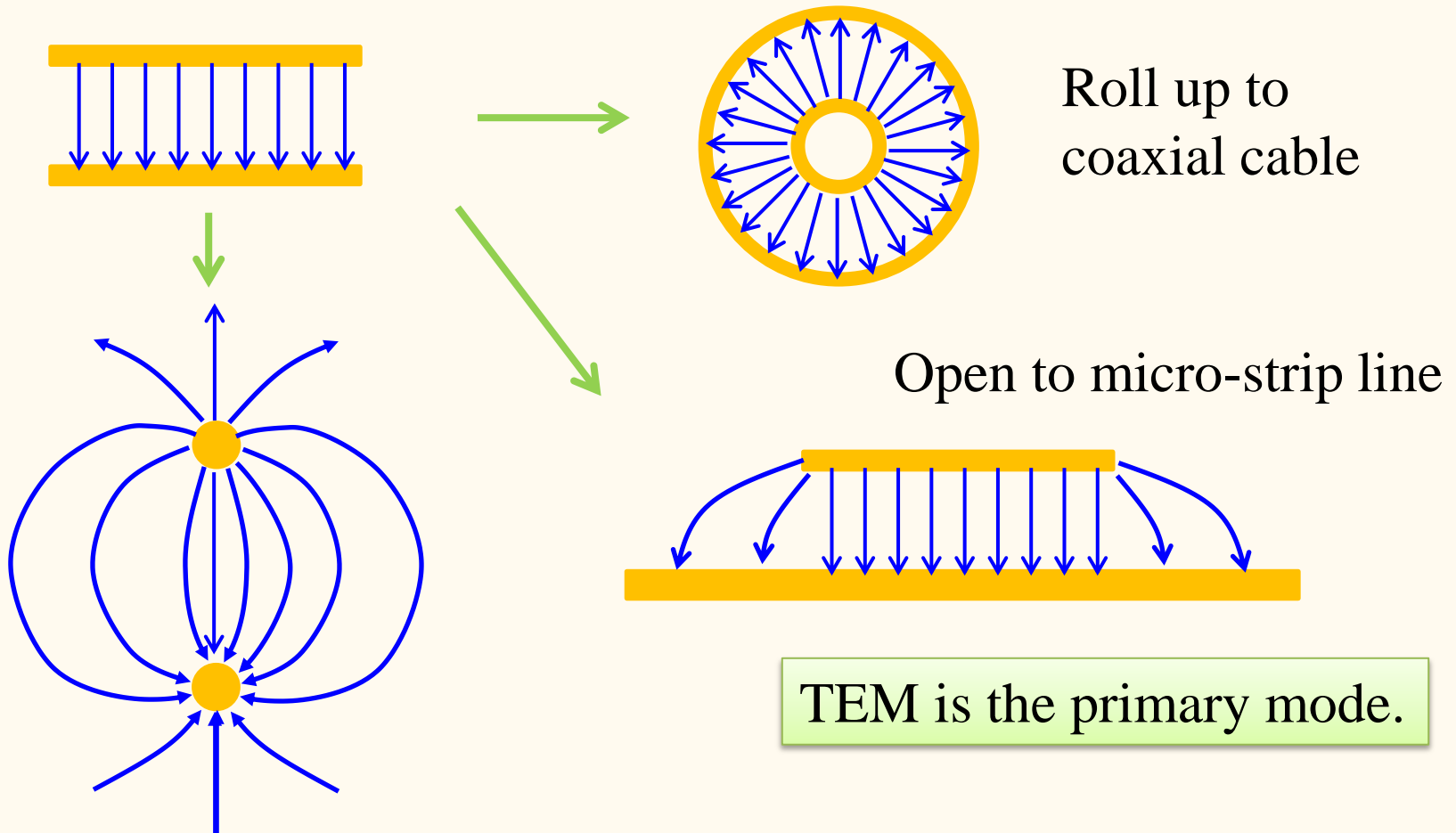




# Transmission lines with TEM mode

Transmission lines with two conductors are “families”.

Electromagnetic field confinement with parallel-plate capacitor



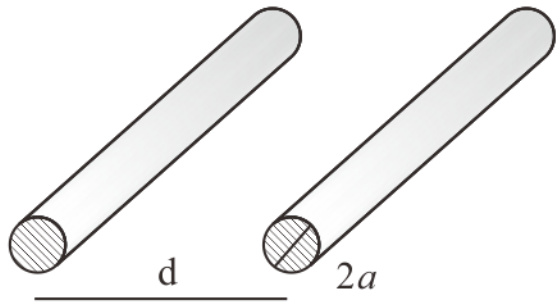
Roll up to  
coaxial cable

Open to micro-strip line

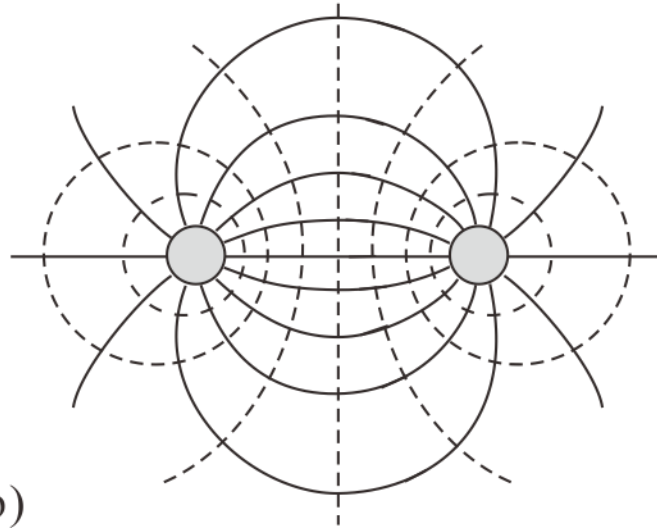
TEM is the primary mode.

Shrink to dipole (Lecher line)

# Lecher line



(a)



(b)

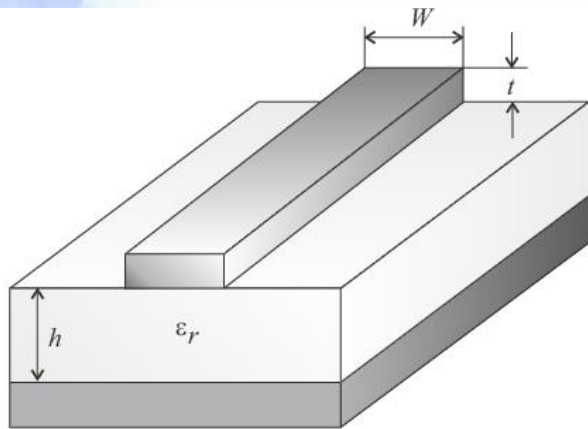


(c)

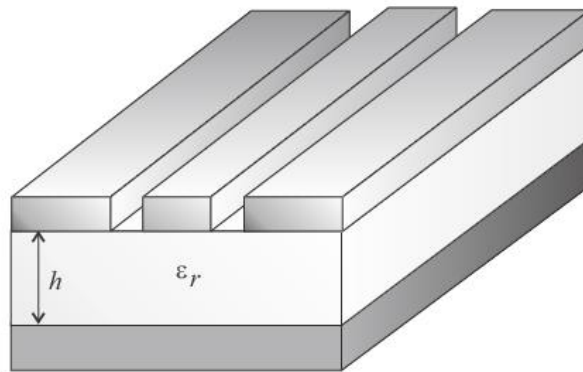
$$\phi_1 = -\phi_2 = \frac{J\sqrt{\mu}}{2\pi} \log \frac{d}{a} \quad Z_0 = \sqrt{\frac{\mu}{\epsilon}} \frac{1}{\pi} \log \frac{d}{a}$$



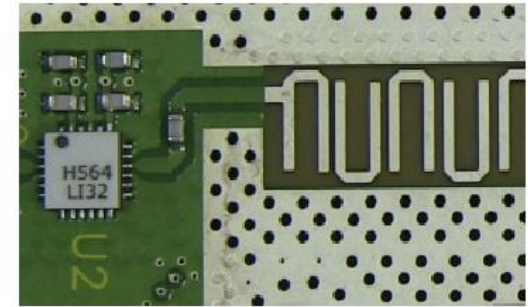
# Micro strip line



(a)



(b)



(c)

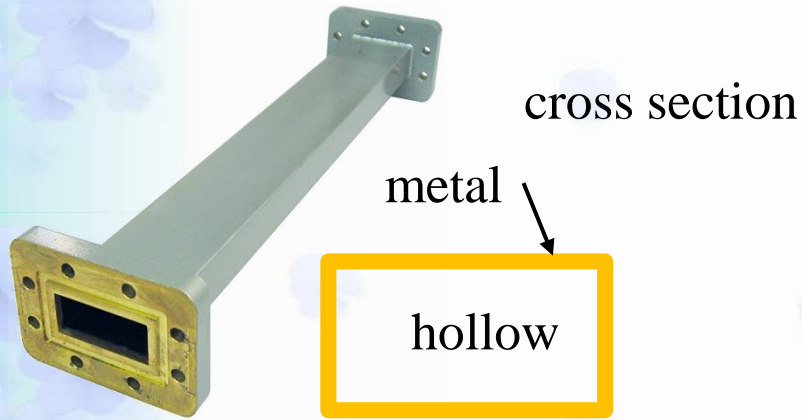
Wide ( $W/h > 3.3$ ) strip

$$Z(W, h, \epsilon_r) = \frac{Z_{F0}}{2\sqrt{\epsilon_r}} \left\{ \frac{W}{2h} + \frac{1}{\pi} \log 4 + \frac{\epsilon_r + 1}{2\pi\epsilon_r} \log \left[ \frac{\pi e}{2} \left( \frac{W}{2h} + 0.94 \right) \right] \frac{\epsilon_r - 1}{2\pi\epsilon_r^2} \log \frac{e\pi^2}{16} \right\}^{-1}$$

Narrow ( $W/h < 3.3$ ) strip

$$Z(W, h, \epsilon_r) = \frac{Z_{F0}}{\pi\sqrt{2(\epsilon_r + 1)}} \left\{ \log \left[ \frac{4h}{W} + \sqrt{\left( \frac{4h}{W} \right)^2 + 2} \right] - \frac{1}{2} \frac{\epsilon_r - 1}{\epsilon_r + 1} \left( \log \frac{\pi}{2} + \frac{1}{\epsilon_r} \log \frac{4}{\pi} \right) \right\}$$

# Waveguide



Electromagnetic field is confined into a simply-connected space.



TEM mode cannot exist.

Maxwell equations give

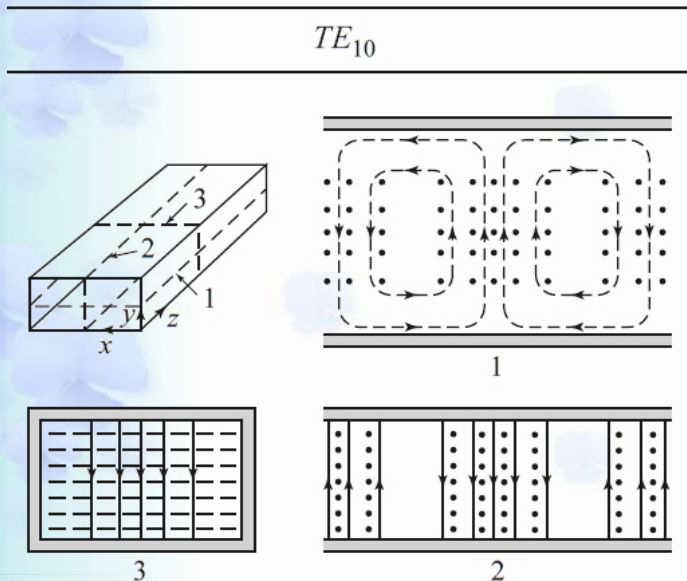
$$\left[ \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right] E_z = -(\omega^2 \epsilon \mu + \gamma^2) E_z,$$

$$\left[ \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right] H_z = -(\omega^2 \epsilon \mu + \gamma^2) H_z.$$

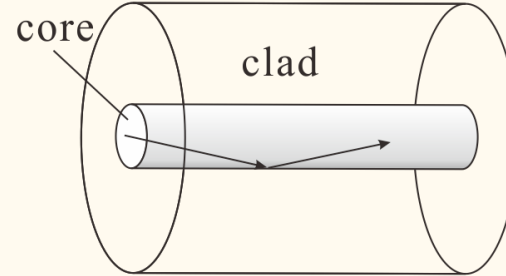
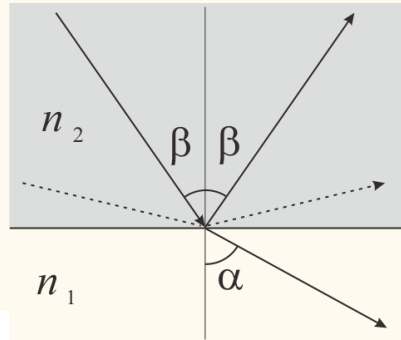
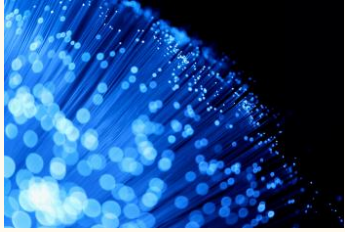
Helmholtz equation

$$E_z = 0: \text{TE mode,}$$

$$H_z = 0: \text{TM mode}$$

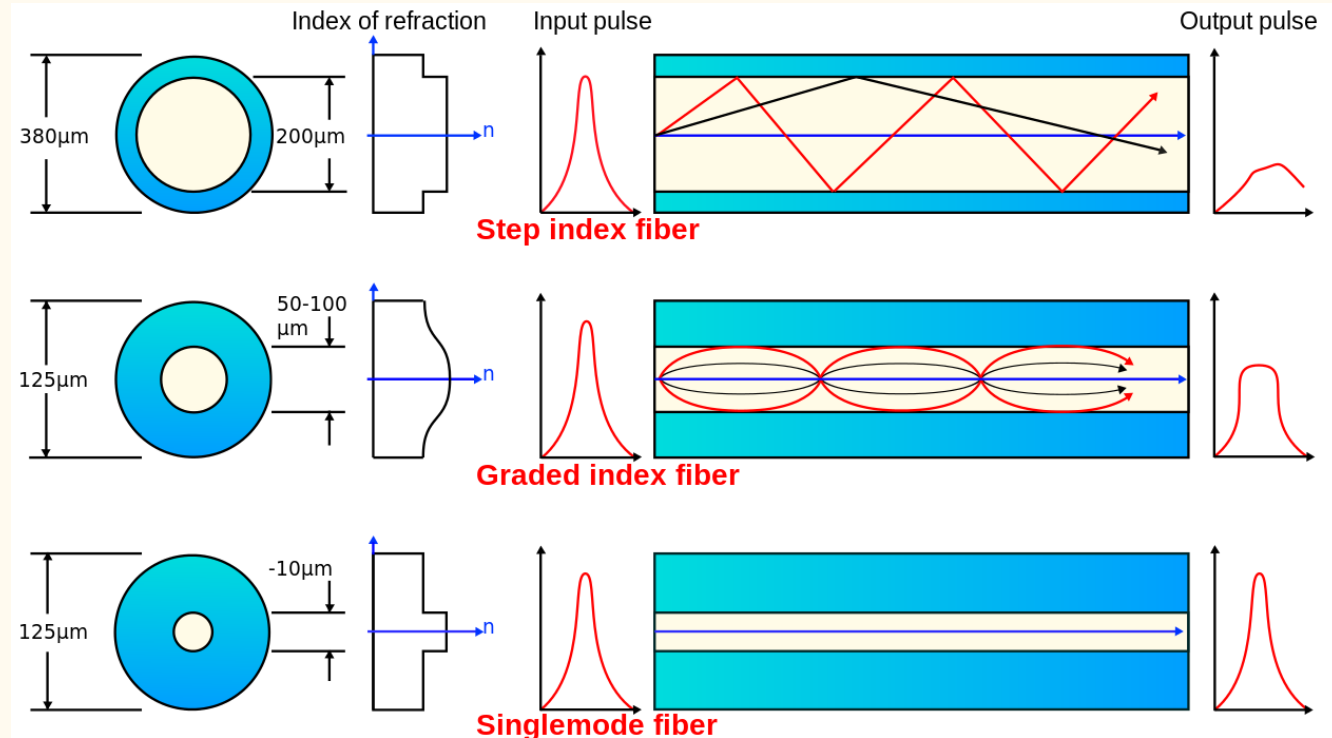
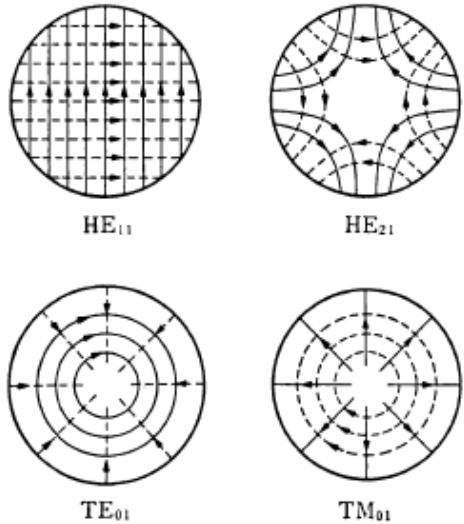


# Optical fiber



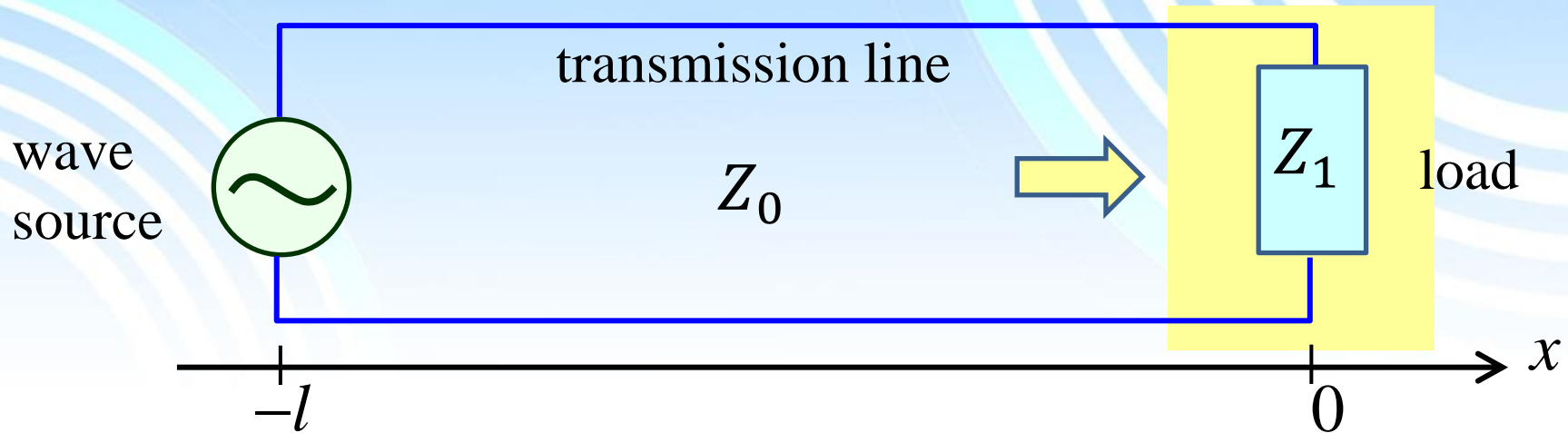
step-type  
optical fiber

Difference in dielectric constant



no dispersion

# Termination of transmission line



Termination of a transmission line with length  $l$  and characteristic impedance  $Z_0$  at  $x = 0$  with a resistor  $Z_1$ .

$$\text{At } x = 0: \begin{cases} J = \underline{J_+} + \underline{J_-} & \text{(definition right positive)} \\ \text{progressive} & \text{retrograde} \\ V = V_+ + V_- = Z_0(J_+ - J_-) \end{cases}$$

*Comment:* Sign of Ohm's law in transmission lines reflects direction of waves (depends on the definitions).

# Termination of transmission line

$$\pm 2Z_0 J_{\pm} = 2V_{\pm} = J \pm Z_0 V$$

synthesized impedance:  $Z_1 = \frac{V}{J} = \frac{J_+ - J_-}{J_+ + J_-} Z_0$

reflection coefficient:  $r = \frac{V_-}{V_+} = -\frac{J_-}{J_+} = \frac{Z_1 - Z_0}{Z_1 + Z_0}$

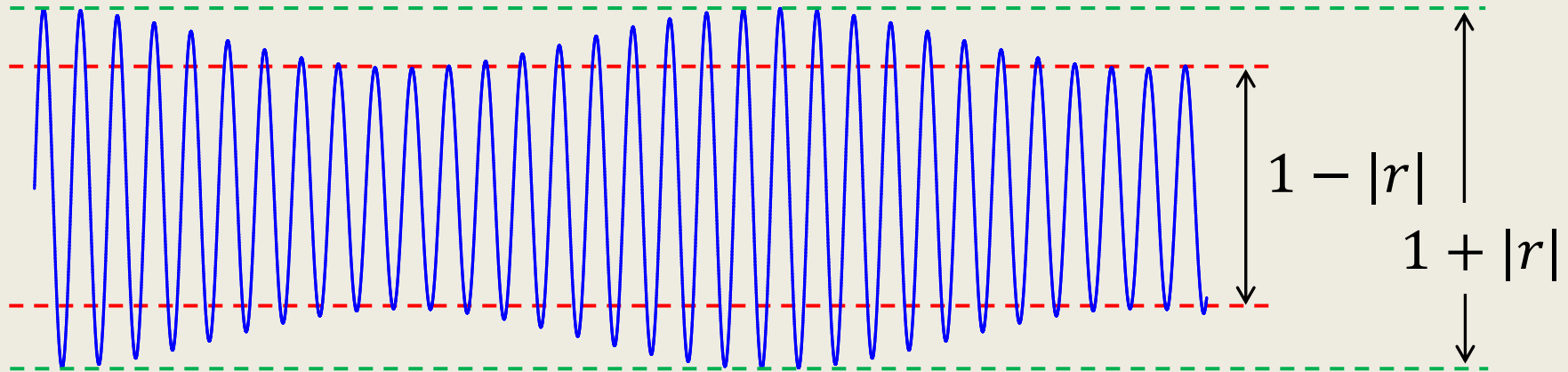
$Z_1 = Z_0$  : no reflection, i.e., **impedance matching**

$Z_1 = +\infty$  (open circuit end) :  $r = 1$ , i.e., **free end**

$Z_1 = 0$  (short circuit end) :  $r = -1$ , i.e., **fixed end**

# Connection and termination

Finite reflection  $\rightarrow$  Standing wave



Voltage-Standing Wave Ratio (VSWR):  $= \frac{1 + |r|}{1 - |r|}$



# SWR measurement

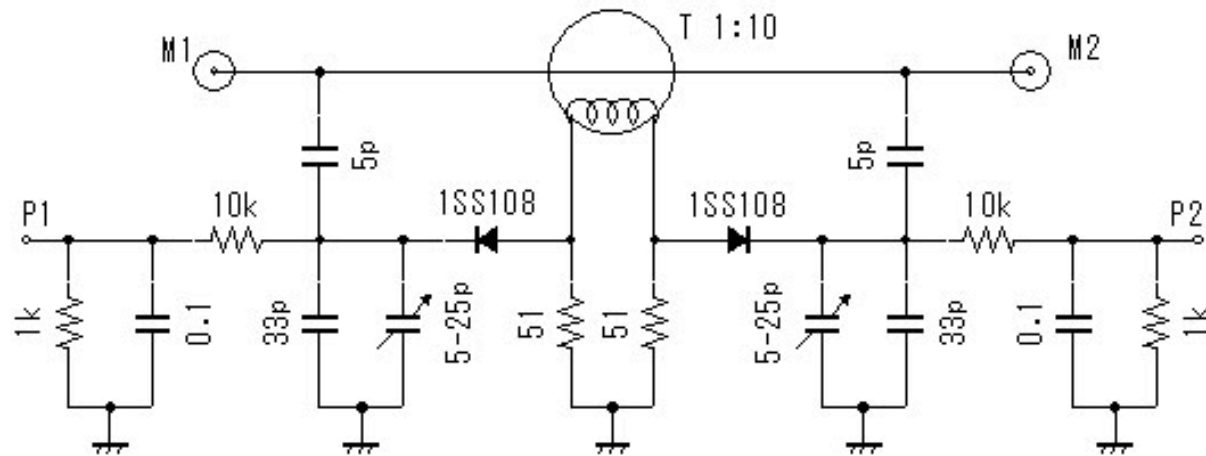
SWR Meters: desktop types



cross-meter



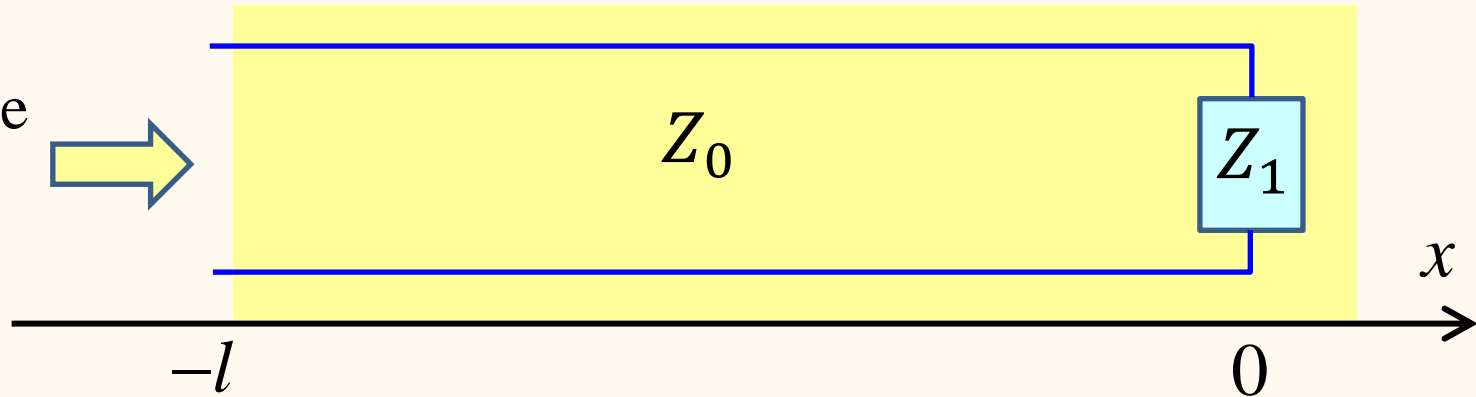
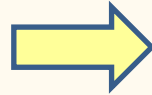
handy type



directional coupler

# Synthesized impedance

total impedance  
from this side



At  $x = -l$

$$\left. \begin{aligned} V &= V_{+0} \exp(\kappa l) + V_{-0} \exp(-\kappa l) = [J_{+0} \exp(\kappa l) - J_{-0} \exp(-\kappa l)] Z_0 \\ J &= J_{+0} \exp(\kappa l) + J_{-0} \exp(-\kappa l) \end{aligned} \right\}$$

$$Z_l = \frac{V}{J} = \frac{J_{+0} e^{\kappa l} - J_{-0} e^{-\kappa l}}{J_{+0} e^{\kappa l} + J_{-0} e^{-\kappa l}} Z_0$$

Reflection coefficient:  $r_l = \frac{V_-}{V_+} = \frac{V_{-0} e^{-\kappa l}}{V_{+0} e^{\kappa l}} = r \exp(-2\kappa l)$

# Connection and termination

Transmission line connection.

Characteristic impedance  $Z_0, Z_0'$

At the connection point, only the local relation between  $V$  and  $J$  affects the reflection coefficient.

The local impedance from the left hand side is  $Z_0'$ .

$$r = \frac{Z_0' - Z_0}{Z_0' + Z_0}$$



## 5.2.3 Smith chart, Immittance chart

End impedance  $Z_1$ : Normalized end impedance  $Z_n \equiv Z_1/Z_0$

$$Z_n = x + iy, \quad r = u + iw \quad (x, y, u, w \in \mathbb{R})$$

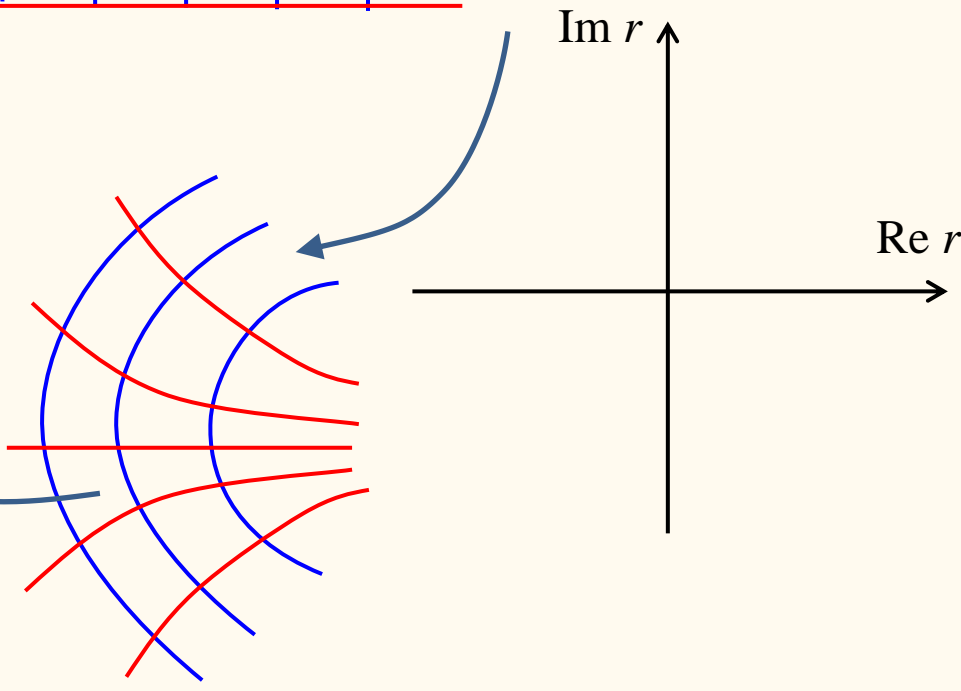
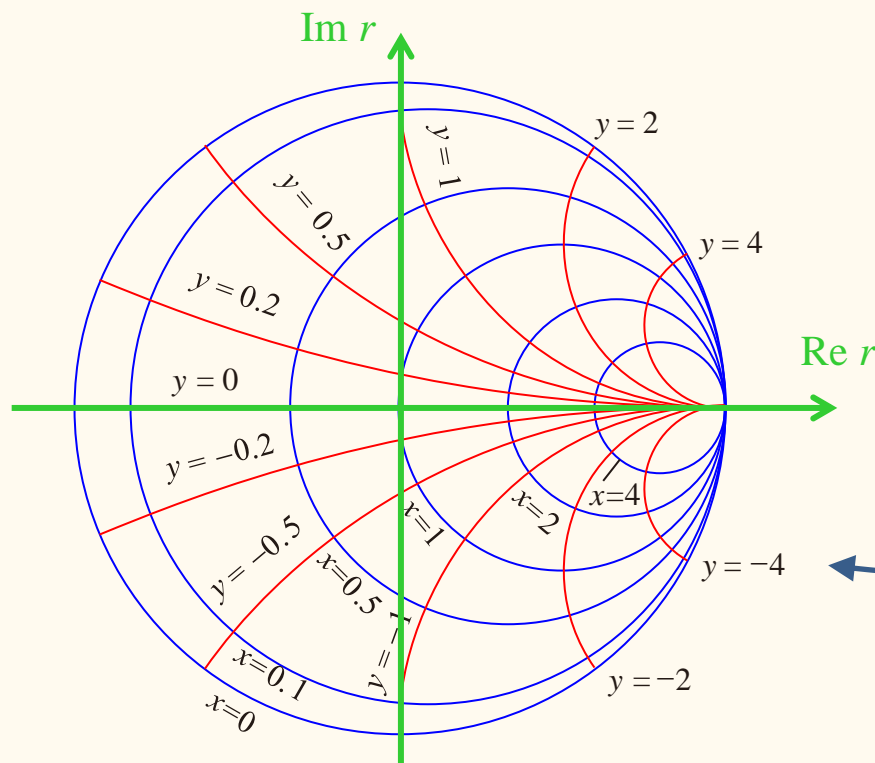
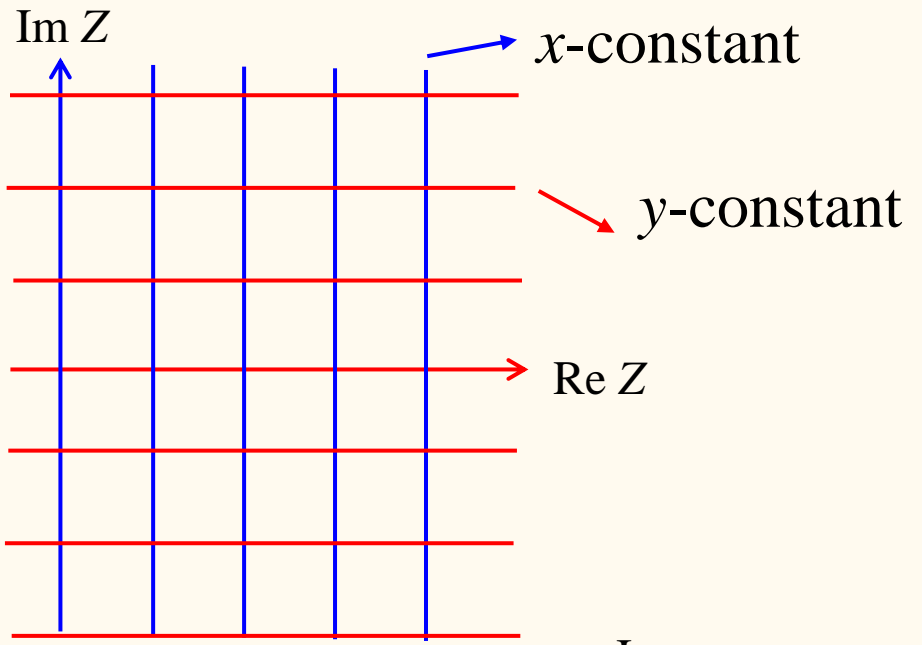
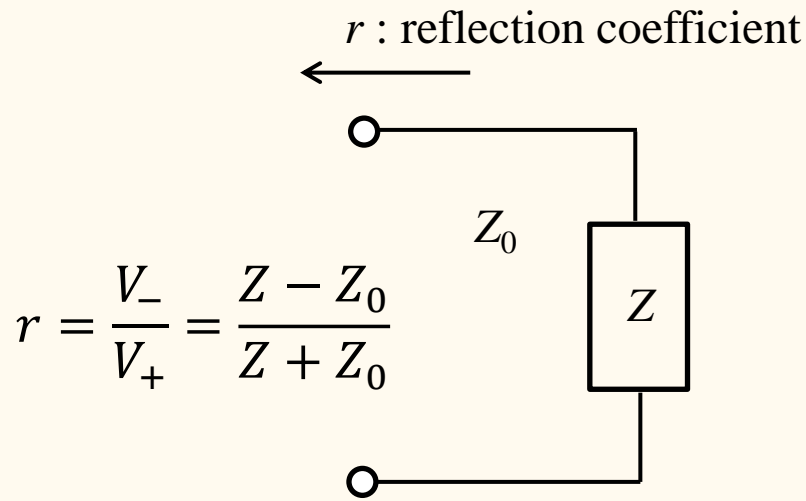
$$u + iw = r = \frac{Z_n - 1}{Z_n + 1} = \frac{(x - 1) + iy}{(x + 1) + iy}$$

$$\left. \begin{array}{l} \text{real:} \quad x - 1 = (x + 1)u - yw \\ \text{imaginary:} \quad y = yu + w(x + 1) \end{array} \right\}$$

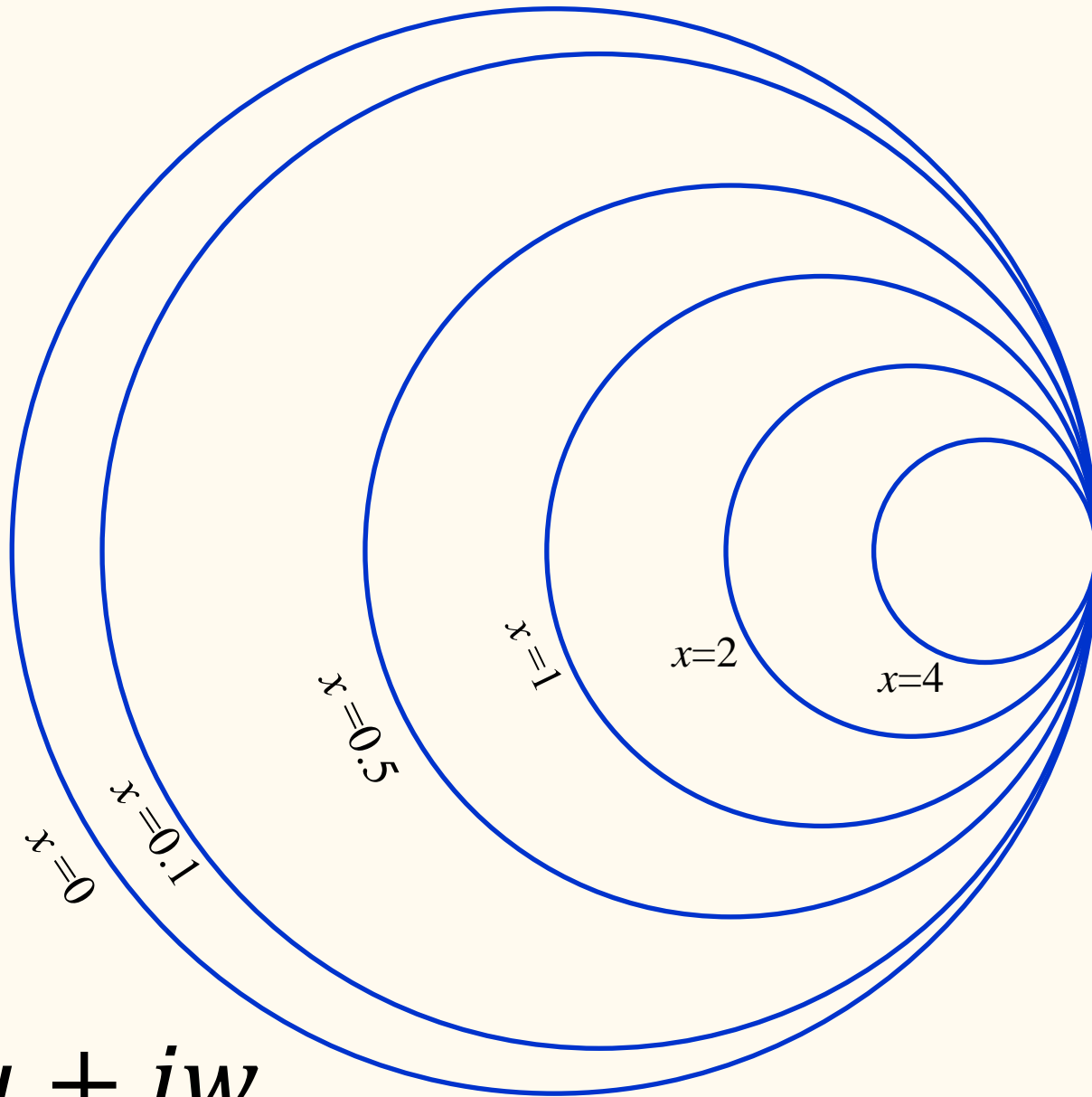
$$x: \text{ constant} \rightarrow \left(u - \frac{x}{x+1}\right)^2 + w^2 = \frac{1}{(x+1)^2} \quad \text{constant resistance circle}$$

$$y: \text{ constant} \rightarrow (u - 1)^2 + \left(w - \frac{1}{y}\right)^2 = \frac{1}{y^2} \quad \text{constant reactance circle}$$

# 5.2.3 Smith chart, Immittance chart



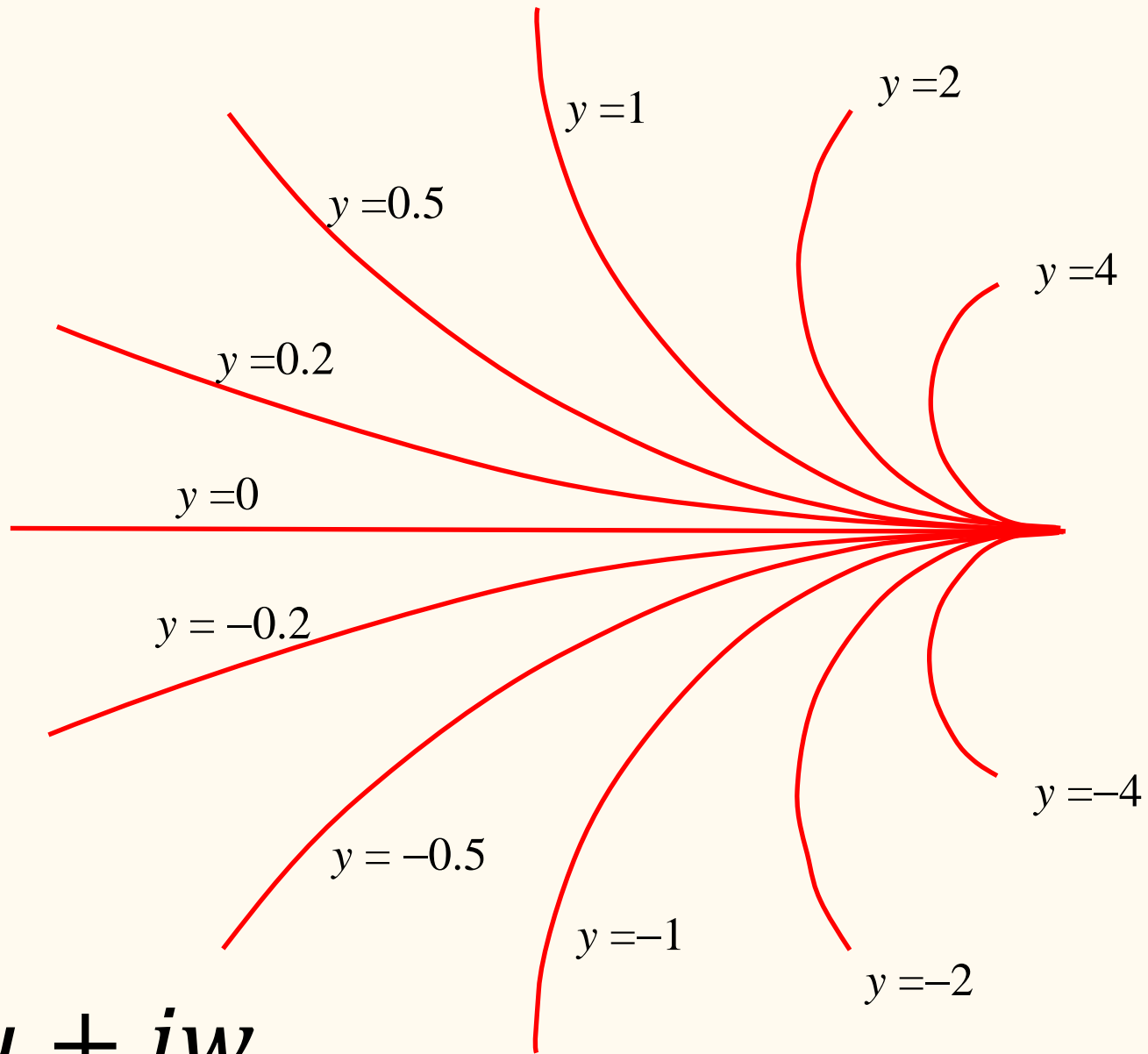
## 5.2.3 Smith chart, Immittance chart



$$r = u + iw$$

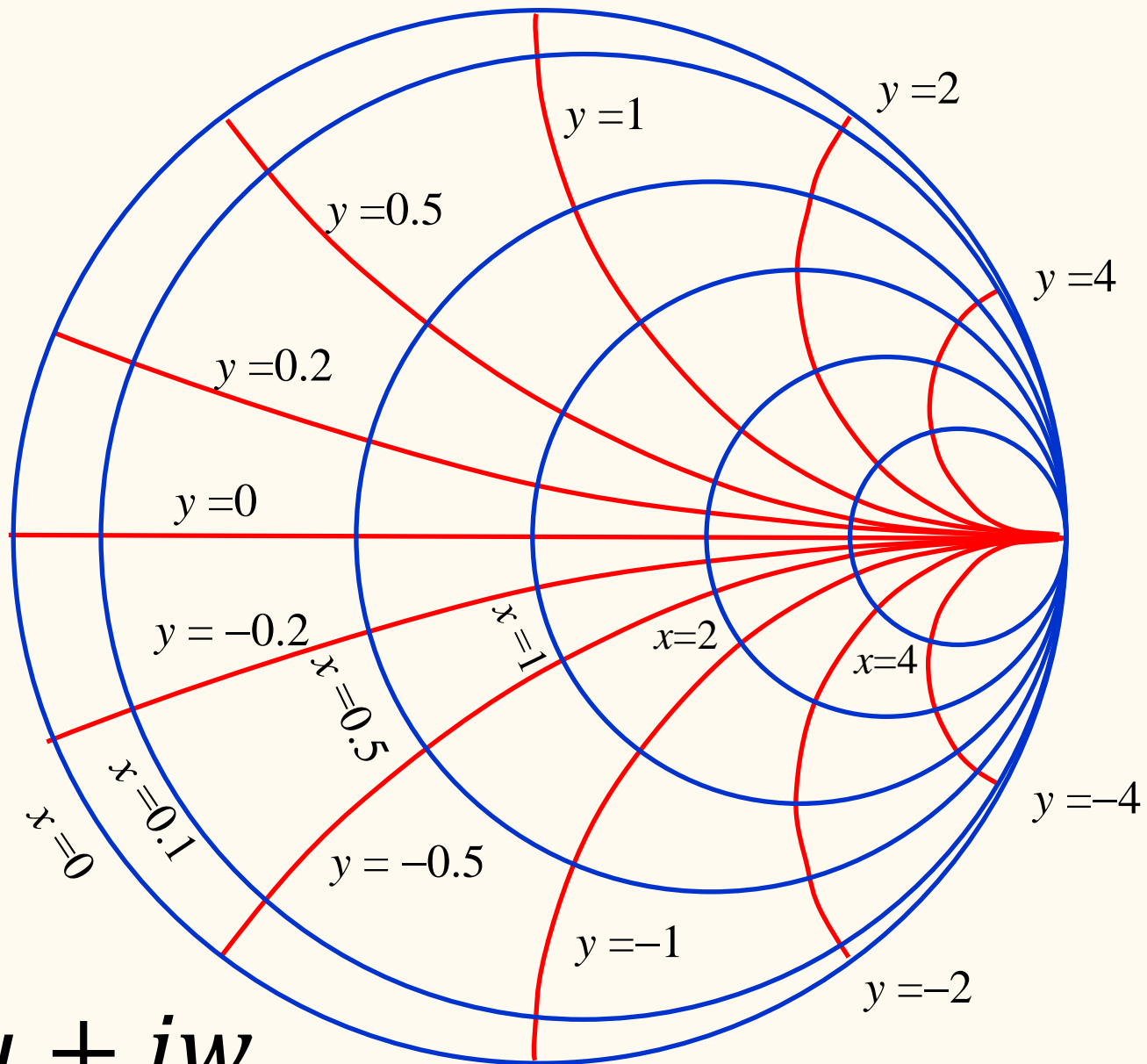


## 5.2.3 Smith chart, Immittance chart



$$r = u + iw$$

## 5.2.3 Smith chart, Immittance chart



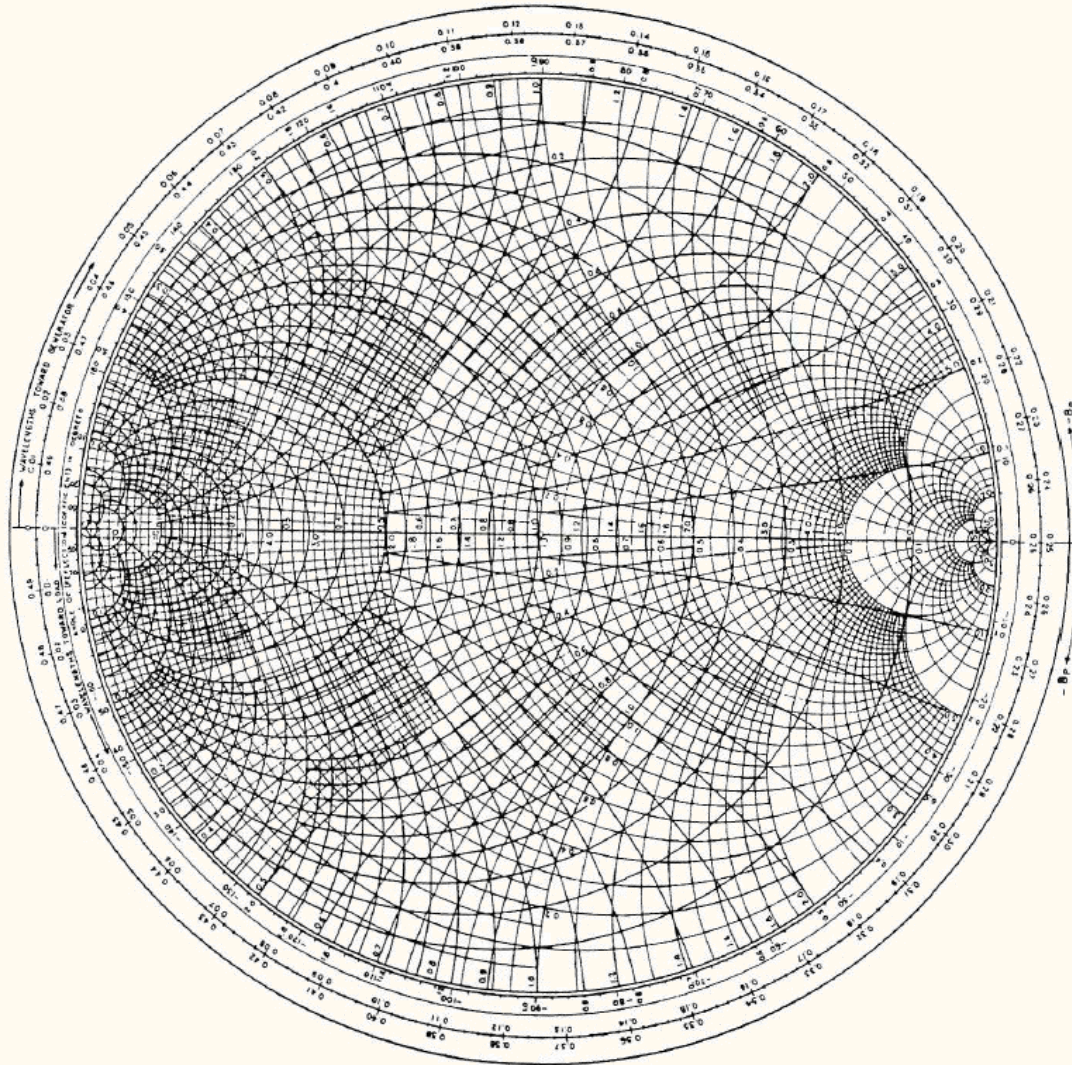
$$r = u + iw$$

Smith chart





## 5.2.3 Smith chart, Immittance chart



Immittance chart

$$r = u + iw$$

# 5.3 Scattering (S) matrix (S parameters)

How to treat multipoint (crossing point) systematically?

Transmission lines: wave propagating modes  $\rightarrow$  Channels

Take  $|a_i|^2$ ,  $|b_i|^2$  to be powers (energy flow).

$$\begin{matrix} \text{output} & \text{S-matrix} & \text{input} \\ \begin{pmatrix} b_1 \\ \vdots \\ b_i \\ \vdots \\ b_n \end{pmatrix} & = & \begin{pmatrix} S_{11} & \cdots & S_{1i} & \cdots & S_{1n} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ S_{i1} & & S_{ii} & & S_{in} \\ \vdots & & \vdots & \ddots & \vdots \\ S_{n1} & \cdots & S_{ni} & \cdots & S_{nn} \end{pmatrix} \begin{pmatrix} a_1 \\ \vdots \\ a_i \\ \vdots \\ a_n \end{pmatrix} \end{matrix}$$

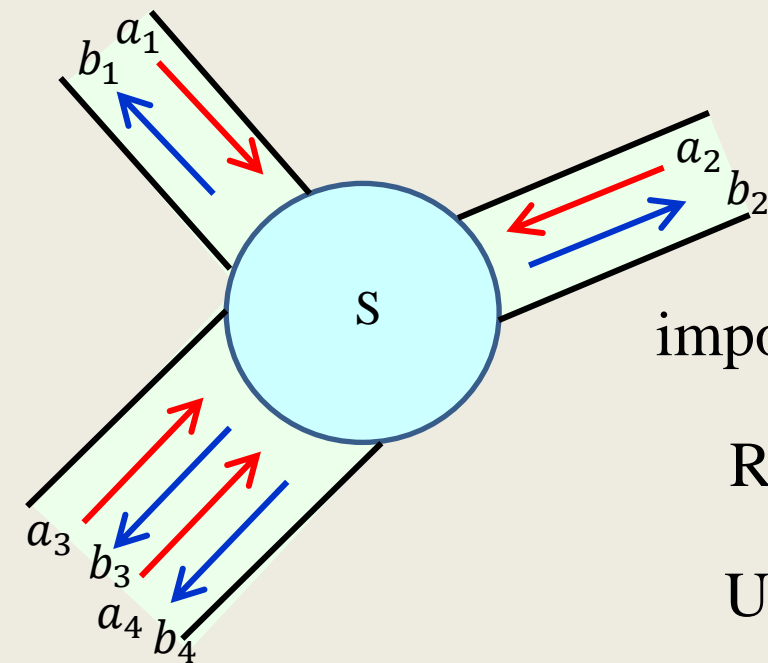
$$\mathbf{b} = \mathbf{S}\mathbf{a}$$

important properties:

Reciprocity  $S_{ij} = S_{ji}$

Unitarity  $\sum_j S_{ji} S_{jk}^* = \delta_{ik}$

(In case, no dissipation, no amplification)



## 5.3 S matrix (S parameters)

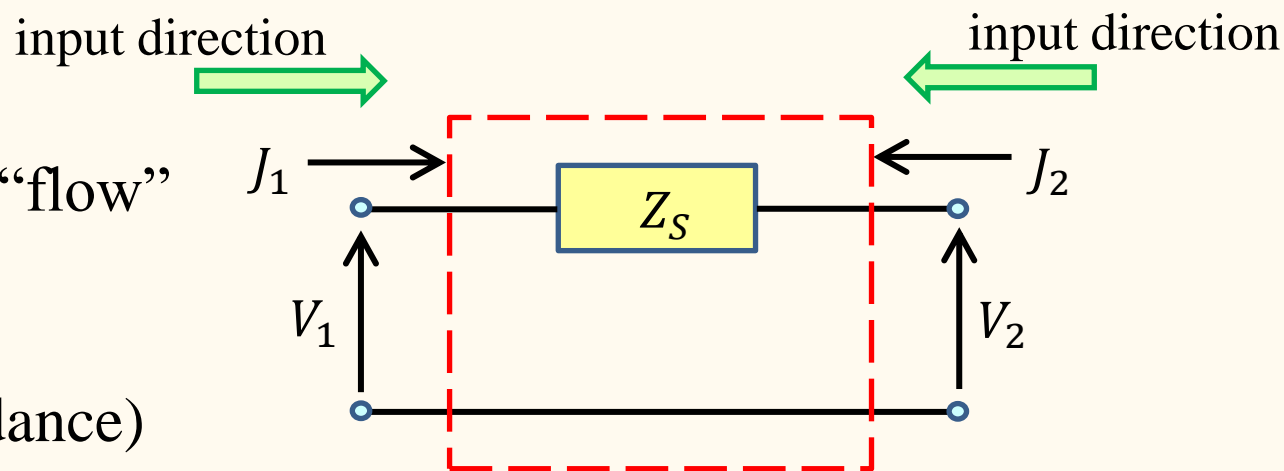
Propagation with no dissipation

$$\begin{cases} a_n = \frac{V_{n+}}{\sqrt{Z_{0n}}} = J_{n+} \sqrt{Z_{0n}}, & \text{incident power wave} \\ b_n = \frac{V_{n-}}{\sqrt{Z_{0n}}} = J_{n-} \sqrt{Z_{0n}} & \text{reflected (transmitted) power wave} \end{cases}$$

$$|a_n|^2 = \frac{|V_{n+}|^2}{Z_{0n}} = |J_{n+}|^2 Z_{0n}$$

Simplest example: series impedance  $Z_S$

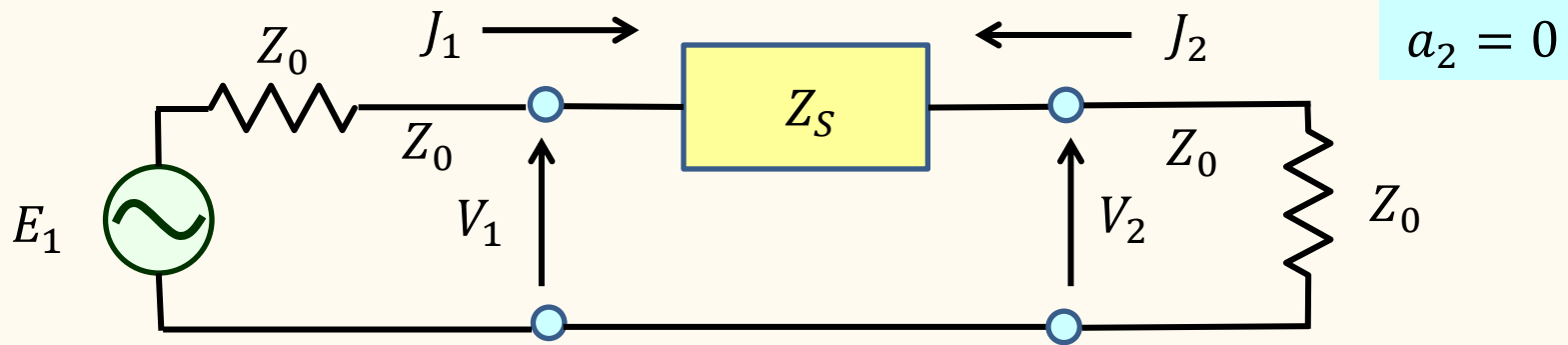
Take voltage as the “flow” quantity.  
(assume common characteristic impedance)





## 5.3 S-matrix (S-parameters)

$$\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \quad \begin{pmatrix} V_{1-} \\ V_{2-} \end{pmatrix} = \begin{pmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{pmatrix} \begin{pmatrix} V_{1+} \\ V_{2+} \end{pmatrix}$$

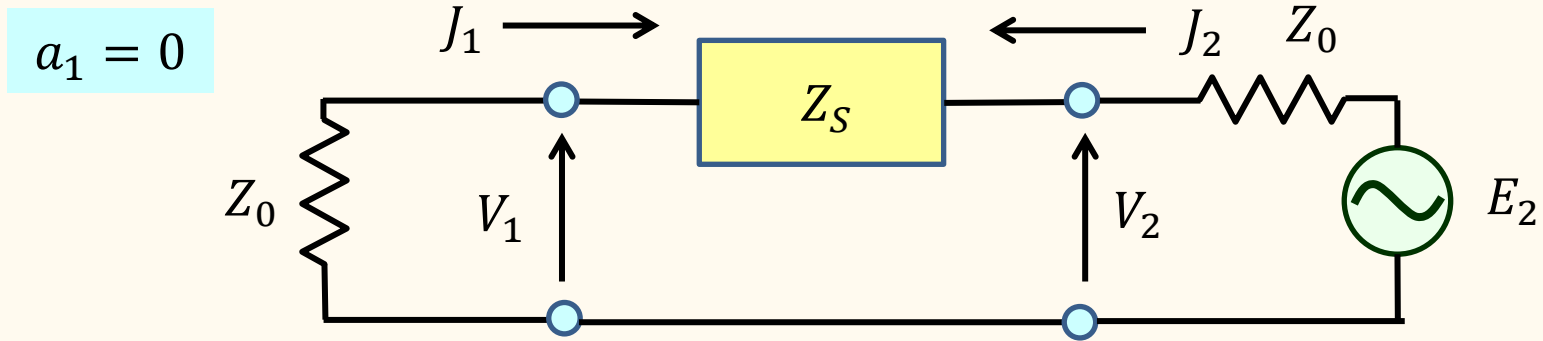


Terminate 2 with  $Z_0 \rightarrow a_2 = 0$

$$S_{11} = \frac{V_{1-}}{V_{1+}} = \frac{V_1 - Z_0 J_1}{V_1 + Z_0 J_1} = \frac{Z_1 - Z_0}{Z_1 + Z_0} = \frac{(Z_S + Z_0) - Z_0}{(Z_S + Z_0) + Z_0} = \frac{Z_S}{Z_S + 2Z_0}$$

$$S_{21} = \frac{V_{2-}}{V_{1+}} = \frac{V_2 - Z_0 J_2}{V_1 + Z_0 J_1} = \frac{Z_0 J_1 + Z_0 J_1}{(Z_S + Z_0) J_1 + Z_0 J_1} = \frac{2Z_0}{Z_S + 2Z_0} \quad (J_2 = -J_1)$$

## 5.3 S-matrix (S-parameters)



Terminate 1 with  $Z_0 \rightarrow a_1 = 0$  (should be symmetric)

$$S_{12} = \frac{2V_1}{V_2 + Z_0 J_2} = \frac{2Z_0 J_2}{(Z_S + Z_0)J_2 + Z_0 J_2} = \frac{2Z_0}{Z_S + 2Z_0}$$

$$S_{22} = \frac{Z_S}{Z_S + 2Z_0}$$

Generally

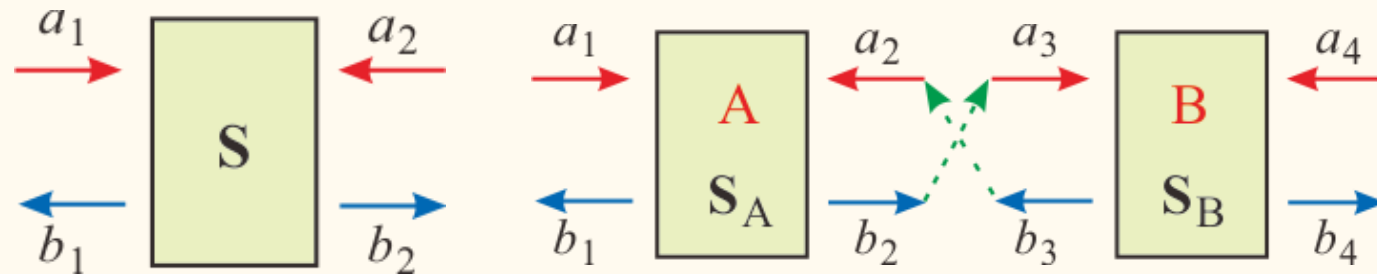
$$S = \frac{1}{\det Z} \times \begin{pmatrix} (Z_{11} - Z_0)(Z_{22} + Z_0) - Z_{12}Z_{21} & 2Z_0 Z_{12} \\ 2Z_0 Z_{21} & (Z_{11} + Z_0)(Z_{22} - Z_0) - Z_{12}Z_{21} \end{pmatrix}$$

# Cascade connection of S-matrices

$$\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \mathbf{S} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} r_L & t_R \\ t_L & r_R \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$r_{L,R}, t_{L,R}$ : complex reflection, transmission coefficients satisfying

$$T_{L,R} = |t_{L,r}|^2 = 1 - R_{L,R} = 1 - |r_{L,R}|^2$$



$$\mathbf{S}_{AB} = \begin{pmatrix} r_L^{AB} & t_R^{AB} \\ t_L^{AB} & r_R^{AB} \end{pmatrix} = \begin{pmatrix} r_L^A + t_R^A r_L^B (I - r_R^A r_L^B)^{-1} t_L^A & t_R^A (I - r_L^B r_R^A)^{-1} t_R^B \\ t_L^B (I - r_R^A r_L^B)^{-1} t_L^A & r_R^B + t_L^B (I - r_R^A r_L^B)^{-1} r_R^A t_R^B \end{pmatrix}$$

$$(I - r_R^A r_L^B)^{-1} = I + r_R^A r_L^B + (r_R^A r_L^B)^2 + \dots$$

# Conduction channels in quantum transport



Rolf Landauer

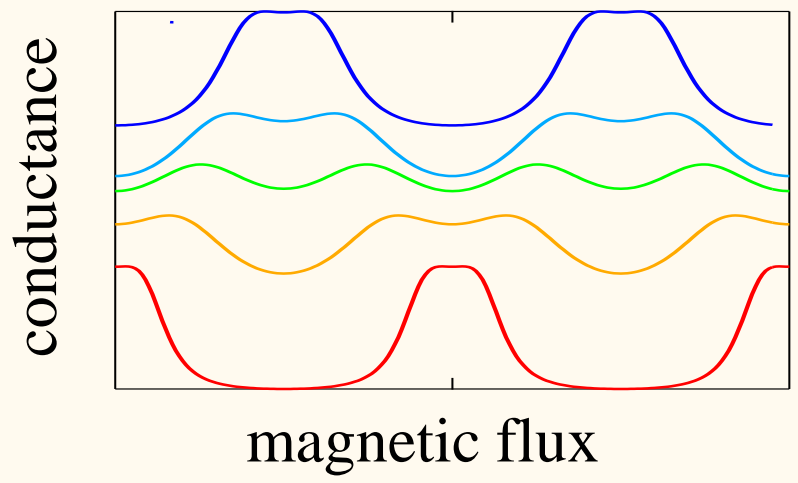
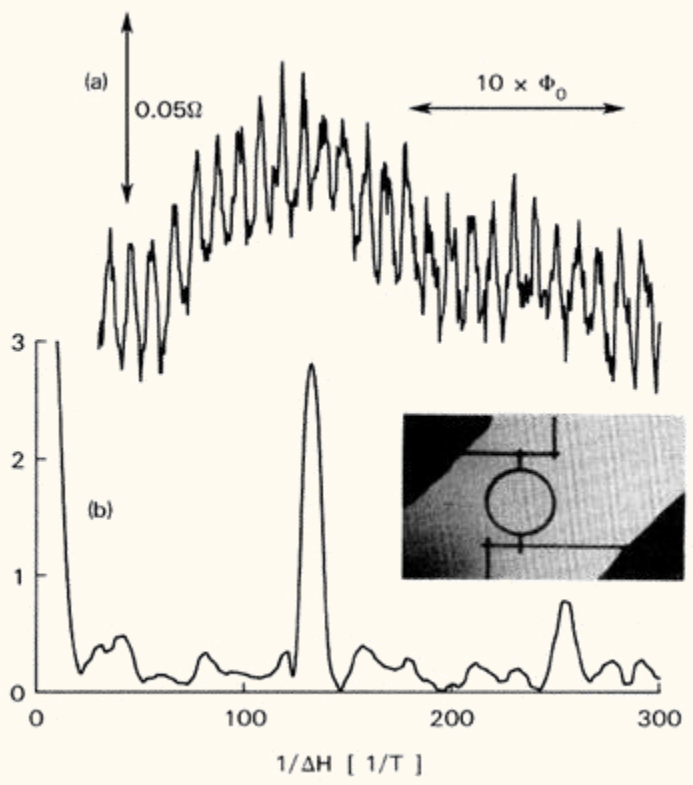
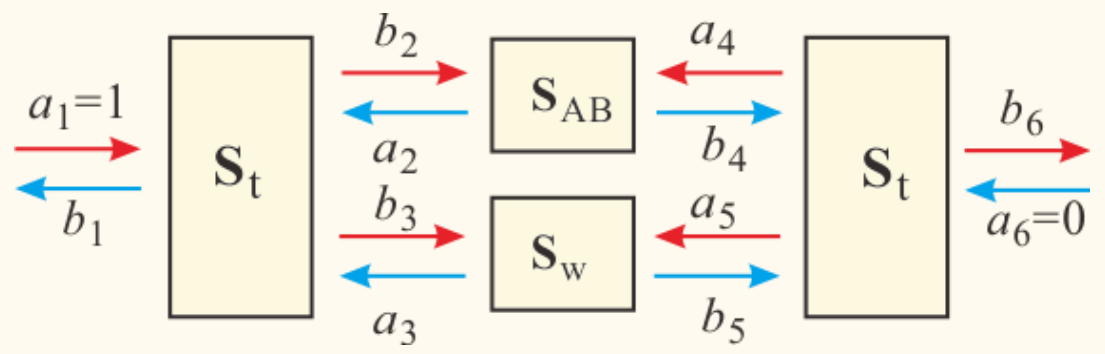
Electron (quantum mechanical) waves also have propagating modes in solids.

→ Conduction channel

Landauer eq.:

the conductance of a single perfect quantum channel is  $\frac{e^2}{h}$

AB ring S-matrix model



# S-parameter representation of high-frequency devices



**NEC**

DATA SHEET

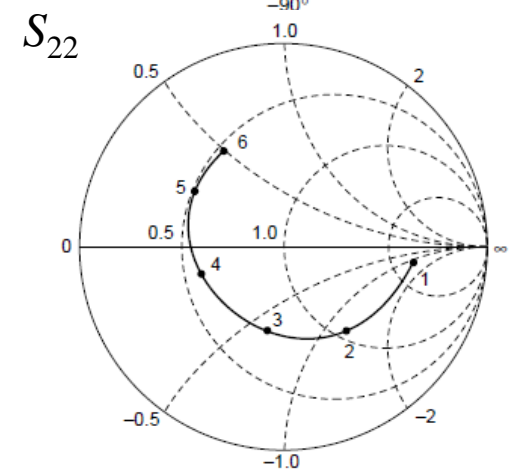
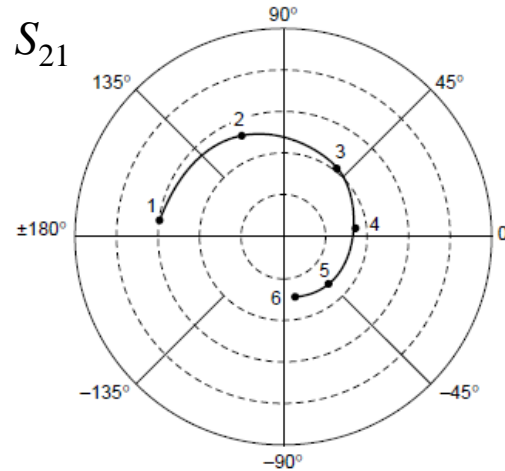
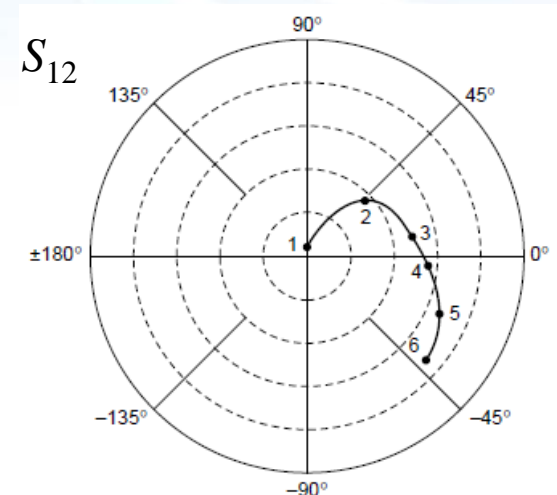
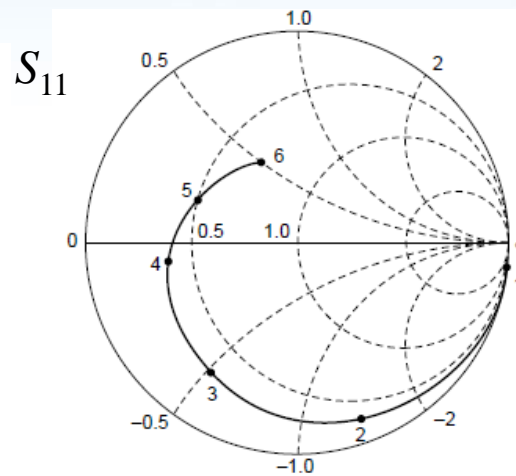
GaAs MES FET  
**NE76084**

C to Ku BAND LOW NOISE AMPLIFIER  
N-CHANNEL GaAs MES FET

## S-PARAMETERS

$V_{DS} = 3 \text{ V}$ ,  $I_D = 10 \text{ mA}$

START 500 MHz, STOP 18 GHz, STEP 500 MHz

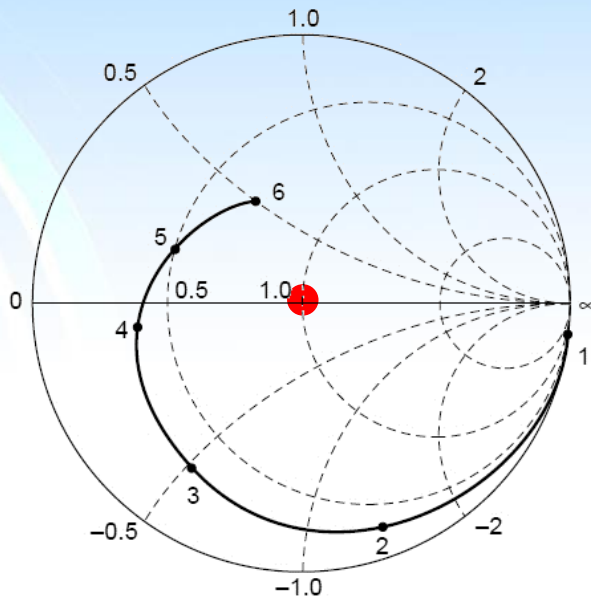


# S-parameter representation of high-frequency devices

Ex) NE76084 MES FET 0.5 ~ 18GHz



$S_{11}$



The datasheet tells that we need impedance matching circuits with transmission lines.

If we know Z-parameters:

From Ho-Thevenin theorem

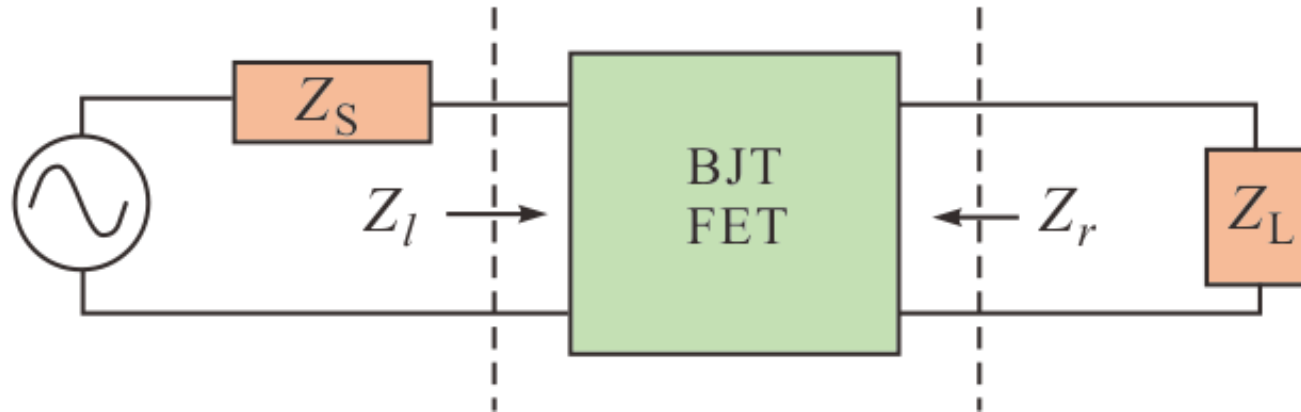
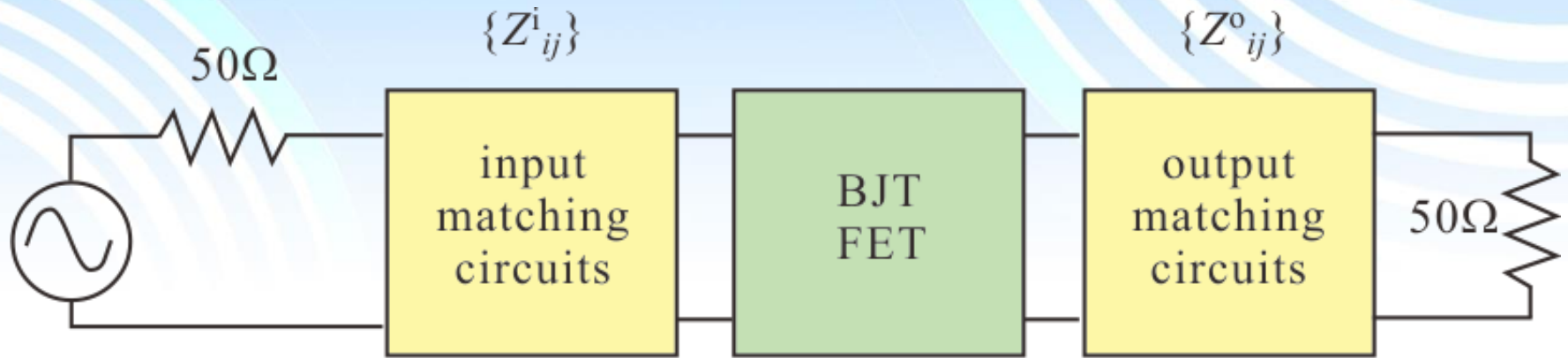
$$Z_S = Z_{22}^i - \frac{Z_{12}^i Z_{21}^i}{50 + Z_{11}^i}, \quad Z_L = Z_{11}^o - \frac{Z_{12}^o Z_{21}^o}{50 + Z_{22}^o}$$

$\{Z_{ij}\}$  : BJT (FET) Z-parameters, again Ho-Thevenin says

$$Z_l = Z_{11} - \frac{Z_{12} Z_{21}}{Z_L + Z_{22}}, \quad Z_r = Z_{22} - \frac{Z_{12} Z_{21}}{Z_S + Z_{11}}$$



# S-parameter representation of high-frequency devices



# Impedance matching with S-parameters

Generally the unitarity does not hold for amplification.

$$R_{\text{in}} = S_{11} + \frac{S_{12}S_{21}R_L}{1 - S_{22}R_L} \quad R_{\text{out}} = S_{22} + \frac{S_{12}S_{21}R_S}{1 - S_{11}R_S}$$

Matching condition:  $R_L = R_{\text{out}}^*$ ,  $R_S = R_{\text{in}}^*$

Solution  $R_S = \frac{B_1 \pm \sqrt{B_1^2 - 4|M|^2}}{2M}$ ,  $R_L = \frac{B_2 \pm \sqrt{B_2^2 - 4|N|^2}}{2N}$  with

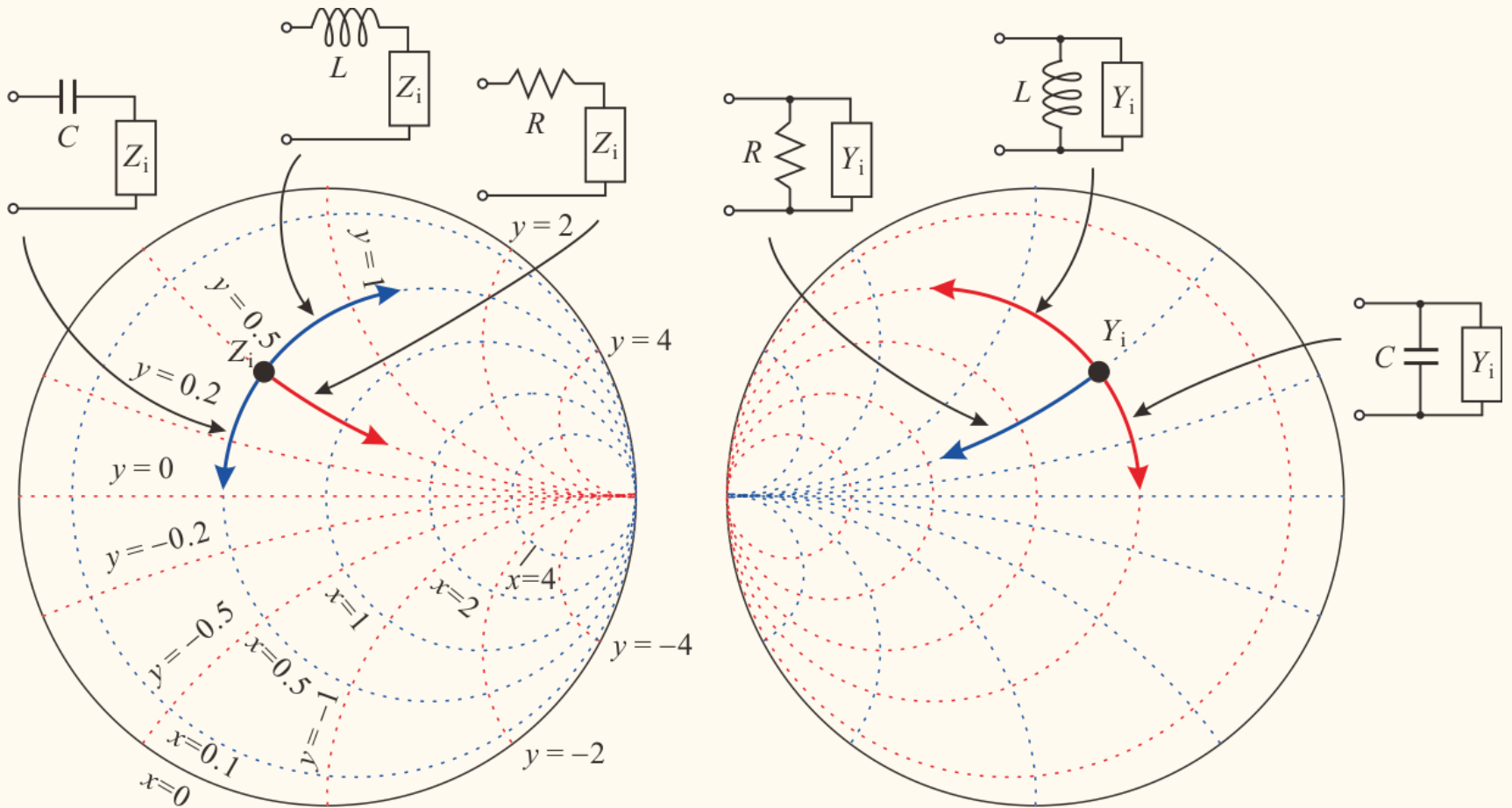
$$B_1 = 1 + |S_{11}|^2 - |S_{22}|^2 - |\det S|^2, \quad B_2 = 1 - |S_{11}|^2 + |S_{22}|^2 - |\det S|^2,$$

$$N = S_{22} - S_{11}^* \det S, \quad M = S_{11} - S_{22}^* \det S$$

maximum available power gain  $G_{\text{max}} = \left| \frac{S_{21}}{S_{12}} \right| (K - \sqrt{K^2 - 1})$

$$K = \frac{1 + |\det S|^2 - |S_{11}|^2 - |S_{22}|^2}{2|S_{12}S_{21}|} \quad \text{stability factor}$$

# Practical impedance matching with Simth chart

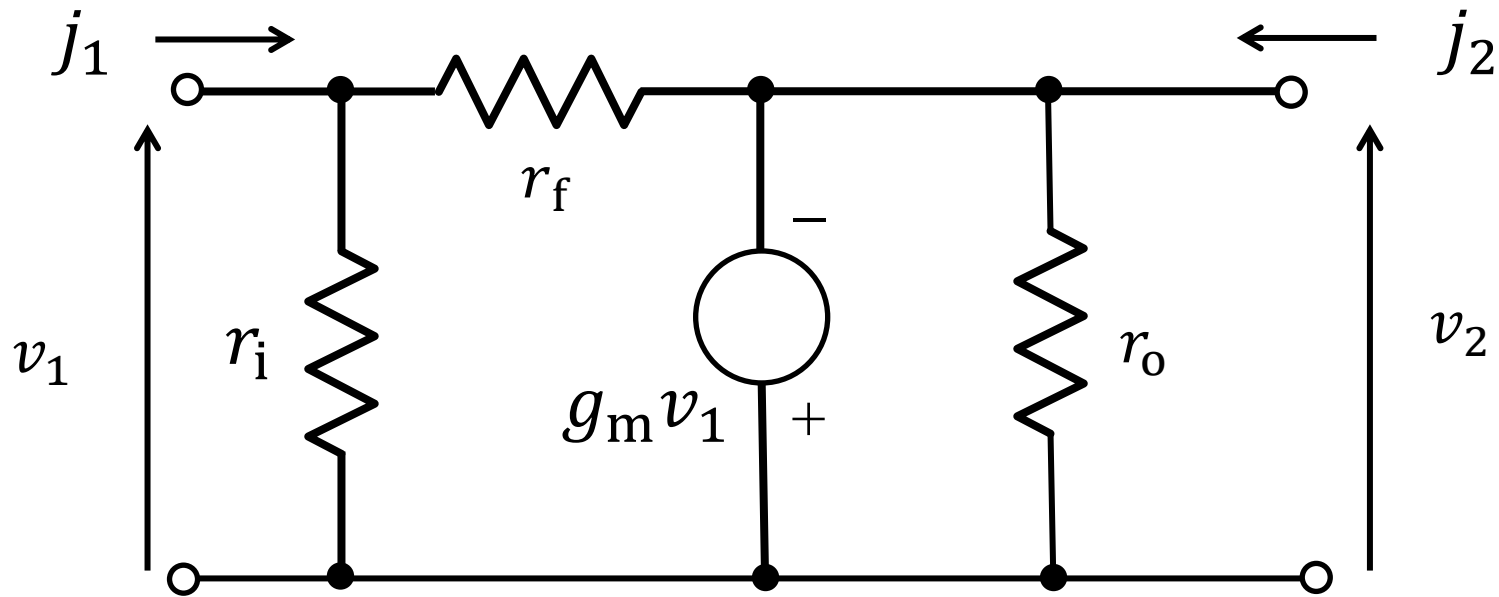


# Impedance matching designer

<http://home.sandiego.edu/~ekim/e194rfs01/jwmatcher/matcher2.html>

[http://leleivre.com/rf\\_lcmatch.html](http://leleivre.com/rf_lcmatch.html)

# Exercise D-1



Obtain the Y matrix for the above equivalent circuit ( $\pi$ -shape circuit).

## Exercise D-2

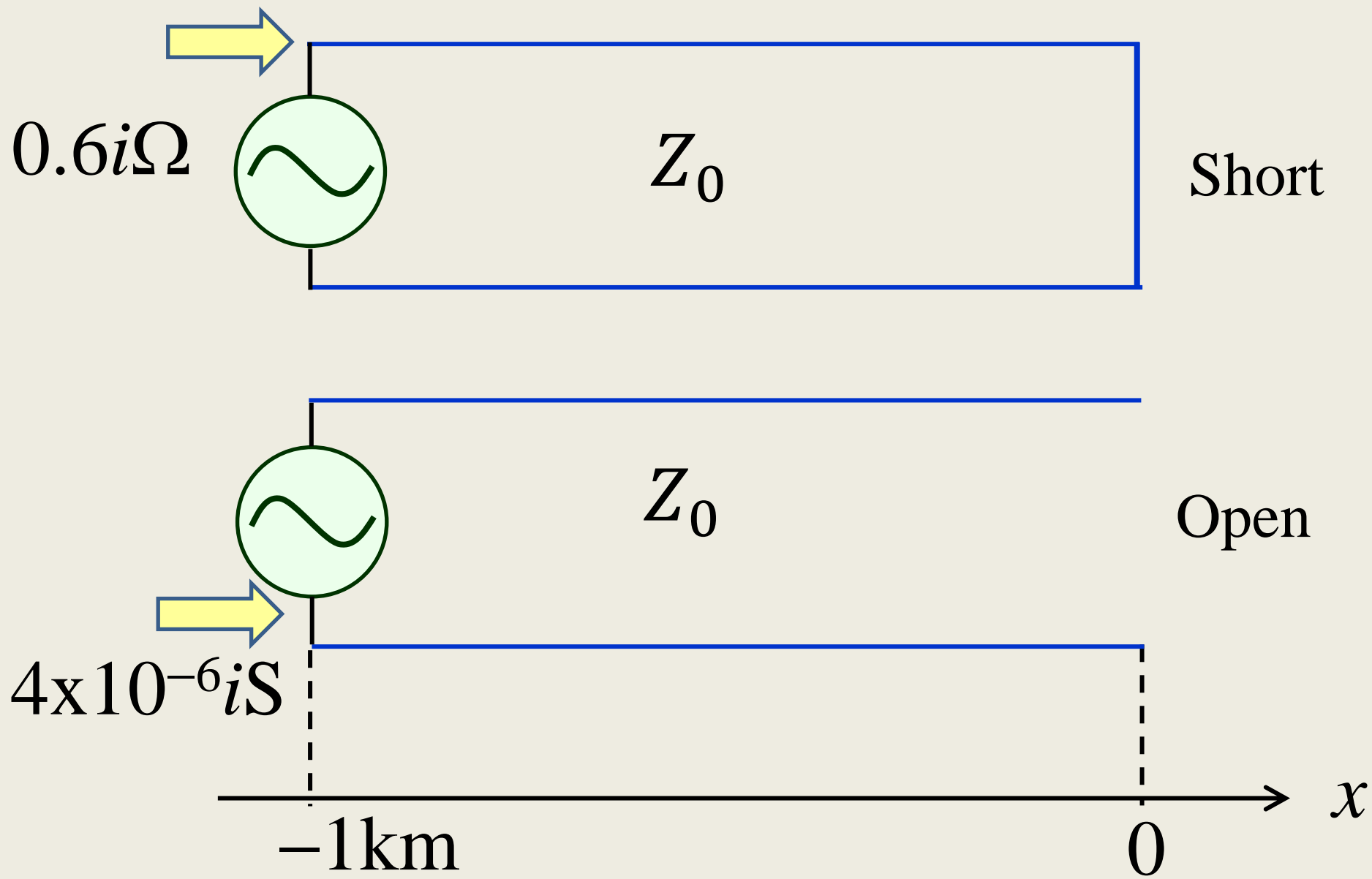
$l=1\text{km}$  の伝送線路がある。終端側を短絡したところ、電源側から測定したインピダンスは  $0.6i \Omega$  であった。一方、終端側を開放して電源側からアドミタンスを測定すると  $4 \times 10^{-6}i \text{ S}$  であった。  
この伝送線路の特性インピダンスを求めよ。

Consider a transmission line with the length  $l = 1\text{km}$ . First we short-circuited the end and measured the impedance from the signal source and obtained  $0.6i \Omega$ . Next we opened the end and measured the admittance from the signal source and obtained  $4 \times 10^{-6}i \text{ S}$ .

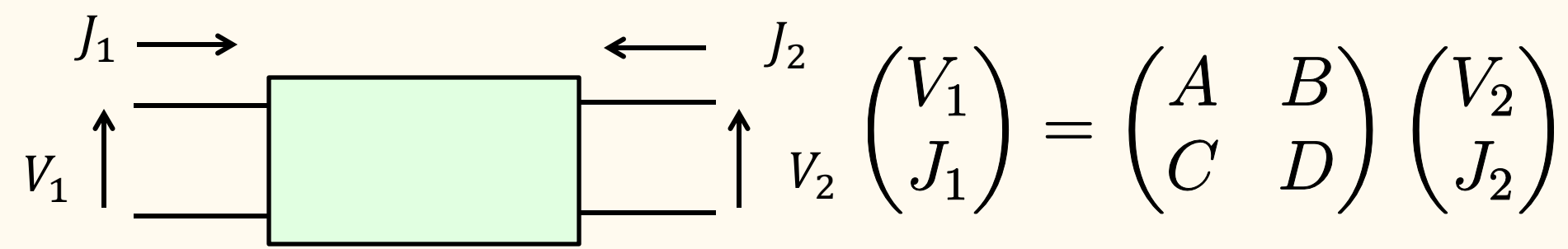
What is the characteristic impedance of the transmission line?



# Exercise D-2

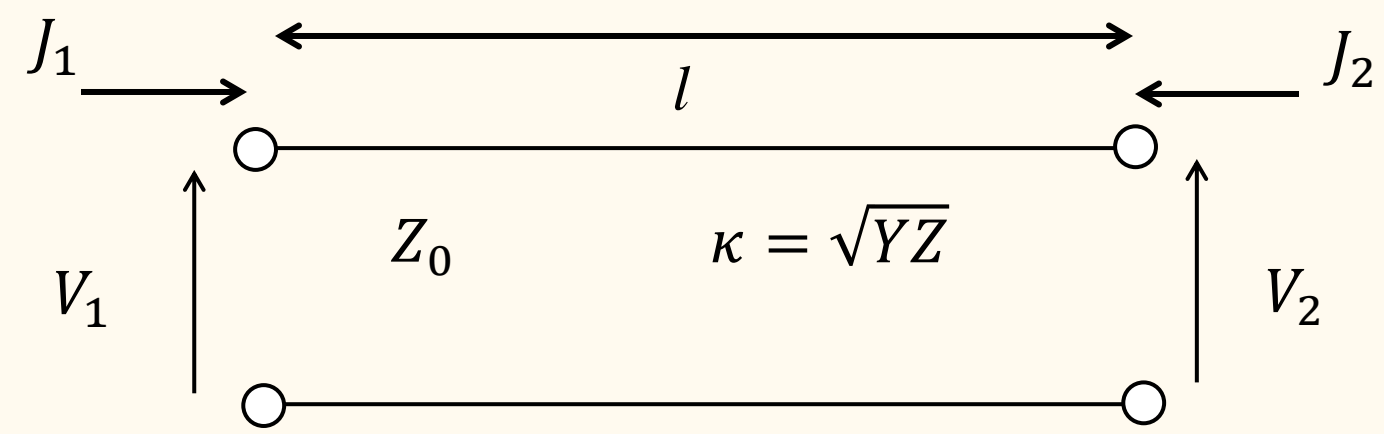


# Exercise D-3



Remember F-matrix (cascade matrix) defined above.

Write down the F-matrix form of the transmission line shown below.

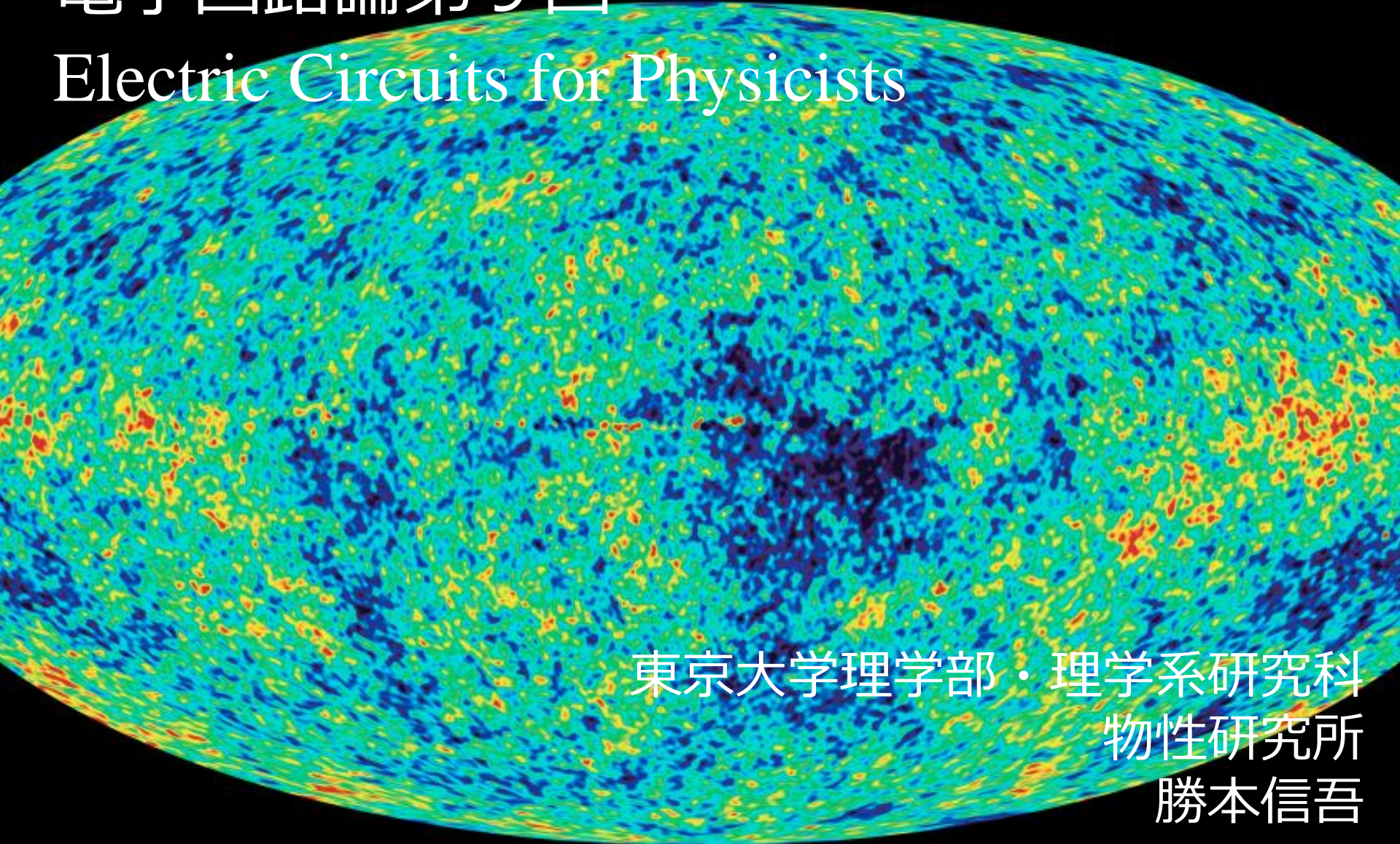


# 電子回路論第 9 回

## Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto







# Outline

## 5.3 S-parameter representation of devices

Impedance matching with  $Z$ ,  $S$  parameters

Impedance matching with immittance chart

## 5.4 Non-TEM mode transmission lines

## 5.5 Non-linear elements and Toda lattice

## Ch.6 Noises and Signals

### 6.1 Fluctuations

### 6.2 Fluctuation-dissipation theorem

# Review: Scattering (S) matrix (S parameters)

Transmission lines: wave propagating modes  $\rightarrow$  Channels

Take  $|a_i|^2$ ,  $|b_i|^2$  to be powers (energy flow).

output

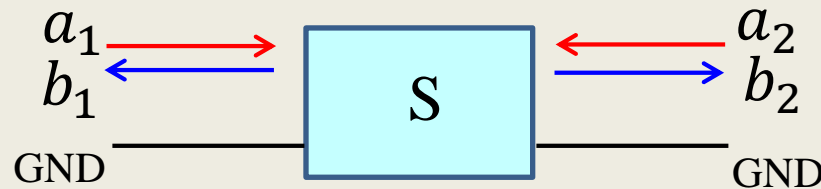
S-matrix

input

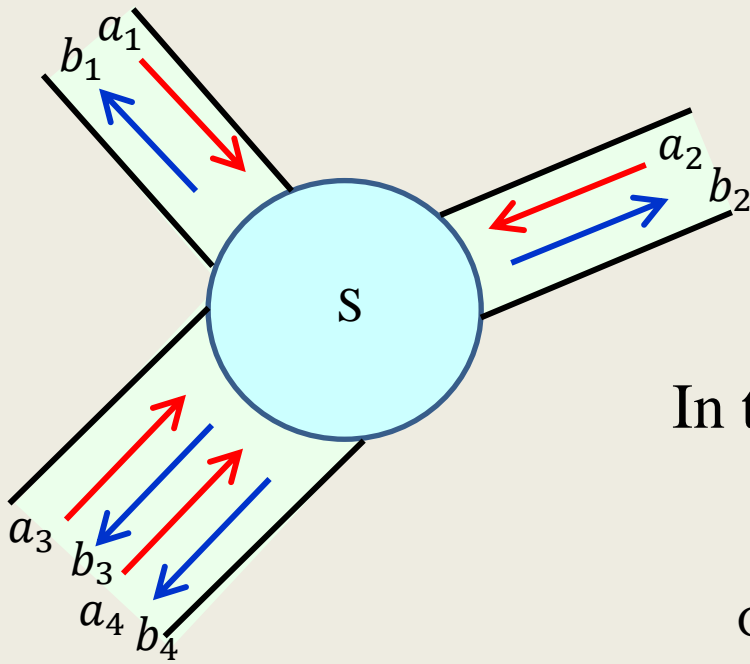
$$\begin{pmatrix} b_1 \\ \vdots \\ b_i \\ \vdots \\ b_n \end{pmatrix} = \begin{pmatrix} S_{11} & \cdots & S_{1i} & \cdots & S_{1n} \\ \vdots & \ddots & \vdots & & \vdots \\ S_{i1} & & S_{ii} & & S_{in} \\ \vdots & & \vdots & \ddots & \vdots \\ S_{n1} & \cdots & S_{ni} & \cdots & S_{nn} \end{pmatrix} \begin{pmatrix} a_1 \\ \vdots \\ a_i \\ \vdots \\ a_n \end{pmatrix}$$

$$\mathbf{b} = \mathbf{S}\mathbf{a}$$

In the case of two-terminal pair circuit



$$\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} r_1 & t_r \\ t_1 & r_r \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$





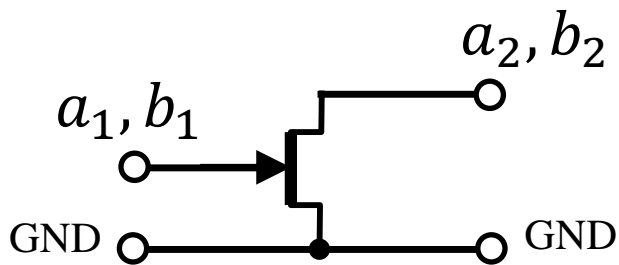
# S-parameter representation of high-frequency devices



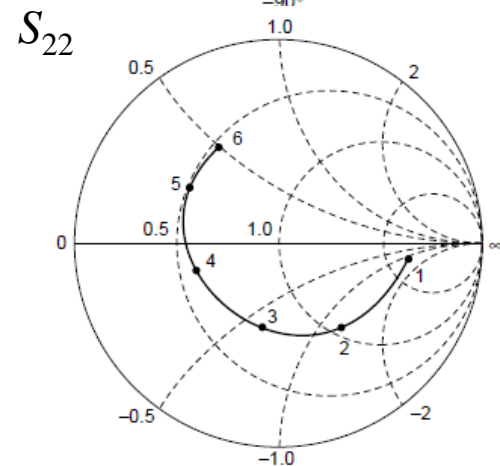
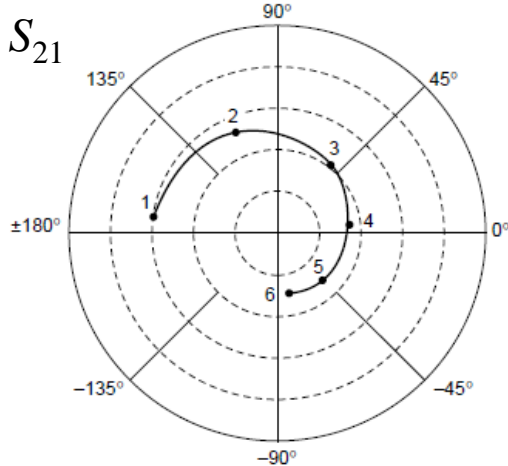
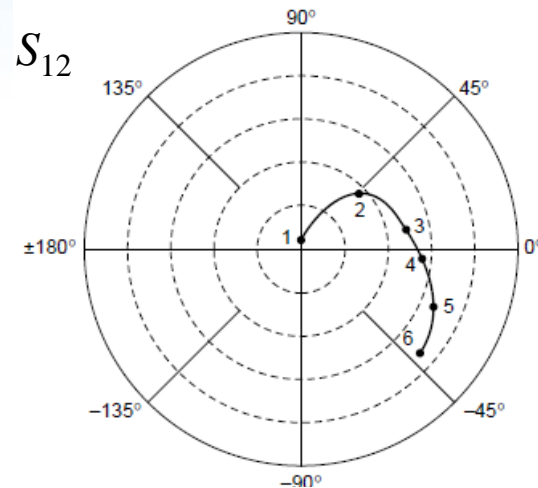
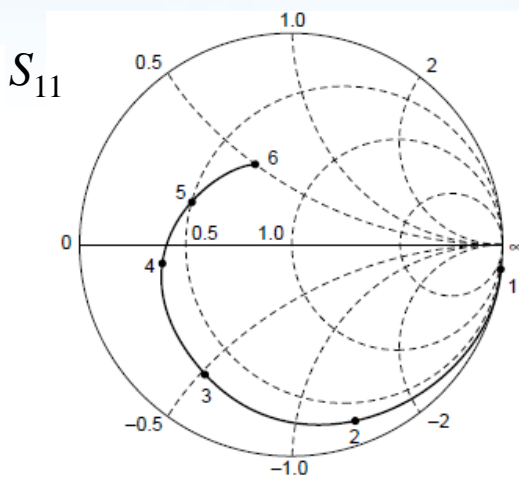
<b>NEC</b>	<b>DATA SHEET</b>
<b>GaAs MES FET</b> <b>NE76084</b>	
<b>C to Ku BAND LOW NOISE AMPLIFIER</b> <b>N-CHANNEL GaAs MES FET</b>	

## S-PARAMETERS

$V_{DS} = 3\text{ V}$ ,  $I_D = 10\text{ mA}$   
 START 500 MHz, STOP 18 GHz, STEP 500 MHz



$$S_{11} = r_l, S_{22} = r_r$$

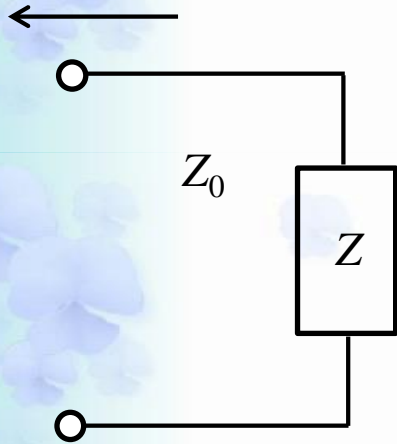


# Review: Smith Chart

P.H. Smith  
1905-1987

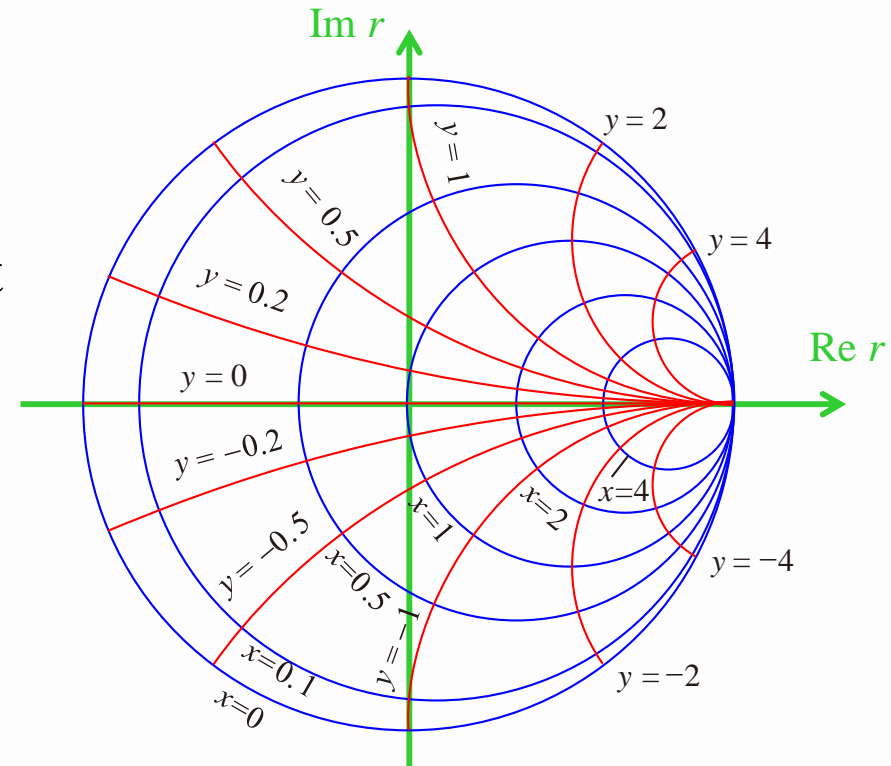
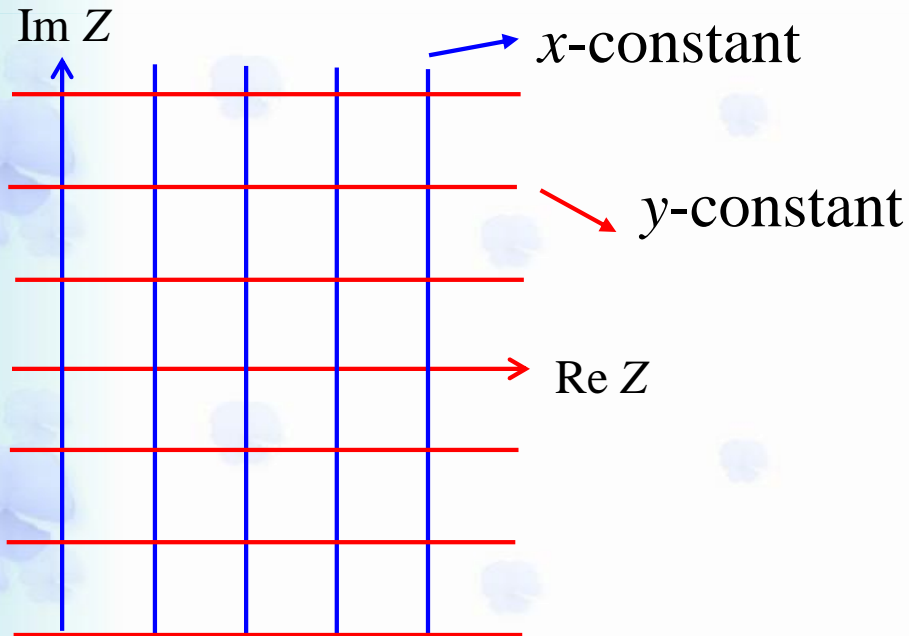


$r$  : reflection coefficient



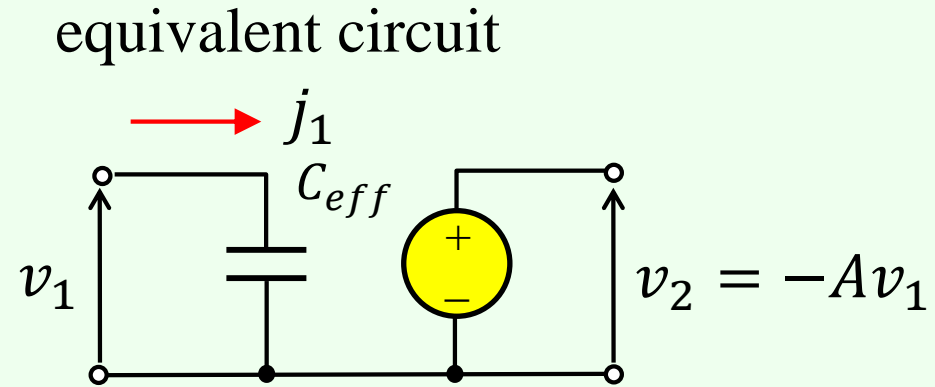
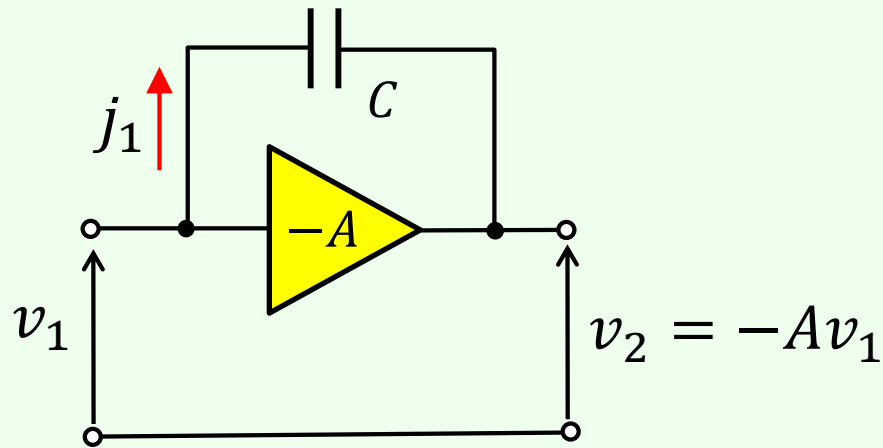
$$r = \frac{V_-}{V_+} = \frac{Z - Z_0}{Z + Z_0} = \frac{z - 1}{z + 1}$$

$$z = \frac{Z}{Z_0} = x + iy$$



# Comment: Mirror effect

An amplifier may change the effective impedance of passive elements.



$$j_1 = sC(v_1 - v_2) = sC(1 + A)v_1$$

$$s = \frac{j_1}{(1 + A)Cv_1}$$

$$C_{eff} \frac{dv_1}{dt} = sC_{eff}v_1 = j_1$$

$$s = \frac{1}{C_{eff}} \frac{j_1}{v_1}$$

$$C_{eff} = (1 + A)C$$

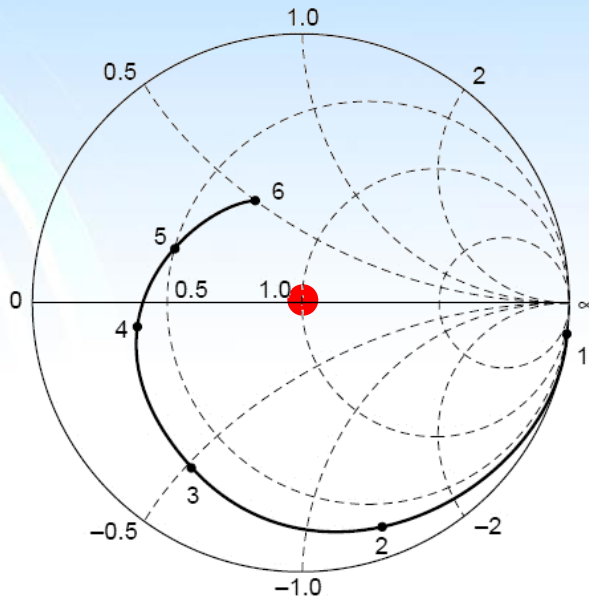
: mirror effect

# S-parameter representation of high-frequency devices

Ex) NE76084 MES FET 0.5 ~ 18GHz

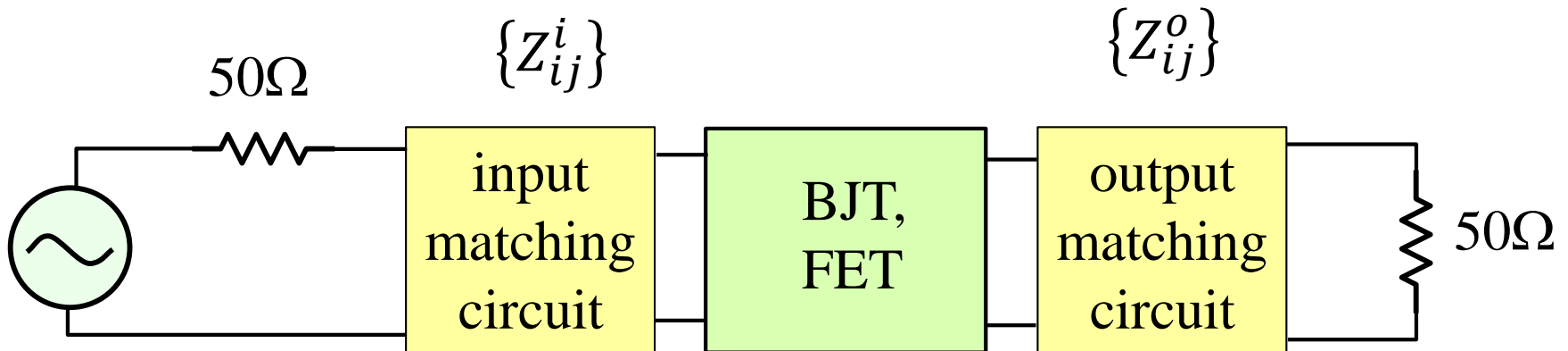


$S_{11}$



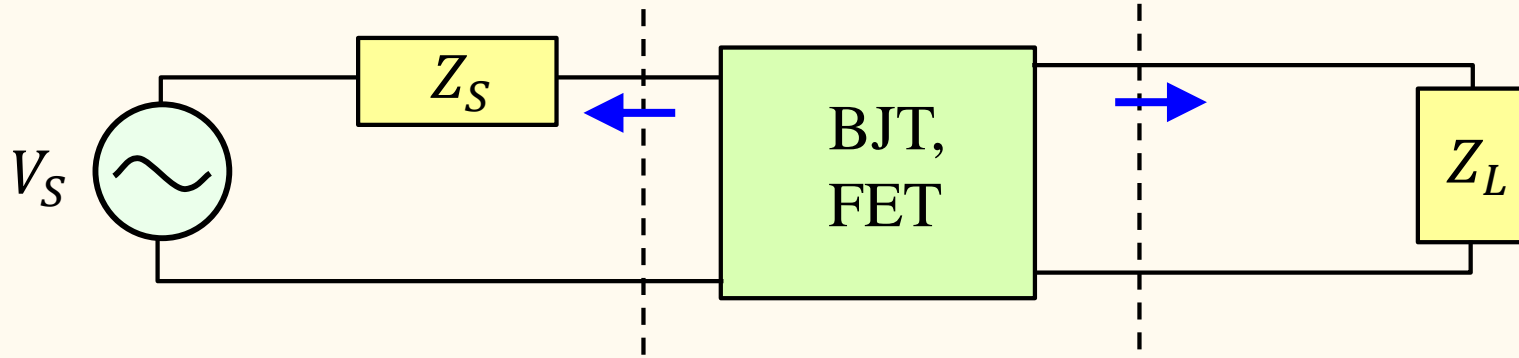
The datasheet tells that we need impedance matching circuits with transmission lines with  $Z_0 = 50 \Omega$ .

Insert input and output matching circuits to kill reflections.



# Impedance matching circuits

The circuit is summarized at the boundaries as

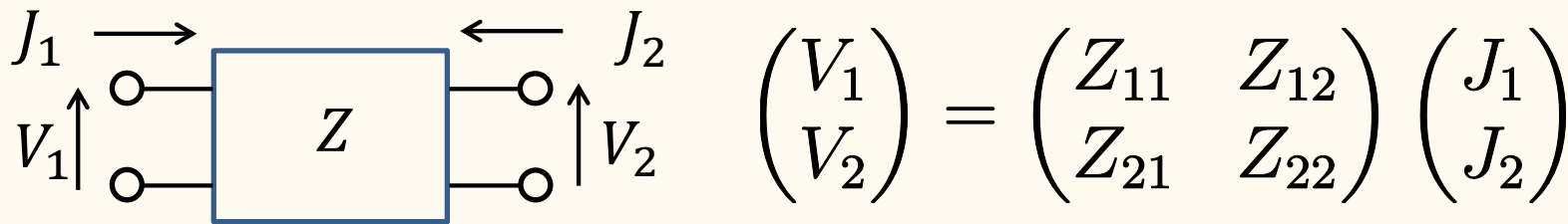


If we know Z-parameters of the input/output matching circuits, from Ho-Thevenin's theorem

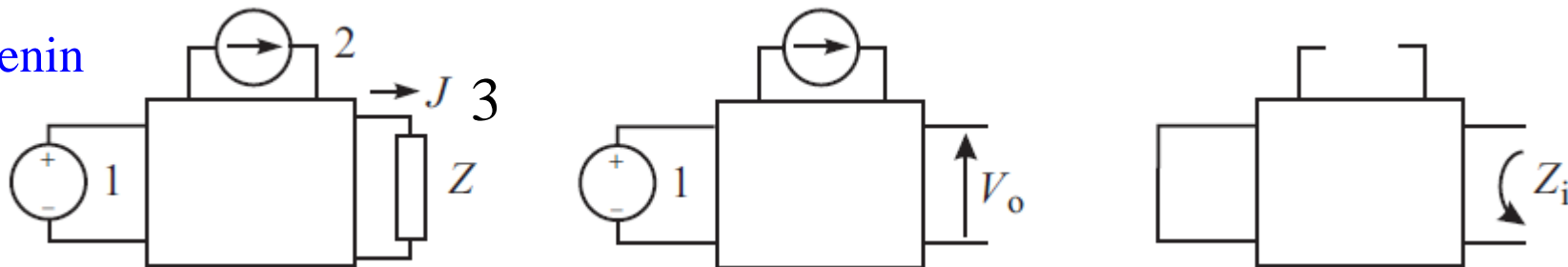
$$Z_S = Z_{22}^i - \frac{Z_{12}^i Z_{21}^i}{50 + Z_{11}^i}, \quad Z_L = Z_{11}^o - \frac{Z_{12}^o Z_{21}^o}{50 + Z_{22}^o}.$$

# Z-matrix, Ho-Thevenin's theorem

Z-matrix



Ho-Thevenin



1. Measure the open terminal voltage  $V_0$ .
2. Turn off all the power sources (voltage sources: short, current sources: open). Measure the open circuit impedance  $Z_i$ .

Then

$$J = \frac{V_0}{Z + Z_i}$$

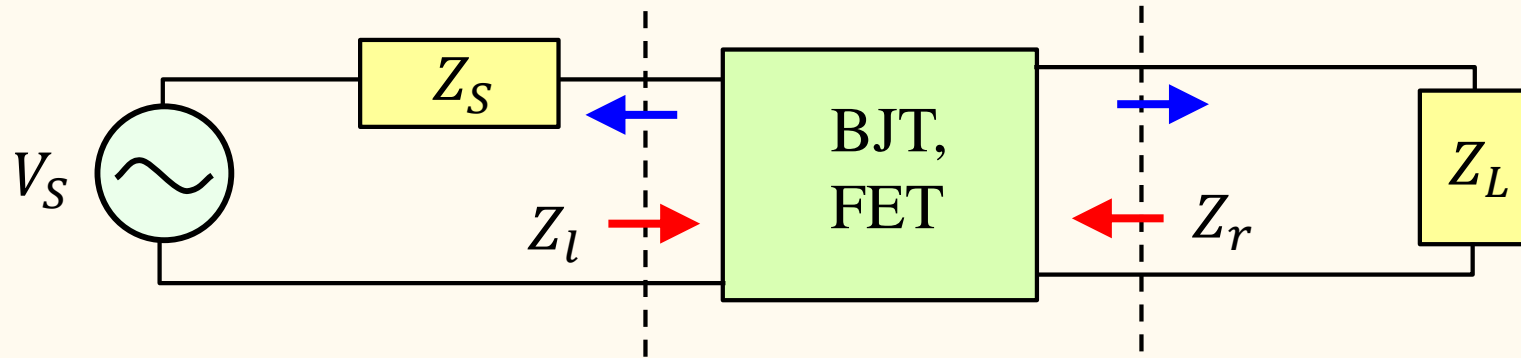
$$V_s = 0 \quad \therefore V_1 = -50J_1 = Z_{11}J_1 + Z_{12}J_2 \quad \therefore J_1 = -\frac{Z_{12}}{50 + Z_{11}}J_2$$

$$V_2 = Z_{21}J_1 + Z_{22}J_2 = \left( Z_{22} - \frac{Z_{21}Z_{12}}{50 + Z_{11}} \right) J_2 \rightarrow Z_S$$



# Impedance matching circuits

The circuit is summarized at the boundaries as



If we know Z-parameters of the input/output matching circuits, from Ho-Thevenin's theorem

$$Z_S = Z_{22}^i - \frac{Z_{12}^i Z_{21}^i}{50 + Z_{11}^i}, \quad Z_L = Z_{11}^o - \frac{Z_{12}^o Z_{21}^o}{50 + Z_{22}^o}.$$

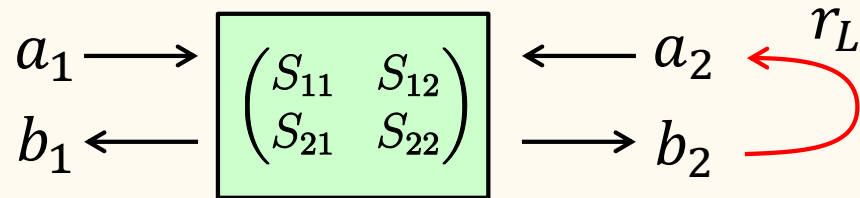
$\{Z_{ij}\}$  : BJT (FET) Z-parameters, again Ho-Thevenin says

$$Z_l = Z_{11} - \frac{Z_{12} Z_{21}}{Z_L + Z_{22}}, \quad Z_r = Z_{22} - \frac{Z_{12} Z_{21}}{Z_S + Z_{11}}$$

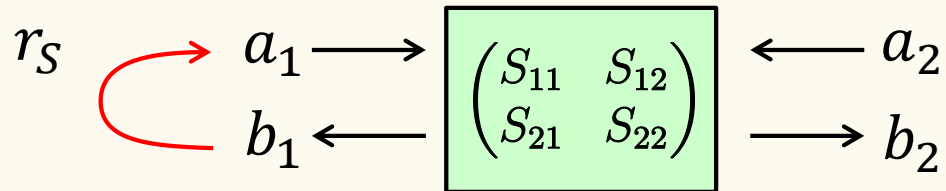
matching condition:  $Z_l = Z_S^*$ ,  $Z_r = Z_L^*$

# Impedance matching with S-parameters

In S-parameter treatment, we use complex reflection coefficients to express load, source etc.



$$r_{\text{in}} = \frac{b_1}{a_1} = S_{11} + \frac{S_{12}S_{21}r_L}{1 - S_{22}r_L}$$



$$r_{\text{out}} = \frac{b_2}{a_2} = S_{22} + \frac{S_{12}S_{21}r_S}{1 - S_{11}r_S}$$

Matching condition:  $r_L = r_{\text{out}}^*$ ,  $r_S = r_{\text{in}}^*$

Solution

$$r_S = \frac{B_1 \pm \sqrt{B_1^2 - 4|M|^2}}{2M}, \quad r_L = \frac{B_2 \pm \sqrt{B_2^2 - 4|N|^2}}{2N}$$

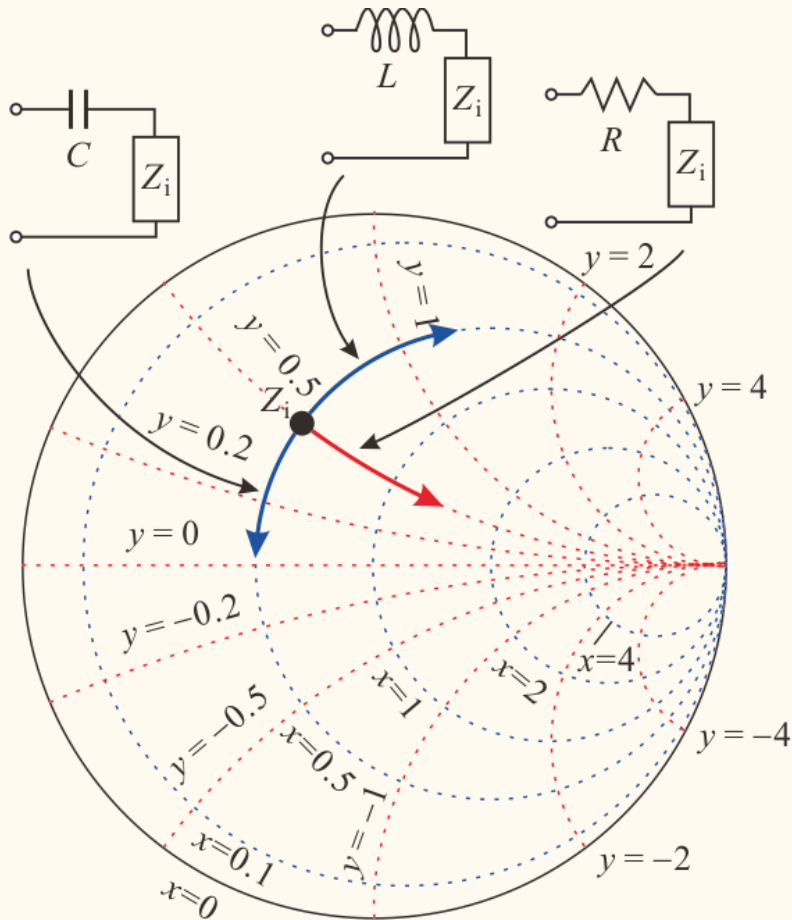
with

$$B_1 = 1 + |S_{11}|^2 - |S_{22}|^2 - |\det S|^2, \quad B_2 = 1 - |S_{11}|^2 + |S_{22}|^2 - |\det S|^2,$$

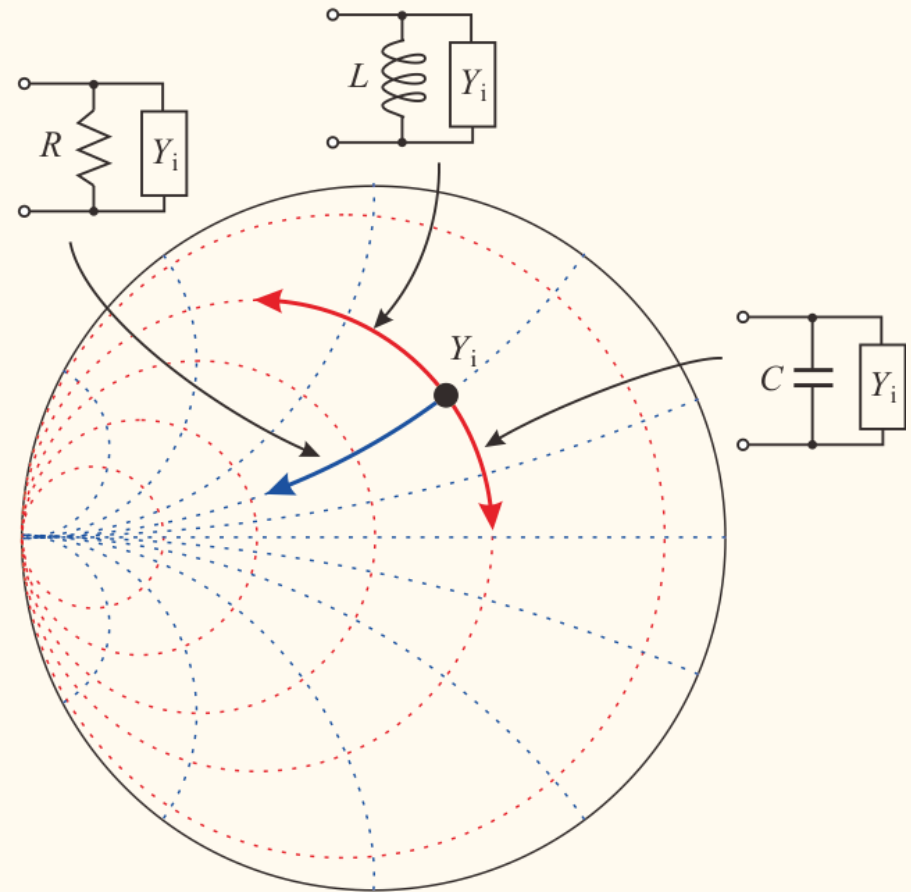
$$N = S_{22} - S_{11}^* \det S, \quad M = S_{11} - S_{22}^* \det S$$

# Practical impedance matching with Smith chart

Series and parallel connection of passive elements and traces on charts



Smith chart



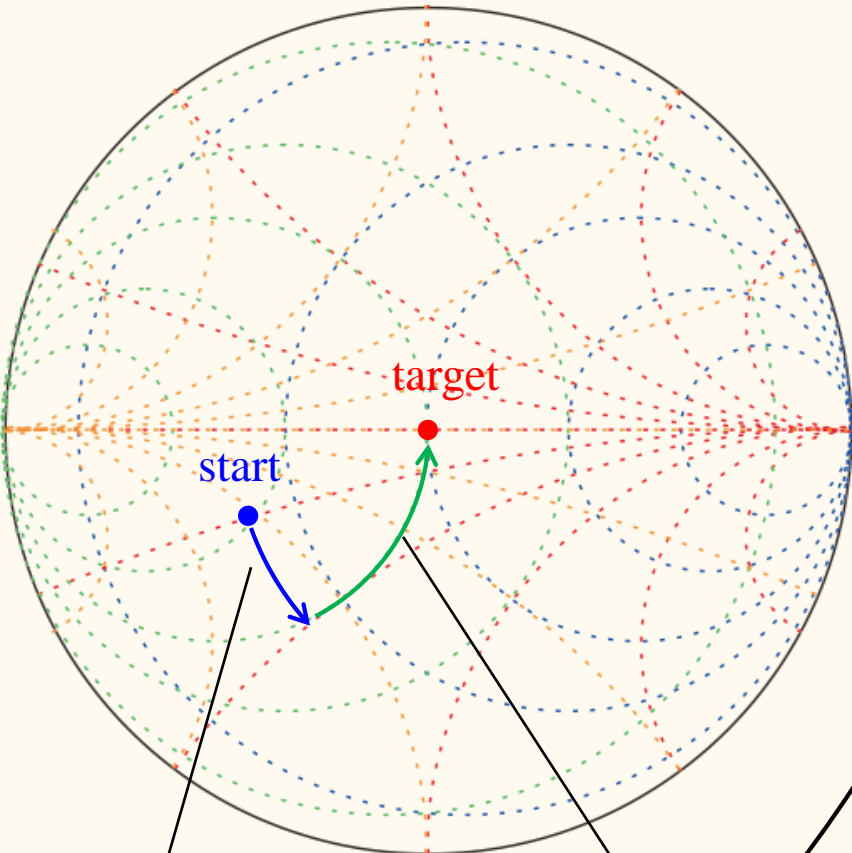
Admittance chart

# An example of impedance matching

frequency 100 MHz  $\approx$  628 Mrad/s

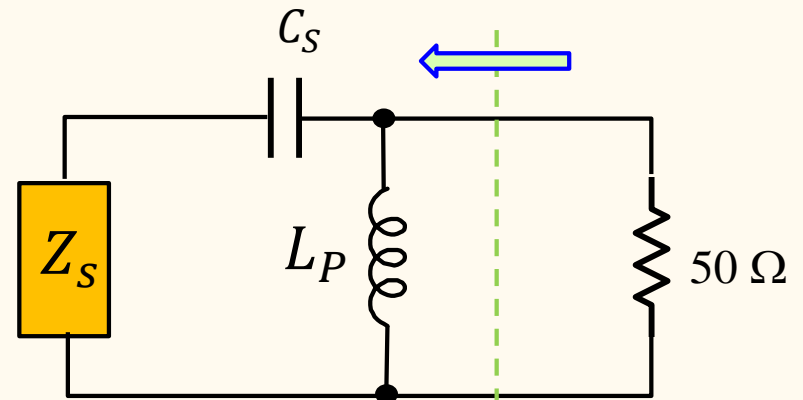
immittance chart

Im  $r$   $\uparrow$



Re[Z]=0.4

Re[Y]=1



$$Z_s = 20 - 10i \quad (\Omega)$$

$$= 0.4 - 0.2i \quad (Z_0)$$

$$\text{equalize: } 0.4 + iy = \frac{1}{1 + iq}$$

$$y = -\sqrt{0.24} \approx -0.49$$

$$-0.49 = -0.2 - \frac{1}{\omega C_S Z_0}$$

$$C_S \approx \frac{1}{2\pi \times 10^6 \times 50 \times 0.29} \approx 110 \text{ pF}$$

similarly

$$L_P \approx 65 \text{ nH}$$

# Impedance matching designer

<http://home.sandiego.edu/~ekim/e194rfs01/jwmatcher/matcher2.html>

[http://leleivre.com/rf\\_lcmatch.html](http://leleivre.com/rf_lcmatch.html)

# Useful freeware: Smith v4.0

<http://fritz.dellsperger.net/smith.html>

Navigation menu:

- Home
- Personal
- Smith Chart
- Downloads
- Links

Header: Fritz Dellsperger

## Smith-Chart Software and Related Documents

**NEW Software Smith V4.0**

[Smith V4.0](#) 6'664kB exe **Computer Smith-Chart Tool** and S-Parameter Plot, Setup Smith V4.0.exe 11.2016

### 1. Smith-Chart Diagram

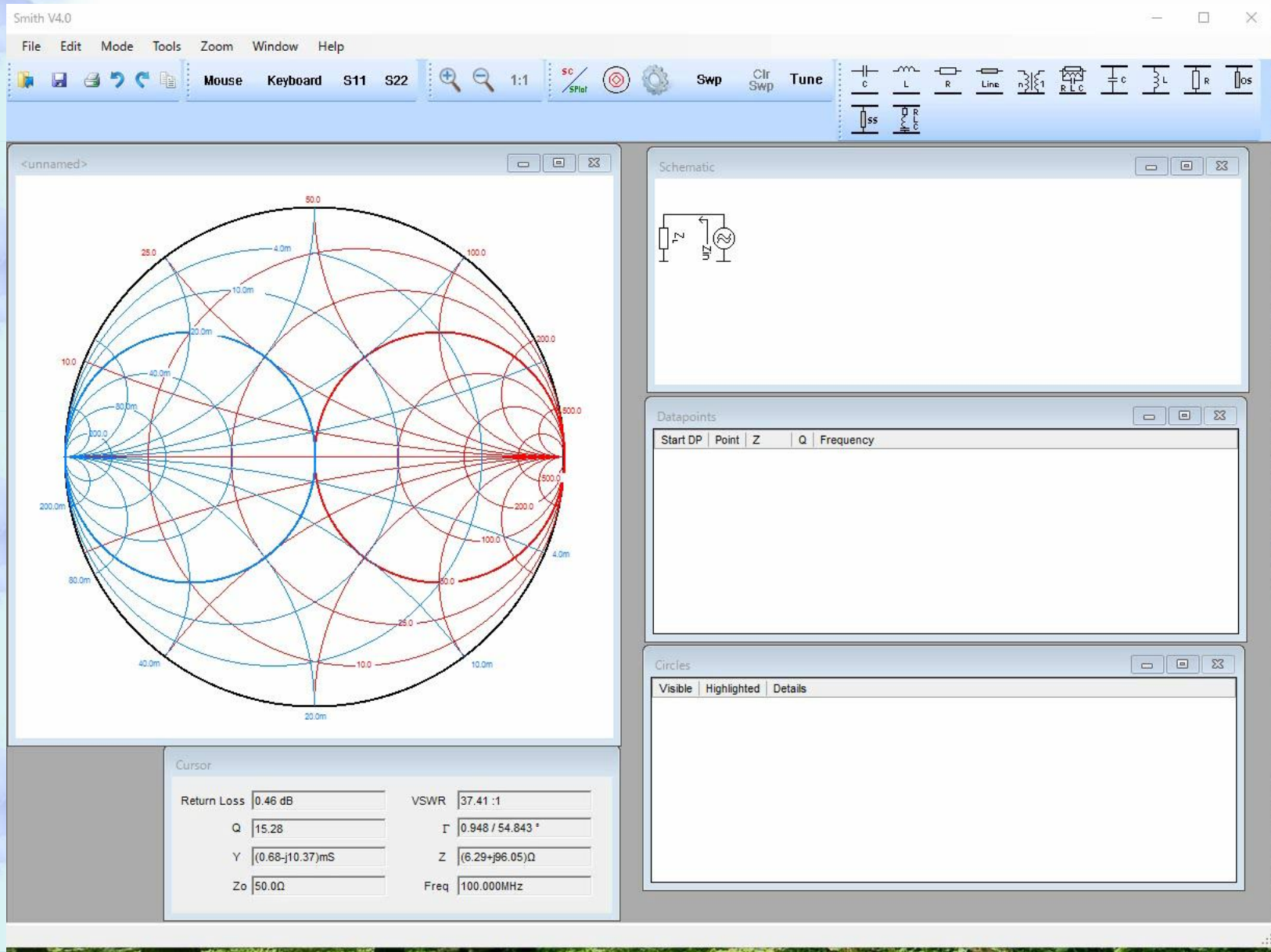
- Matching ladder networks with capacitors, inductors, resistors, serie and parallel RLC, transformers, serie lines and open or shorted stubs
- Free settable normalisation impedance for the Smith chart
- Circles and contours for stability, noise figure, gain, VSWR and Q
- Edit element values after insertion
- Tune element values using sliders (Tuning Cockpit) **NEW**
- Sweep versus frequency or datapoints
- Serial transmission line with loss
- Export datapoint and circle info to ASCII-file for post-processing in spreadsheets or math software
- Import datapoints from S-parameter files (Touchstone, CITI, EZNEC)
- Undo- und Redo-Function
- Save and load designs (licensed version only)
- Save netlist (licensed version only)
- Print Smith-Chart, schematic, datapoints, circle info and S-Plot graphs
- Copy to clipboard for documentation purposes
- Settings for color and line widths for all graphs

### 2. S-Plot

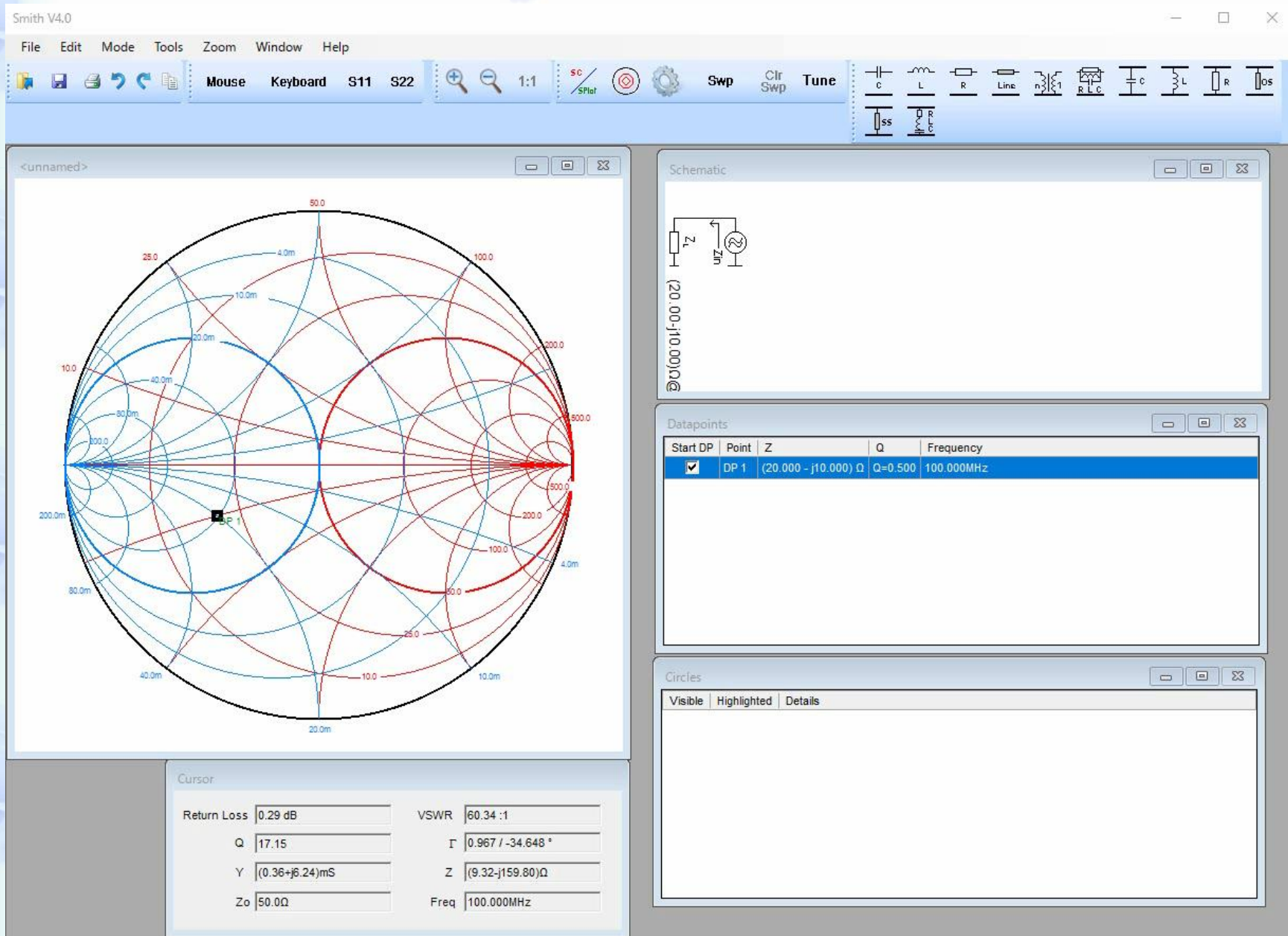
- Read S-Parameter - Files in Touchstone@-, CITI- and EZNEC-Format
- Graphical display of s11, s12, s21 and s22
- Graphical display and listing of MAG (maximum operating power gain), MSG (maximum stable gain), stability factor k and u and returnloss
- Linear or logarithmic frequency axis



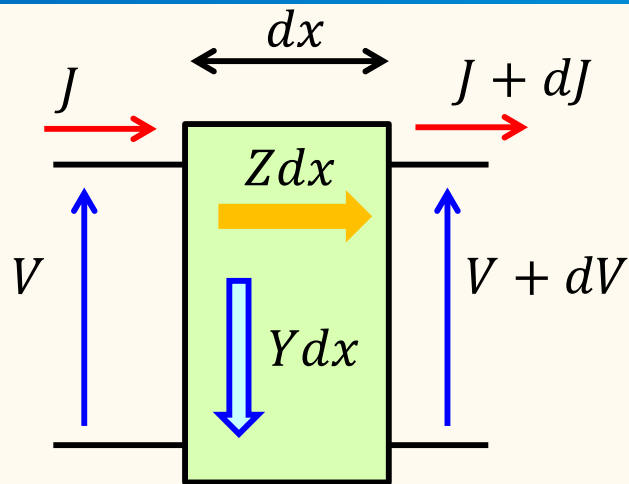
# Impedance matching with Smith V4 (1)



# Impedance matching with Smith V4 (2)



## 5.4 Non-TEM mode transmission line



$$\frac{V}{J} = \mp \frac{Z}{\kappa} = \mp \sqrt{\frac{Z}{Y}}$$

Characteristic impedance

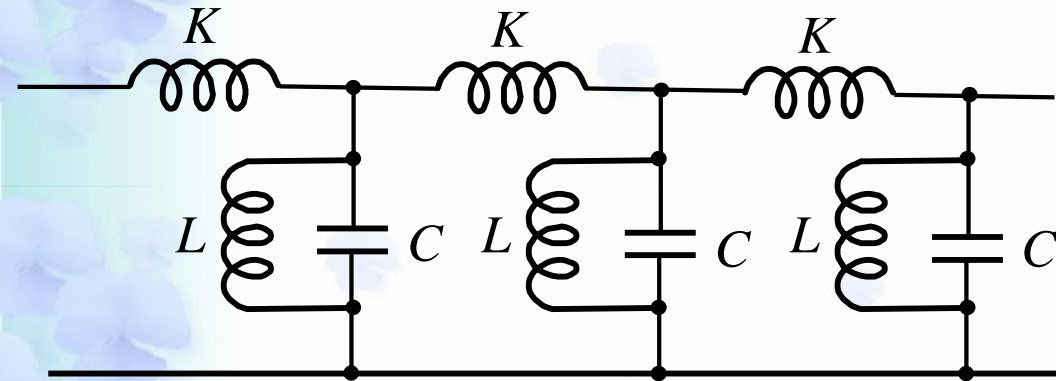
$$\text{LC model: } Z = i\omega L, \quad Y = i\omega C$$

The inductance represents magnetic fields circulating the core and the capacitance electric fields directing from the core to the shield.

$$Z_0 = \sqrt{\frac{L}{C}} \quad : \text{ real, dispersionless (no } \omega\text{-}k \text{ relation)}$$

Non-linear  $\omega$ -term in  $Z$  or  $Y \rightarrow$  dispersion (longitudinal components)

## 5.4 Non-TEM mode gives mass in transmission line



$C$ : capacitance per unit length  
 $L$ : inductance per inverse unit length  
 $K$ : inductance per unit length

$$Y = i\omega C + \frac{1}{i\omega L}$$

$$-k^2 = YZ = \left( i\omega C + \frac{1}{i\omega L} \right) i\omega K = -CK\omega^2 + \frac{K}{L}$$

Constant finite mass:  $E = \hbar\omega \propto k^2$

(Schrodinger eq.: Parabolic partial differential equation)

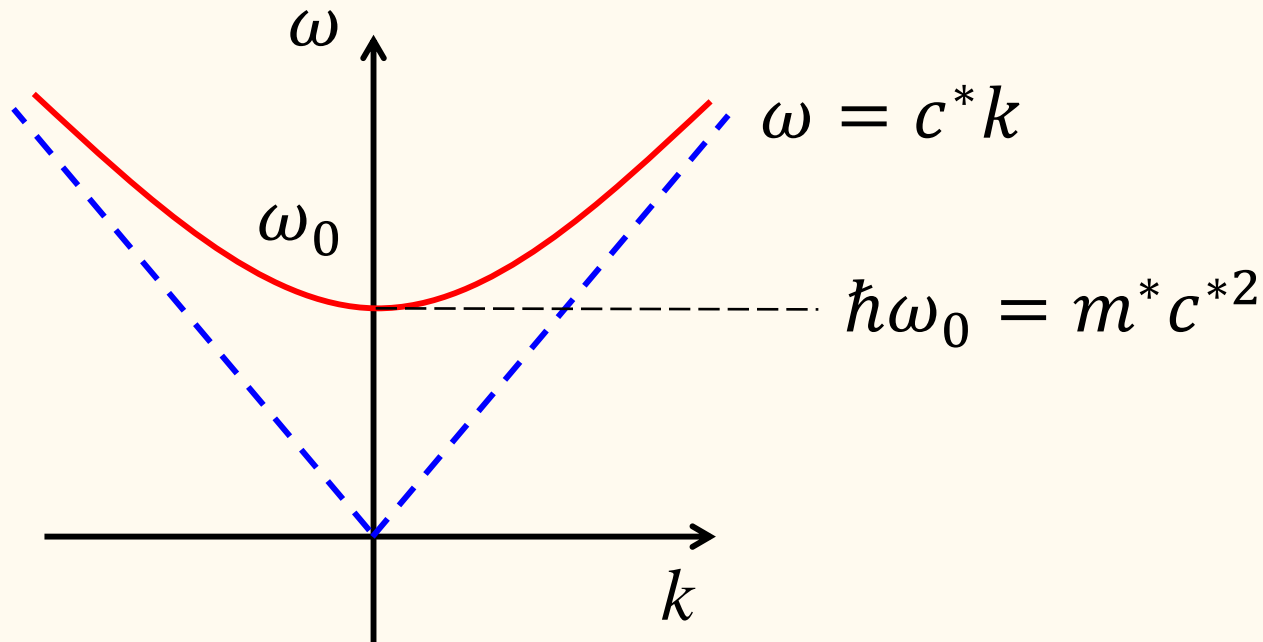
Coupling between linear dispersions: mass mechanism *cf.* Higgs

## 5.4 Non-TEM mode gives mass in transmission line

$$\frac{1}{\sqrt{LC}} = \omega_0 \text{ unchanged with } dx \rightarrow 0$$

$$Z = i\omega K, \quad Y = \frac{1 - (\omega/\omega_0)^2}{i\omega L}$$

$$ik = \kappa = \sqrt{YZ} = i \sqrt{\frac{K}{L} \left[ \left( \frac{\omega}{\omega_0} \right)^2 - 1 \right]} \quad \eta^2 \equiv \frac{K}{L}$$



## 5.4 Giving mass to LC transmission line

$$\omega \gg \omega_0 \rightarrow k \sim \eta \frac{\omega}{\omega_0} \quad \text{No dispersion}$$

$$\text{Velocity: } c^* = \frac{\omega}{k} = \frac{\omega_0}{\eta} = \frac{1}{\sqrt{KC}}$$

$$\omega \sim \omega_0 \quad \omega = \omega_0 + \delta\omega$$

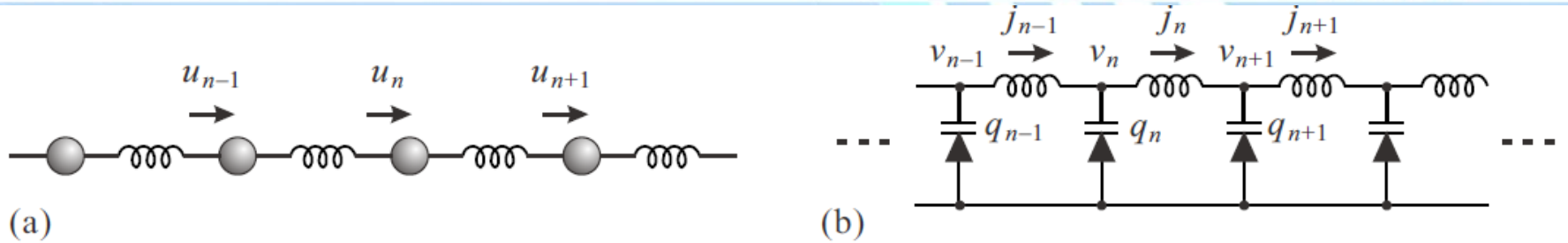
$$k^2 \approx 2\eta^2 \frac{\delta\omega}{\omega_0} \quad \therefore \epsilon \equiv \hbar\delta\omega = \frac{\hbar k^2}{2(\eta^2/\omega_0)} = \frac{\hbar^2 k^2}{2m^*}$$

$$m^* \equiv \frac{\hbar\eta^2}{\omega_0}$$

$$E_0 = \hbar\omega_0 = \frac{\hbar\eta^2}{\omega_0} \cdot \left(\frac{\omega_0}{\eta}\right)^2 = m^* c^{*2}$$



## 5.5 Non-linear LC transmission line and Toda lattice



Toda lattice is a typical non-linear system with exact (soliton) solutions. It is defined as follows:

The springs in (a) have Toda-potential:  $\phi(r) = \frac{a}{b}e^{-br} + ar \quad (ab > 0)$

Equation of motion:

$$m \frac{d^2 u_n}{dt^2} = -a \exp[-b(u_{n+1} - u_n)] + a \exp[-b(u_n - u_{n-1})]$$

For relative shift

$$r_n = u_{n+1} - u_n \quad m \frac{d^2 r_n}{dt^2} = a(2e^{-br_n} - e^{-br_{n+1}} - e^{-br_{n-1}})$$

Force of a spring:  $f = -\phi'(r) = a(e^{-br} - 1)$

# Solitons in Toda lattice

$$\frac{d^2}{dt^2} \log \left( 1 + \frac{f_n}{a} \right) = \frac{b}{m} (f_{n+1} + f_{n-1} - 2f_n)$$

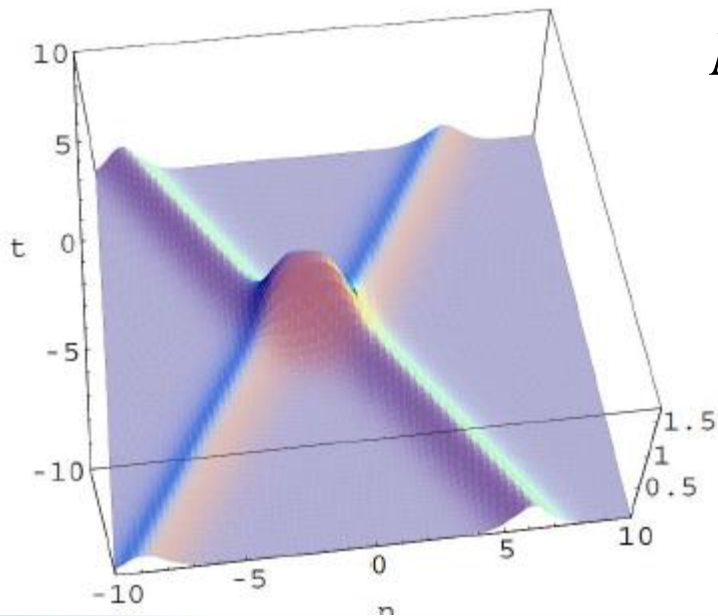
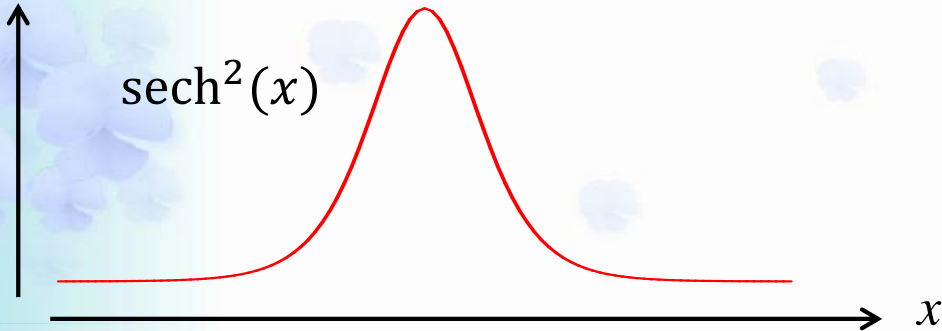
Soliton solution:

$$u_n = \omega^2 \operatorname{sech}^2(\kappa n + \sigma \omega t + \delta),$$

$$\sigma = \pm 1, \quad \omega = \sinh \kappa,$$

$\kappa, \delta$  : constants

$\operatorname{sech}^2(x)$



$N = 2$  soliton solution:

$$u_n = \frac{\tau_{n+1}\tau_{n-1}}{\tau_n^2} - 1,$$

$$\tau_n = 1 + e^{2\eta_1} + e^{2\eta_2} + A_{12}e^{2(\eta_1+\eta_2)},$$

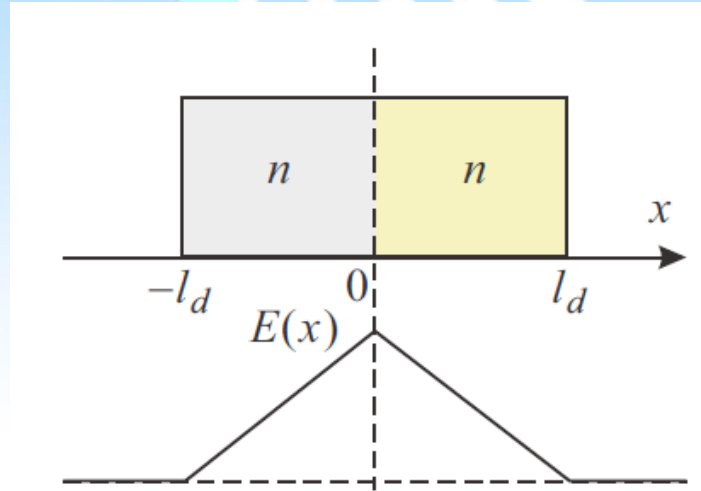
$$\eta_i = \kappa_i n + \sigma_i \omega_i t + \delta_i, \quad \sigma_i = \pm 1, \quad \omega_i = \sinh \kappa_i,$$

$$A_{12} = \frac{ab \sinh^2(\kappa_1 - \kappa_2) - m(\sigma_1 \omega_1 - \sigma_2 \omega_2)^2}{m(\sigma_1 \omega_1 + \sigma_2 \omega_2)^2 - ab \sinh^2(\kappa_1 + \kappa_2)}$$

# Non-linear capacitance: Vari-cap



Varicap BB505

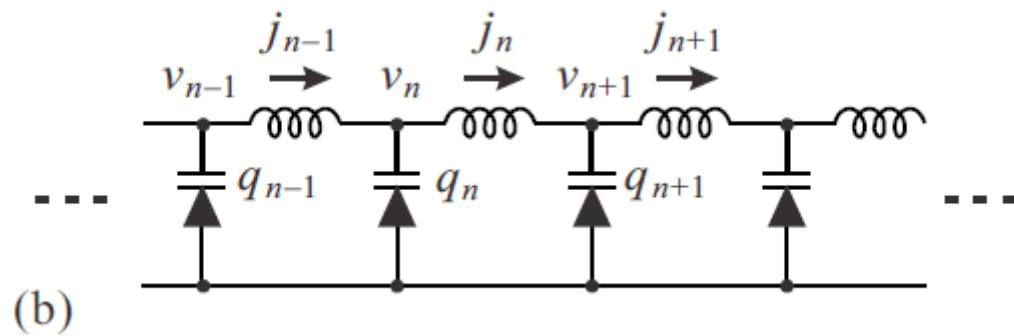


$$V_b = \frac{en}{\epsilon} \int_{-l_d}^0 2(x + l_d) dx + \frac{en}{\epsilon} \int_0^{l_d} 2(l_d - x) dx = \frac{2enl_d^2}{\epsilon}$$

$$V + V_b = \frac{2en}{\epsilon} \left( l_d + \frac{Q}{nS} \right)^2 \quad \therefore C = \frac{dQ}{dV} = \sqrt{\frac{\epsilon}{2en}} \frac{nS}{\sqrt{V + V_b}}$$

$$V + V_b = V_0 + \delta V \quad \delta V \rightarrow V$$

# L-Varicap transmission line



$$L \frac{dJ_n}{dt} = v_n - v_{n-1},$$

$$\frac{dq_n}{dt} = J_{n-1} - J_n,$$

$$q_n = \int_0^{v_n} C(V) dV, \quad C(V) = \frac{Q(V_0)}{F(V_0) + V - V_0}$$

$$q_n = Q(V_0) \log \left[ 1 + \frac{V_n}{F(V_0)} \right] + \text{const.}$$

$$\frac{d^2}{dt^2} \log \left[ 1 + \frac{V_n}{F(V_0)} \right] = \frac{1}{LQ(V_0)} (V_{n-1} + V_{n+1} - 2V_n)$$

# Solitons in non-linear circuit

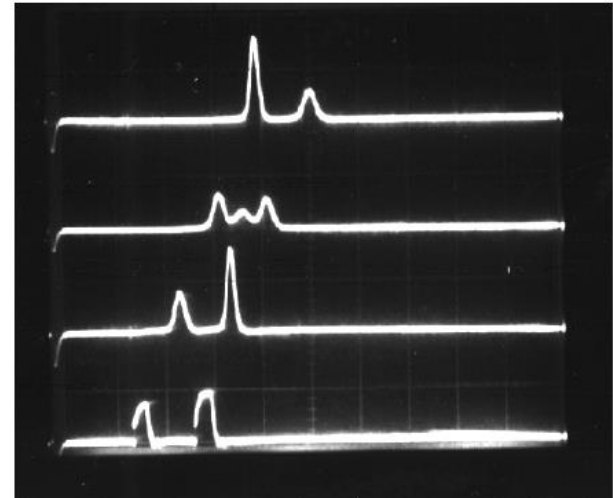
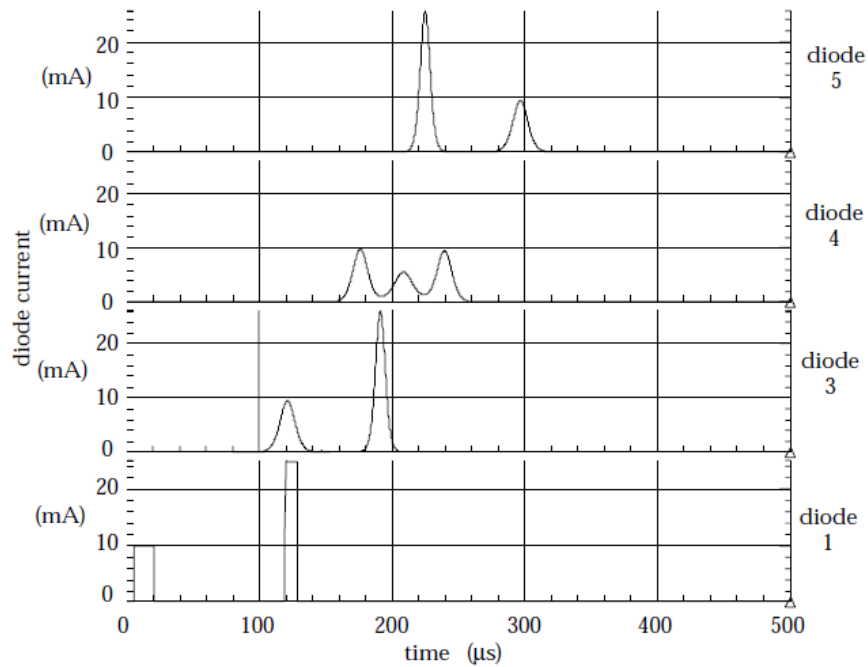
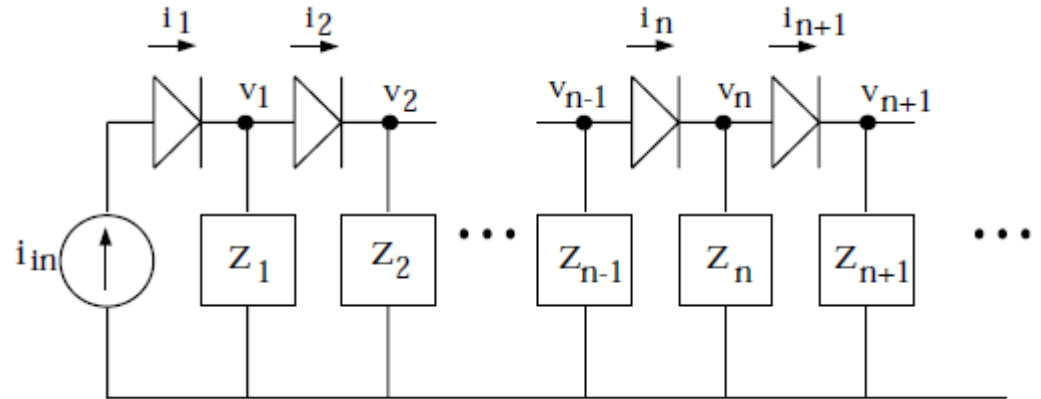
International Journal of Bifurcation and Chaos, Vol. 9, No. 4 (1999) 571-590  
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## CIRCUIT IMPLEMENTATIONS OF SOLITON SYSTEMS\*

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Received May 27, 1998; Revised October 6, 1998



# Toda lattice circuit, Soliton circuit

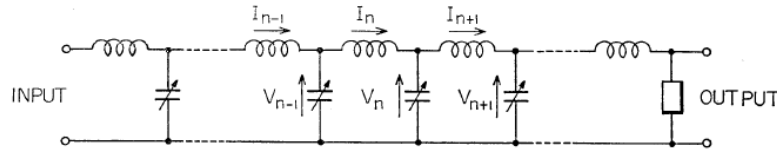
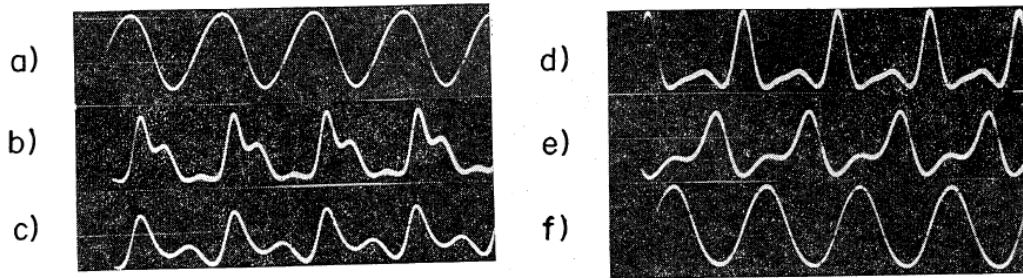


Fig. 1. A nonlinear network equivalent to a one-dimensional anharmonic lattice. The circuit element have an inductance  $L=22 \mu\text{H}$  or capacitance  $C(V)=27 V^{-0.48} \text{ pF}$ .



J. PHYS. SOC. JAPAN 28 (1970) 1366~1367

## Studies on Lattice Solitons by Using Electrical Networks

Ryogo HIROTA and Kimio SUZUKI

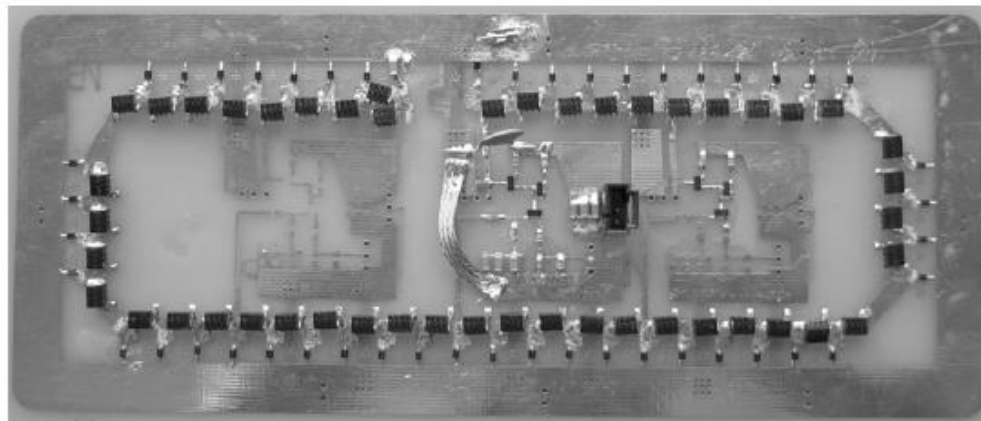
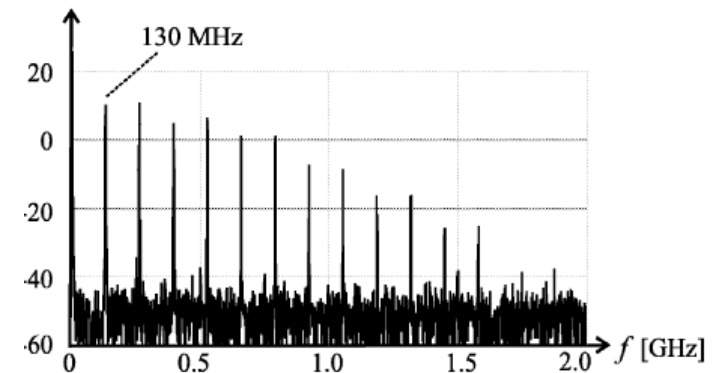
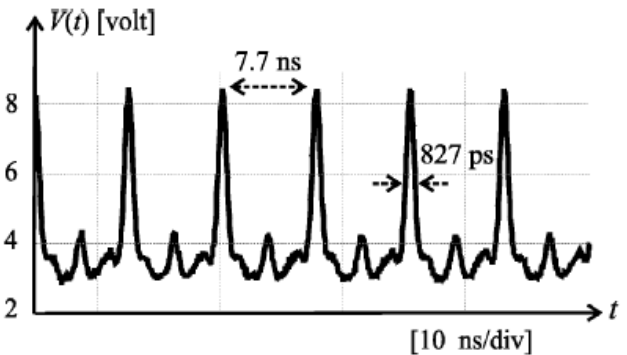


Fig. 16. Microwave soliton oscillator prototype.





# 電子回路論第10回

## Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto

# Comment: Impedance match/mismatch

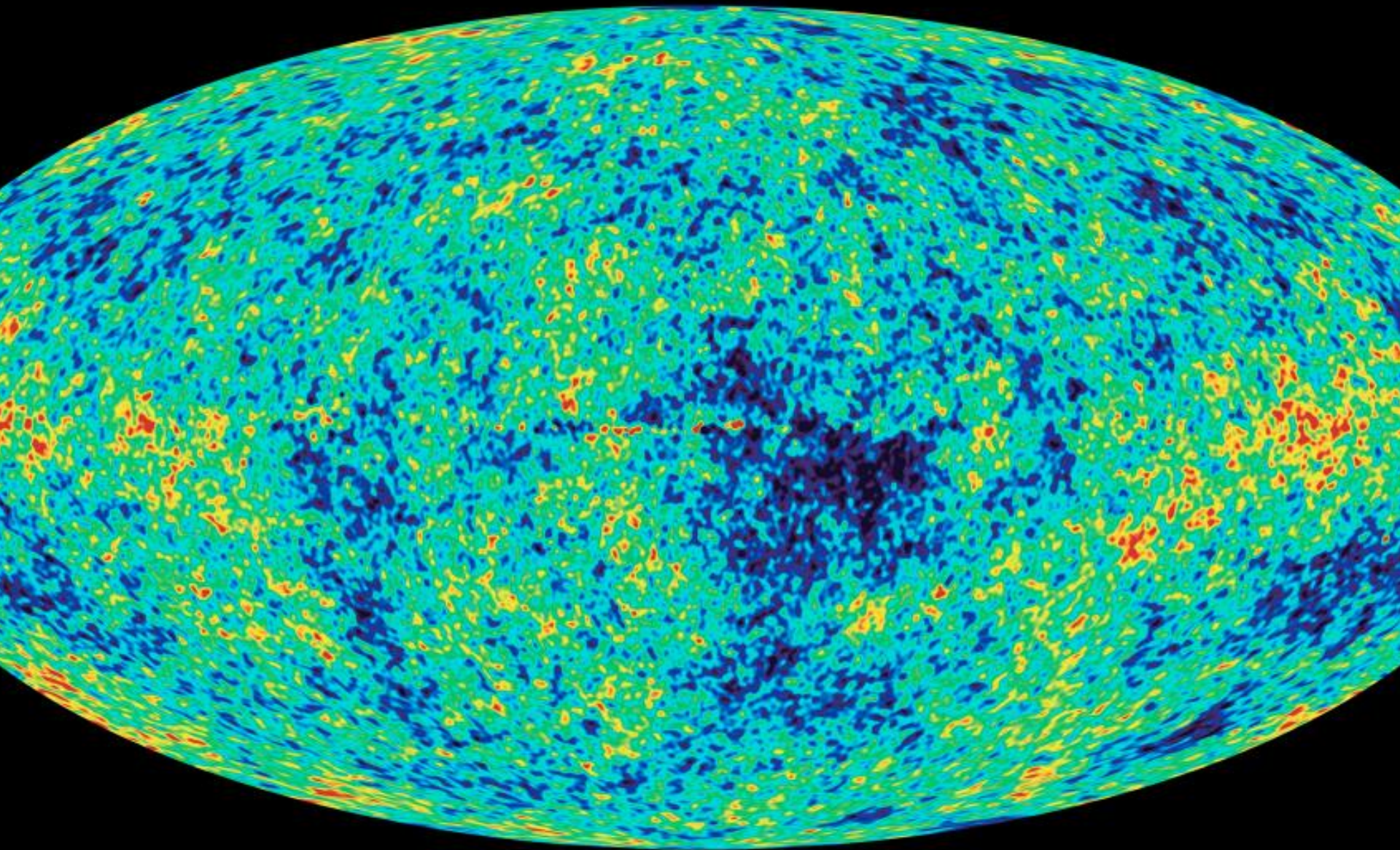
Propagation of a wave:	Impedance match: complete absorption (propagation without reflection)
	Mismatch: wave reflection

Impedance match/mismatch is an important concept applicable to a broad area of physics.

- Antenna: should be matched to the vacuum.  
EM wave propagation simulation: boundary is shunted with the characteristic impedance of vacuum.
- Optics: impedance mismatch → disagreement in refractive index
- Plasma: should be matched to electrodes for excitation.
- Phonon impedance mismatch at low temperatures: Kapitza resistance
- Sound insulated booth: should have sound impedance mismatch.



# Ch6. Noises and Signals



## Outline

### 6.1 Fluctuation

6.1.1 Fluctuation-Dissipation theorem

6.1.2 Wiener-Khintchine theorem

6.1.3 Noises in the view of circuits

6.1.4 Nyquist theorem

6.1.5 Shot noise

6.1.6  $1/f$  noise

6.1.7 Noise units

6.1.8 Other noises

### 6.2 Noises from amplifiers

6.2.1 Noise figure

6.2.2 Noise impedance matching

# Noises

Electric circuits transform: 1) Information  
2) Electromagnetic power  
on some physical quantities like voltages, current, ...

Noises: stochastic (uncontrollable, unpredictable by human) variation  
in other words, fluctuation in such a quantity.

Internal  
noise

Intrinsic noise: Thermal noise (Johnson-Nyquist noise),  
Shot noise

Noise related to a specific physical phenomenon

Avalanche, Popcorn, Barkhausen, etc.

1/f noise: Name for a group of noises with spectra  $1/f$ .

External  
noise

EMI, microphone noise, etc.



# 6.1 Fluctuation

Quantity  $x$ , fluctuation  $\delta x = x - \bar{x}$

$$\overline{(\delta x)^2} = \overline{(x - \bar{x})^2} = \overline{x^2} - \bar{x}^2 \quad (\overline{\delta x} = 0)$$

$g(x)$ : distribution function of  $x$

Fourier transform:  $u(q) = \mathcal{F}\{g(x)\} = \int_{-\infty}^{\infty} g(x) e^{ixq} \frac{dx}{\sqrt{2\pi}}$

$u(q)$  : **characteristic function** of the distribution

From Taylor expansion, any moment can be obtained as

$$\overline{x^n} = \frac{\sqrt{2\pi}}{i^n} \left[ \frac{d^n}{dq^n} u(q) \right]_{q=0}$$

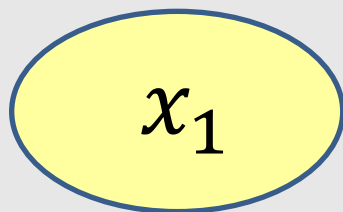
Moments to high orders  $\rightarrow$  reconstruction of  $g(x)$



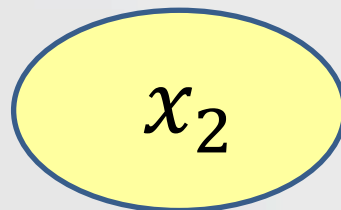
# 6.1 Fluctuation

In electric circuits we need to consider two kinds of averages:

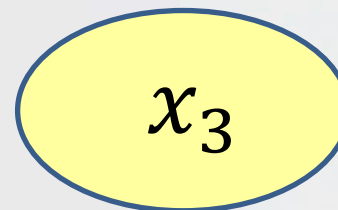
substance 1



substance 2



substance 3



...

$x_j$ : independent

Ensemble average:  $\bar{x}$

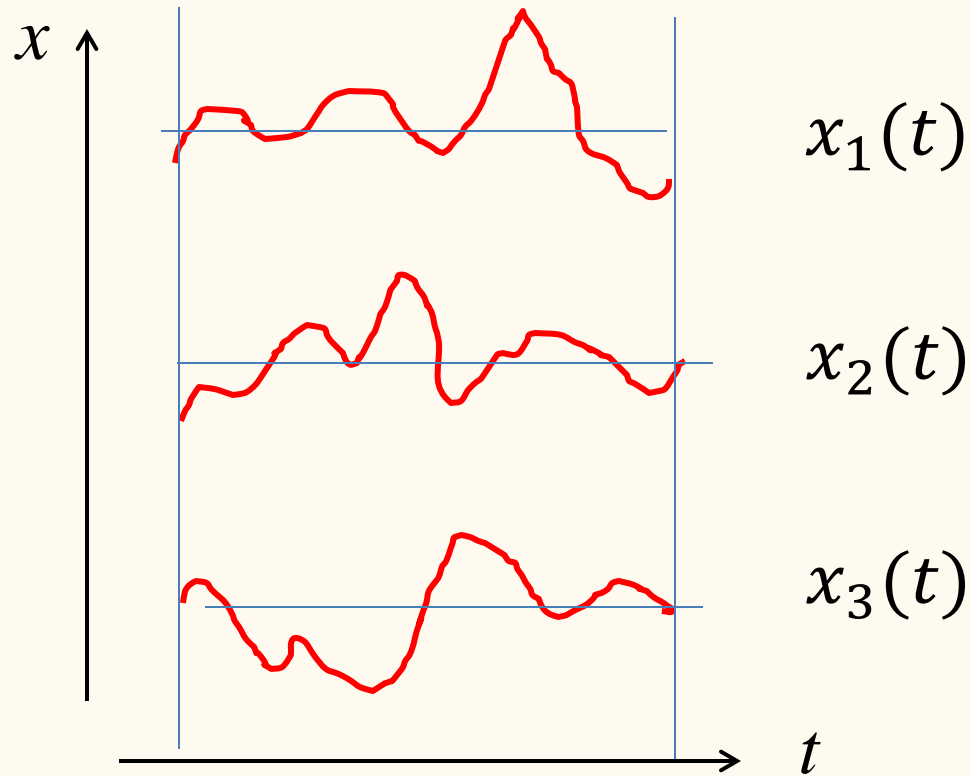
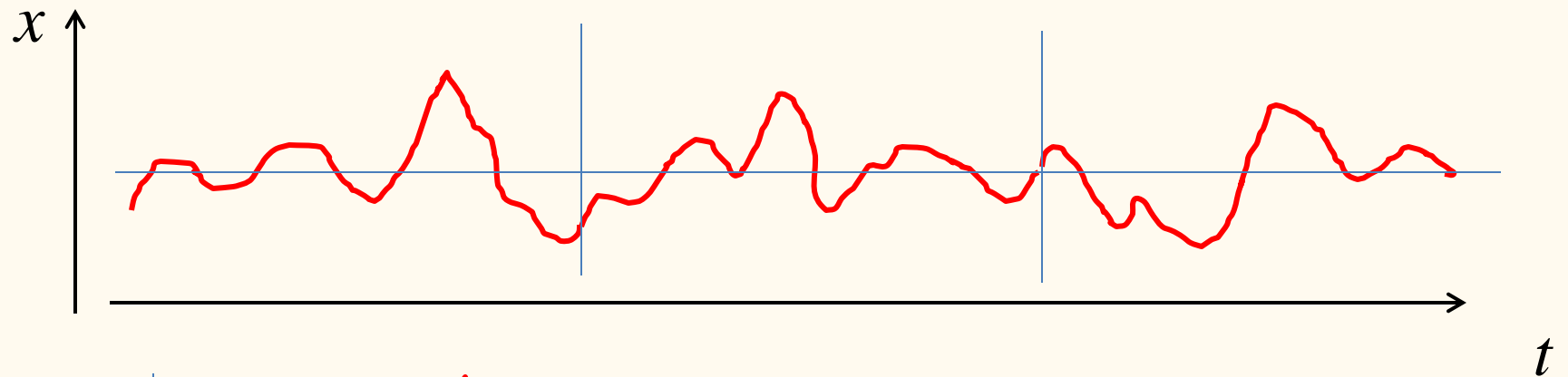


$x_1, \dots, x_m$  affect  $x_{m+1}$

$m$ -th order Markovian

Time average of fluctuating variable:  
 $\langle x \rangle$

# Random process to distribution



The averaging interval should be longer than  $m$  in  $m$ -th order Markovian.

## 6.1.1 Fluctuation-Dissipation Theorem



久保亮五

Ryogo Kubo 1920-1995



Harry Nyquist  
1889-1976



Nobert Wiener  
1894-1964



Aleksandr Khinchin  
1894-1959

# Power Spectrum

Consider probability sets in the interval  $[0, T)$ .

$$\text{set index: } j \quad x_j(t) = \sum_{n=1}^{\infty} (a_{jn} \cos \omega_n t + b_{jn} \sin \omega_n t), \quad \omega_n = \frac{2n\pi}{T}$$

$$\mathcal{P}_{jn} = (a_{nj} \cos \omega_n t + b_{nj} \sin \omega_n t)^2 \quad (\text{Power})$$

$$\langle \mathcal{P}_n \rangle = \frac{1}{2} \langle a_n^2 + b_n^2 \rangle \quad \because \text{cross product terms are averaged out}$$

Random process:

Gaussian distribution in time

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{x^2}{2\sigma^2}\right]$$

$$\overline{(\delta x)^2} = \sigma^2, \quad \overline{\left(\sum_{j=1}^m \delta x_j\right)^2} = m\sigma^2$$

Then  $\overline{\langle \mathcal{P}_n \rangle} = \sigma_n^2$  (non-Markovian)

# Power Spectrum

## Power spectrum $G(\omega)$

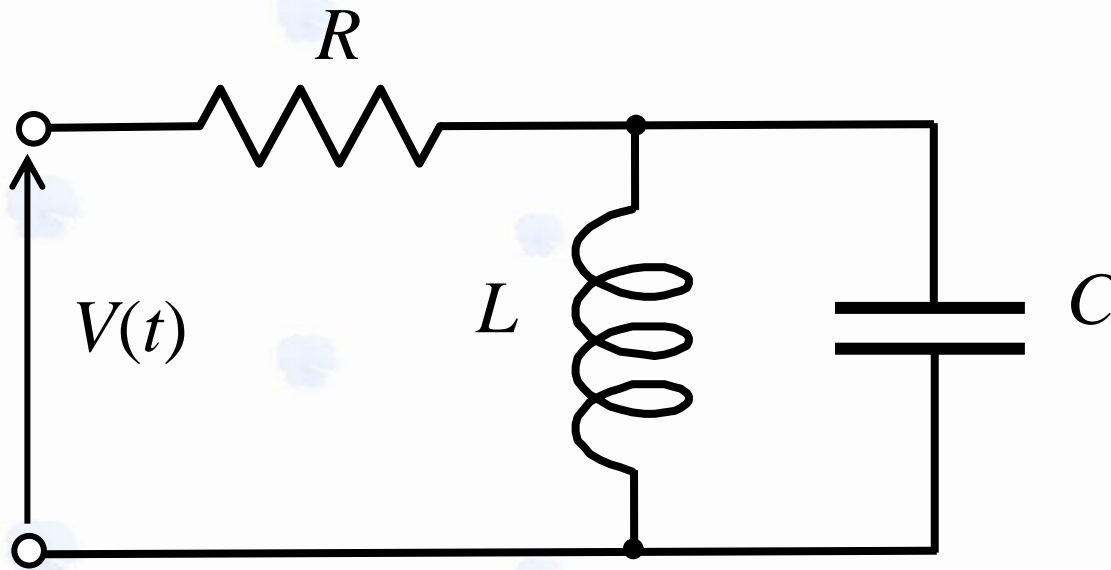
Frequency band width  $\delta\omega$  : separation between two adjacent frequencies

$$\delta\omega = \omega_{n+1} - \omega_n = \frac{2(n+1)\pi}{T} - \frac{2n\pi}{T} = \frac{2\pi}{T}$$

$$G(\omega_n) \frac{\delta\omega}{2\pi} = \overline{\langle \mathcal{P}_n \rangle} (= \sigma_n^2)$$

$$\begin{aligned} \overline{\langle x^2(t) \rangle} &= \sum_{n=1}^{\infty} \overline{\langle \mathcal{P}_n \rangle} \quad (\overline{\langle x(t) \rangle} = 0) \\ &= \sum_n G(\omega_n) \frac{\delta\omega}{2\pi} \rightarrow \int_0^{\infty} G(\omega) \frac{d\omega}{2\pi} \end{aligned}$$

## 6.1.1 Fluctuation-Dissipation Theorem



$$\omega_0 \equiv 1/\sqrt{LC}$$

$$Z(i\omega) = \frac{R(\omega_0^2 - \omega^2) + i\omega_0^2\omega L}{\omega_0^2 - \omega^2},$$

$$Y(i\omega) = \frac{\omega_0^2 - \omega^2}{R(\omega_0^2 - \omega^2) + i\omega_0^2\omega L}$$



# Johnson-Nyquist noise

$V(t)$  noise power spectrum  $\rightarrow G_v(\omega)$

$$G_v(\omega) = 4k_B T \operatorname{Re}[Z(i\omega)]$$

$$G_v(\omega) = 4k_B T R \quad \begin{array}{l} \text{Johnson-Nyquist noise} \\ \text{Thermal noise} \end{array}$$

White noise

One representation of the fluctuation-dissipation theorem

## 6.1.2 Wiener-Khintchine Theorem

Autocorrelation function  $C(\tau) = \overline{\langle x(t)x(t + \tau) \rangle}$

$$\begin{aligned} &= \overline{\sum_{n,m} \langle [a_n \cos \omega_n t + b_n \sin \omega_n t][a_m \cos \omega_m(t + \tau) + b_m \sin \omega_m(t + \tau)] \rangle} \\ &= \frac{1}{2} \sum_n \overline{\langle a_n^2 + b_n^2 \rangle} \cos \omega_n \tau = \sum_n \overline{\langle \mathcal{P}_n \rangle} \cos \omega_n \tau \\ &= \int_0^\infty G(\omega) \cos \omega \tau \frac{d\omega}{2\pi} \end{aligned}$$

$$C(\tau) = \int_0^\infty G(\omega) \cos \omega \tau \frac{d\omega}{2\pi}$$

$$G(\omega) = 4 \int_0^\infty C(\tau) \cos \omega \tau d\tau$$

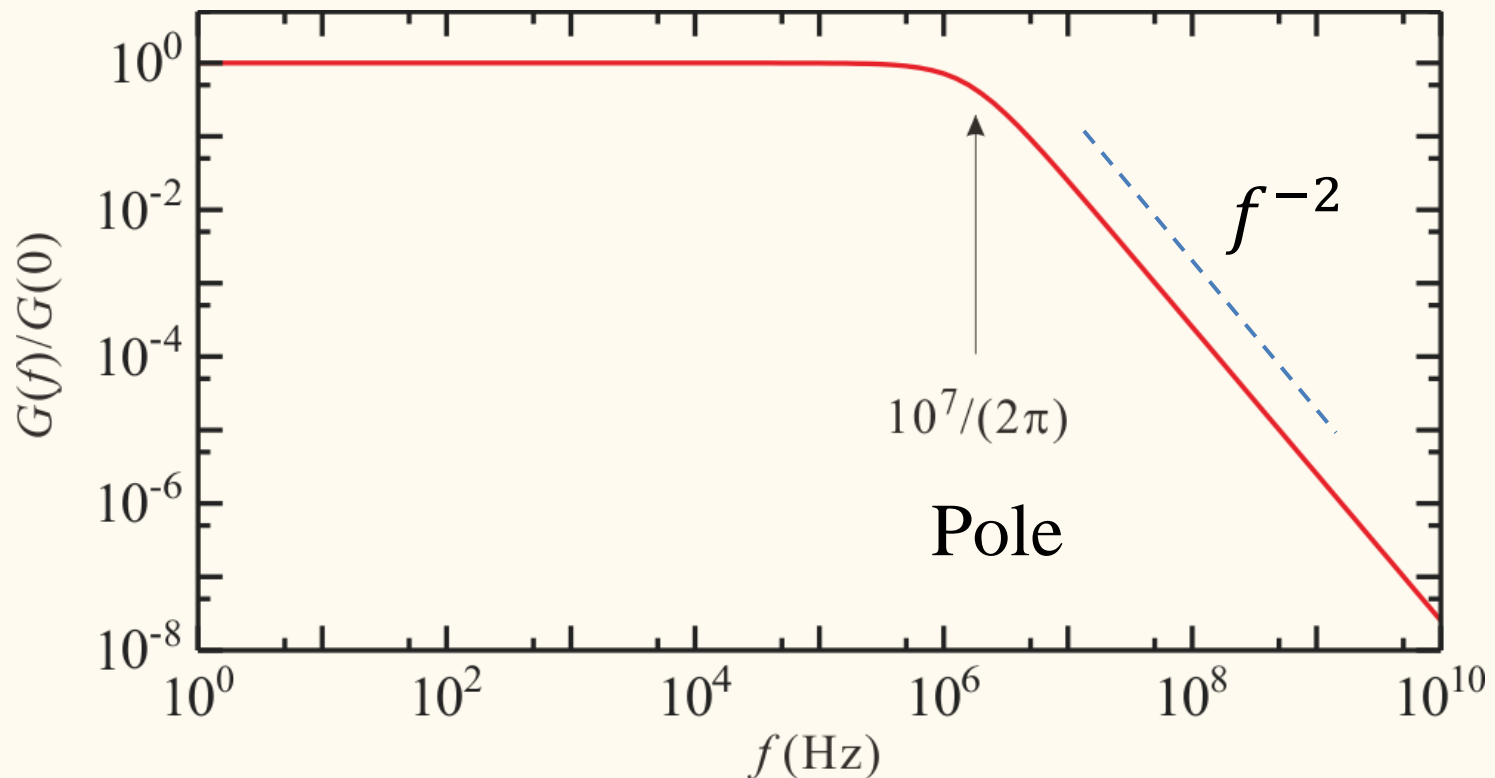
Wiener-Khintchine theorem

## 6.1.2 Wiener-Khintchine Theorem

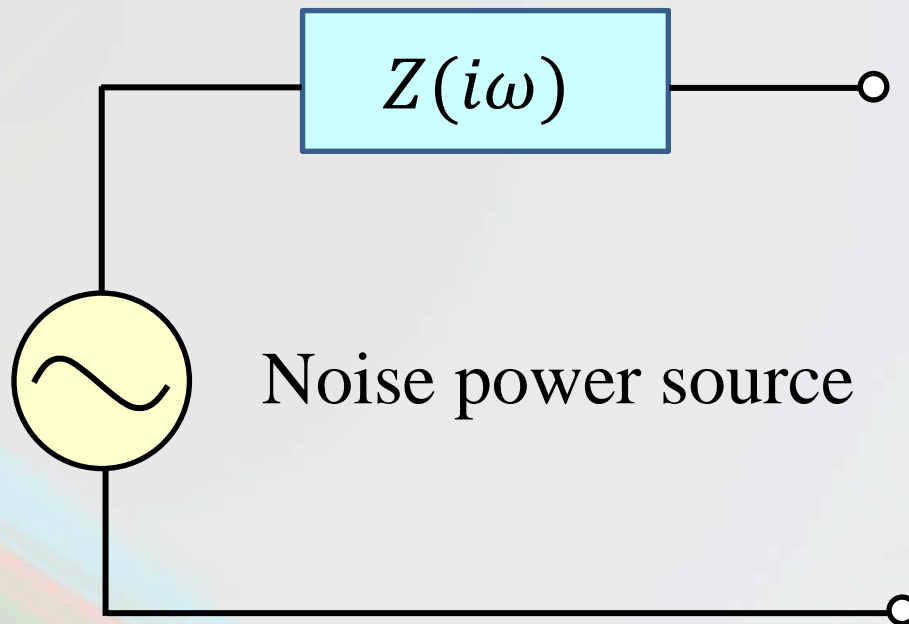
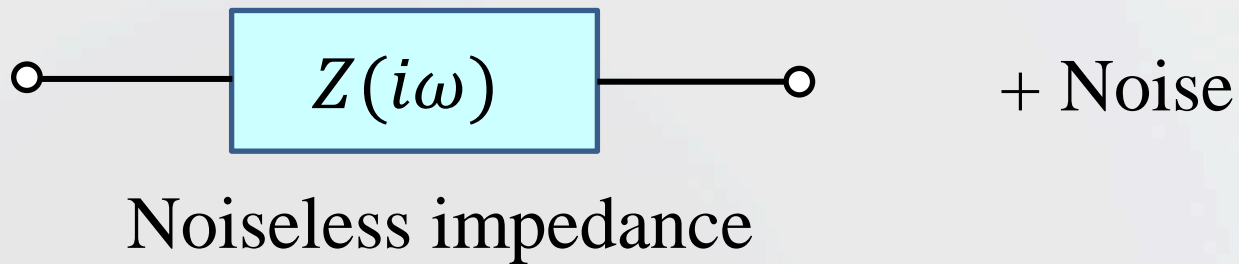
Example)  $C(\tau) = \exp\left(-\frac{\tau}{\tau_0}\right)$

$$G(f) = 4 \int_0^{\infty} e^{-\tau/\tau_0} \cos(2\pi f\tau) d\tau = \frac{4\tau_0}{1 + (2\pi f\tau_0)^2}$$

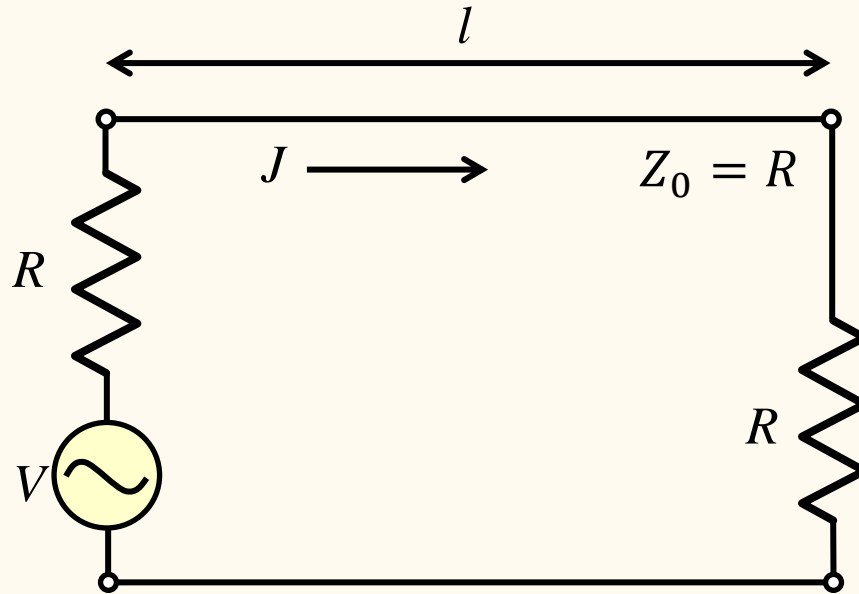
$\tau_0 = 10^{-7} \text{ s}$  (10MHz)



## 6.1.3 Electric circuit treatment of noise



## 6.1.4 Nyquist Theorem



Mode density on a transmission line with length  $l$

$$\omega_n = c^* k_n = \frac{2\pi n c^*}{l} \quad \therefore \quad \delta\omega = \frac{2\pi c^*}{l}$$

Bidirectional  $\rightarrow$  Freedom  $\times 2$

Bose distribution

$$f(\hbar\omega, T) = \frac{1}{\exp(\hbar\omega/k_B T) - 1}$$

## 6.1.4 Nyquist Theorem

Thermal energy density per freedom

$$\frac{\hbar\omega}{\exp(\hbar\omega/k_{\text{B}}T) - 1} \sim \frac{\hbar\omega}{1 + (\hbar\omega/k_{\text{B}}T) - 1} = k_{\text{B}}T \quad (k_{\text{B}}T \gg \hbar\omega)$$

Thermal energy density in band  $\Delta\omega$

$$2 \frac{\Delta\omega}{\delta\omega} k_{\text{B}}T = \frac{2k_{\text{B}}Tl}{2\pi c^*} \Delta\omega, \text{ a half of which flows in one-direction}$$

Energy flowing out from the end:

$$\frac{k_{\text{B}}Tl}{2\pi c^*} \Delta\omega \times \frac{1}{l} \times c^* = k_{\text{B}}T \Delta f \quad (2\pi f = \omega)$$

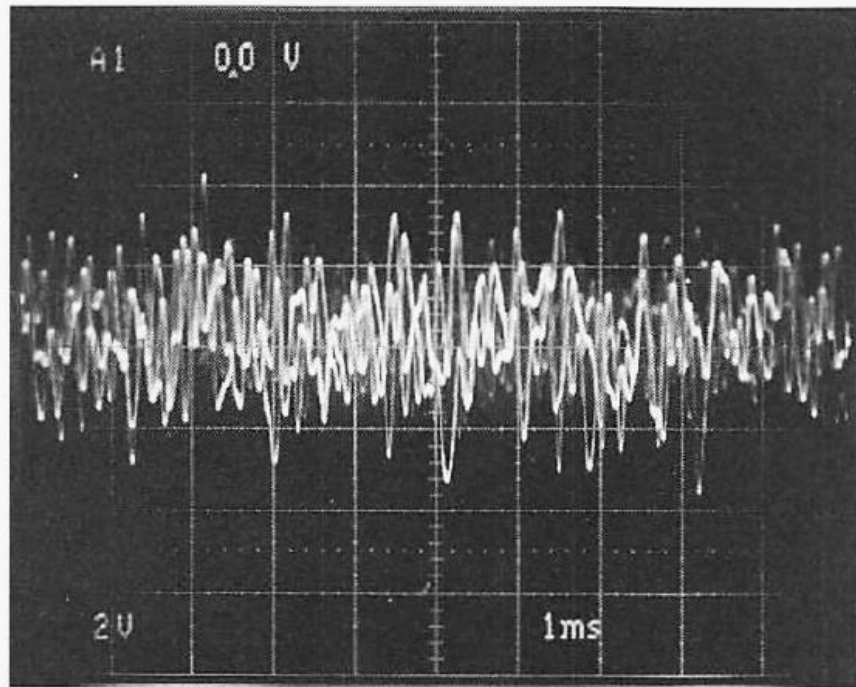
equals the energy supplied from the noise source.

$$\overline{J^2} R = k_{\text{B}}T \Delta f, \quad \overline{V^2} = 4Rk_{\text{B}}T \Delta f \quad (V = 2RJ)$$

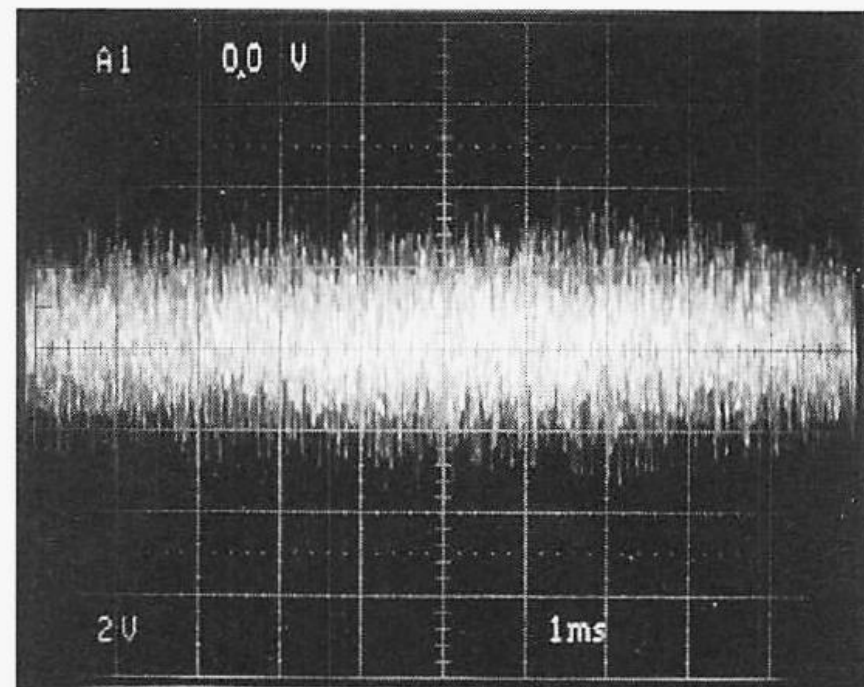
$$\sqrt{\overline{J^2 V^2}} = 2k_{\text{B}}T \Delta f \quad \rightarrow \text{Noise Temperature}$$



# Thermal noise



(a) 上限周波数5 kHz (-3dB) 1 V<sub>rms</sub>の熱雑音を1 ms/divで観測



(b) 上限周波数100 kHz (-3dB) 1 V<sub>rms</sub>の熱雑音を1 ms/divで観測

〈写真 1-1〉 熱雑音の測定

## 6.1.5 Shot Noise

### Single Electron

Time domain:  $\delta$ -function approximation

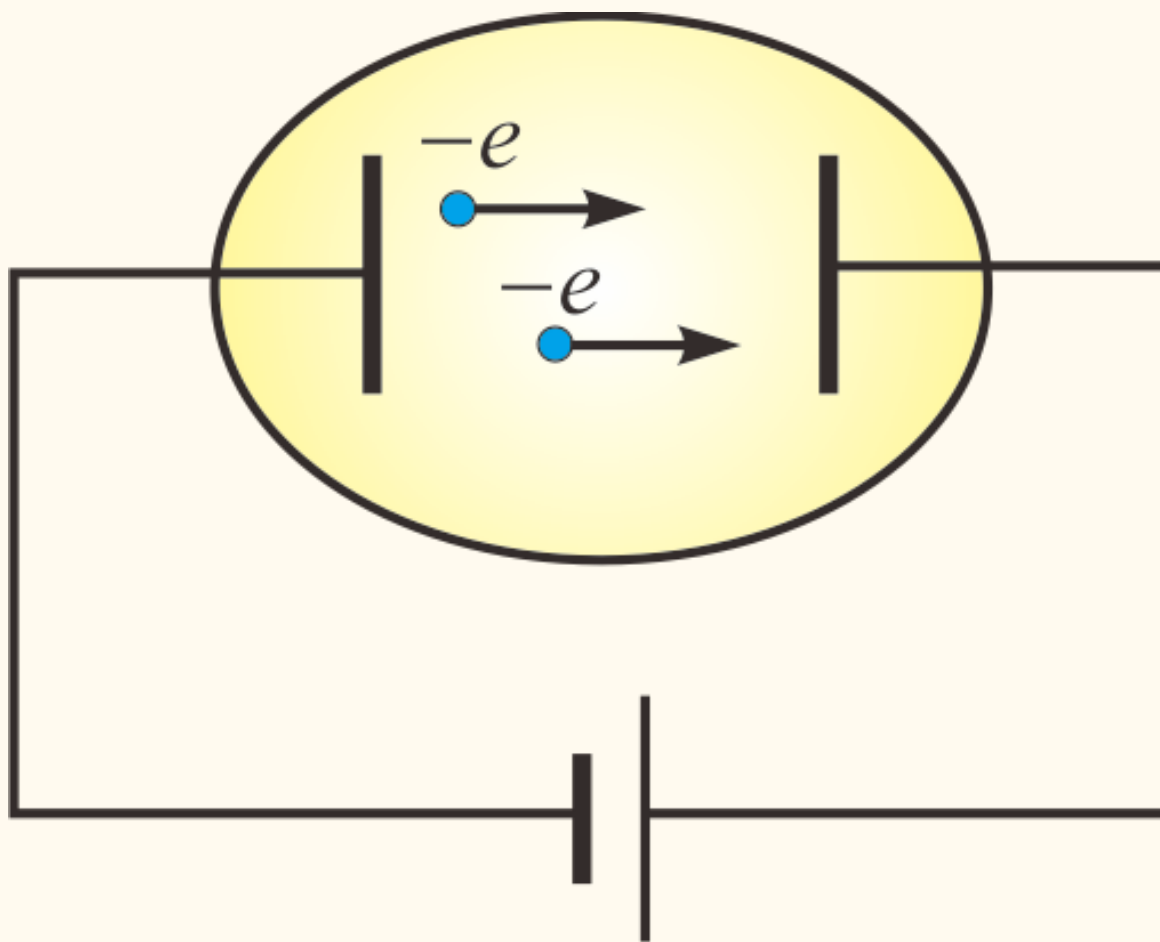
$$\begin{aligned} J_e(t) &= e\delta(t - t_0) \\ &= e \int_{-\infty}^{\infty} e^{2\pi i f(t-t_0)} df = 2e \int_0^{\infty} \cos [2\pi f(t - t_0)] df \end{aligned}$$

Uniform  $2e$  in frequency domain: fluctuation at each frequency  
Coherent only at  $t = t_0$

Current fluctuation density for infinitesimal band  $df$

$$\delta J = d\sqrt{\langle J_e^2 \rangle} = \frac{2e}{\sqrt{2}} df = \sqrt{2}e df$$

## 6.1.5 Shot Noise



## 6.1.5 Shot Noise

### Double Electron

$$\overline{\langle \delta j^2 \rangle} = (j_p + j_q e^{i\phi})(j_p + j_q e^{-i\phi}) = j_p^2 + j_q^2 + 2j_p j_q \cos \phi$$

$\phi$ : coherent phase shift  $\rightarrow$  averaged out

$$\overline{\langle \delta j^2 \rangle} = j_p^2 + j_q^2 = 2 \times (\sqrt{2}e)^2 df$$

### N-Electron

$$\overline{\langle \delta J^2 \rangle} = N \times 2e^2 df = 2e\bar{J}df \quad (\bar{J} = eN)$$

Quantum mechanical correlation  $\rightarrow$  Modification from random

## 6.1.5 Shot Noise

### Example: pn junction

Current-Voltage characteristics:  $J(V) = J_0 \left[ \exp\left(\frac{eV}{k_B T}\right) - 1 \right]$

Differential resistance  $r_d = \left(\frac{dJ}{dV}\right)^{-1} = \left[\frac{eJ_0}{k_B T} \exp\left(\frac{eV}{k_B T}\right)\right]^{-1} = \frac{k_B T}{e} \frac{1}{J + J_0}$

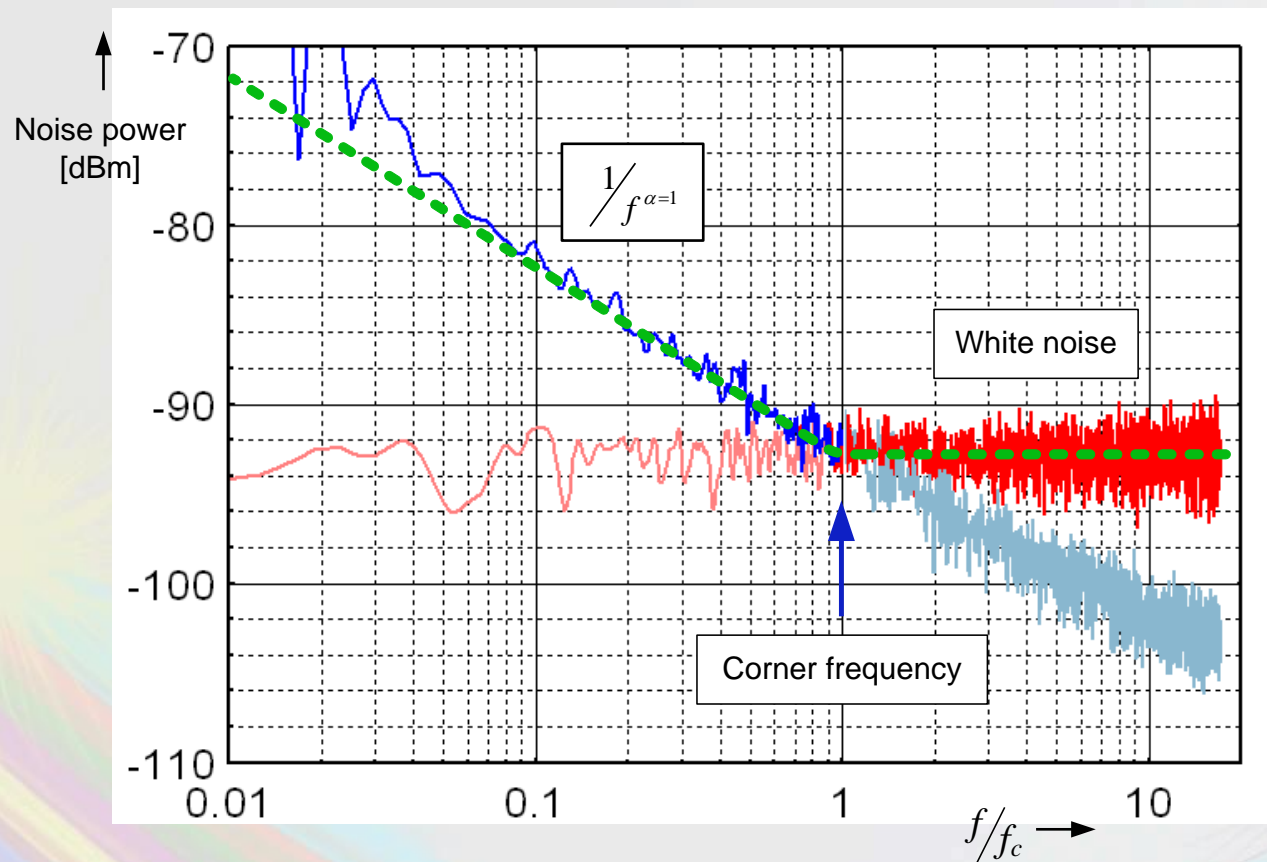
$$J \gg J_0 \rightarrow r_d \sim k_B T / eJ$$

$$\overline{\langle (\delta J)^2 \rangle} = 2e \frac{k_B T}{e r_d} df = 4k_B T \frac{1}{2r_d} df$$

$$(\delta V)^2 = 4 \frac{r_d}{2} k_B T \Delta f$$

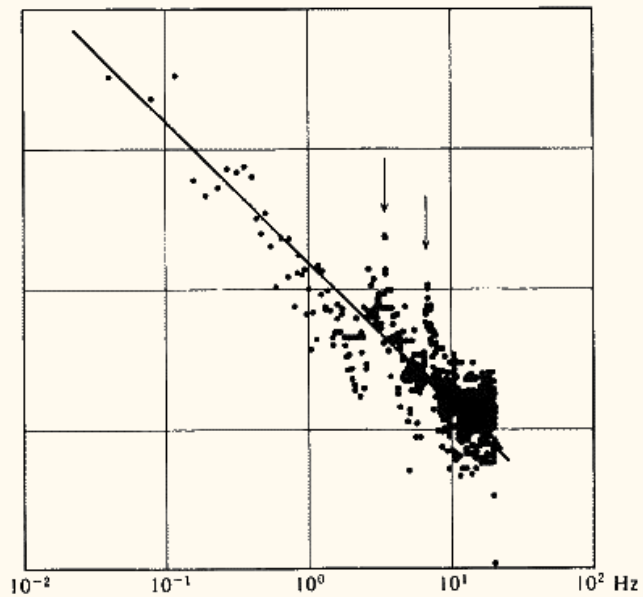
## 6.1.6 1/f noise

$$(\delta V)^2 = K J^a R^2 \frac{\Delta f}{f^\alpha}$$

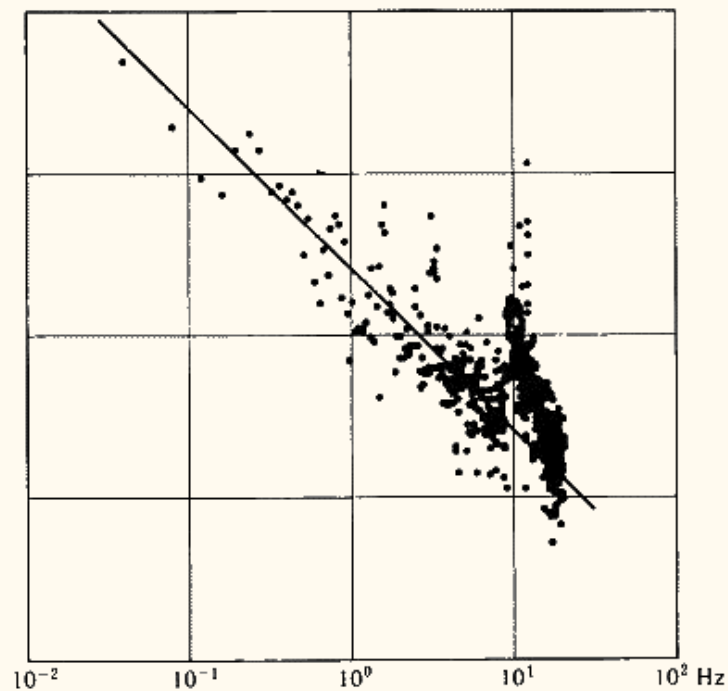




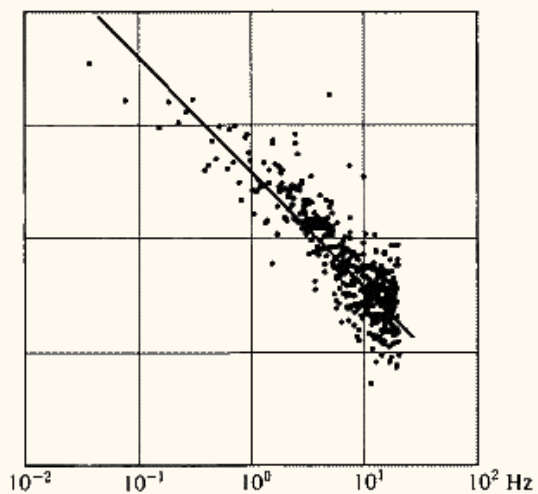
## 6.1.6 1/f noise



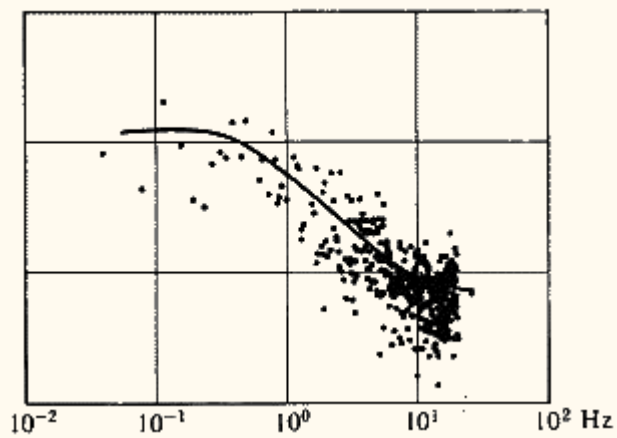
J. S. Bach, Brandenburg Concerto No.1



A. Vivaldi, Four Seasons, Spring



Kawai Naoko, Smile for me



S. Sato, Keshin (incarnation) II

# “Unit” of Noise

Noise: Power spectrum per frequency

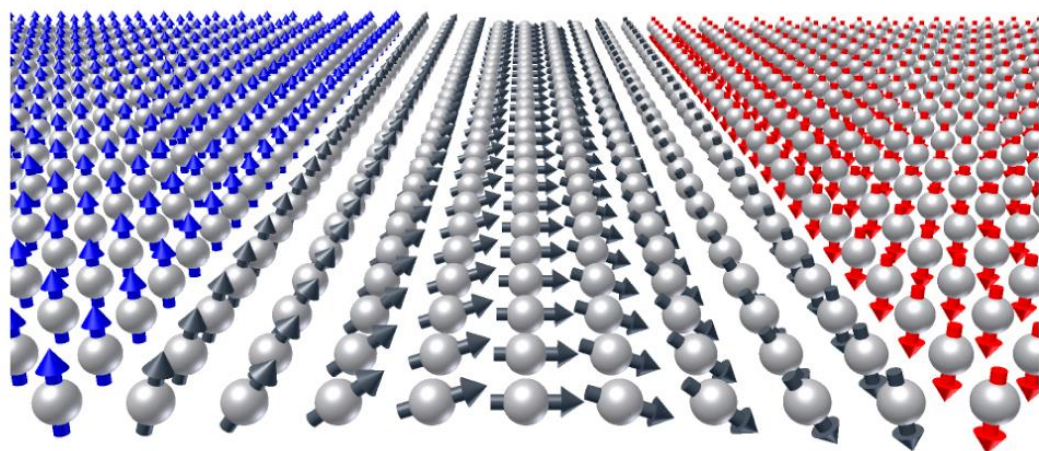
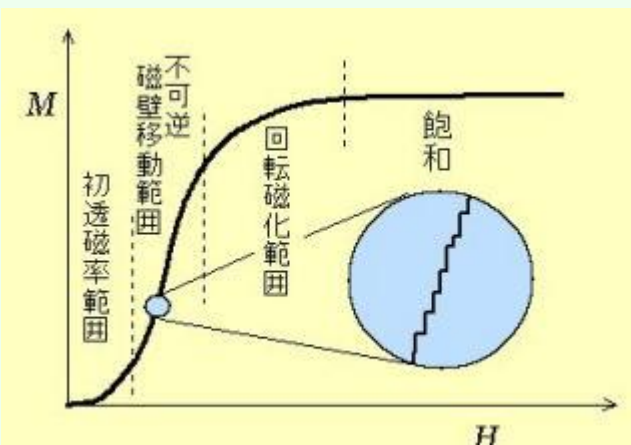
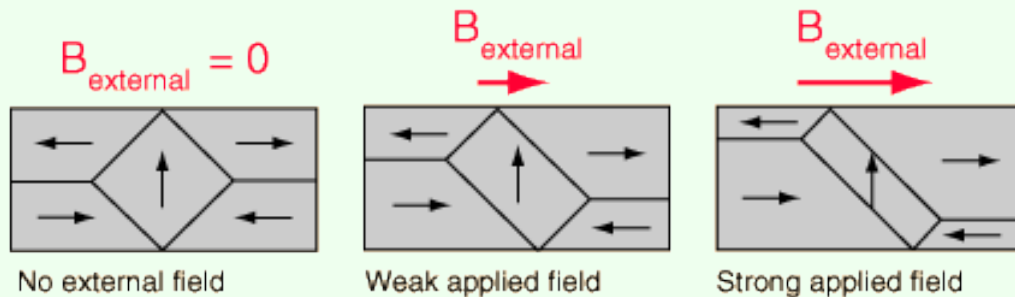
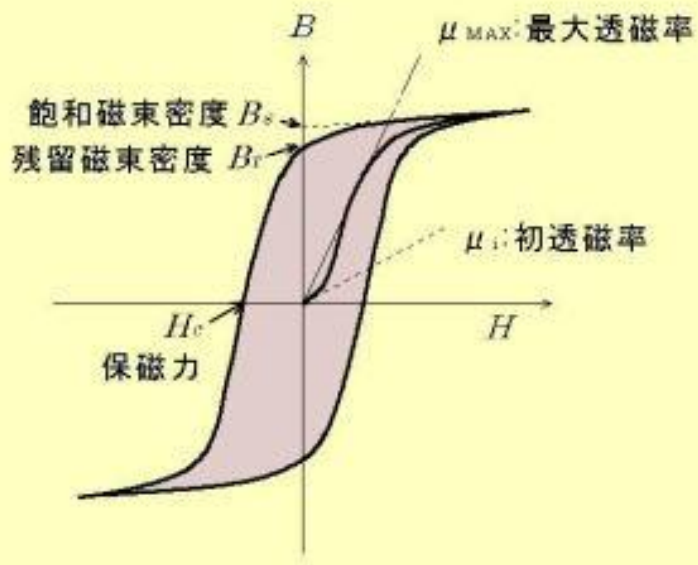
$$\overline{j_n^2} = \overline{\delta J^2} / \Delta f, \quad \overline{e_n^2} = \overline{\delta V^2} / \Delta f$$



unit of  $\sqrt{\overline{j_n^2}}$ ,  $\sqrt{\overline{e_n^2}}$

$$A / \sqrt{\text{Hz}}, \quad V / \sqrt{\text{Hz}}$$

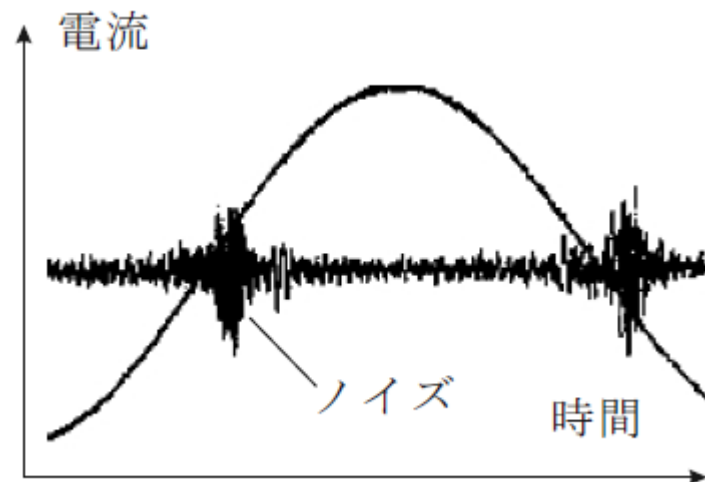
# Other noises: Barkhausen noise



Domain 1

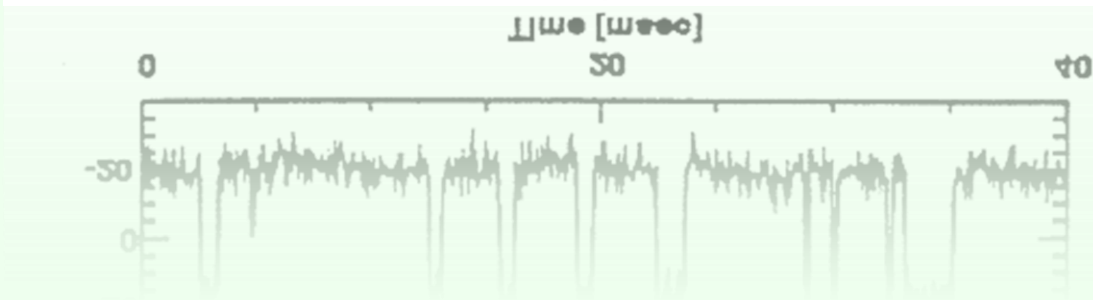
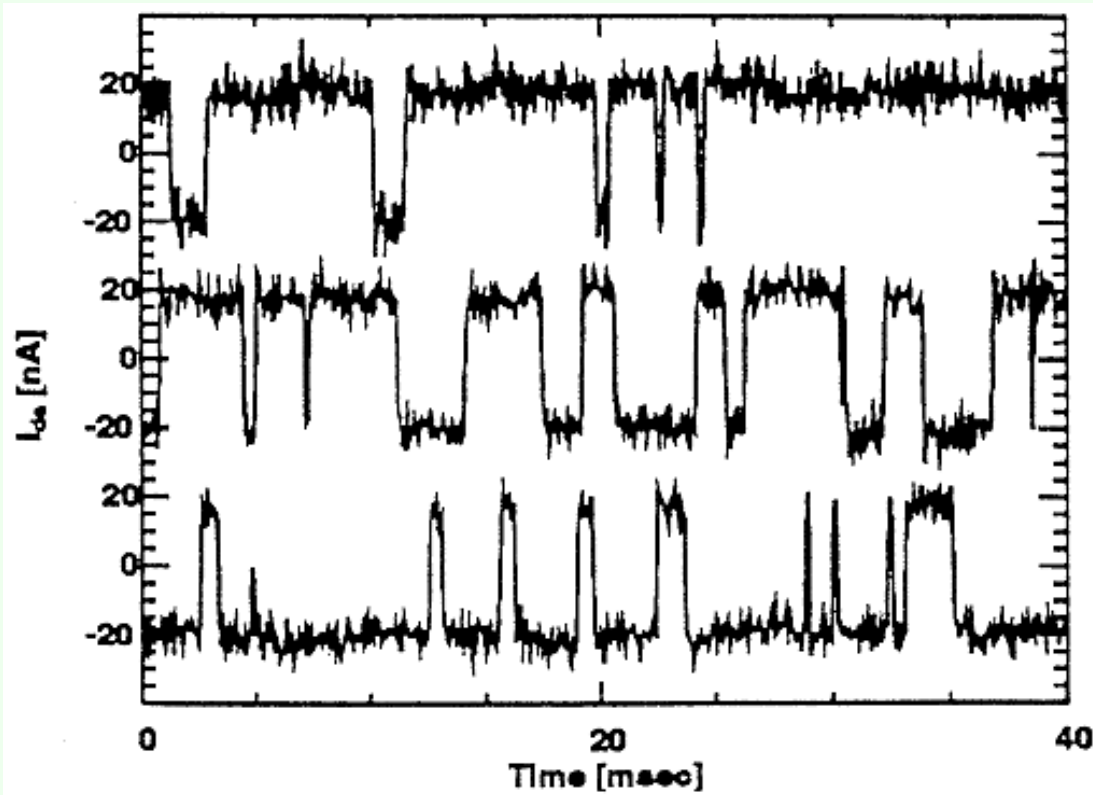
Domain wall

Domain 2

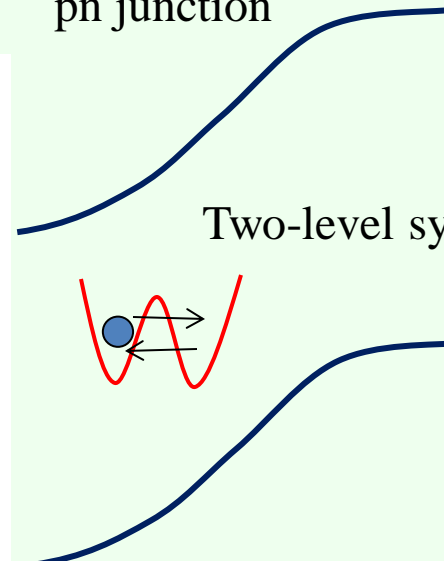


# Popcorn noise

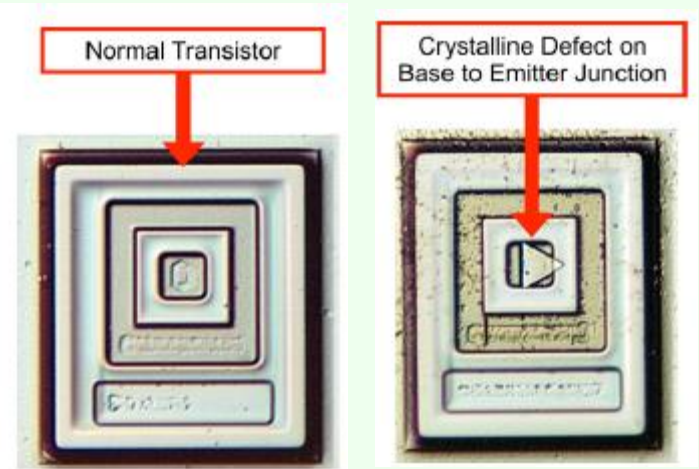
Popcorn noise, Burst noise



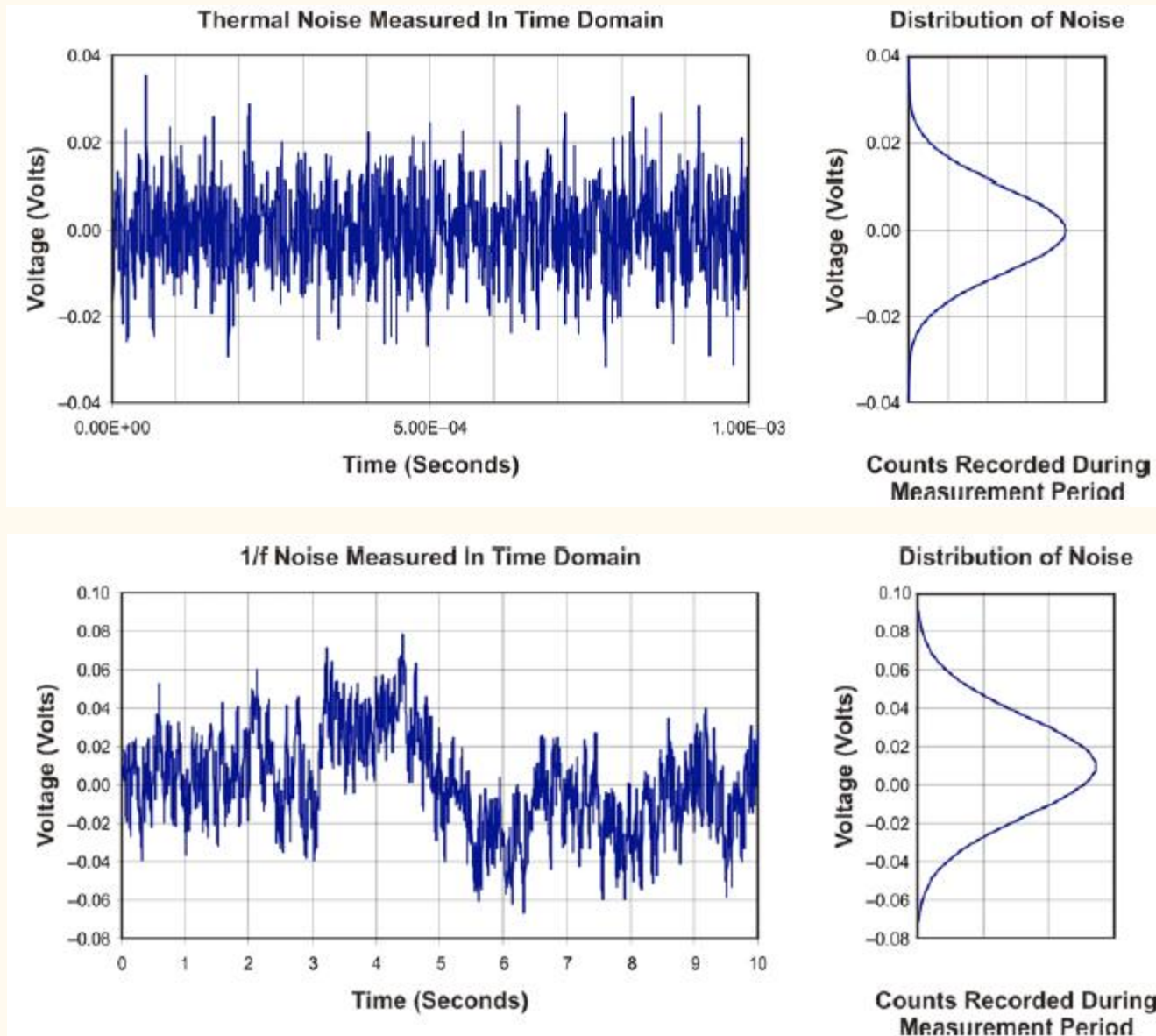
pn junction



Two-level system

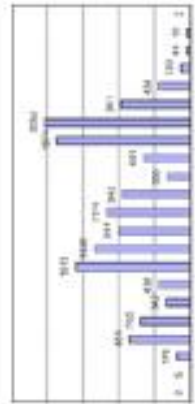


# Amplitude distributions of random-type noises

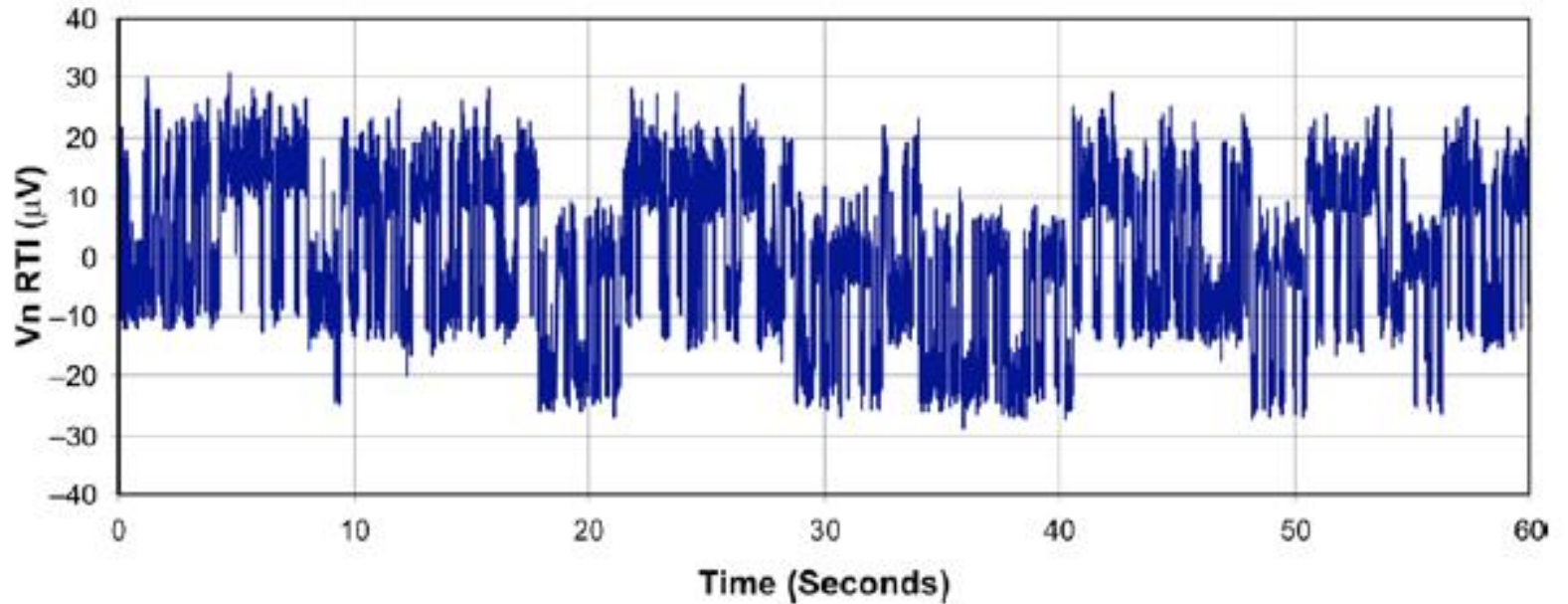




# Amplitude distribution of popcorn noise

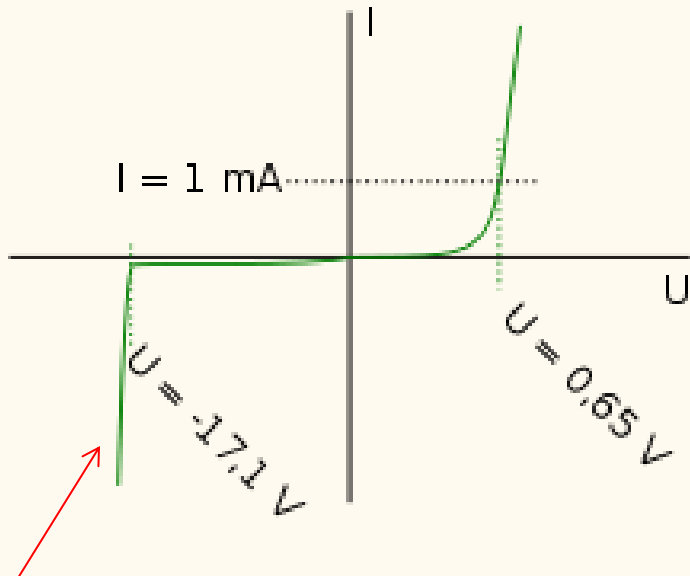


Popcorn Noise ( $f_c = 300\text{Hz}$ )





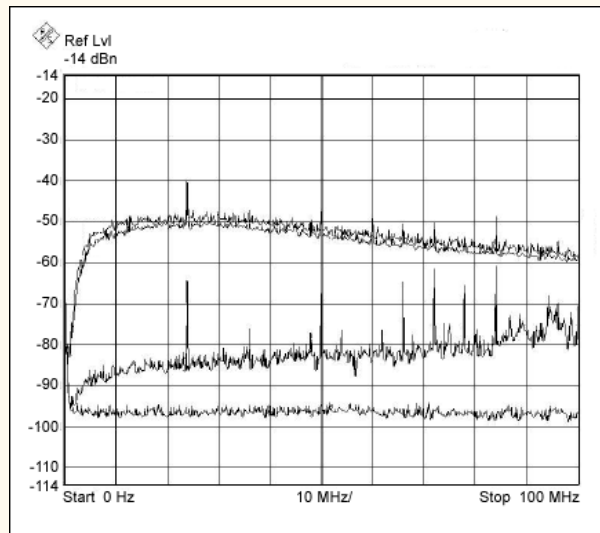
# Avalanche noise



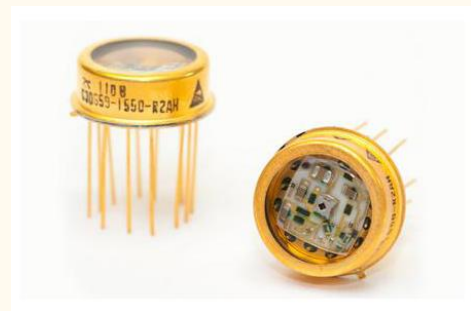
avalanche or Zener breakdown



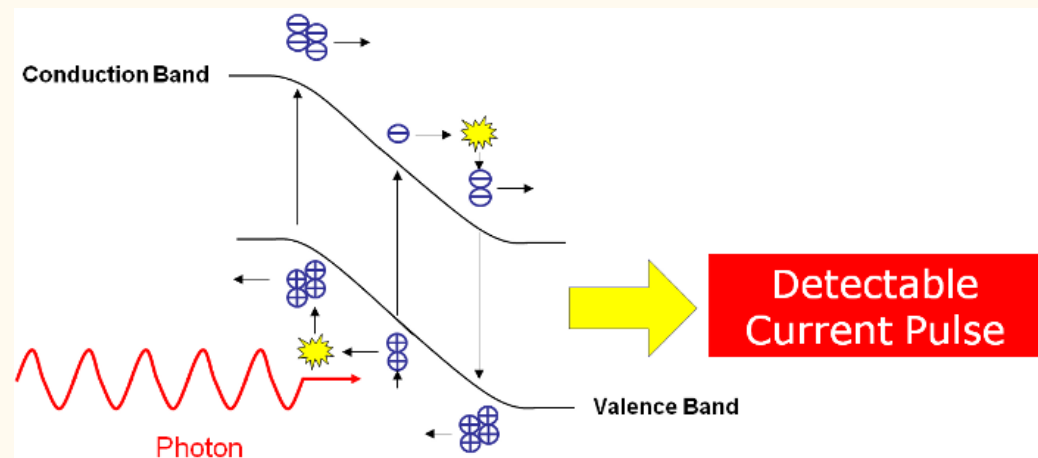
Zener voltage standard diode



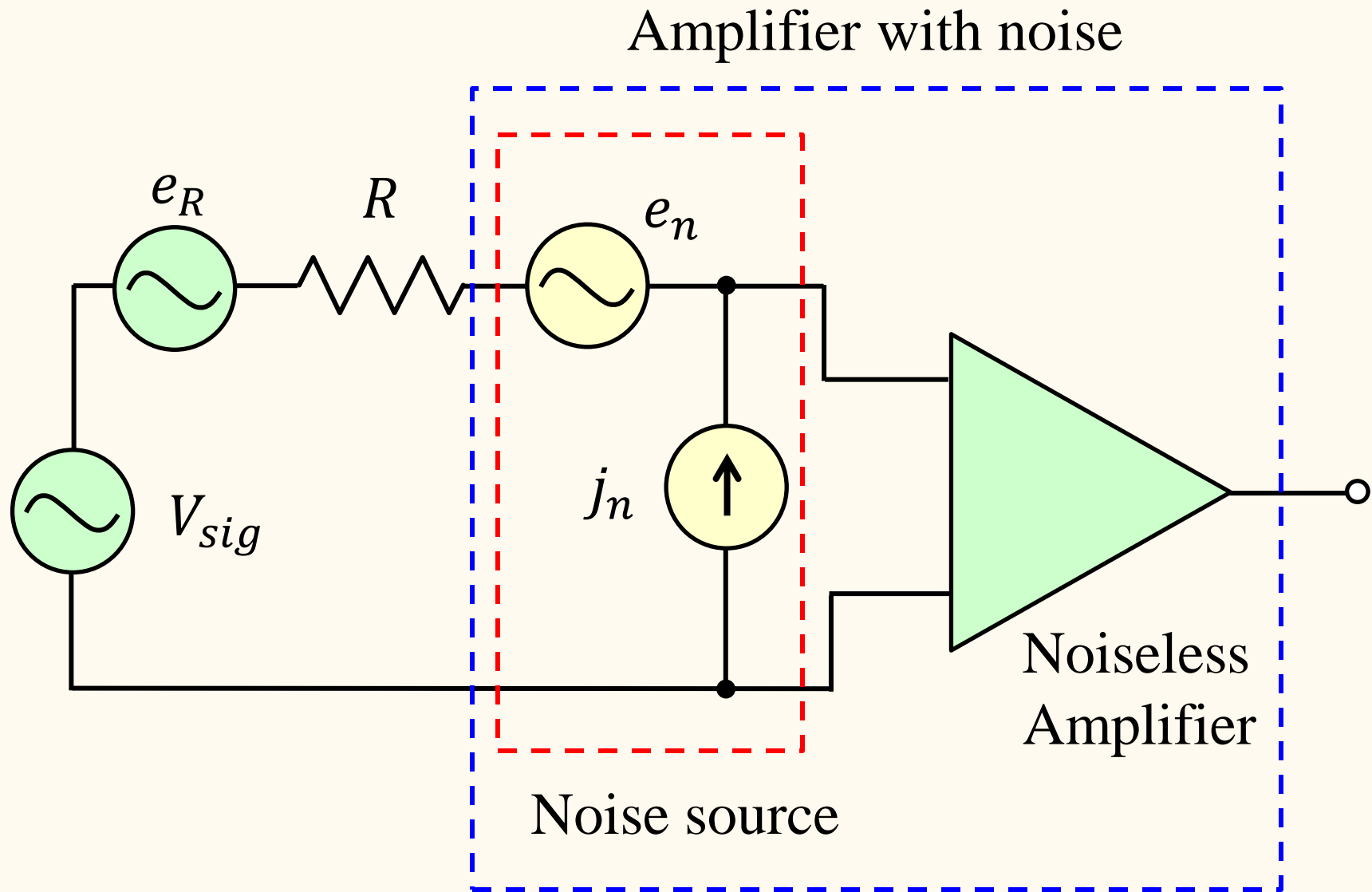
white noise



Avalanche Photo-Diode (APD)



## 6.2 Noises from Amplifiers



## 6.2 Noises from Amplifiers

Amplifiers: the elements have characteristic noises,  
power sources work as noise sources

➔ Noiseless amplifier + Noise source = Amplifier with noise

Power gain  $G_p$

$$e_{\text{intotal}}^2 = j_n^2 R^2 + e_R^2 + e_n^2 = e_{\text{out}}^2 / G_p$$

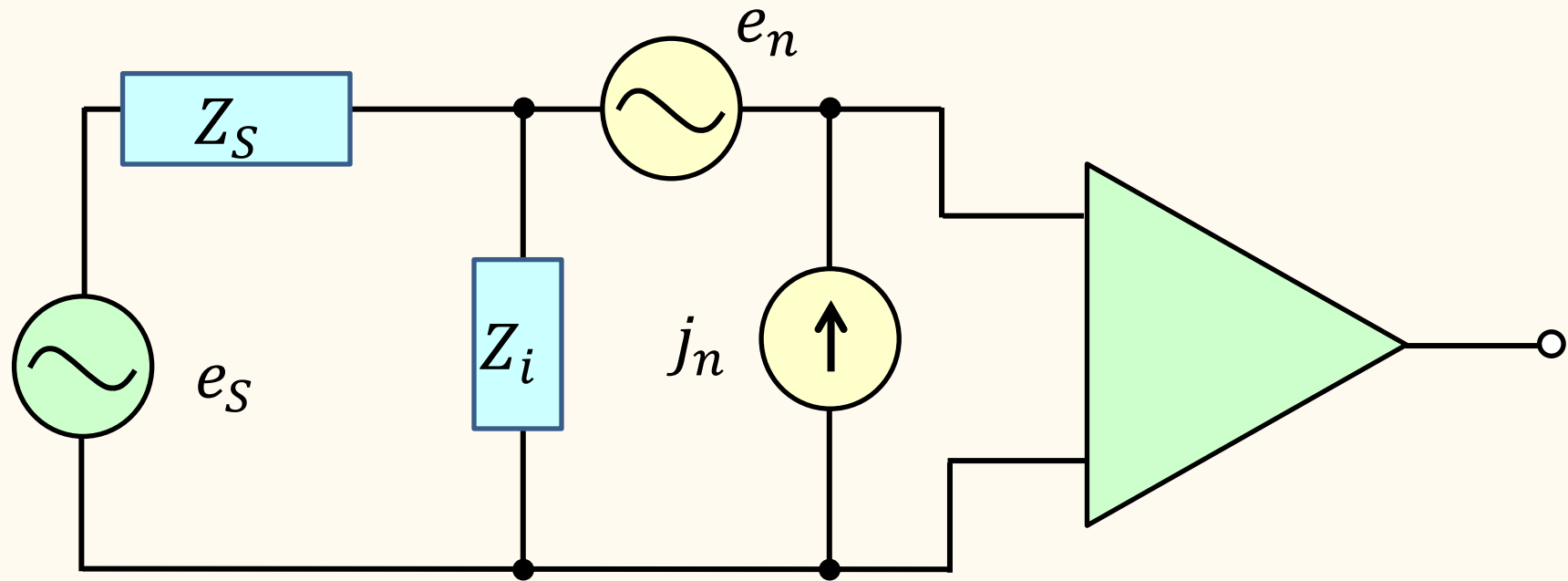
Signal to noise ratio: **S/N ratio**

**Noise Figure:** 
$$\text{NF} = 10 \log_{10} \frac{(S/N)_{\text{in}}}{(S/N)_{\text{out}}} = 10 \log_{10} \frac{S_{\text{in}} N_{\text{out}}}{S_{\text{out}} N_{\text{in}}}$$

$$N_{\text{out}} = G_p \overline{e_N^2}$$

$$\text{NF} = 10 \log_{10} \frac{S_{\text{in}} G_p \overline{e_N^2}}{S_{\text{in}} G_p \overline{e_R^2}} = 10 \log_{10} \frac{\overline{e_N^2}}{\overline{e_R^2}} = 10 \log_{10} \frac{\overline{e_n^2} + \overline{e_R^2} + \overline{j_n^2 R^2}}{\overline{e_R^2}}$$

## 6.2.2 Noise impedance matching



## 6.2.2 Noise impedance matching

Noise temperature and  
matched source impedance

$$T_a = \frac{\sqrt{e_n^2 j_n^2}}{2k_B}, \quad R_{bs} = \sqrt{\frac{e_n^2}{j_n^2}}$$

Output noise temperature:

$$T_n = \left(1 + \frac{\operatorname{Re}(1/Z_i)}{\operatorname{Re}(1/Z_s)}\right) \frac{T_a}{2\operatorname{Re}Z} \left(\frac{|Z|^2}{R_{bs}} + R_{bs}\right), \quad \frac{1}{Z} \equiv \frac{1}{Z_i} + \frac{1}{Z_s}$$

Minimize  $T_n$ :  $Z_i = \frac{1}{R_{bs}^{-1} - Z_s^{-1}}$  Noise matching condition

$$T_n = \left(1 + \frac{\operatorname{Re}(1/Z_i)}{\operatorname{Re}(1/Z_s)}\right) T_a$$

# References

C. Kittel, "Elementary Statistical Physics", (Dover, 2004).

遠坂俊昭「計測のためのアナログ回路設計」(CQ出版社, 1997).

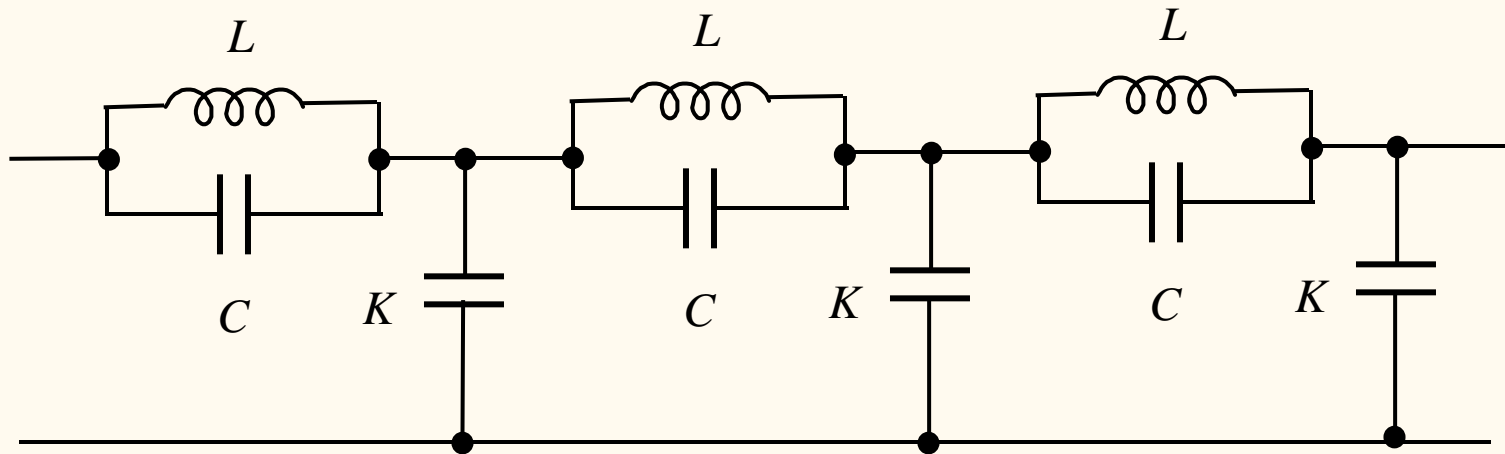
Anton F. P. van Putten, "Electronic Measurement Systems",  
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寺本英, 広田良吾, 武者利光, 山口昌哉  
「無限・カオス・ゆらぎ」(培風館, 1985).



# Exercise E-1

Obtain the dispersion relation in the following transmission line.



## Exercise E-2

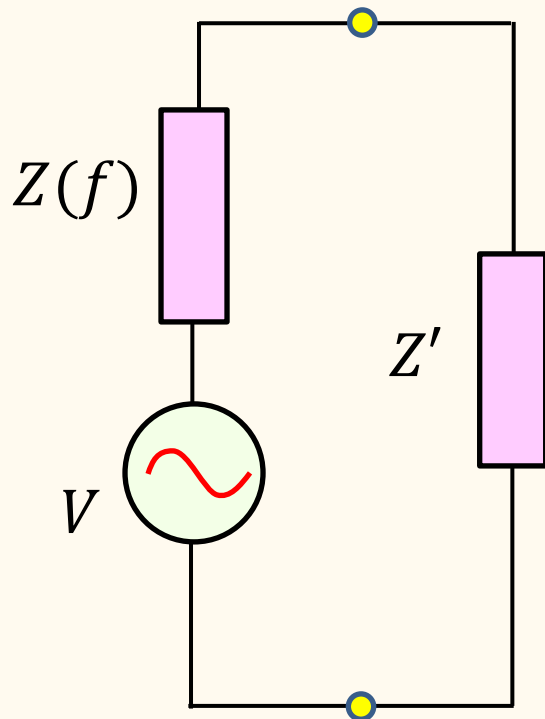
Show that the power spectrum  $G(f)$  of voltage noise across the impedance

$$Z(f) = R(f) + iY(f)$$

is given as

$$G(f) = 4R(f)k_B T.$$

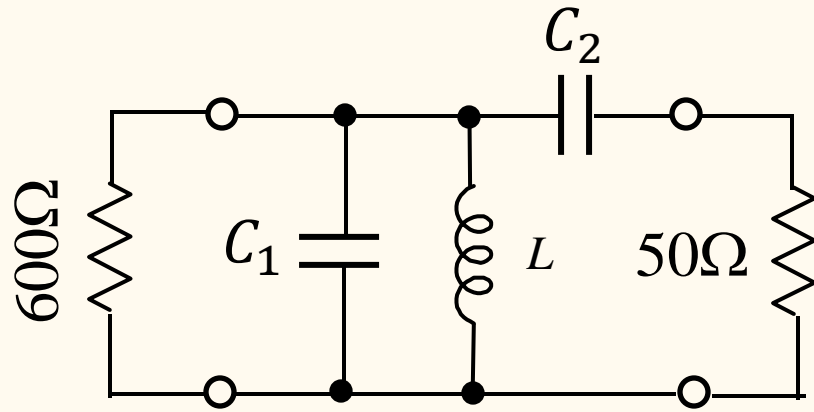
Assume that thermal noise energy per unit time is  $k_B T \Delta f$ .



(hint) From the above assumption we can skip the discussion on the mode energy in transmission line. Instead consider the case in the left figure, in which  $Z'$  is matched to  $Z$  as

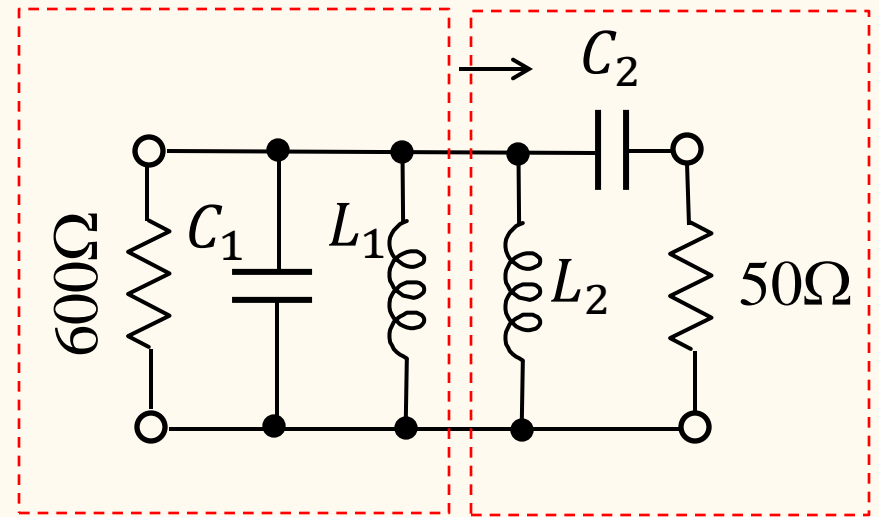
$$Z'(f) = Z^*(f) = R(f) - iY(f)$$

# Exercise E-3



(a)

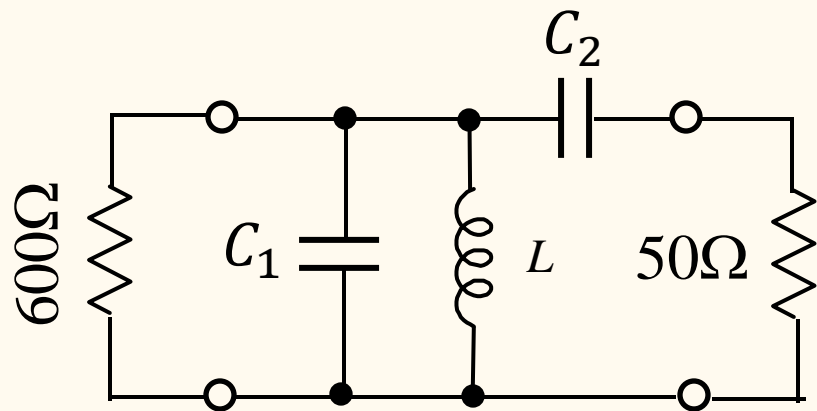
(b)



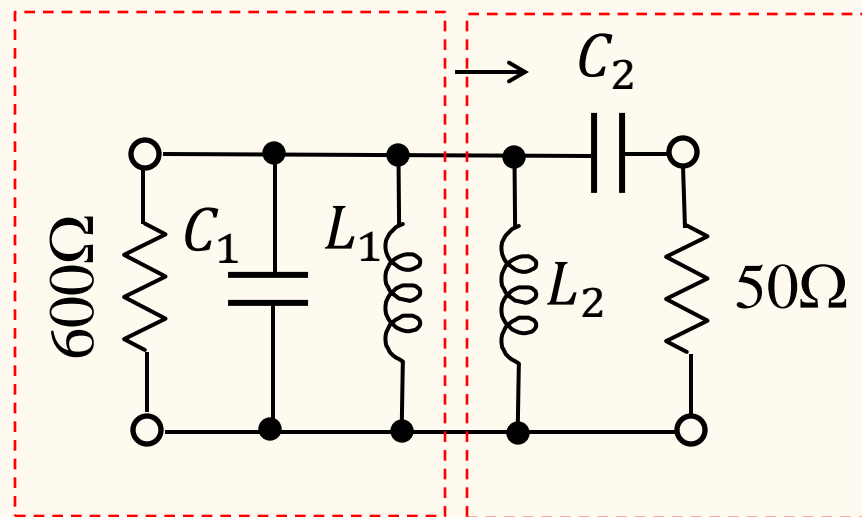
A preamplifier with FETs for an FM receiver has the output impedance of  $600\Omega$ . The FM receiver has the input impedance of  $50\Omega$  and we need to make impedance matching. The central frequency is  $85\text{MHz}$ , the effective width of amplification is  $10\text{MHz}$ . Obtain  $C_1$ ,  $C_2$ ,  $L$  in the matching circuit with 3 digits significant figures.

(hint) Express  $L$  with a parallel of  $L_1$  and  $L_2$  as shown in (b). The left resonance circuit should be tuned to  $85\text{MHz}$ , width  $10\text{MHz}$ . Then the left and the right circuit should be impedance matched.

# Exercise E-3



(a)



(b)

FM受信機のプリアンプをFETで作ったところ、出力インピーダンスが $600\Omega$ になった。受信機の入力インピーダンスは $50\Omega$ なので、インピーダンスマッチを取る必要がある。中心周波数を $85\text{MHz}$ 、有効周波数幅を $10\text{MHz}$ 、として(a)のような回路でマッチを取ると、回路定数 $C_1, C_2, L$ はどうか。有効数字3桁で答えよ。

(ヒント) (b)のようにインダクタンスを2つに分割し、左の共鳴回路で $85\text{MHz}$ 、 $10\text{MHz}$ 幅に同調させる。この後、左右のインピーダンスが一致するように定数を求める。

# 電子回路論第11回

## Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所

勝本信吾

Shingo Katsumoto





# Outline

## 6.2 Noise from amplifiers

6.2.1 Noise figure

6.2.2 Noise impedance matching

## 6.3 Modulation and signal transfer

6.3.1 Modulation/demodulation

6.3.2 Amplitude modulation

6.3.3 Angle modulation

6.3.4 Demodulation of frequency  
modulated signal

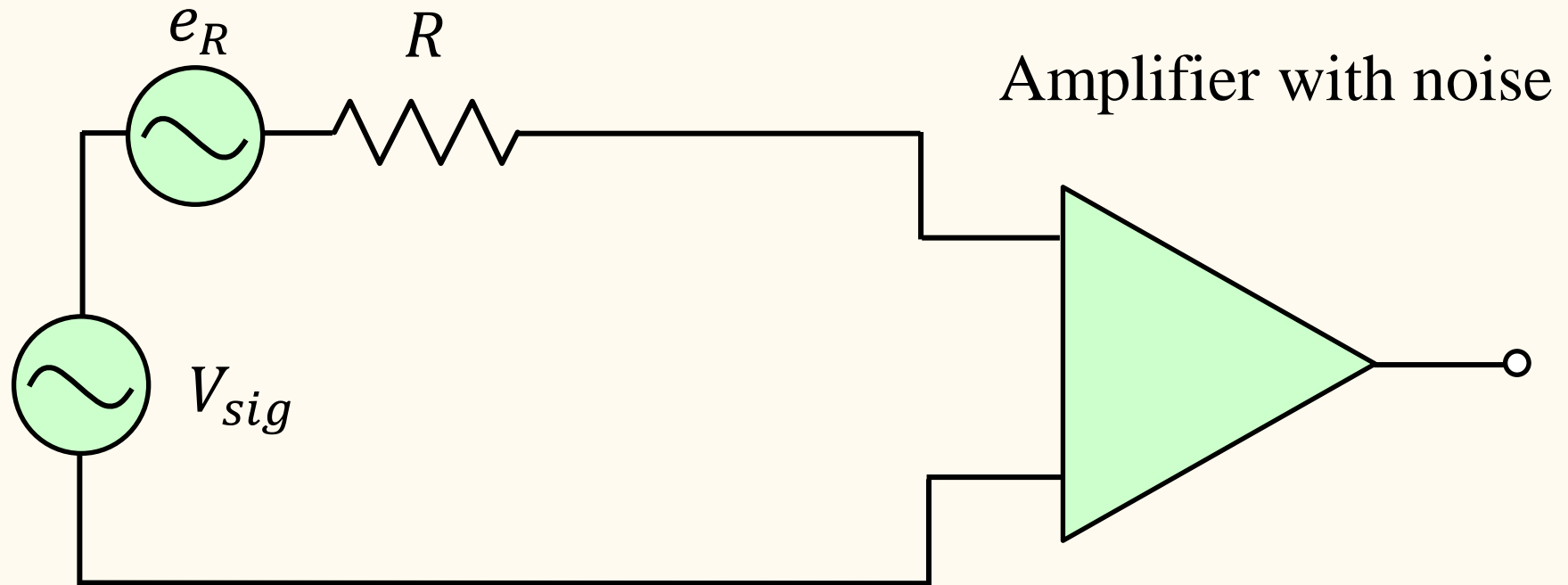
6.3.5 Modulation and noise



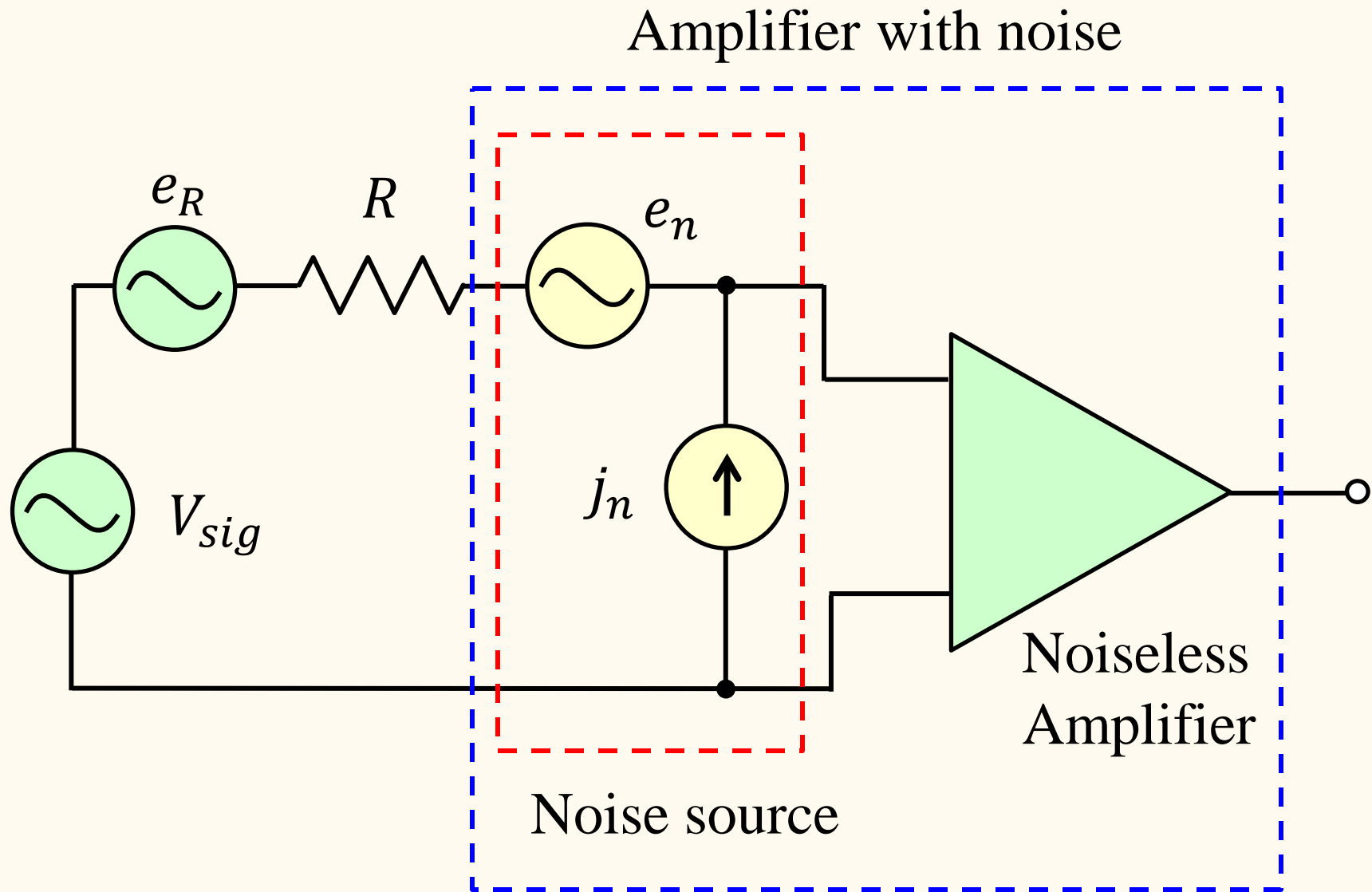
FM broadcast test



## 6.2 Noise from Amplifiers



## 6.2 Noise from Amplifiers



## 6.2 Noise from Amplifiers

Amplifiers: the elements have characteristic noises,  
power sources work as noise sources



Noiseless amplifier + Noise source = Amplifier with noise

Power gain  $G_p$        $e_{\text{intotal}}^2 = j_n^2 R^2 + e_R^2 + e_n^2 = e_{\text{out}}^2 / G_p$

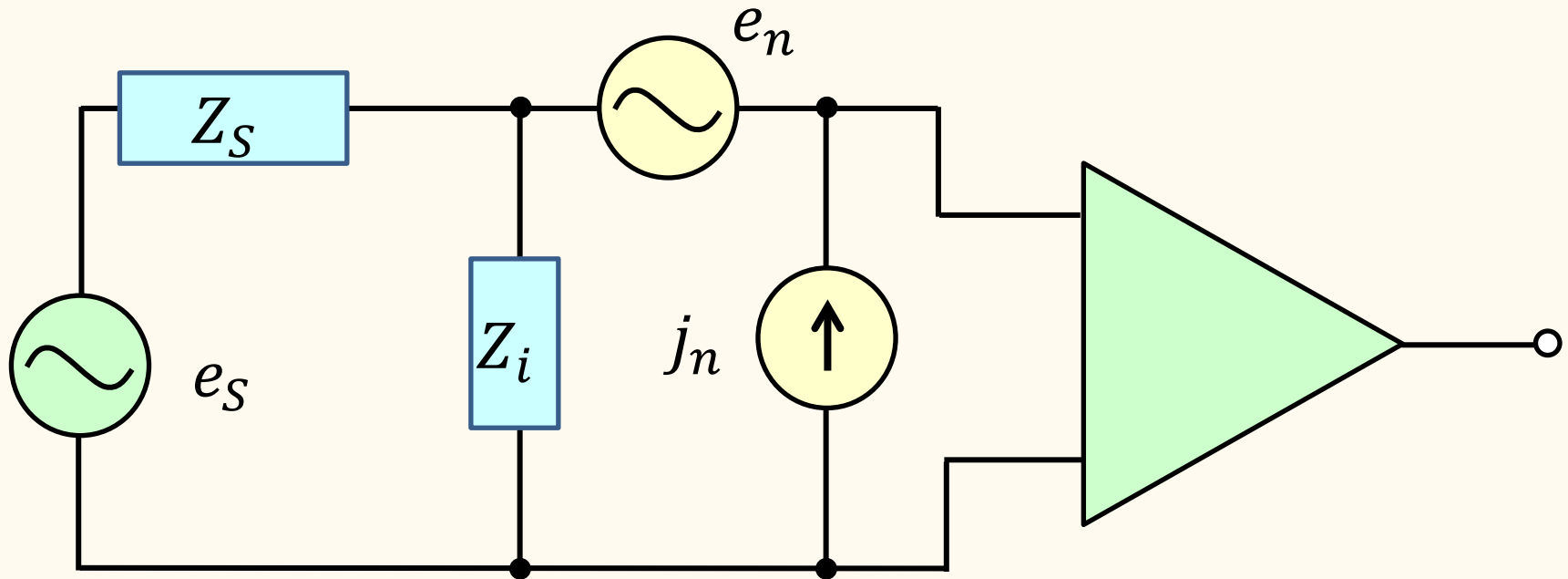
Signal to noise ratio: **S/N ratio**

**Noise Figure:** 
$$NF = 10 \log_{10} \frac{(S/N)_{\text{in}}}{(S/N)_{\text{out}}} = 10 \log_{10} \frac{S_{\text{in}} N_{\text{out}}}{S_{\text{out}} N_{\text{in}}}$$

$$N_{\text{out}} = G_p \overline{e_N^2}$$

$$NF = 10 \log_{10} \frac{S_{\text{in}} G_p \overline{e_N^2}}{S_{\text{in}} G_p \overline{e_R^2}} = 10 \log_{10} \frac{\overline{e_N^2}}{\overline{e_R^2}} = 10 \log_{10} \frac{\overline{e_n^2} + \overline{e_R^2} + \overline{j_n^2 R^2}}{\overline{e_R^2}}$$

## 6.2.2 Noise impedance matching



Optimization of S/N ratio including the noise-source in the amplifier  
(a care should be taken to the effect of noise to the object)

Noises from the signal source, amplifiers: repel as much as possible  
Signals from the source: absorb ...

Noise temperature method: not almighty

## 6.2.2 Noise impedance matching

Nyquist theorem:

$$\sqrt{J^2 V^2} = 2k_B T \Delta f \quad \text{Noise temperature definition } (J(f), V(f))$$

Noise temperature and matched source impedance

$$T_a = \frac{\sqrt{e_n^2 j_n^2}}{2k_B}, \quad R_{bs} = \sqrt{\frac{e_n^2}{j_n^2}}$$

Output noise temperature:

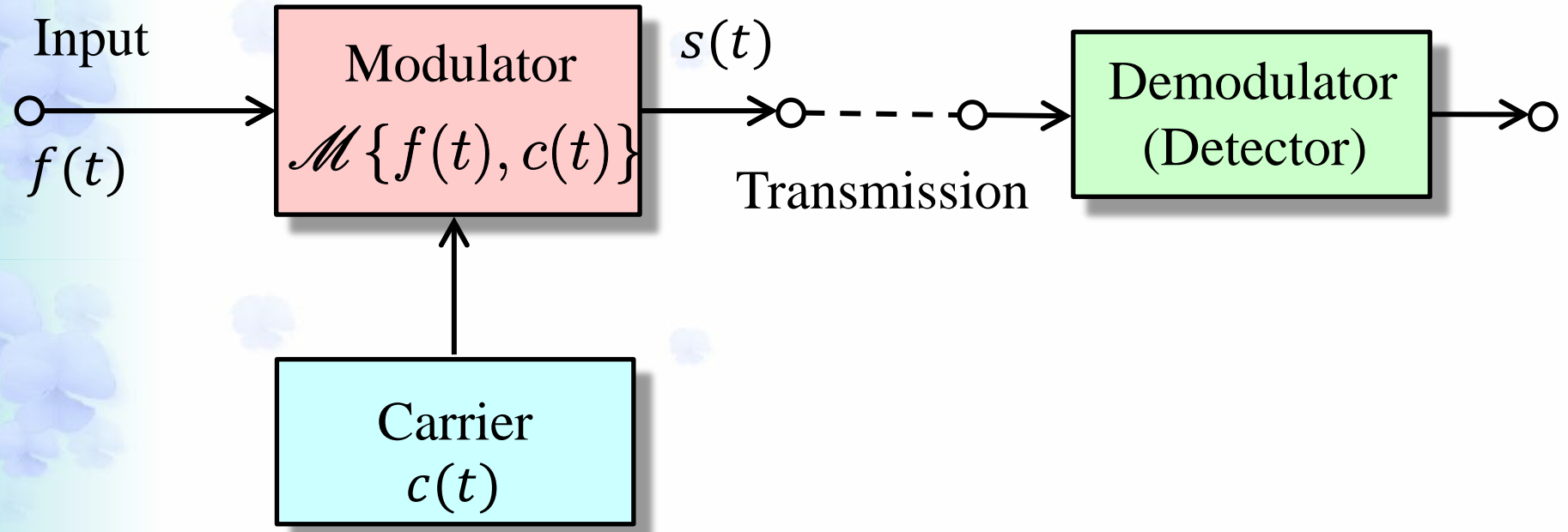
$$T_n = \left(1 + \frac{\operatorname{Re}(1/Z_i)}{\operatorname{Re}(1/Z_s)}\right) \frac{T_a}{2\operatorname{Re}Z} \left(\frac{|Z|^2}{R_{bs}} + R_{bs}\right), \quad \frac{1}{Z} \equiv \frac{1}{Z_i} + \frac{1}{Z_s}$$

Minimize  $T_n$ :  $Z_i = \frac{1}{R_{bs}^{-1} - Z_s^{-1}}$  Noise matching condition

$$T_n = \left(1 + \frac{\operatorname{Re}(1/Z_i)}{\operatorname{Re}(1/Z_s)}\right) T_a$$

# 6.3 Signal transmission

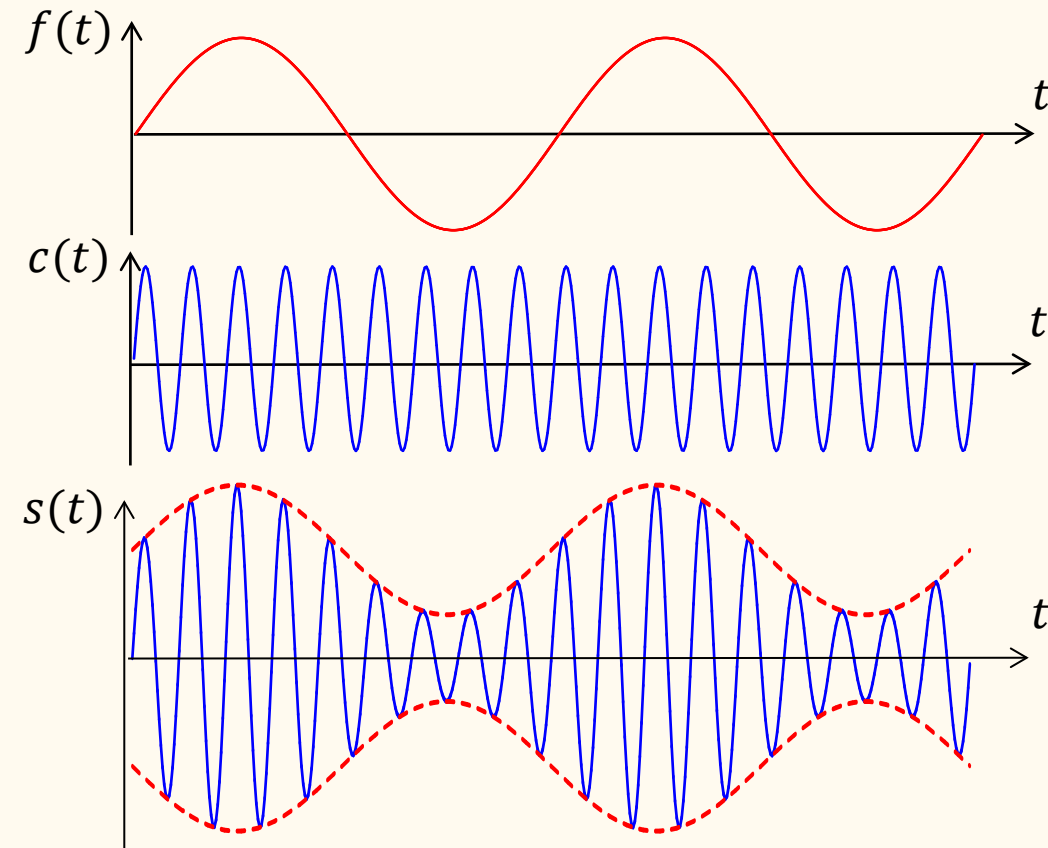
Electric communication {  
Baseband communication  
Carrier communication



Modulation {  
Amplitude modulation  
Frequency (Phase) modulation } Analog  
Pulse



## 6.3.2 Amplitude modulation



$$c(t) = A \cos \omega_c t$$

$$s(t) = A[1 + m f(t)] \cos \omega_c t$$

$m$ : Modulation index

$$0 < m \leq 1$$

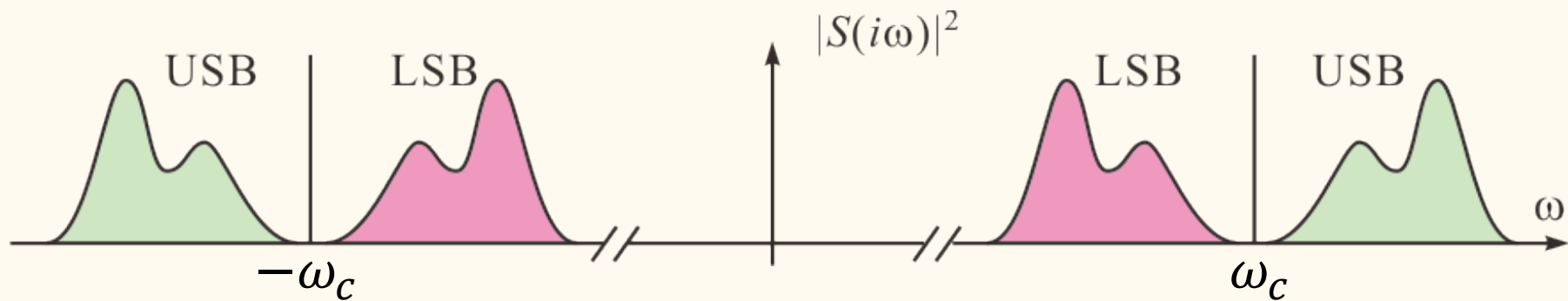
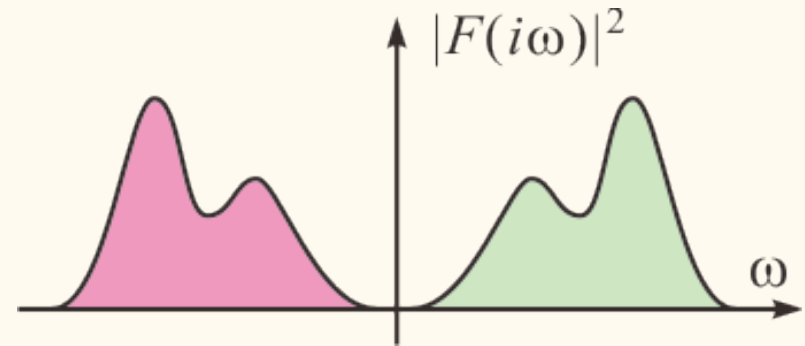
$$\begin{aligned} S(i\omega) &= \int_{-\infty}^{\infty} s(t) e^{i\omega t} dt = \int_{-\infty}^{\infty} A[1 + m f(t)] \cos(\omega_c t) e^{i\omega t} dt \\ &= A \left\{ \pi [\delta(\omega - \omega_c) + \delta(\omega + \omega_c)] \right. \\ &\quad \left. + \frac{m}{2} [F(i(\omega - \omega_c)) + F(i(\omega + \omega_c))] \right\} \end{aligned}$$

## 6.3.2 Amplitude modulation

$$\begin{aligned} S(i\omega) &= \int_{-\infty}^{\infty} s(t)e^{i\omega t} dt = \int_{-\infty}^{\infty} A[i + mf(t)] \cos(\omega_c t)e^{i\omega t} dt \\ &= A \left\{ \pi[\delta(\omega - \omega_c) + \delta(\omega + \omega_c)] \right. \\ &\quad \left. + \frac{m}{2}[F(i(\omega - \omega_c)) + F(i(\omega + \omega_c))] \right\} \end{aligned}$$

$$F(i\omega) = \mathcal{F}\{f(t)\}$$

$$f(t): \text{Real} \quad F(i\omega) = F^*(-i\omega)$$

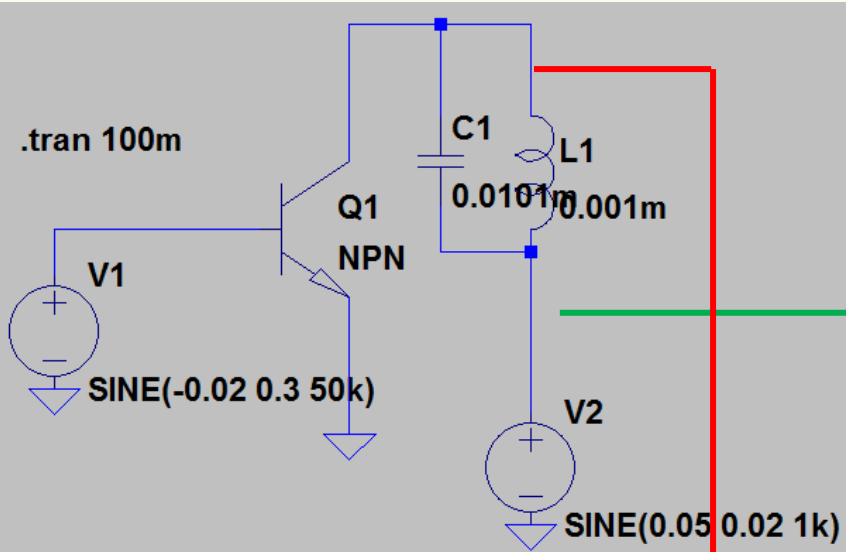


Upper side band (USB), Lower side band (LSB)

# 6.3.2 Amplitude modulation (circuit example)

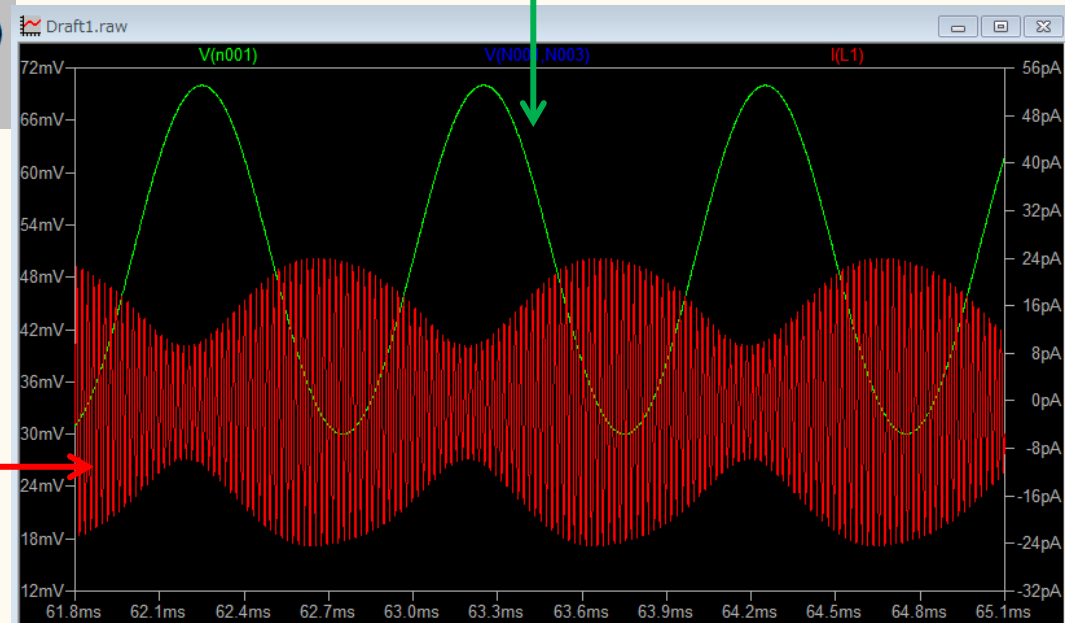
Collector modulation circuit

C-class amplification (non-linear) region



Modulation voltage

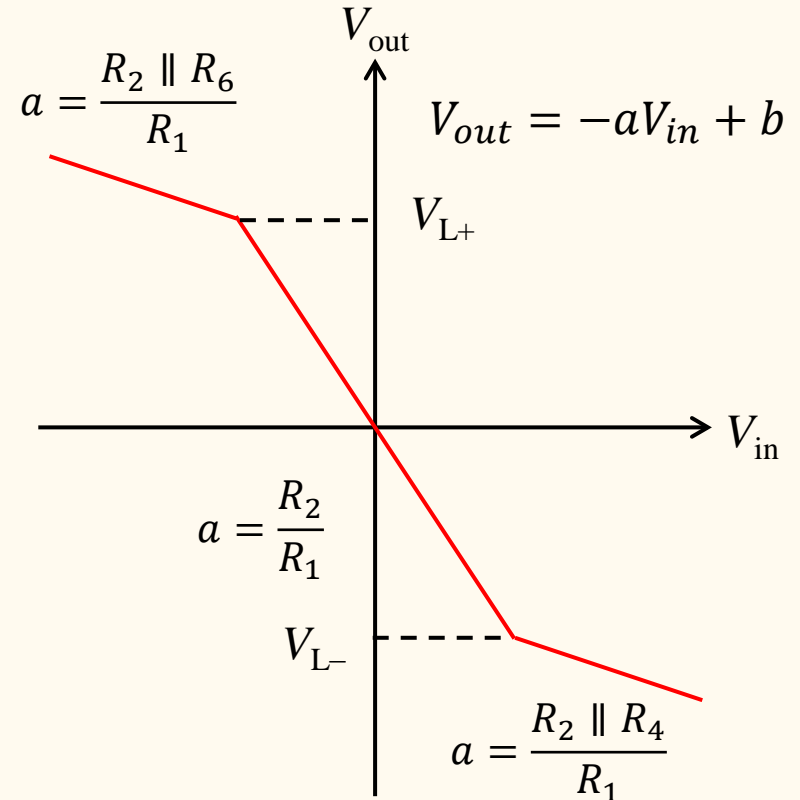
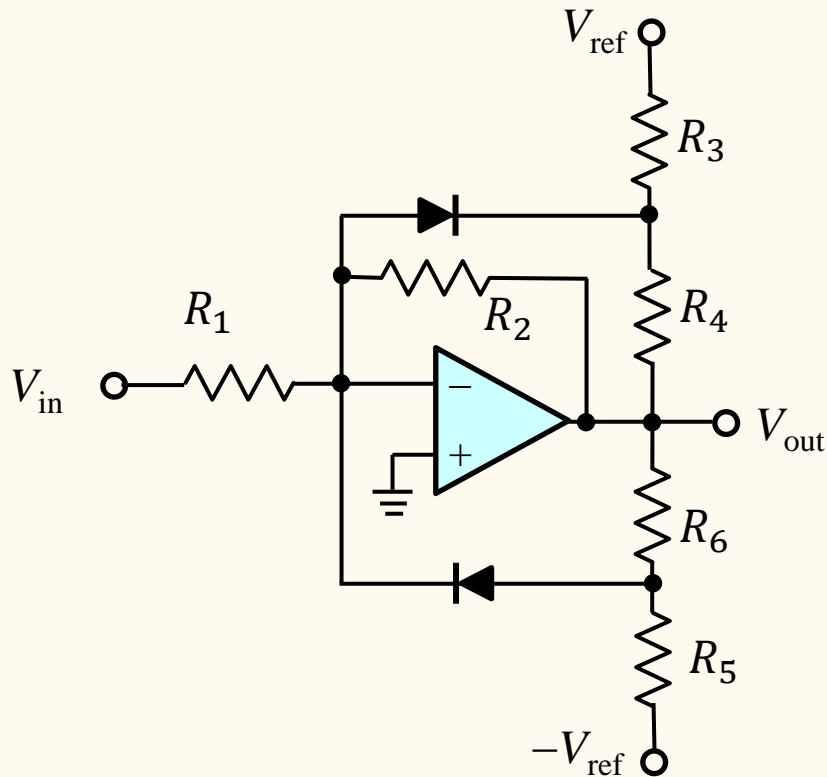
Current through the inductor



## 6.3.2 Amplitude modulation (circuit example2)

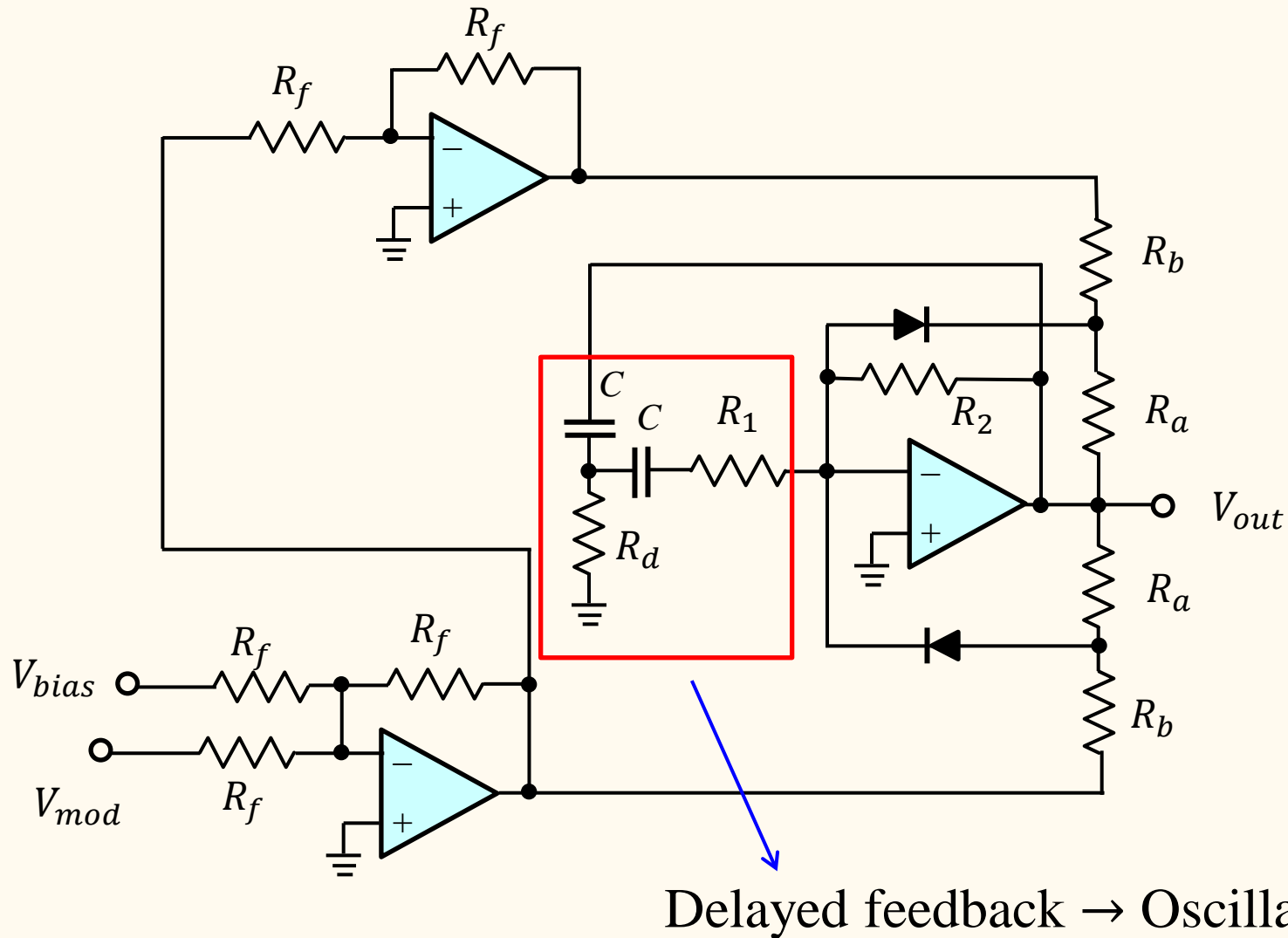
### Modulation of oscillator circuit

#### Soft limiter circuit



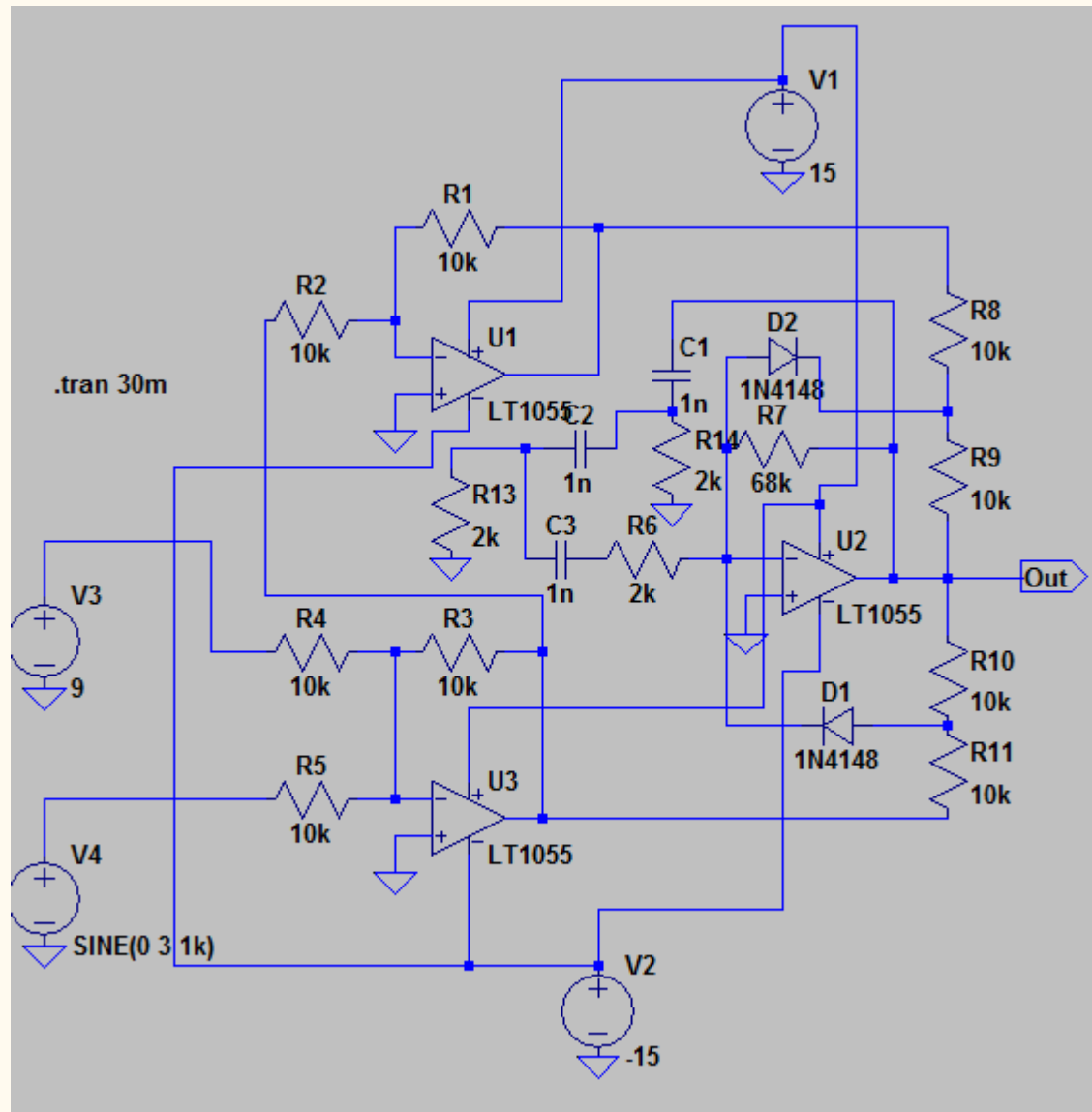
$$V_{L-} = -\frac{R_4}{R_3} V_{ref} - \left(1 + \frac{R_4}{R_3}\right) V_{th} \quad : \text{controllable with } V_{ref}$$

## 6.3.2 Amplitude modulation (circuit example2)



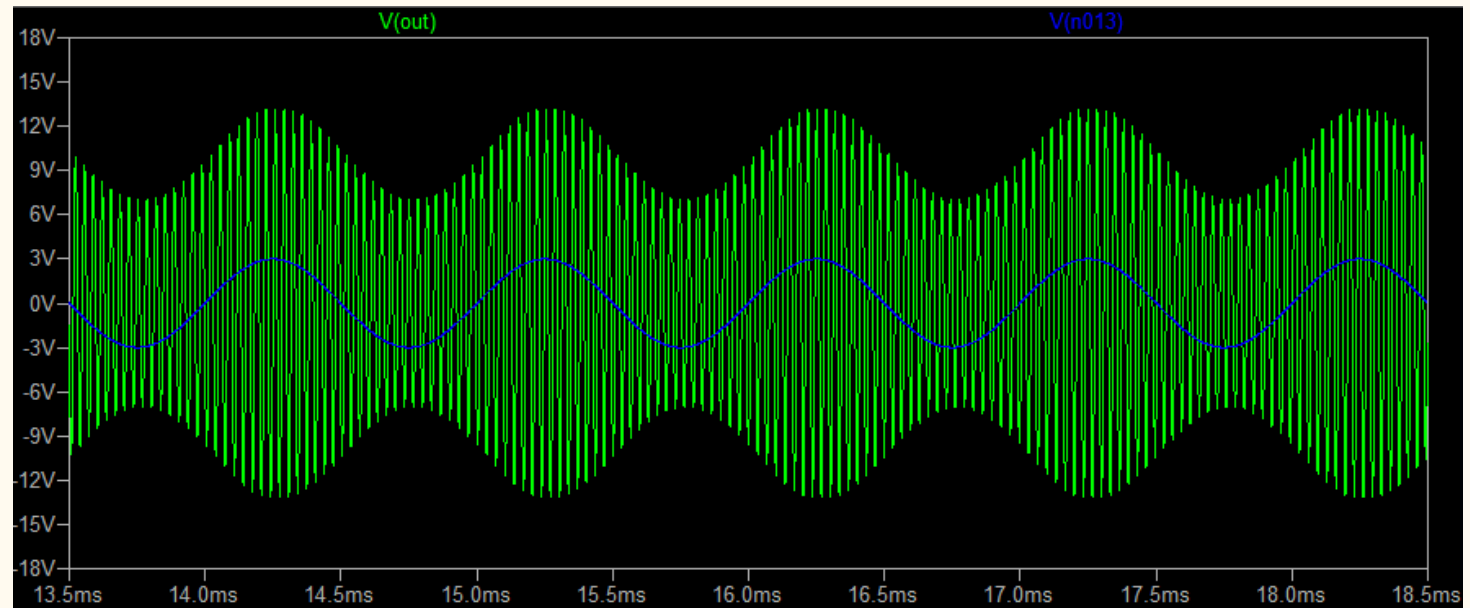
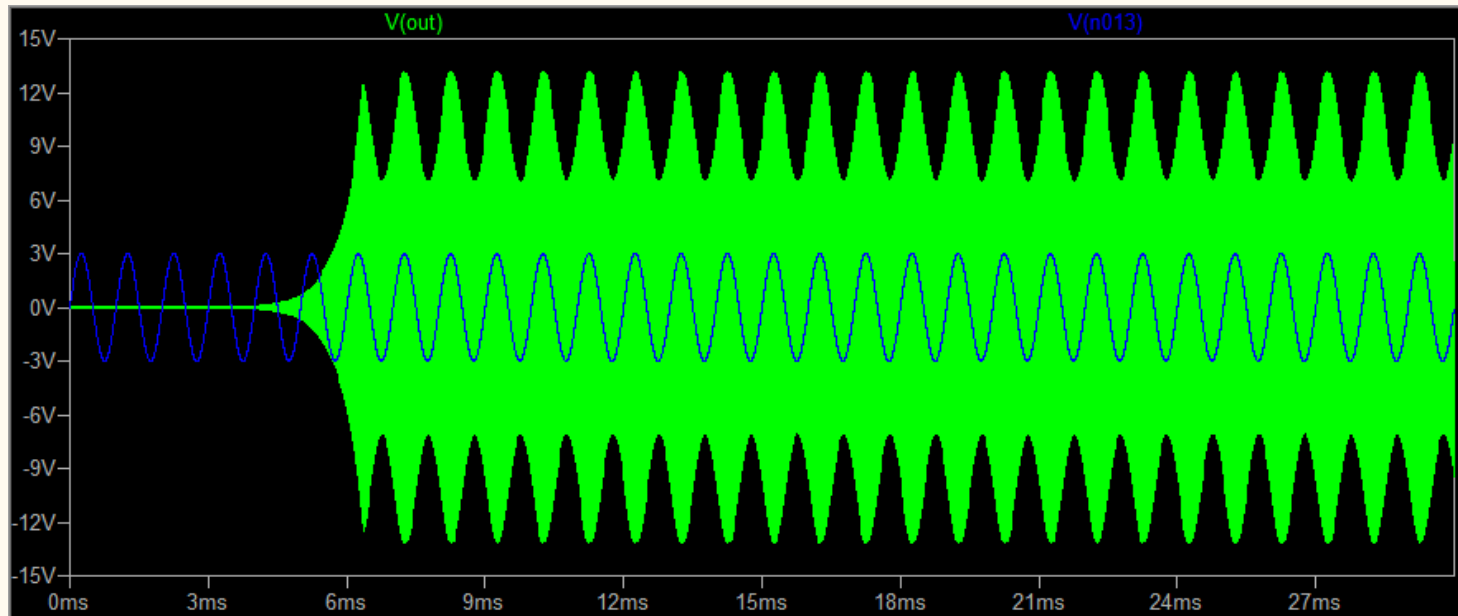
The amplitude is softly limited with the modulation voltage.

## 6.3.2 Amplitude modulation (circuit example2)

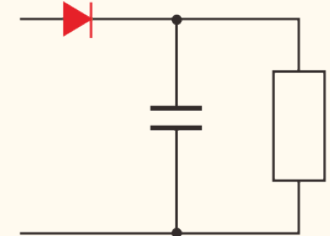
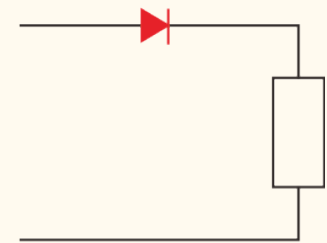
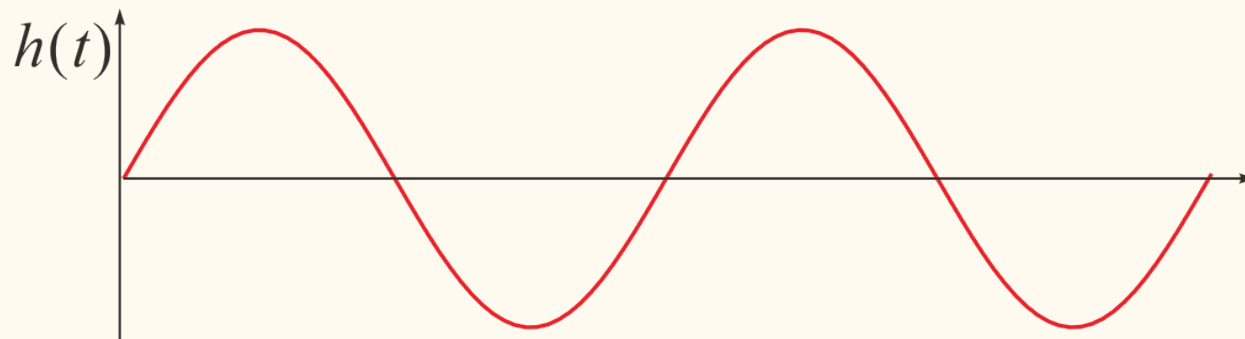
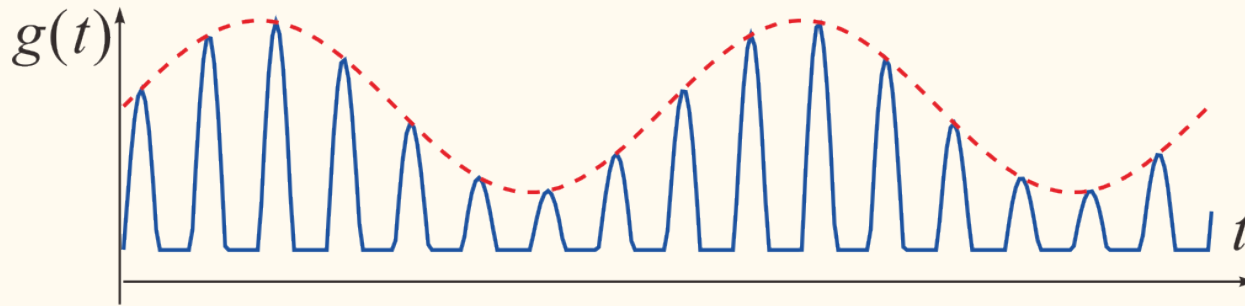
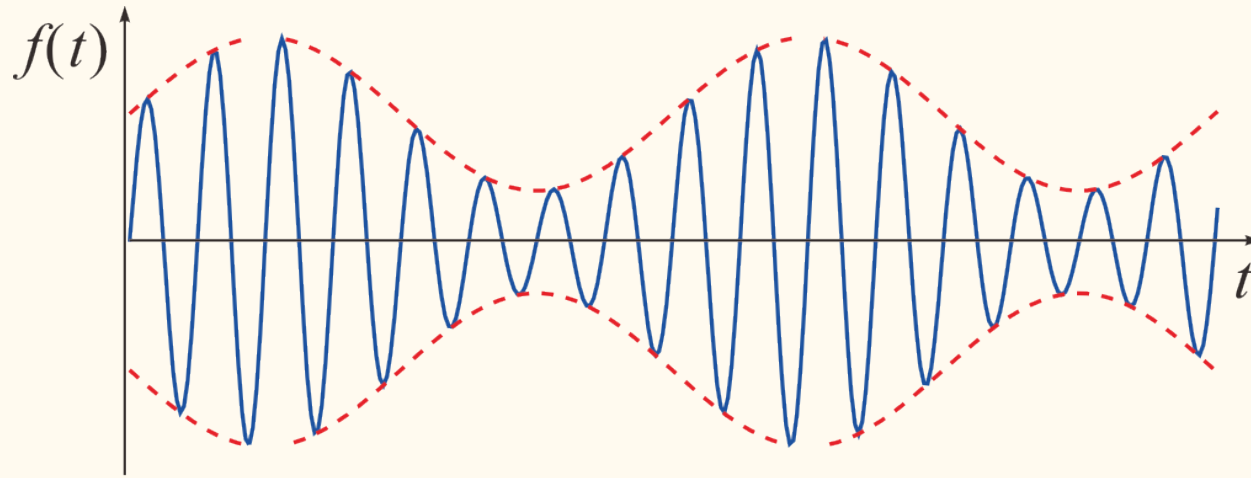




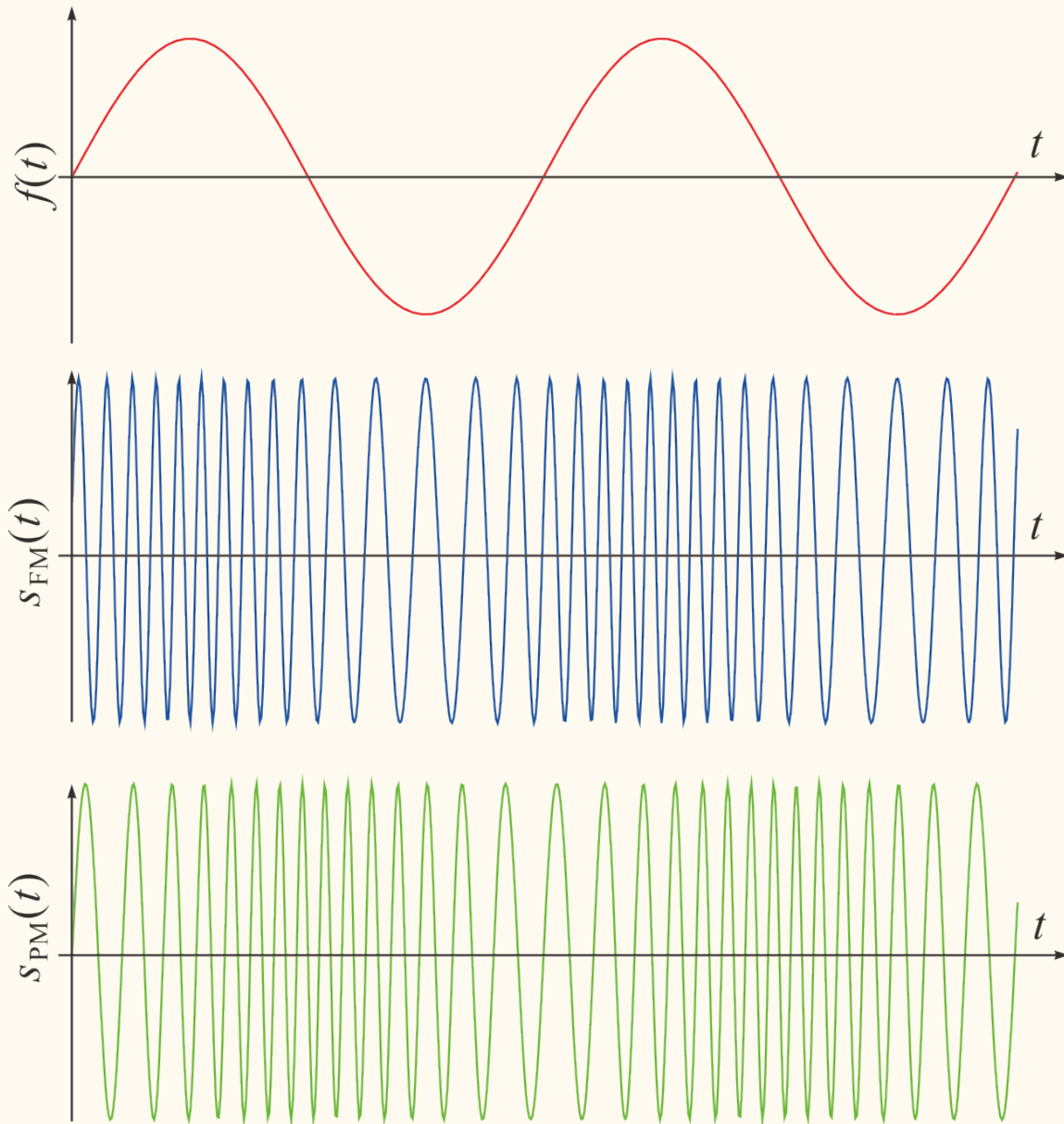
## 6.3.2 Amplitude modulation (circuit example2)



## 6.3.2 Amplitude modulation (demodulation)



## 6.3.3 Angle modulation



## 6.3.3 Angle modulation

$$s(t) = A \cos \theta_i(t), \quad \theta_i(t) = \omega_c t + \phi[t, f(t)]$$

Differential angular frequency  $\omega_i(t) = \frac{d\theta_i(t)}{dt} = \omega_c + \frac{d\phi[t, f(t)]}{dt}$

$$\frac{d\phi[t, f(t)]}{dt} = k_f f(t) \quad (\text{Frequency Modulation, FM}),$$

$$\phi[t, f(t)] = k_p f(t) \quad (\text{Phase Modulation, PM})$$

$$s_{\text{FM}}(t) = A \cos \left[ \omega_c t + k_f \int^t f(\tau) d\tau \right],$$

$$s_{\text{PM}}(t) = A \cos[\omega_c t + k_p f(t)]$$

Frequency  $\omega$  component: only phase shift  $\pi/2$  :

No difference in signal outlook.

### 6.3.3 Angle modulation (Frequency modulation)

$$f(t) = A_p \cos \omega_p t$$

$$s_{\text{FM}} = A \cos(\omega_c t + \beta \sin \omega_p t) = A \operatorname{Re} [\exp(i\omega_c t) \exp(i\beta \sin \omega_p t)]$$

$$\left( \beta \equiv \frac{k_f A_p}{\omega_p} = \frac{\Delta f}{f_p} \right)$$

$\sin \omega_p t$  : Periodic function with  $T = 2\pi/\omega_p$

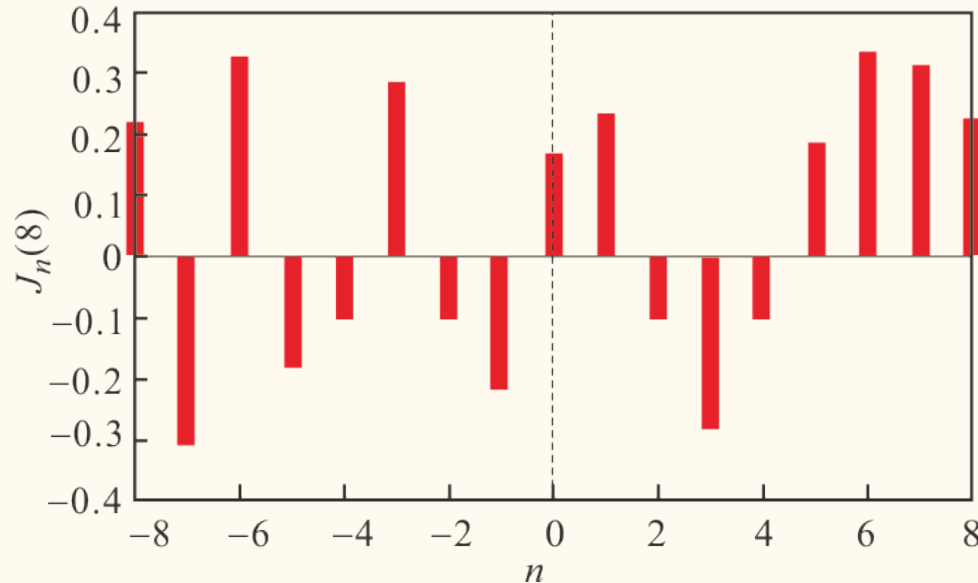
$$\exp(i\beta \sin \omega_p t) = \sum_{n=-\infty}^{\infty} c_n \exp(in\omega_p t), \quad \text{Fourier series expansion}$$

$$c_n = \frac{1}{T} \int_{-T/2}^{T/2} \exp(i\beta \sin \omega_p t) \exp(-in\omega_p t) dt$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \exp[i(\beta \sin \theta - n\theta)] d\theta = J_n(\beta)$$

First kind Bessel function

## 6.3.3 Angle modulation (Frequency modulation)



$$s_{\text{FM}}(t) = A \sum_{n=-\infty}^{\infty} J_n(\beta) \cos[(\omega_c + n\omega_p)t]$$

$$S_{\text{FM}}(i\omega) = \pi A \sum_{n=-\infty}^{\infty} J_n(\beta) \{ \delta[\omega - (\omega_c + n\omega_p)] + \delta[\omega + (\omega_c + n\omega_p)] \}$$

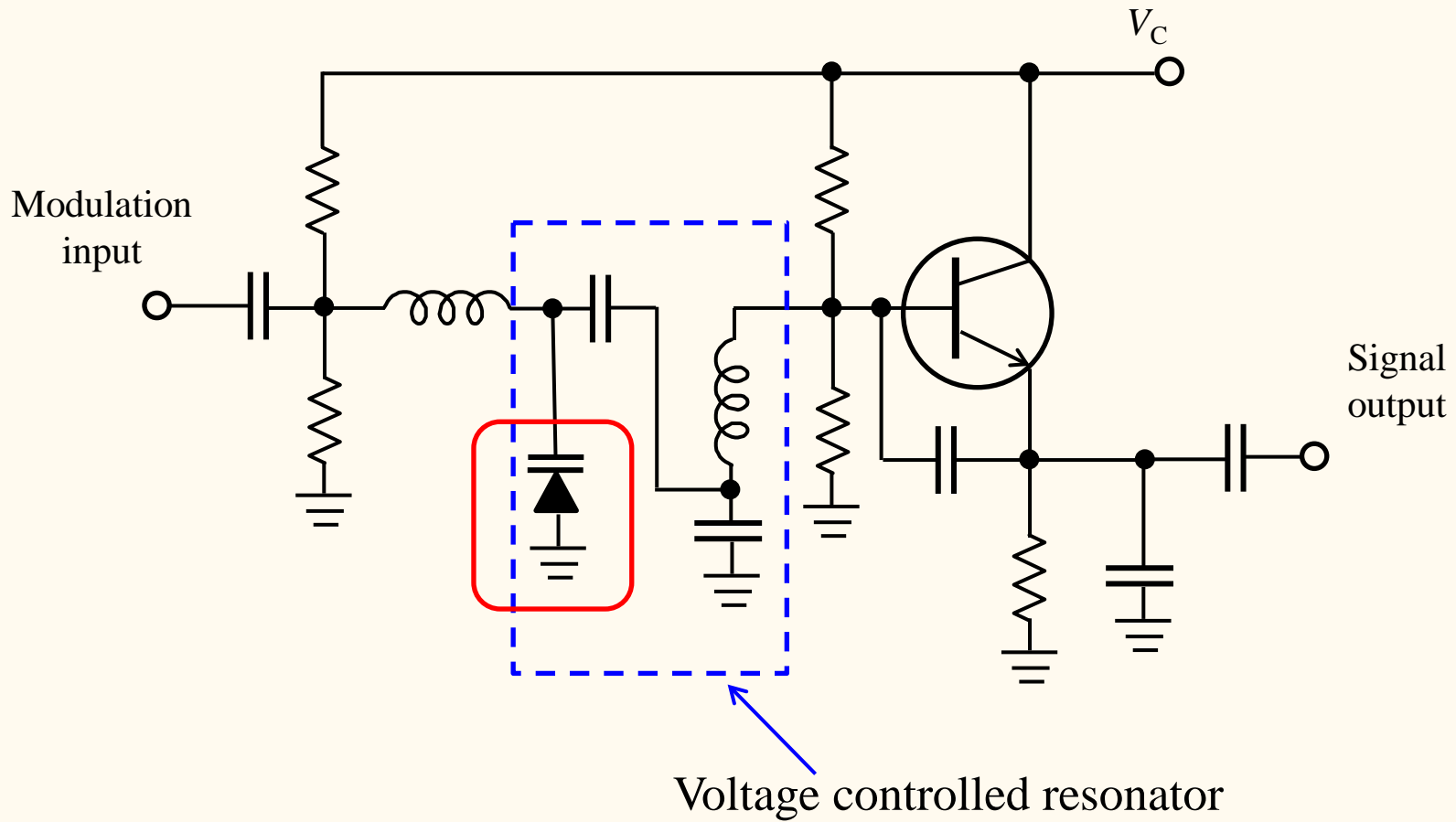
Actual band width:

$$\omega_{\text{bw}} = 2(\omega_f + \xi\omega_w) \quad 1 \leq \xi \leq 2$$

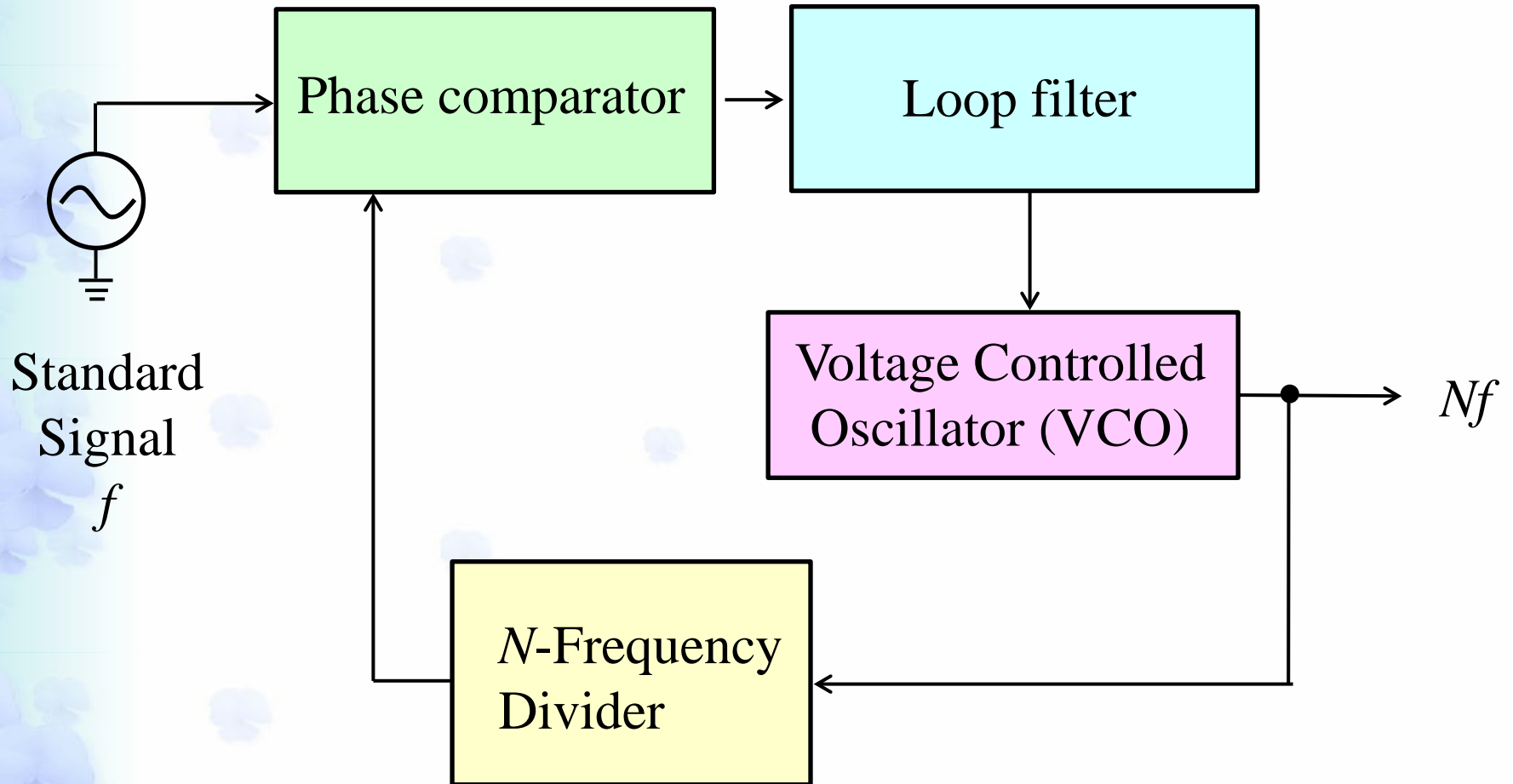


## 6.3.3 Angle modulation (circuit example)

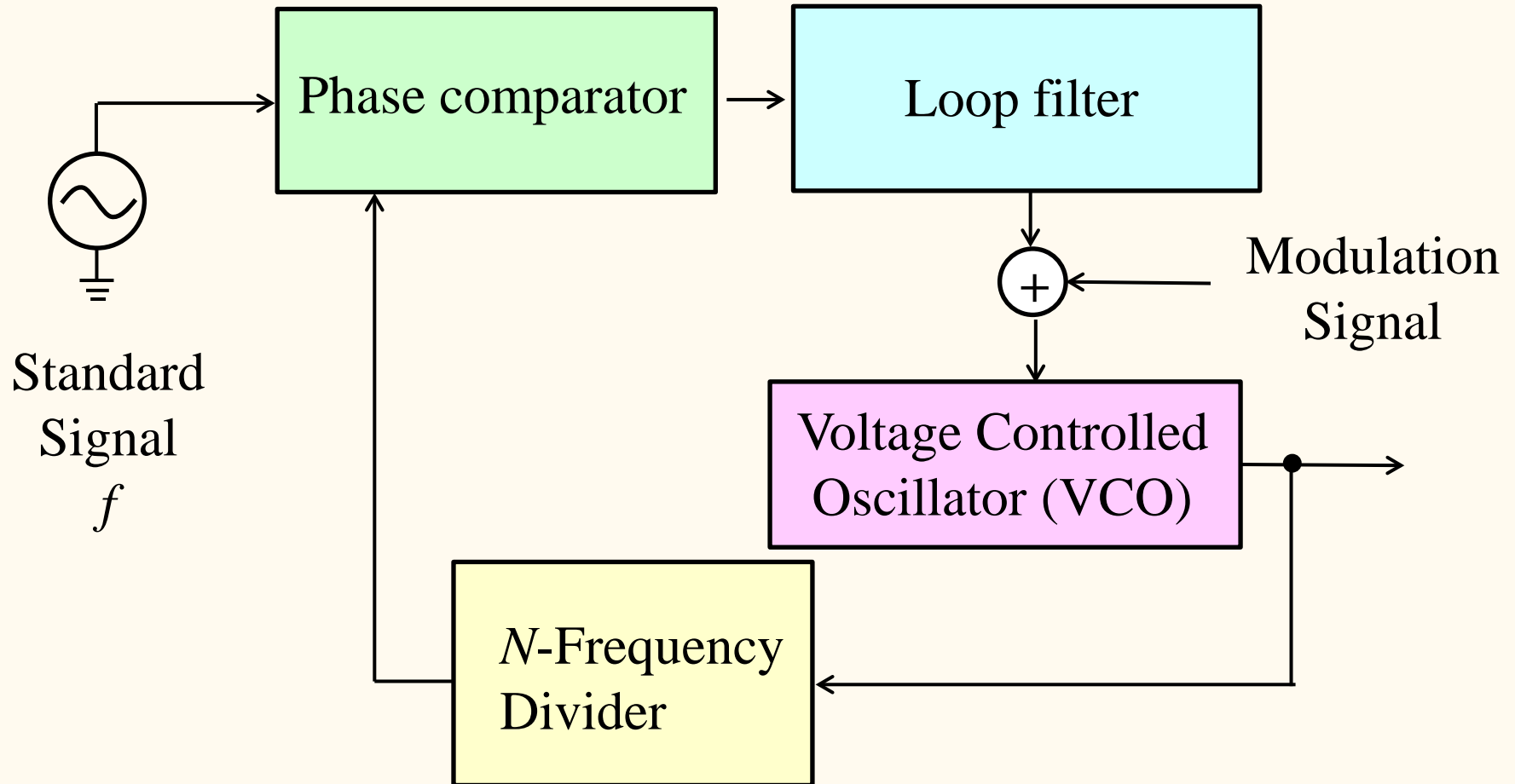
### Voltage Controlled Oscillator (VCO)



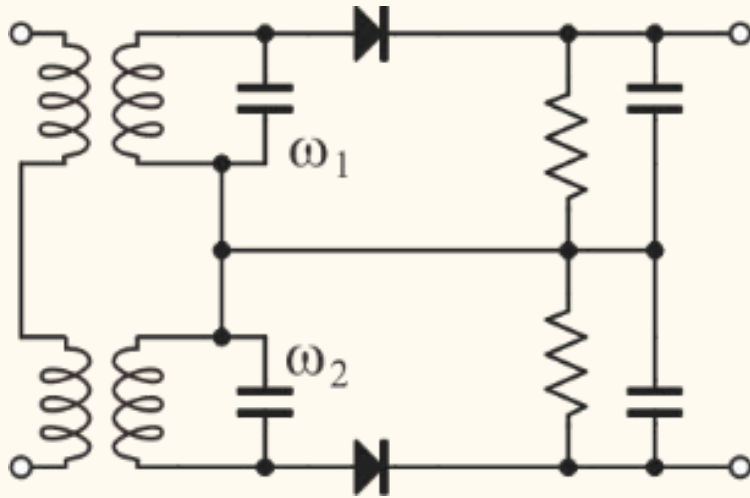
# Phase Lock Loop (PLL)



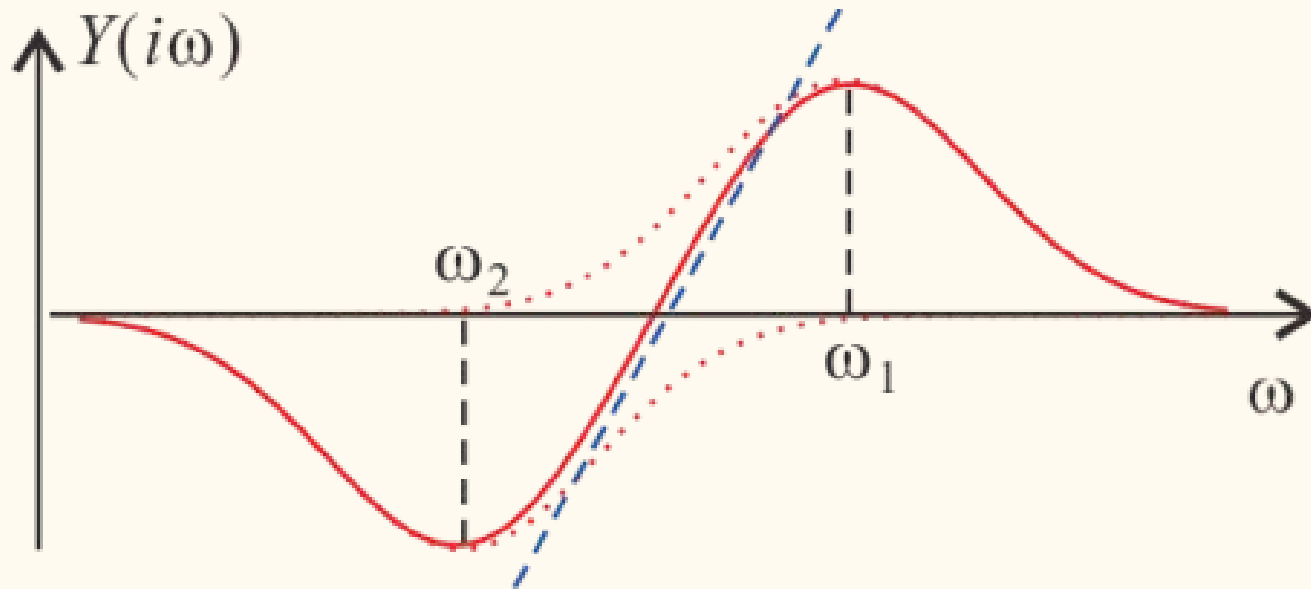
## 6.3.3 Angle modulation (circuit example)



## 6.3.4 Angle modulation (Frequency demodulation)

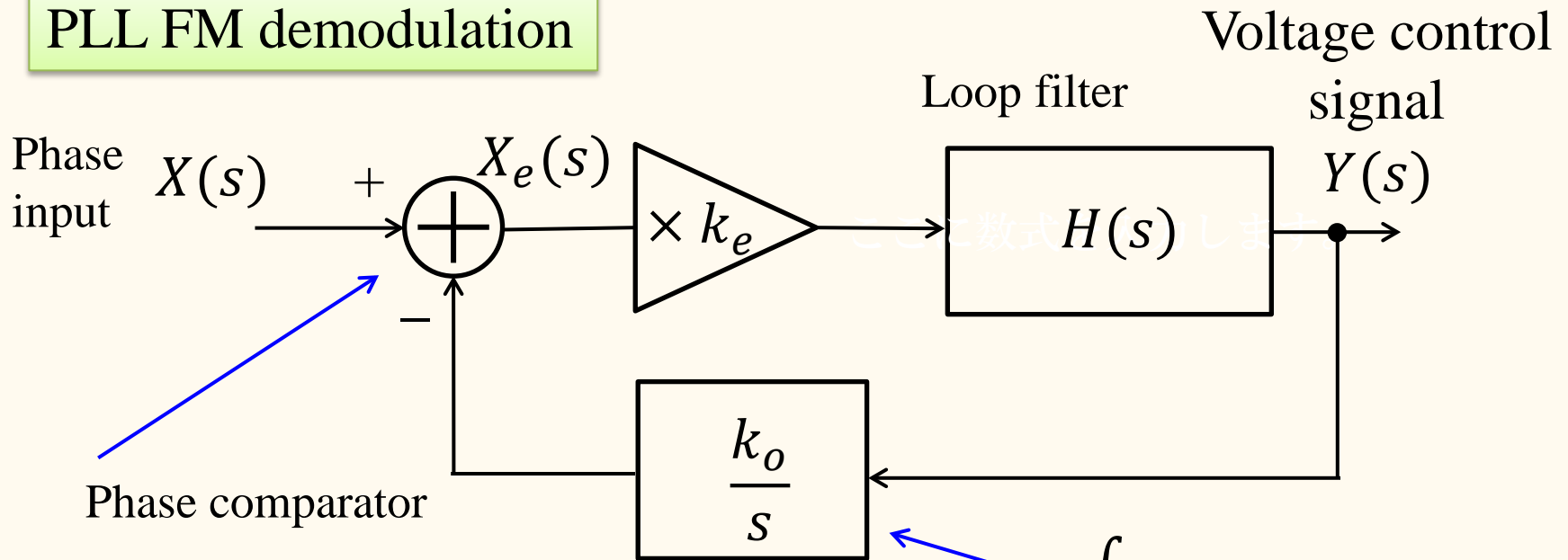


Double tuned circuit



## 6.3.4 Angle modulation (frequency demodulation)

### PLL FM demodulation



$$Y(s) = \frac{sk_e H(s)}{s + k_e k_o H(s)} X(s)$$

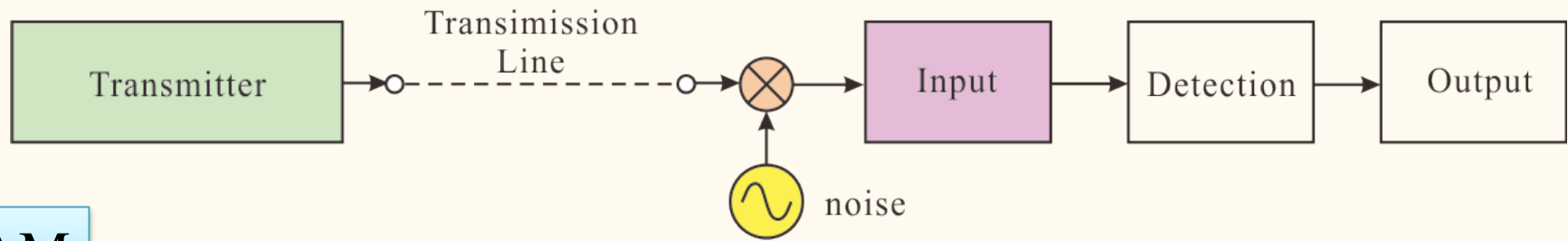
$k_o \int y(t) dt$

$g(t)$ : Frequency modulation signal (original)

$$\phi(t) = k_f \int_{-\infty}^t g(\tau) d\tau, \quad sX(s) = k_f G(s)$$

$$\therefore Y(s) = \frac{k_f k_e H(s)}{s + k_e k_o H(s)} G(s) \approx \frac{k_f}{k_o} G(s)$$

# 6.3.5 Modulation and noise



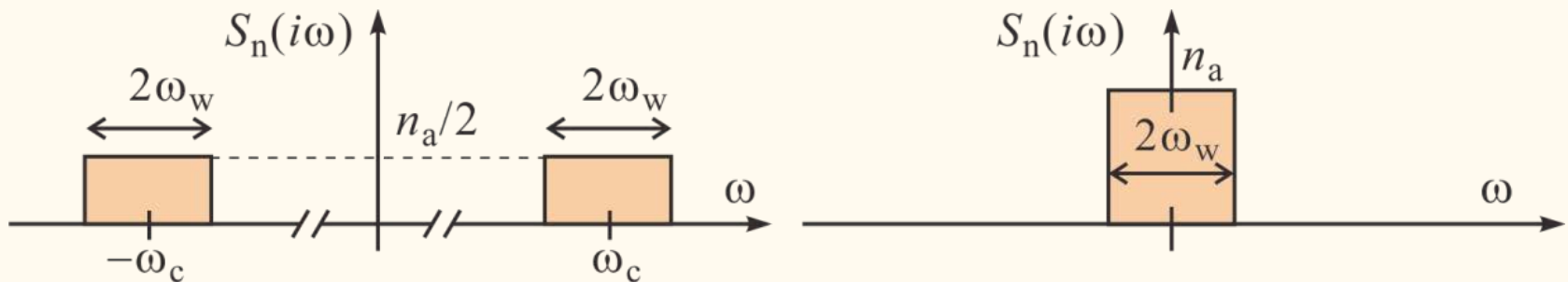
## AM

Received signal  $r(t) = A_r [1 + m f(t)] \cos \omega_c t + n_i(t)$

Demodulated output  $g(t) = A_r m f(t) + n_o(t)$

Averaged signal power

received:  $S_{pr} = \frac{A_r^2}{2} + \frac{(A_r m)^2}{2} \langle f^2 \rangle$ ,    output:  $S_{po} = A_r^2 m^2 \langle f^2 \rangle$



Received

Demodulated



## 6.3.5 Modulation and noise

$\omega_W$  : Noise bandwidth (assumption: white)

$$\text{Noise power: } \underbrace{2 \times \frac{n_a}{2 \times 2\pi} \times 2\omega_W}_{\text{Received}} = \frac{n_a \omega_W}{\pi}, \quad \underbrace{\frac{n_a \times 2\omega_W}{2\pi}}_{\text{Demodulated}} = \frac{n_a \omega_W}{\pi}$$

$$\left. \frac{S}{N} \right|_{\text{in}} = \frac{\pi [A_r^2 + (A_r m)^2 \langle f^2 \rangle]}{2n_a \omega_W}, \quad \left. \frac{S}{N} \right|_{\text{out}} = \frac{\pi A_r^2 m^2 \langle f^2 \rangle}{n_a \omega_W} = 2\eta \left. \frac{S}{N} \right|_{\text{in}}$$

$$\eta = \frac{m^2 \langle f^2 \rangle}{1 + m^2 \langle f^2 \rangle} \quad \text{:Power transmission efficiency}$$

$$0 < m \leq 1 \rightarrow \eta < \frac{1}{2}$$

$$\text{Input sinusoidal: } \langle f^2 \rangle = \frac{1}{2} \rightarrow \eta < \frac{1}{3}$$

## 6.3.5 Modulation and noise

FM, PM

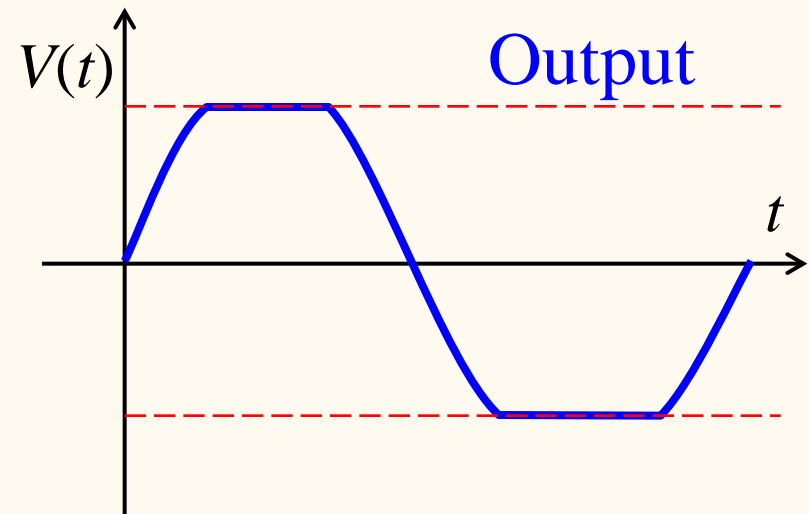
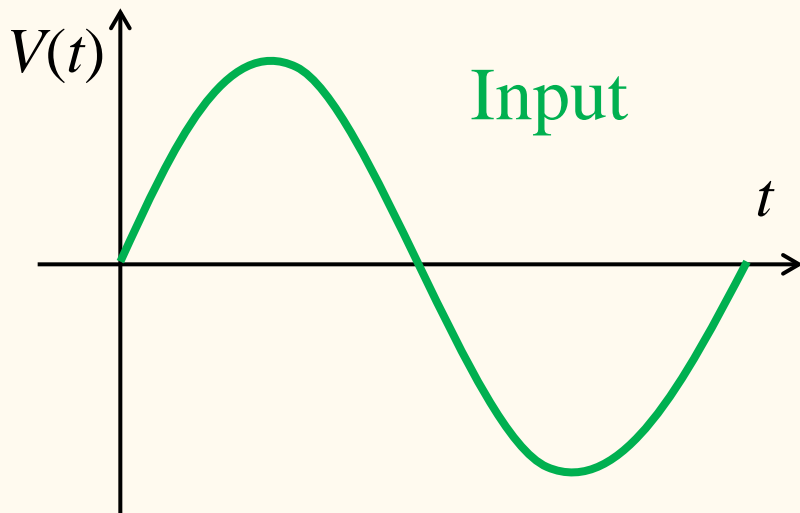
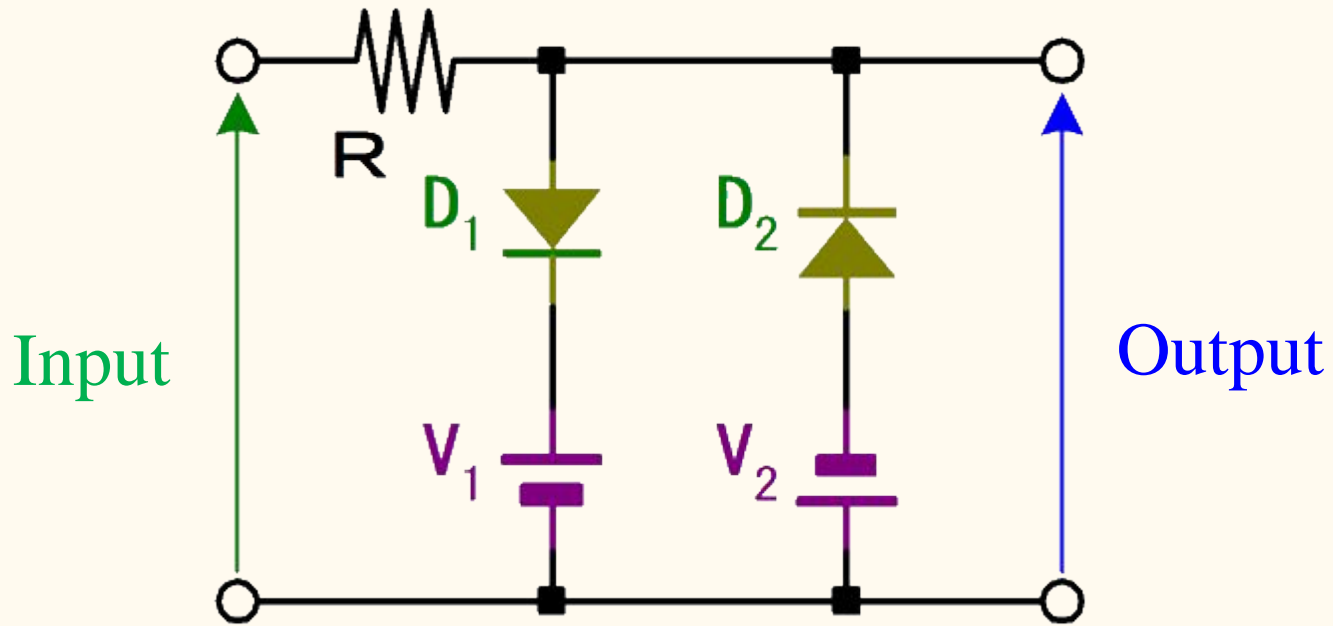
$$\begin{aligned} r(t) &= \underbrace{A_r \cos[\omega_c t + \phi(t)]}_{\text{Signal}} + \underbrace{n_l(t) \cos \omega_c t}_{\text{In phase}} - \underbrace{n_r(t) \sin \omega_c t}_{\text{Out of phase}} \\ &= A_r \cos[\omega_c t + \phi(t)] + A_n(t) \cos[\omega_c t + \phi_n(t)] \\ &= V_r(t) \cos[\omega_c t + \theta(t)] \quad (\theta(t) = \phi(t) + \underbrace{\phi_{\text{no}}(t)}_{\text{Phase noise}}) \end{aligned}$$

$$V_r(t) = \sqrt{A_r^2 + A_n^2(t) + 2A_r A_n(t) \cos[\phi_n(t) - \phi(t)]},$$

$$\phi_{\text{no}}(t) = \arctan \frac{A_n(t) \sin[\phi_n(t) - \phi(t)]}{A_r + A_n(t) \cos[\phi_n(t) - \phi(t)]}$$

Time-dependent part in  $V_r(t)$  can be cut with a limiter circuit.

## 6.3.5 Modulation and noise (Diode limiter)



## 6.3.5 Modulation and noise

$$A_r \gg A_n(t)$$

$$\phi_{\text{no}} \cong \arctan \left[ \frac{A_n(t)}{A_r} \sin[\phi_n(t) - \phi(t)] \right] \cong \frac{A_n(t)}{A_r} \sin[\phi_n(t) - \phi(t)]$$

Noise: White, Power spectrum density  $n_a/2$ , Band width  $\omega_B$

$$\text{Noise power: } N_i = \frac{n_a \omega_B}{2\pi} \quad \text{Signal power: } \frac{A_r^2}{2} \quad \frac{S_i}{N_i} = \frac{\pi A_r^2}{n_a \omega_B}$$

Phase modulation

$$\phi[t, f(t)] = k_p f(t)$$

Averaged signal power:  $k_p^2 \langle f^2 \rangle$

Averaged noise power:  $N_{\text{oPM}} \cong \frac{1}{A_r^2} \langle A_n(t)^2 \sin^2[\phi_n(t) - \phi(t)] \rangle$

$\phi_n(t)$ : Uniform in  $[0, 2\pi]$   $\rightarrow$  ignored

$$N_{\text{oPM}} \cong \frac{1}{A_r^2} \langle A_n(t)^2 \sin^2 \phi(t) \rangle = \frac{n_a \omega_w}{\pi A_r^2}$$

## 6.3.5 Modulation and noise

$$f(t) = A_p \cos \omega_p t, \quad \beta \equiv k_p A_p \rightarrow S_o = \frac{\beta^2}{2}, \quad \omega_B = 2(\beta + \xi)\omega_w \quad (1 \leq \xi \leq 2)$$

$$\frac{S_o}{N_o} = \frac{\beta^2}{2} \frac{\pi A_r^2}{n_a \omega_w} = \frac{\beta^2}{2} \frac{\omega_B}{\omega_w} \frac{\pi A_r^2}{n_a \omega_B} = \beta^2 (\beta + \xi) \frac{S_i}{N_i}$$

### Frequency modulation

Demodulated output  $d\theta/dt$       Signal, power:  $k_f f(t)$ ,  $k_f^2 \langle f^2 \rangle$

$$N_{o\text{FM}} = \left\langle \frac{dn_{no}}{dt} \right\rangle = \frac{1}{A_r^2} \left\langle \frac{dn_l}{dt} \right\rangle = \frac{1}{A_r^2} \int_{-\omega_w}^{\omega_w} n_a \omega^2 \frac{d\omega}{2\pi} = \frac{n_a \omega_w^3}{3\pi A_r^2}$$

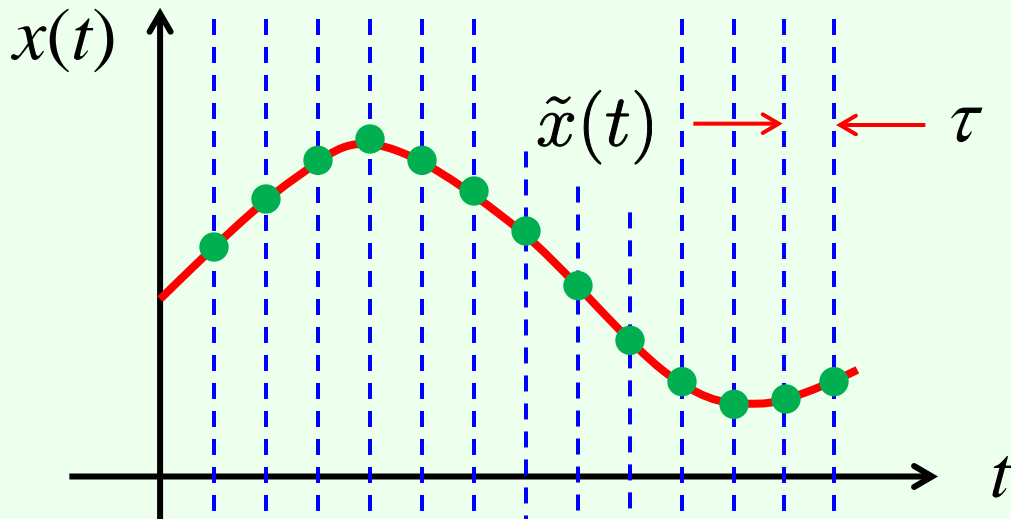
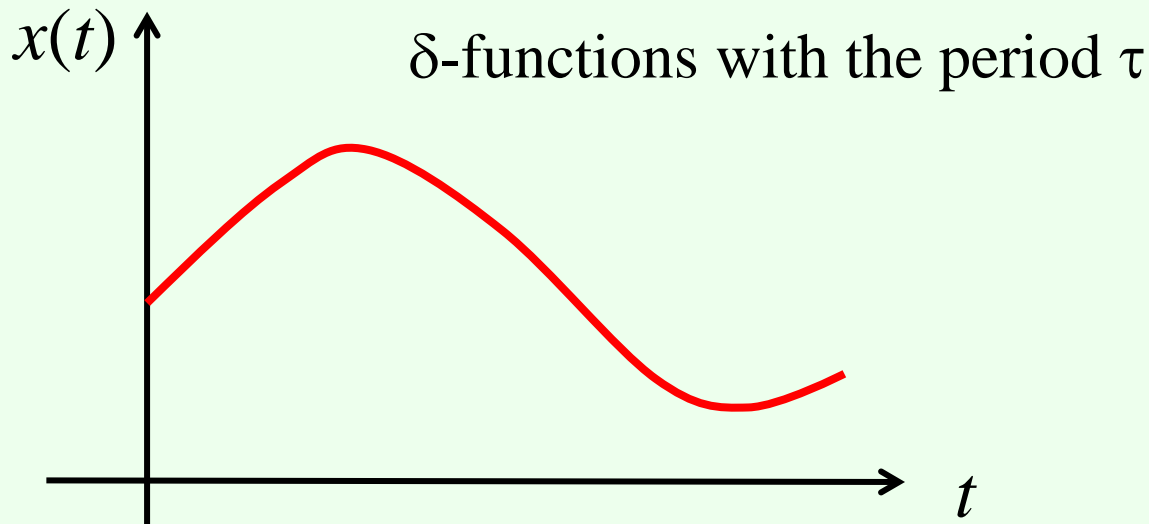
$$\beta \equiv k_f A_p / \omega_w \quad \frac{S_o}{N_o} = 3\beta^2 (\beta + \xi) \frac{S_i}{N_i}$$

$$\left. \frac{S_o}{N_o} \right|_{\text{FM}} = 3\beta^2 \left. \frac{S_o}{N_o} \right|_{\text{AM}}, \quad \left. \frac{S_o}{N_o} \right|_{\text{PM}} = \beta^2 \left. \frac{S_o}{N_o} \right|_{\text{AM}}$$

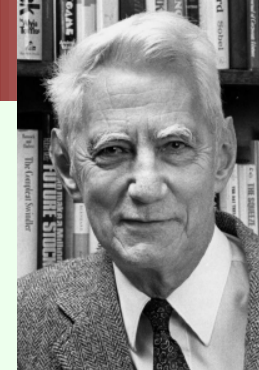
# 6.4 Discrete signal

## 6.4.1 Sampling theorem

Sampled signal  $\tilde{x}(t) = x(t)\delta_\tau(t)$



Isao Someya  
1915-2007

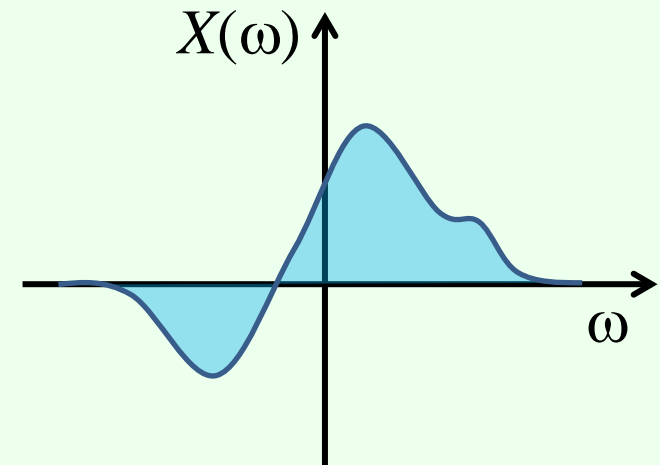


Claude Shannon  
1916-2001

1928 H. Nyquist

1949 C. Shannon

染谷勲





## 6.4.1 Sampling theorem

$$\begin{aligned}\delta_\tau(t) &= \sum_{j=-\infty}^{\infty} \delta(t - j\tau) = \sum_{n=-\infty}^{\infty} \left[ \frac{1}{\tau} \int_{-\pi/\tau}^{\pi/\tau} \delta(s) ds \right] \exp\left(-in\frac{2\pi}{\tau}t\right) \\ &= \frac{1}{\tau} \sum_{n=-\infty}^{\infty} \exp\left(-in\frac{2\pi}{\tau}t\right)\end{aligned}$$

$$\begin{aligned}\mathcal{F}\{\delta_\tau(t)\} &= \int_{-\infty}^{\infty} \left[ \frac{1}{\tau} \sum_{n=-\infty}^{\infty} e^{-in(2\pi/\tau)t} \right] e^{i\omega t} dt = \frac{1}{\tau} \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left[i\left(\omega - n\frac{2\pi}{\tau}\right)t\right] dt \\ &= \frac{2\pi}{\tau} \sum_{n=-\infty}^{\infty} \delta\left(\omega - n\frac{2\pi}{\tau}\right) = \frac{2\pi}{\tau} \delta_{2\pi/\tau}(\omega)\end{aligned}$$

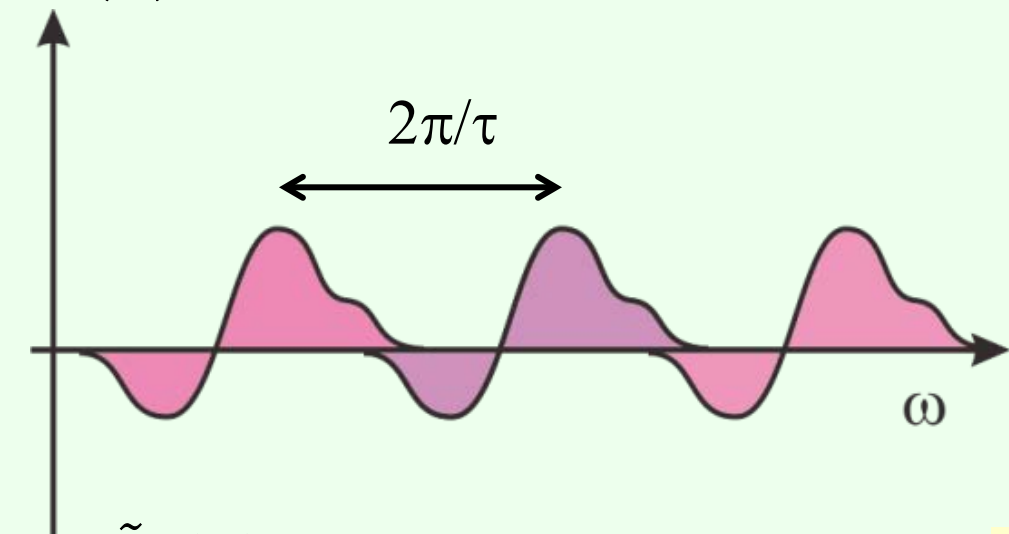
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$$\mathcal{F}\{x(t)\} = X(\omega), \quad \mathcal{F}\{\tilde{x}_\tau(t)\} = \tilde{X}_\tau(\omega)$$

$$\begin{aligned}\tilde{X}_\tau(\omega) &= \frac{1}{2\pi} X(\omega) * \frac{2\pi}{\tau} \delta_{2\pi/\tau}(\omega) = \frac{1}{\tau} X(\omega) * \sum_{n=-\infty}^{\infty} \delta\left(\omega - n\frac{2\pi}{\tau}\right) \\ &= \frac{1}{\tau} \int_{-\infty}^{\infty} X(\omega') \left\{ \sum_{n=-\infty}^{\infty} \delta\left(\omega - n\frac{2\pi}{\tau} - \omega'\right) \right\} d\omega' = \frac{1}{\tau} \sum_{n=-\infty}^{\infty} X\left(\omega - n\frac{2\pi}{\tau}\right)\end{aligned}$$

# 6.4.1 Sampling theorem

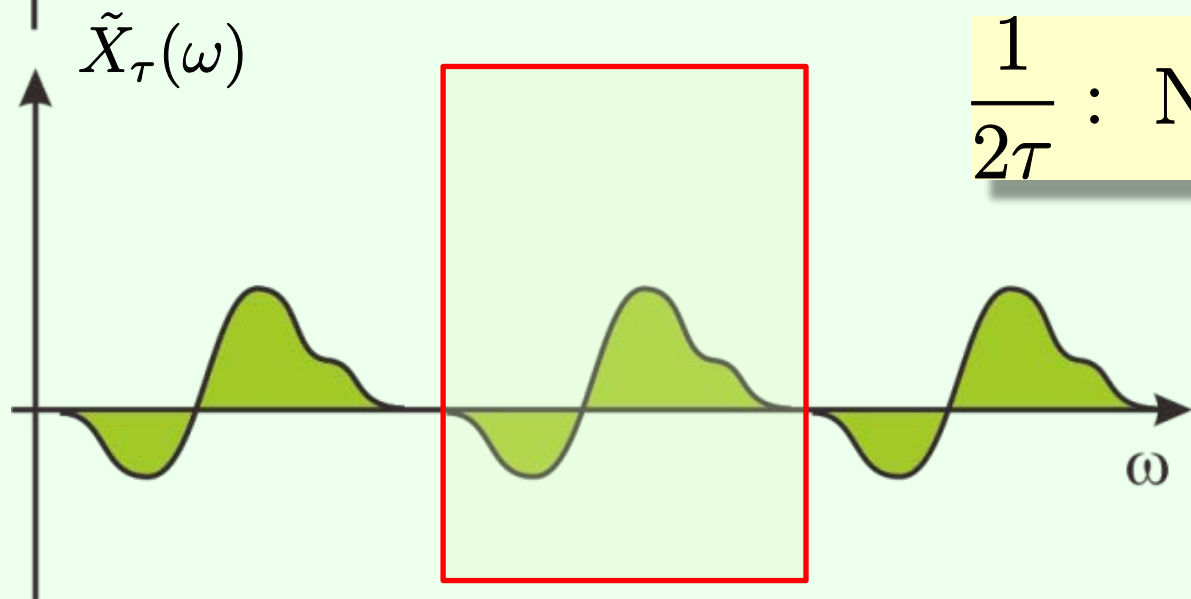
$\tilde{X}_\tau(\omega)$  “Cutting out” the frequency spectrum



$\omega_h$ : Highest frequency in  $\tilde{X}_\tau(\omega)$

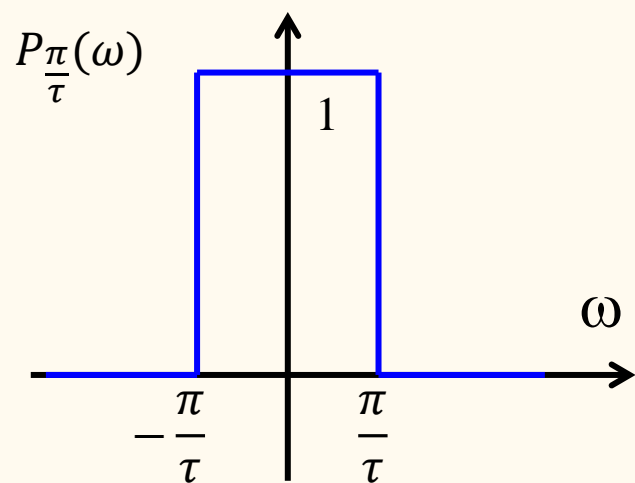
$$\frac{2\pi}{\tau} > 2\omega_h, \quad \tau < \frac{\pi}{\omega_h}$$

$\frac{1}{2\tau}$  : Nyquist frequency

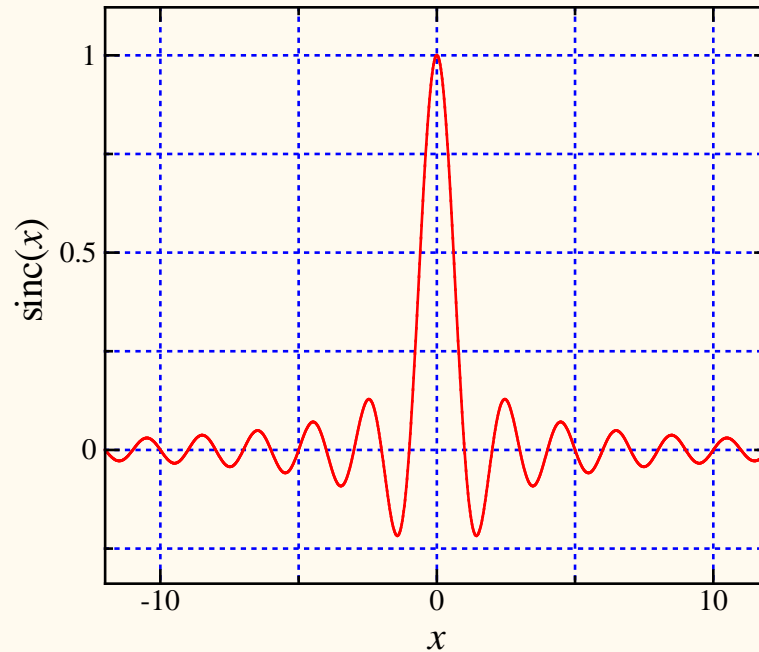


## 6.4.1 Sampling theorem: Reconstructing signal

$$P_{\pi/\tau}(\omega) = \begin{cases} 1 & |\omega| \leq \frac{\pi}{\tau}, \\ 0 & |\omega| > \frac{\pi}{\tau} \end{cases}$$



$$x(t) = \mathcal{F}^{-1}\{\tau P_{\pi/\tau}(\omega)\tilde{X}_\tau(\omega)\}$$



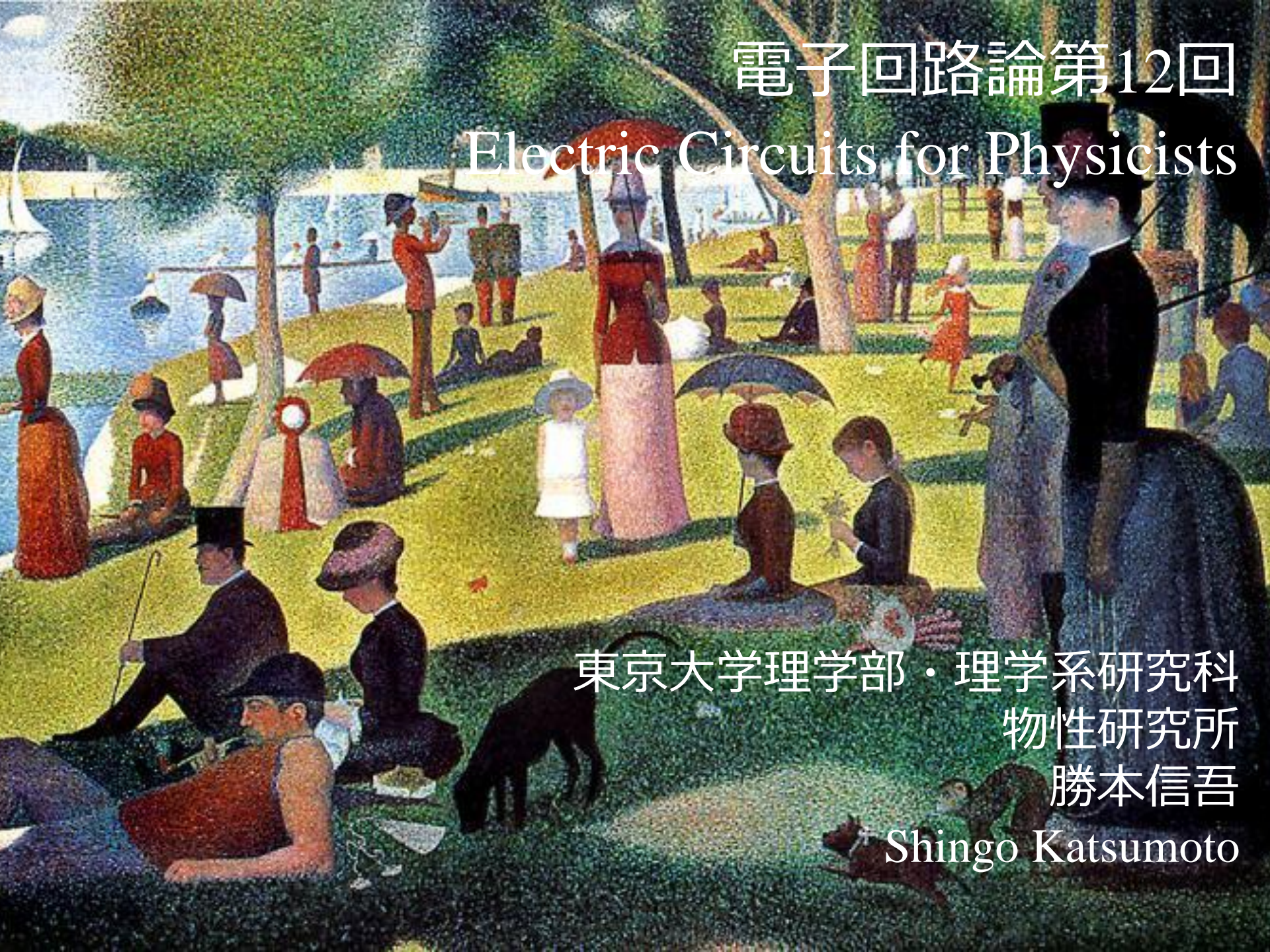
$$x(t) = \tau \frac{1}{\tau} \text{sinc}\left(\frac{t}{\tau}\right) * \tilde{x}_\tau(t) = \text{sinc}\left(\frac{t}{\tau}\right) * \sum_{n=-\infty}^{\infty} x(t)\delta(t - n\tau)$$

$$= \int_{-\infty}^{\infty} \text{sinc}\left(\frac{s}{\tau}\right) \sum_{n=-\infty}^{\infty} x(t-s)\delta(t - n\tau - s)ds = \sum_{n=-\infty}^{\infty} \text{sinc}\left(\frac{t - n\tau}{\tau}\right) x(n\tau)$$



# 電子回路論第12回

## Electric Circuits for Physicists



東京大学理学部・理学系研究科

物性研究所

勝本信吾

Shingo Katsumoto





# Outline



## 6.4 Discrete signal

### 6.4.1 Sampling theorem

### 6.4.2 Pulse amplitude modulation (PAM)

### 6.4.3 Discrete Fourier transform

### 6.4.4 z-transform

### 6.4.5 Transfer function of discrete time signal

## Ch.7 Digital signals and circuits

### 7.2 Logic gates

### 7.3 Implementation of logic gates

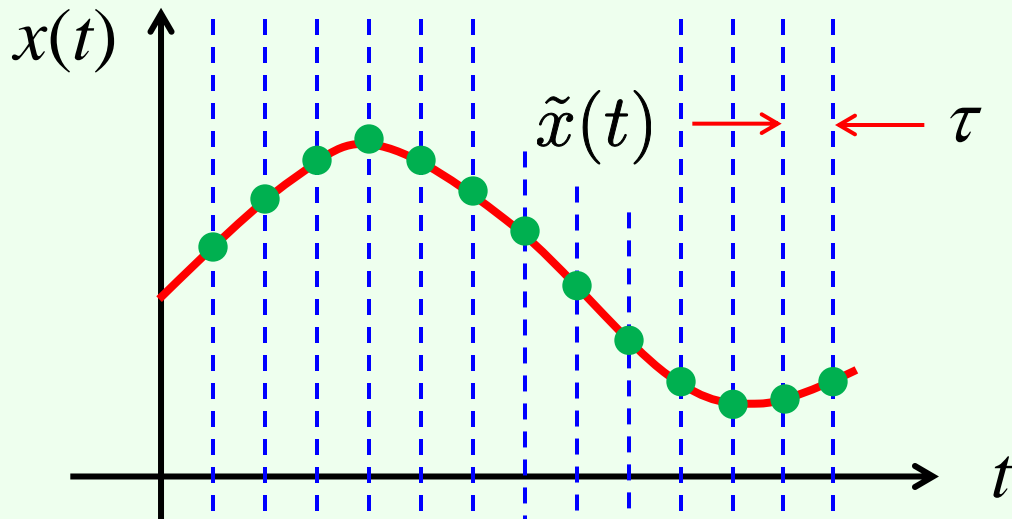
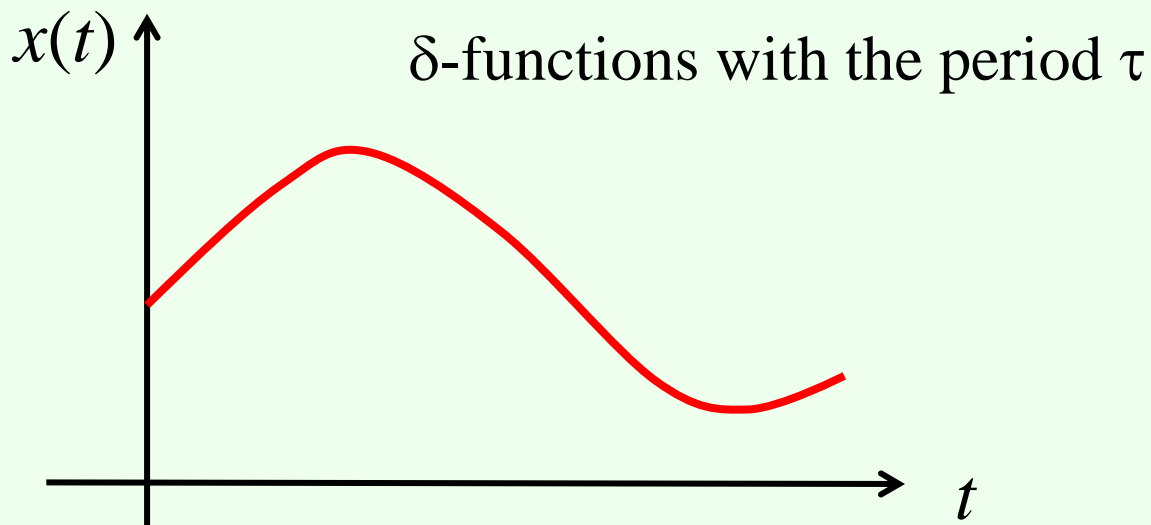
### 7.4 Circuit implementation and simplification of logic operation



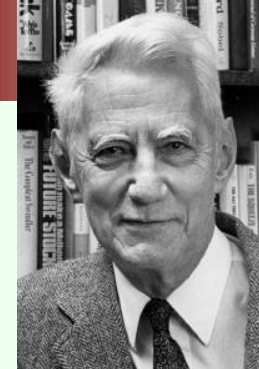
# 6.4 Discrete signal

## 6.4.1 Sampling theorem

Sampled signal  $\tilde{x}(t) = x(t)\delta_\tau(t)$



Isao Someya  
1915-2007

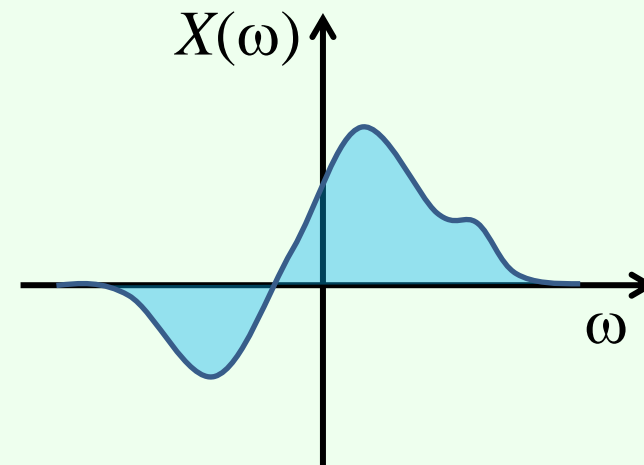


Claude Shannon  
1916-2001

1928 H. Nyquist

1949 C. Shannon

染谷勲



## 6.4.1 Sampling theorem

$$\begin{aligned}\delta_\tau(t) &= \sum_{j=-\infty}^{\infty} \delta(t - j\tau) = \sum_{n=-\infty}^{\infty} \left[ \frac{1}{\tau} \int_{-\pi/\tau}^{\pi/\tau} \delta(s) ds \right] \exp\left(-in\frac{2\pi}{\tau}t\right) \\ &= \frac{1}{\tau} \sum_{n=-\infty}^{\infty} \exp\left(-in\frac{2\pi}{\tau}t\right)\end{aligned}$$

$$\begin{aligned}\mathcal{F}\{\delta_\tau(t)\} &= \int_{-\infty}^{\infty} \left[ \frac{1}{\tau} \sum_{n=-\infty}^{\infty} e^{-in(2\pi/\tau)t} \right] e^{i\omega t} dt = \frac{1}{\tau} \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left[i\left(\omega - n\frac{2\pi}{\tau}\right)t\right] dt \\ &= \frac{2\pi}{\tau} \sum_{n=-\infty}^{\infty} \delta\left(\omega - n\frac{2\pi}{\tau}\right) = \frac{2\pi}{\tau} \delta_{2\pi/\tau}(\omega)\end{aligned}$$

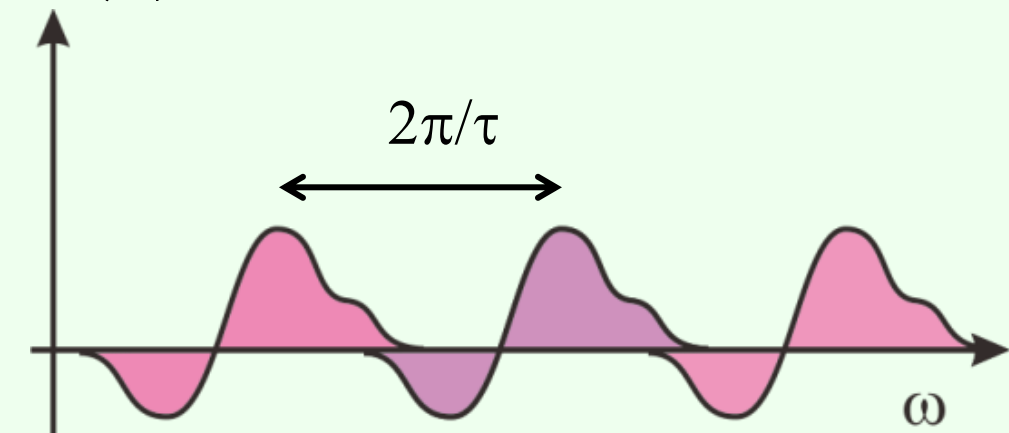
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$$\mathcal{F}\{x(t)\} = X(\omega), \quad \mathcal{F}\{\tilde{x}_\tau(t)\} = \tilde{X}_\tau(\omega)$$

$$\begin{aligned}\tilde{X}_\tau(\omega) &= \frac{1}{2\pi} X(\omega) * \frac{2\pi}{\tau} \delta_{2\pi/\tau}(\omega) = \frac{1}{\tau} X(\omega) * \sum_{n=-\infty}^{\infty} \delta\left(\omega - n\frac{2\pi}{\tau}\right) \\ &= \frac{1}{\tau} \int_{-\infty}^{\infty} X(\omega') \left\{ \sum_{n=-\infty}^{\infty} \delta\left(\omega - n\frac{2\pi}{\tau} - \omega'\right) \right\} d\omega' = \frac{1}{\tau} \sum_{n=-\infty}^{\infty} X\left(\omega - n\frac{2\pi}{\tau}\right)\end{aligned}$$

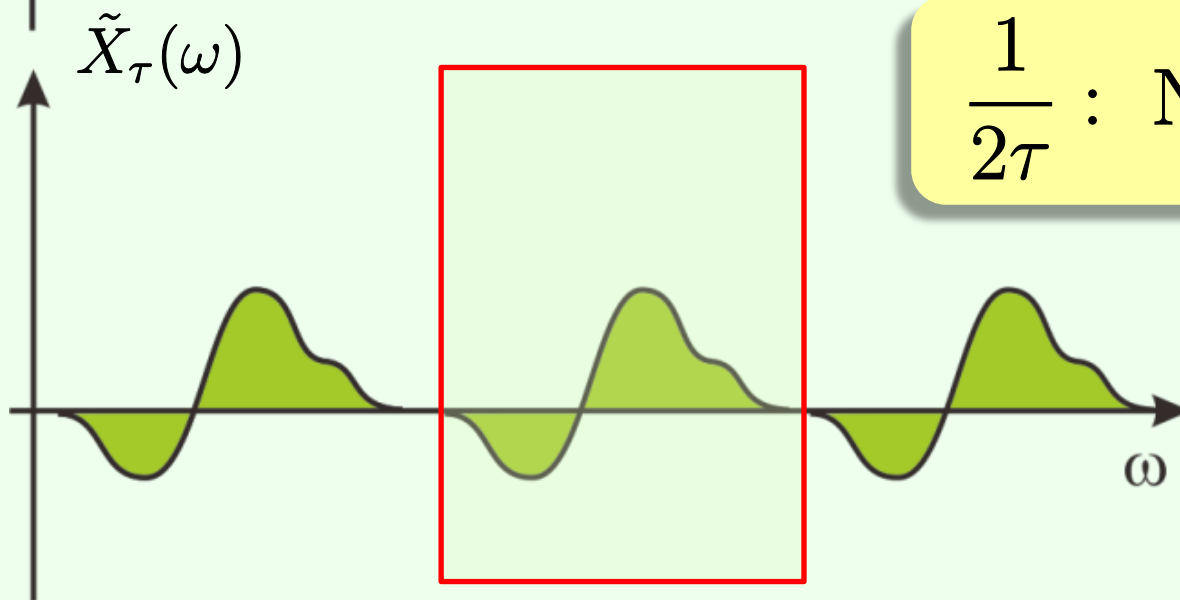
# 6.4.1 Sampling theorem

$\tilde{X}_\tau(\omega)$  “Cutting out” the frequency spectrum



$\omega_h$ : Highest frequency in  $\tilde{X}_\tau(\omega)$

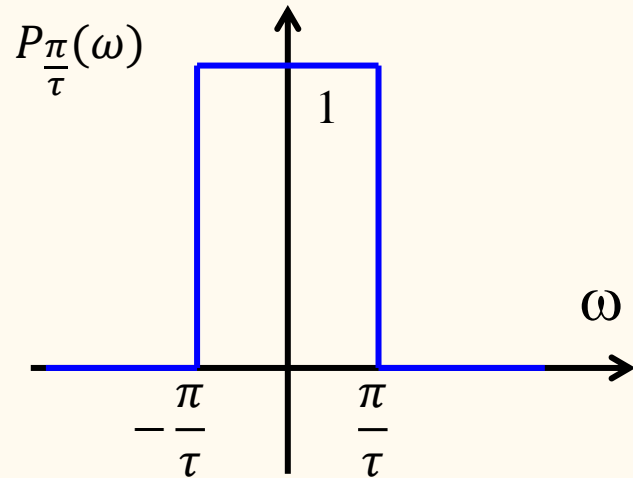
$$\frac{2\pi}{\tau} > 2\omega_h, \quad \tau < \frac{\pi}{\omega_h}$$



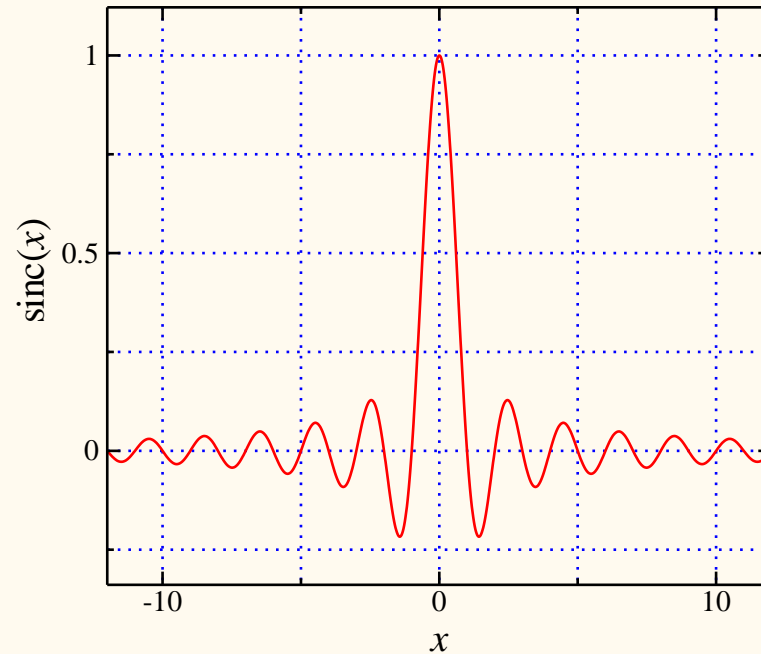
$\frac{1}{2\tau}$  : Nyquist frequency

## 6.4.1 Sampling theorem: Reconstructing signal

$$P_{\pi/\tau}(\omega) = \begin{cases} 1 & |\omega| \leq \frac{\pi}{\tau}, \\ 0 & |\omega| > \frac{\pi}{\tau} \end{cases}$$



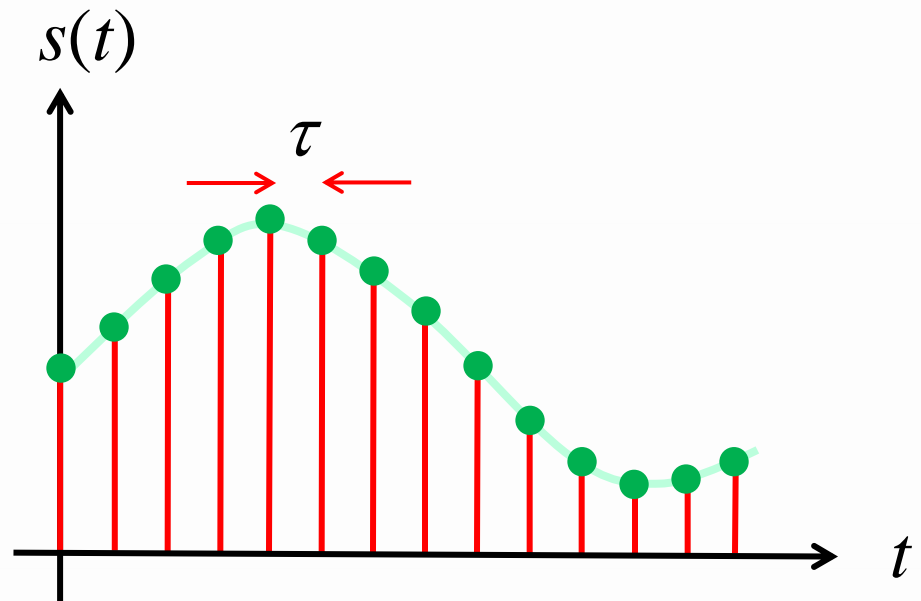
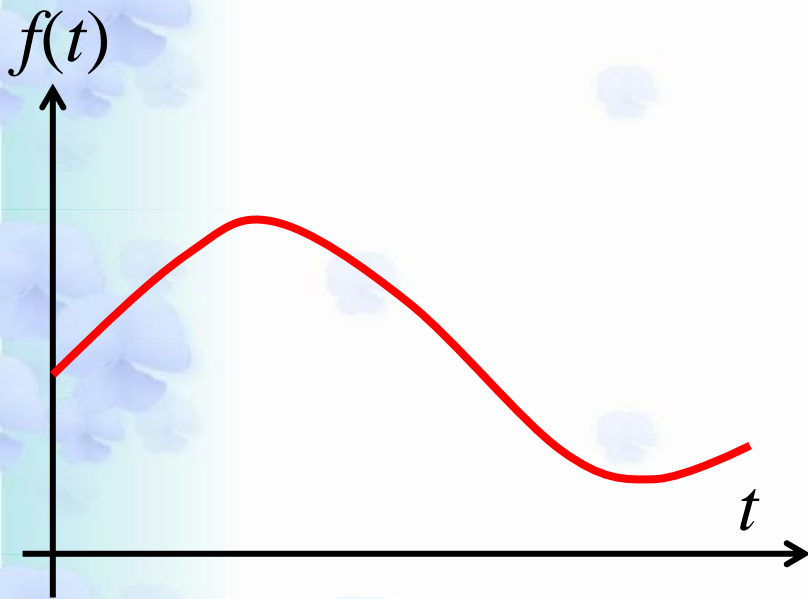
$$x(t) = \mathcal{F}^{-1}\{\tau P_{\pi/\tau}(\omega)\tilde{X}_\tau(\omega)\}$$



$$x(t) = \tau \frac{1}{\tau} \text{sinc}\left(\frac{t}{\tau}\right) * \tilde{x}_\tau(t) = \text{sinc}\left(\frac{t}{\tau}\right) * \sum_{n=-\infty}^{\infty} x(t)\delta(t - n\tau)$$

$$= \int_{-\infty}^{\infty} \text{sinc}\left(\frac{s}{\tau}\right) \sum_{n=-\infty}^{\infty} x(t-s)\delta(t - n\tau - s)ds = \sum_{n=-\infty}^{\infty} \text{sinc}\left(\frac{t - n\tau}{\tau}\right) x(n\tau)$$

## 6.4.2 Pulse amplitude modulation (PAM)



Carrier:  $\delta_\tau(t)$       $s(t) = f(t)\delta_\tau(t) = \sum_{n=-\infty}^{\infty} f(t)\delta(t - n\tau)$

Demodulation = Reconstruction of continuous signal  
from sampled data.

$$f(t) = \mathcal{F}^{-1}\{P_{\pi/\tau}(\omega)\mathcal{F}\{s(t)\}\}$$

# Demodulation of PAM and a trick in the sampling theorem

In the sampling theorem, though we only have discrete-time data, we can reconstruct complete original signal.

↑

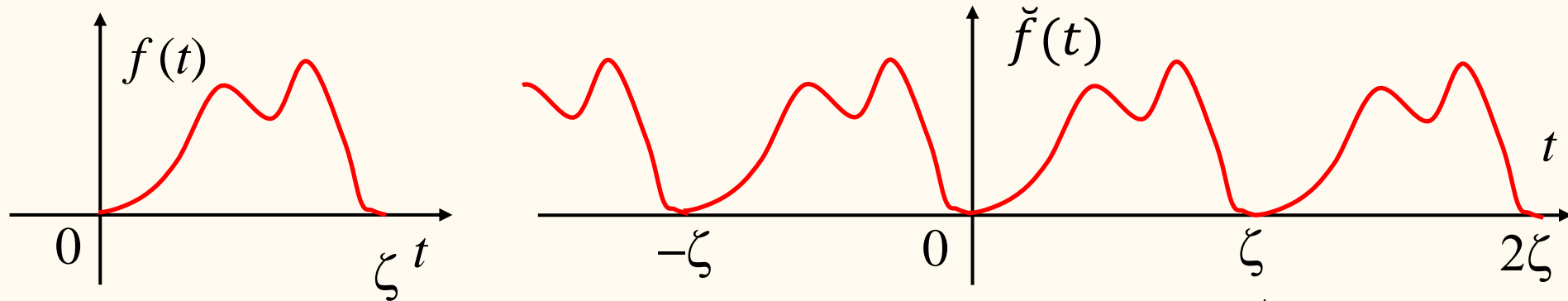
Assumption: we have data in infinite period  $[-\infty, +\infty]$ .

However in actual situations we can never have such data.

Need to consider handling data in a finite period.



## 6.4.3 Discrete Fourier transform



Assumption:

$$F(\omega) = \mathcal{F}\{f(t)\}, \text{ not zero in } \omega \in \left(-\frac{\pi}{\tau}, \frac{\pi}{\tau}\right)$$

$$N = \frac{\zeta}{\tau} \in \mathbb{N}$$

can be assumed without  
loosing generality

$$\check{f}(t) = \sum_{n=-\infty}^{\infty} f(t - n\zeta), \quad \check{F}(\omega) = \sum_{n=-\infty}^{\infty} F\left(\omega + n\frac{2\pi}{\zeta}\right)$$

$$\left( \check{f}(t) = (f * \delta_{\zeta})(t) = \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi) \delta(t - n\zeta - \xi) d\xi \right)$$

Fourier expansion: 
$$\check{f}(t) = \frac{1}{\zeta} \sum_{n=-\infty}^{\infty} F\left(n\frac{2\pi}{\zeta}\right) \exp\left(2n\pi i \frac{t}{\zeta}\right)$$

## 6.4.3 Discrete Fourier transform

$$n = l + mN \quad \sum_{n=-\infty}^{\infty} \rightarrow \sum_{l=0}^{N-1} \sum_{m=-\infty}^{\infty} \quad \text{Discreteness:} \\ t = j\tau \quad j \in \mathbb{Z}$$

$$\begin{aligned} \check{f}(j\tau) &= \frac{1}{\zeta} \sum_{l=0}^{N-1} \sum_{m=-\infty}^{\infty} F \left[ (l + mN) \frac{2\pi}{\zeta} \right] \exp \left[ (l + mN) 2\pi i \frac{j\tau}{\zeta} \right] \\ &= \frac{1}{N\tau} \sum_{l=0}^{N-1} \sum_{m=-\infty}^{\infty} F \left( \frac{2\pi l}{\zeta} + m \frac{2\pi}{\tau} \right) \exp \left( 2\pi i \frac{l j}{N} \right) \\ &= \frac{1}{N\tau} \sum_{l=0}^{N-1} \check{F} \left( l \frac{2\pi}{\zeta} \right) \exp \left( 2\pi i \frac{l j}{N} \right) \end{aligned}$$

Twiddle factor:  $W_N \equiv \exp \left( -i \frac{2\pi}{N} \right)$

$$\eta \equiv \frac{2\pi}{\zeta} \quad \check{f}(j\tau) = \frac{1}{N\tau} \sum_{l=0}^{N-1} \check{F}(l\eta) W_N^{-lj}$$

## 6.4.3 Discrete Fourier transform

$$\forall n, m \in \mathbb{Z} \quad W_N^{n+mN} = W_N^n,$$

Twiddle factor:

$$\frac{1}{N} \sum_{n=0}^{N-1} W_N^{nm} = \begin{cases} 1 & \text{for } m = 0, \\ 0 & \text{for } m \neq 0. \end{cases}$$

$$\tau \sum_{j=0}^{N-1} \check{f}(j\tau) W_N^{mj} = \sum_{j=0}^{N-1} \left[ \frac{1}{N} \sum_{l=0}^{N-1} \check{F}(l\eta) W_N^{(m-l)j} \right] = \check{F}(m\eta)$$

$$f_n \equiv \check{f}(n\tau), \quad F_k \equiv \frac{1}{\tau} \check{F}(k\eta)$$

Discrete Fourier transform:  
(DFT)

$$F_k = \sum_{n=0}^{N-1} f_n W_N^{kn},$$

$$f_n = \frac{1}{N} \sum_{k=0}^{N-1} F_k W_N^{-kn}.$$

## 6.4.3 Discrete Fourier transform

$$\mathbf{F} = {}^t\{F_i\}, \quad \mathbf{W} = \{W_N^{ij}\}, \quad \mathbf{f} = {}^t\{f_i\}$$

$$\mathbf{F} = \mathbf{W} \mathbf{f}, \quad \mathbf{f} = \frac{1}{N} \mathbf{W}^* \mathbf{F}$$

$${}^t\mathbf{W}^* \mathbf{W} = N \mathbf{I}_N \quad i.e., \quad \frac{1}{\sqrt{N}} \mathbf{W} : \text{unitary}$$

## 6.4.4 z-transform

Discrete Laplace transform: z-transform

$$\tilde{f}_\tau(t) = \sum_{n=0}^{\infty} f(n\tau)\delta(t - n\tau) \quad (t \geq 0)$$

$$\begin{aligned}\mathcal{L}\{\tilde{f}_\tau(t)\}(s) &= \mathcal{L}\left\{\sum_{n=0}^{\infty} f(n\tau)\delta(t - n\tau)\right\} \\ &= \sum_{n=0}^{\infty} f(n\tau)\mathcal{L}\{\delta(t - n\tau)\} = \sum_{n=0}^{\infty} f(n\tau)\exp(-sn\tau)\end{aligned}$$

$$z = \exp(s\tau), \quad f_n = f(n\tau), \quad F(z) = \mathcal{L}\{\tilde{f}_\tau(t)\}$$

$$F(z) = \sum_{n=0}^{\infty} f_n z^{-n} = \mathcal{L}[\tilde{f}_\tau(t)]$$

one-sided z-transform

## 6.4.4 z-transform

$f_n$	$F(z)$	conversion area
$\delta(n)$	1	$z$ -plane
1	$\frac{1}{1 - z^{-1}}$	$ z  > 1$
$n$	$\frac{z^{-1}}{(1 - z^{-1})^2}$	$ z  > 1$
$n^k$	$\left(-z \frac{d}{dz}\right)^k \frac{1}{1 - z^{-1}}$	$ z  > 1$
$a^n$	$\frac{1}{1 - az^{-1}}$	$ z  >  a $
$\sin(n\omega\tau)$	$\frac{\sin(\omega\tau)z^{-1}}{1 - 2\cos(\omega\tau)z^{-1} + z^{-2}}$	$ z  > 1$
$e^{-n\alpha\tau} \cos(n\omega\tau)$	$\frac{1 - e^{-\alpha\tau} \cos(\omega\tau)z^{-1}}{1 - 2e^{-\alpha\tau} \cos(\omega\tau)z^{-1} + e^{-2\alpha\tau} z^{-2}}$	$ z  > e^{-\alpha\tau}$



## 6.4.4 z-transform

Property	Signal	z-transform
linearity	$af_n + bg_n$	$aF(z) + bG(z)$
z-domain scaling	$f_{\alpha n}$	$F(z^{1/\alpha})$
time shift	$f_{n+k}$	$z^k \left[ F(z) - \sum_{l=0}^{k-1} f(l)z^l \right]$
time shift II	$f_{n-k}$	$z^{-k} F(z)$
scaling	$e^{\mp \alpha n} f_n$	$F(e^{\pm \alpha} z)$
scaling II	$a^n x_n$	$F(a^{-1} z)$
product with index	$nf_n$	$-z \frac{d}{dz} F(z)$
differentiation	$n^k f_n$	$\left( -z \frac{d}{dz} \right)^k F(z)$
integration	$\frac{f_n}{n+a}$	$z^a \int_z^\infty \xi^{-a+1} F(\xi) d\xi$
convolution	$f_n * g_n$	$F(z) \cdot G(z)$
product	$f_n \cdot g_n$	$\frac{1}{2\pi i} \oint_c F(\xi) G\left(\frac{z}{\xi}\right) \xi^{-1} d\xi$

## 6.4.5 Transfer function for discrete time signal

$$\tilde{f}_\tau(t) = f(t)\delta_\tau(t) = \sum_{k=-\infty}^{\infty} f_k\delta(t - k\tau)$$

$h_n$ : (impulse) response to  $\delta(n\tau)$ , response to discrete signal  $f_n = f(n\tau)$

$$g_n = \mathcal{R}\{\tilde{f}_\tau(n\tau)\} = \mathcal{R}\left\{\sum_{k'=-\infty}^{\infty} f(k'\tau)\delta[(n - k')\tau]\right\}$$

$$= \sum_{k'=-\infty}^{\infty} f_{k'}h_{n-k'} = \sum_{k=-\infty}^{\infty} h_k f_{n-k}$$

$$G(z) = \mathcal{Z}[g_n] = \mathcal{Z}\left[\sum_{k=0}^{\infty} h_k f_{n-k}\right] = \sum_{n=0}^{\infty} \left(\sum_{k=0}^{\infty} h_k f_{n-k}\right) z^{-n}$$

$$= \sum_{k=0}^{\infty} h_k \sum_{n=0}^{\infty} f_{n-k} z^{-n} = \sum_{k=0}^{\infty} h_k z^{-k} F(z)$$

$$H(z) = \mathcal{Z}[h_n] = \sum_{k=0}^{\infty} h_k z^{-k} \quad : \text{Transfer function}$$

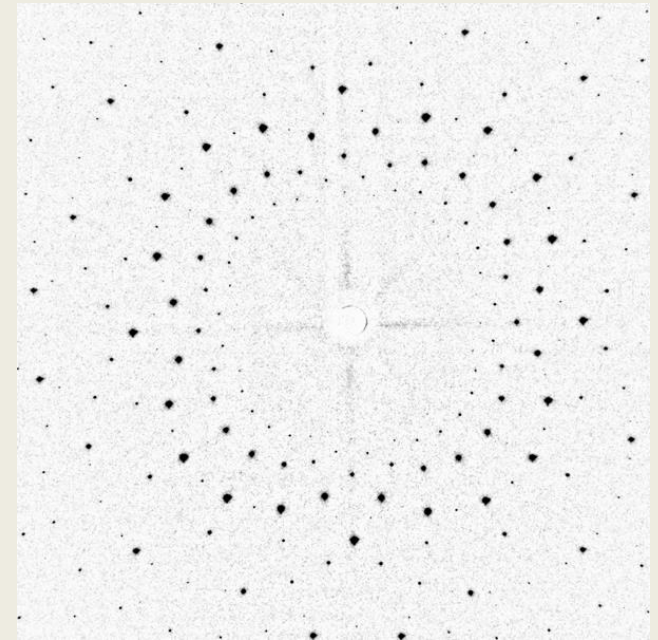
$$G(z) = H(z)F(z)$$

# Crystal lattice and X-ray diffraction

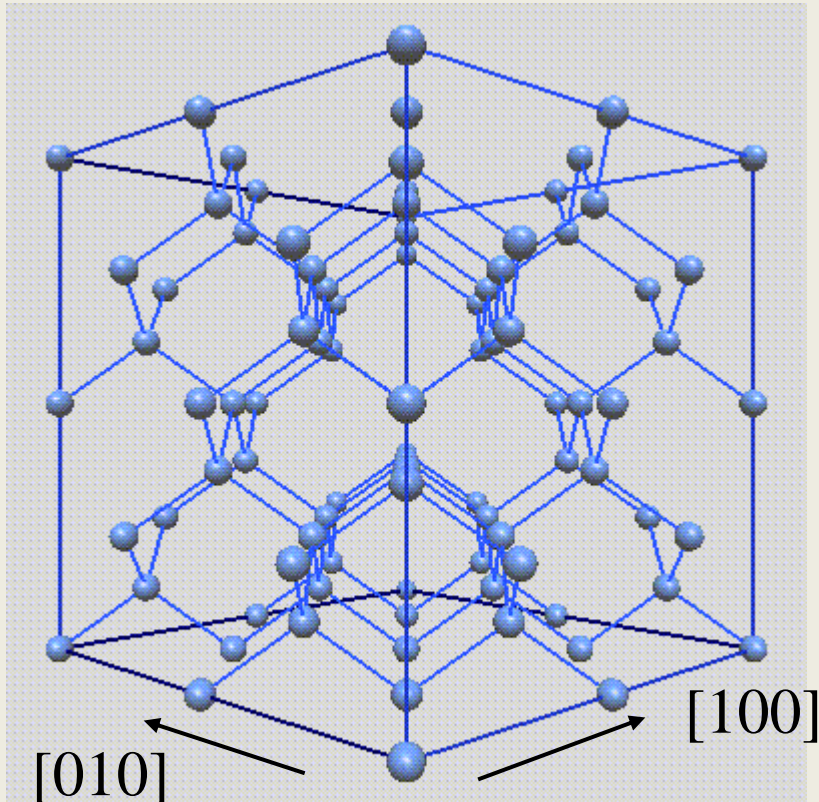


Max von Laue  
1879-1960

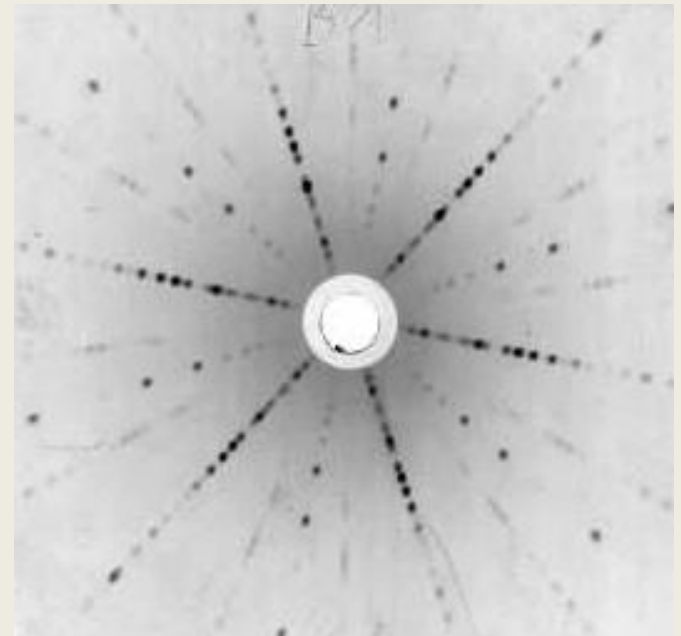
Laue pattern



Diamond lattice



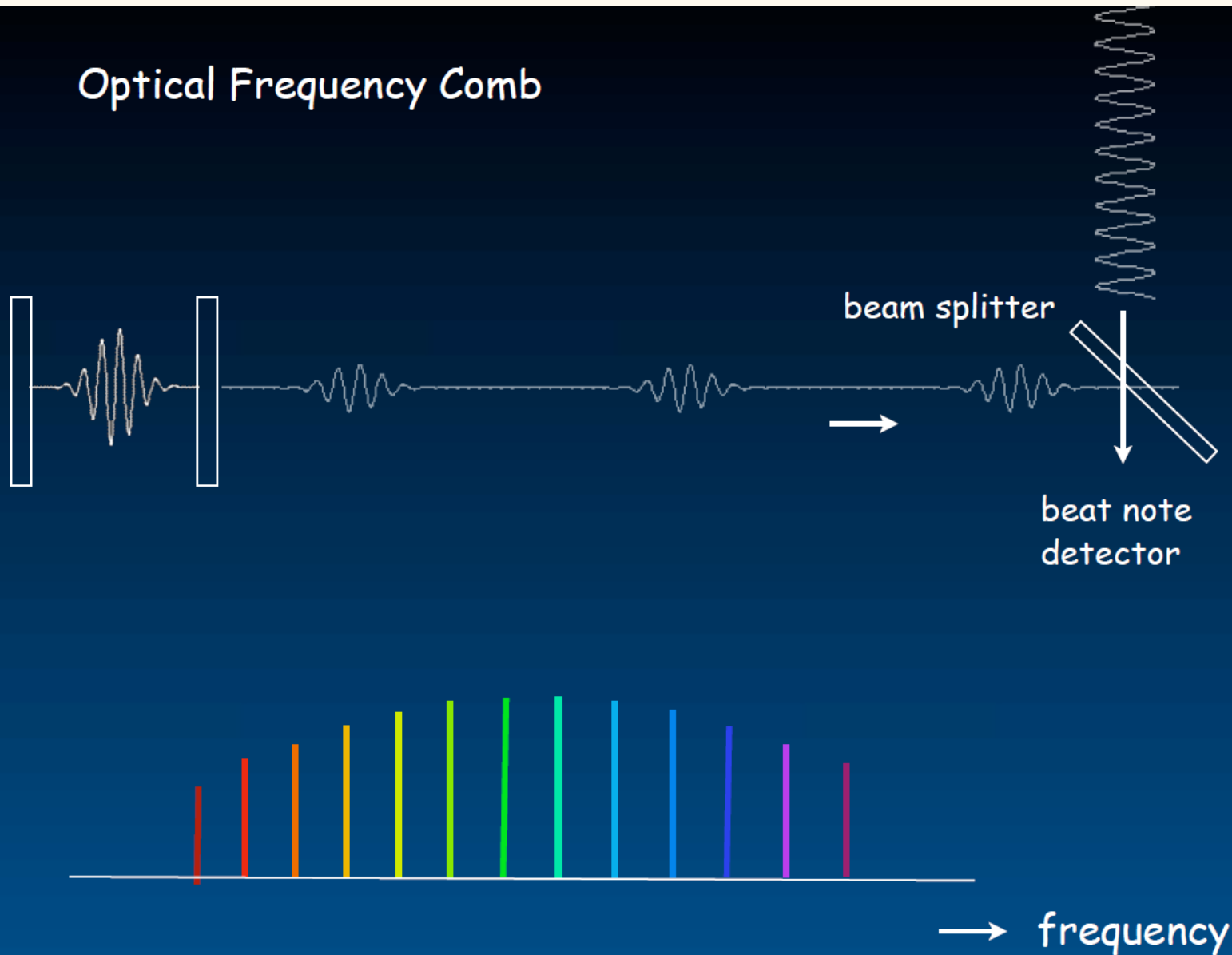
[100]



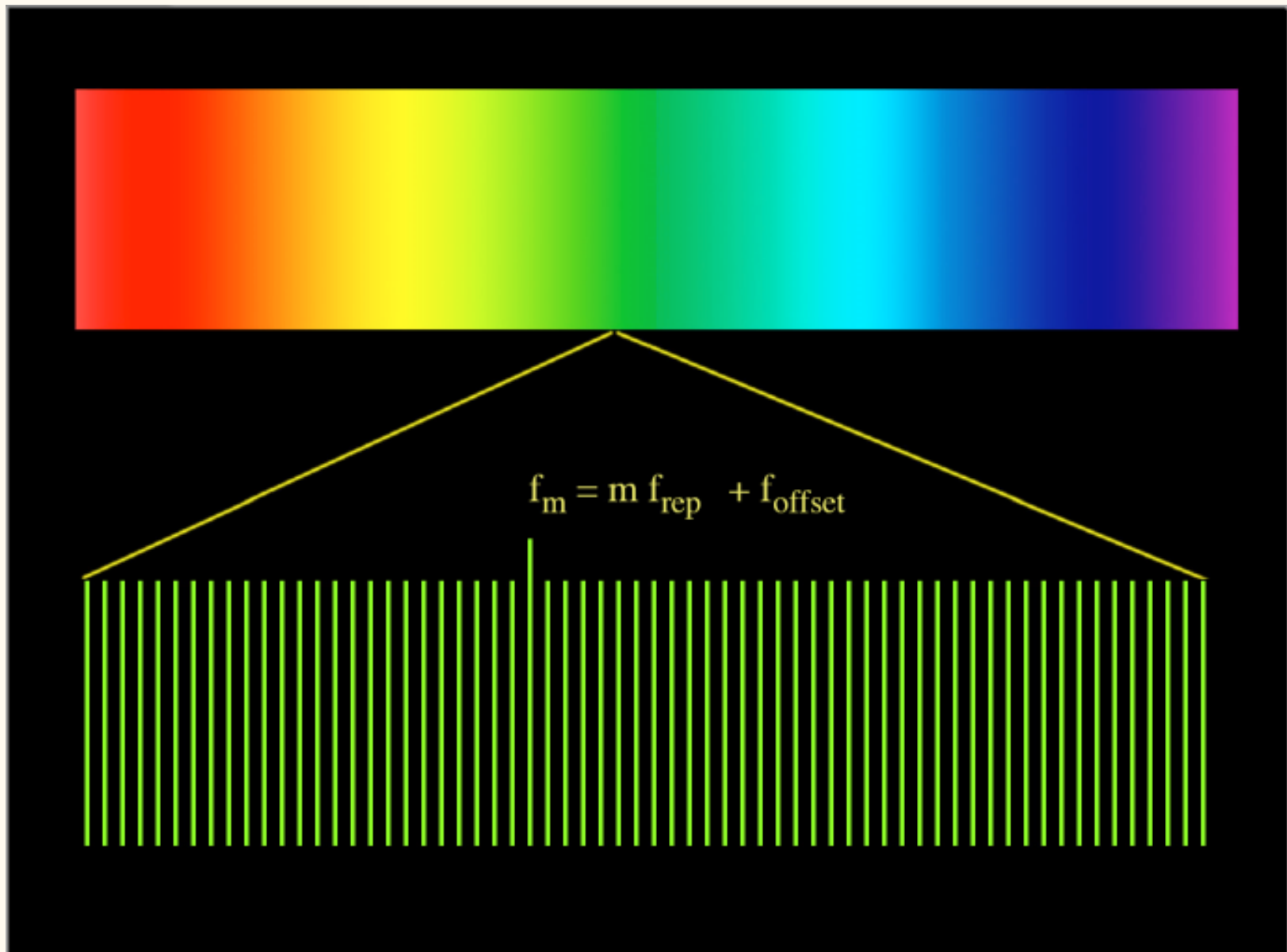
[111]

# Optical Frequency Comb

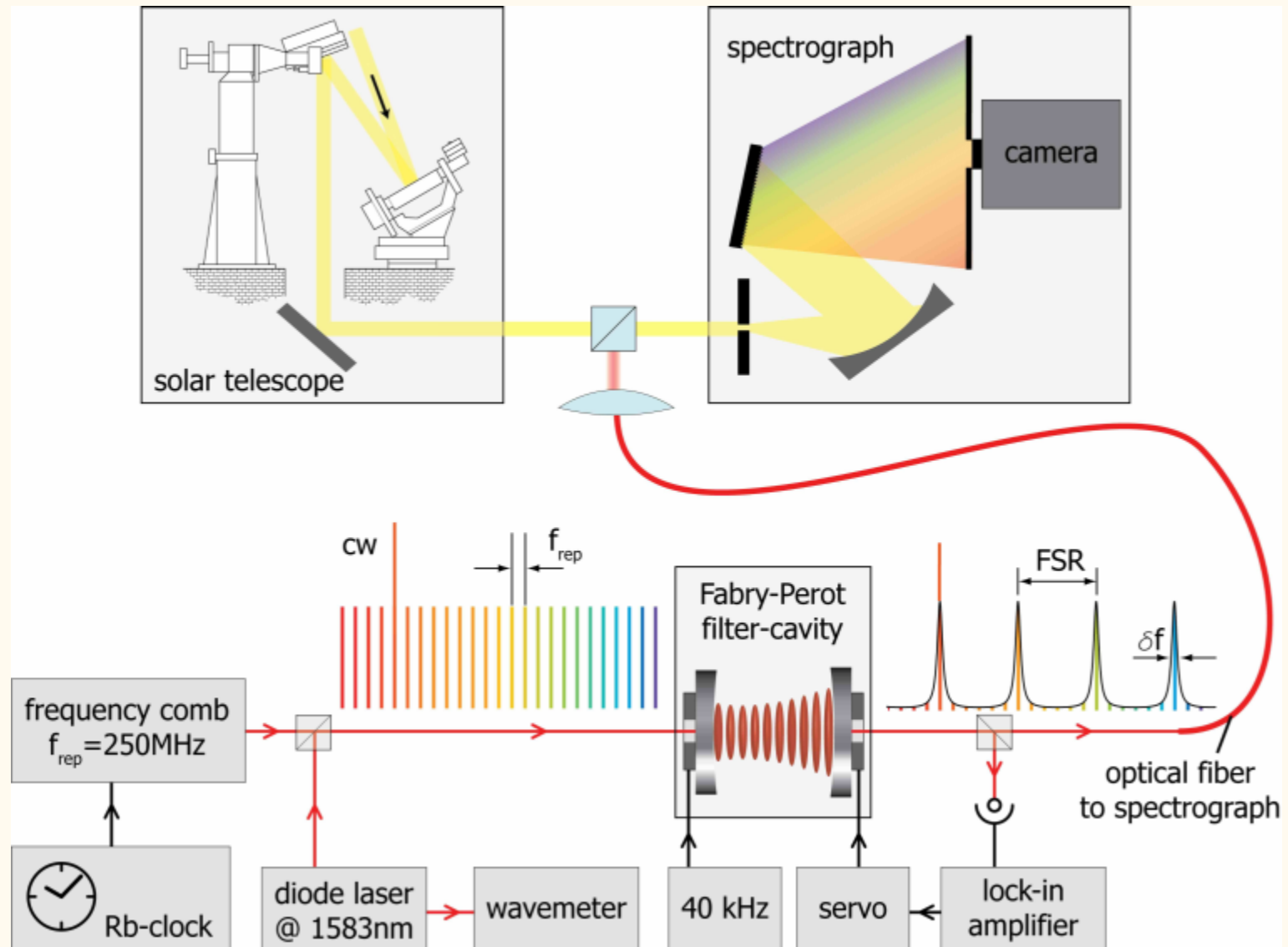
## Optical Frequency Comb



# Frequency Comb



# Measurement of the Doppler effect in cosmic expansion





Byzantine mosaic



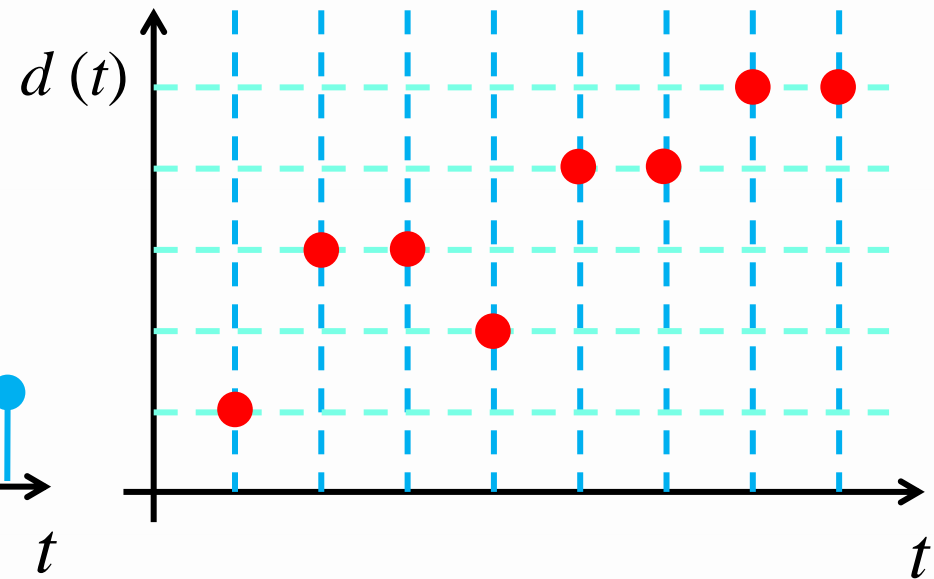
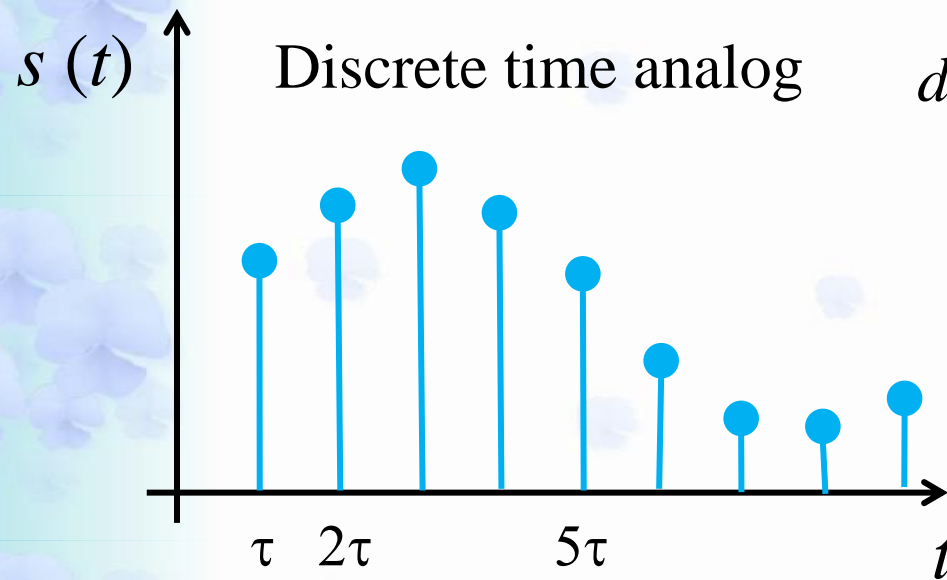
## Chapter 7

# Digital signal and circuits

Chartres Blue  
(Stained glass)



# Ch.7 Digital signal and circuits



Value discretized  $\rightarrow$  Digital signal

Signal unit : 0 xor 1 (bit)

Boolean algebra : F xor T

Voltage level : L xor H

Multiple bit  $\rightarrow$  binary operation  $\rightarrow$  parallel signal

## 7.2 Logic gates

Digital signal=logic value  $\rightarrow$  Logic operation : logic gates

De Morgan's laws:  $\overline{x + y} = \bar{x} \cdot \bar{y}$ ,  $\overline{x \cdot y} = \bar{x} + \bar{y}$

$t$		input				output			
		$t_1$	$t_2$	$\dots$	$t_m$	$t_1$	$t_2$	$\dots$	$t_m$
Ch.	1	0	1	$\dots$	$f_{1m}$	1	1	$\dots$	$q_{1m}$
	2	1	0	$\dots$	$f_{2m}$	2	0	$\dots$	$q_{2m}$
	$\vdots$	$\vdots$	$\vdots$	$\ddots$	$\vdots$	$\vdots$	$\vdots$	$\ddots$	$\vdots$
	$n$	0	1	$\dots$	$f_{nm}$	$l$	0	$\dots$	$f_{lm}$

Combinational logic  $\rightarrow$  Truth table

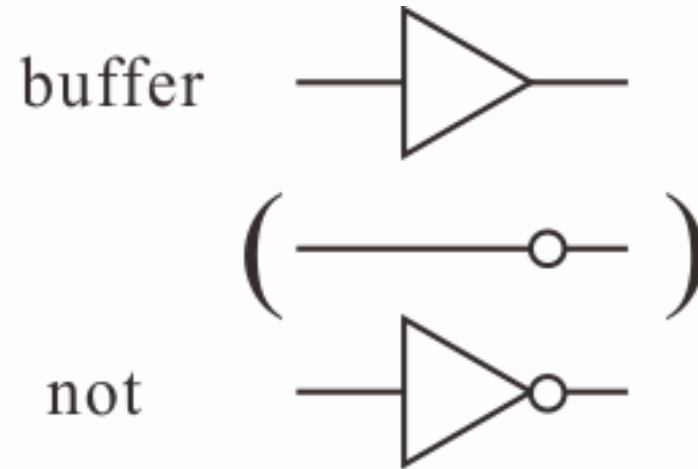
Sequential logic  $\rightarrow$  Timing chart

## 7.2.1 Combinational logic: Single input gates

Truth table

input	buffer	not
0	0	1
1	1	0

Circuit symbol





## 7.2.2 Combinational logic: Double input gates

input1	input 2	and	or	xor	nand
0	0	0	0	0	1
1	0	0	1	1	1
0	1	0	1	1	1
1	1	1	1	0	0



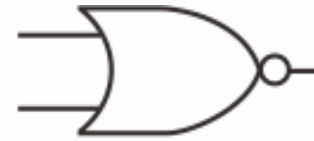
and



nand



or



nor



xor

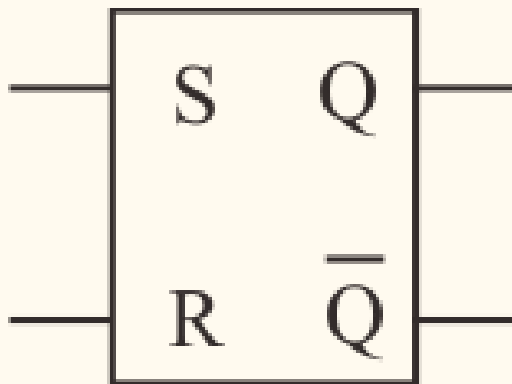
## 7.2.3 Sequential logic: Flip-Flop (FF)

### RS (reset-set) Flip-Flop (FF)

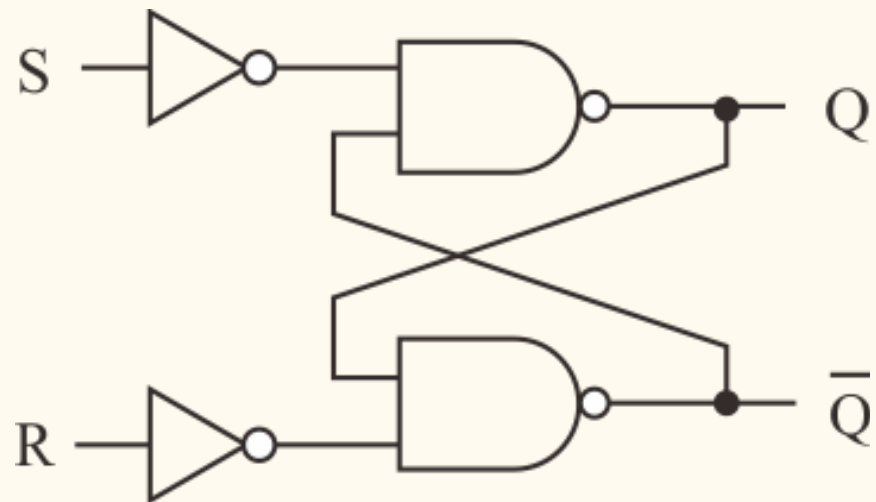
Truth table

S	R	Q	$\bar{Q}$	Response
0	0	Q	$\bar{Q}$	no change
0	1	0	1	reset
1	0	1	0	set
1	1	undetermined		

Symbol



Equivalent circuit with discrete gates





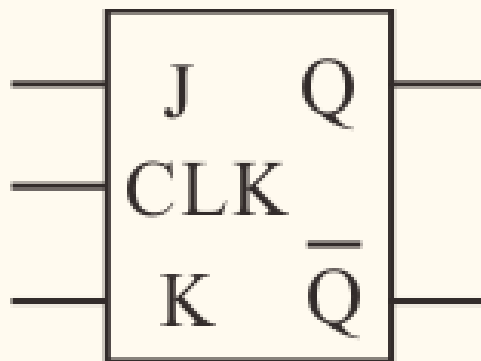
## 7.2.3 Sequential logic: Flip-Flop (FF)

JK Flip-Flop

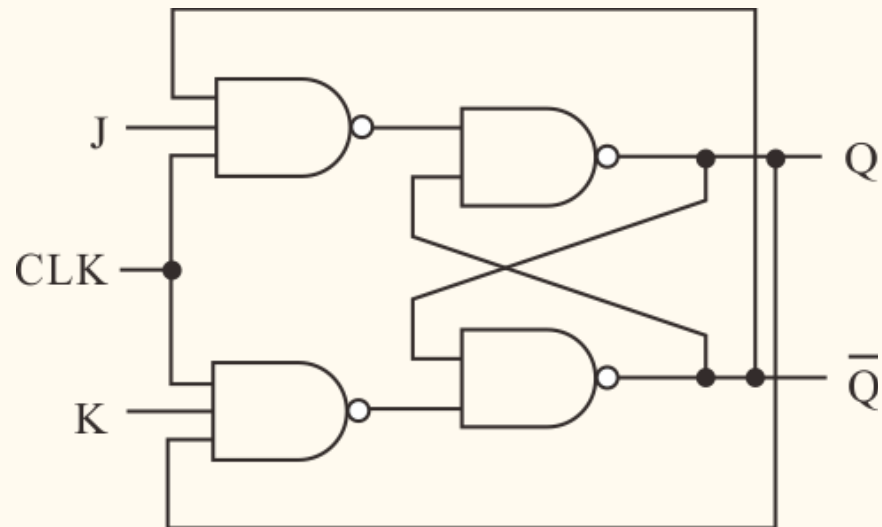
Truth table

J	K	Q	Q for the next CLK
0	0	0	0
0	0	1	1
0	1	—	0
1	0	—	1
1	1	0	1
1	1	1	0

Symbol



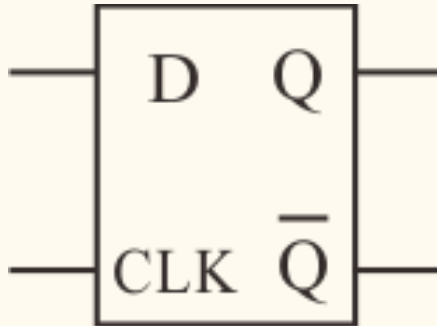
Equivalent circuit with discrete gates



## 7.2.3 Sequential logic: D-FF, T-FF

D-FF

Symbol

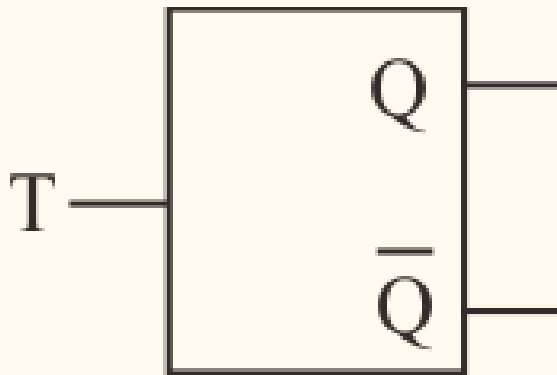


Truth table

D	CLK	Q
0	↑	0
1	↑	1
—	↓	Q (hold)

T-FF

Symbol

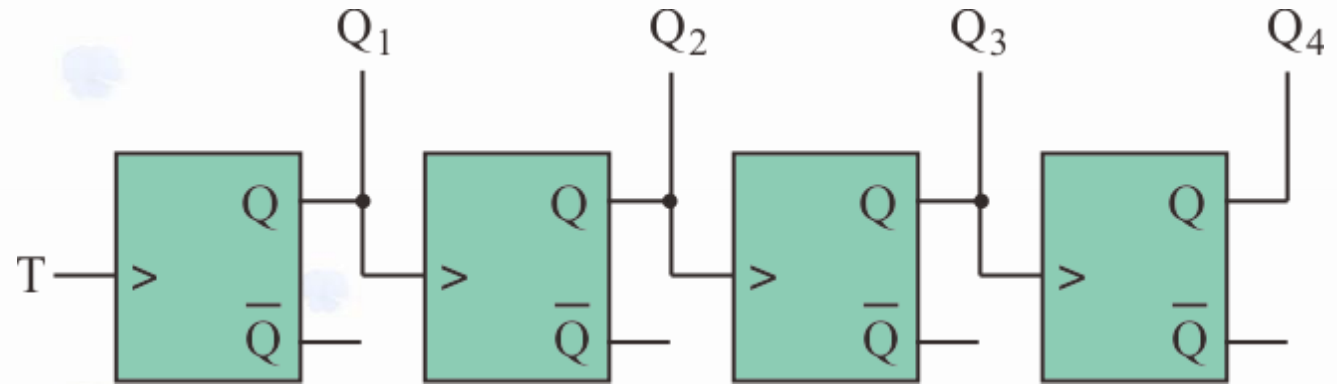


Truth table

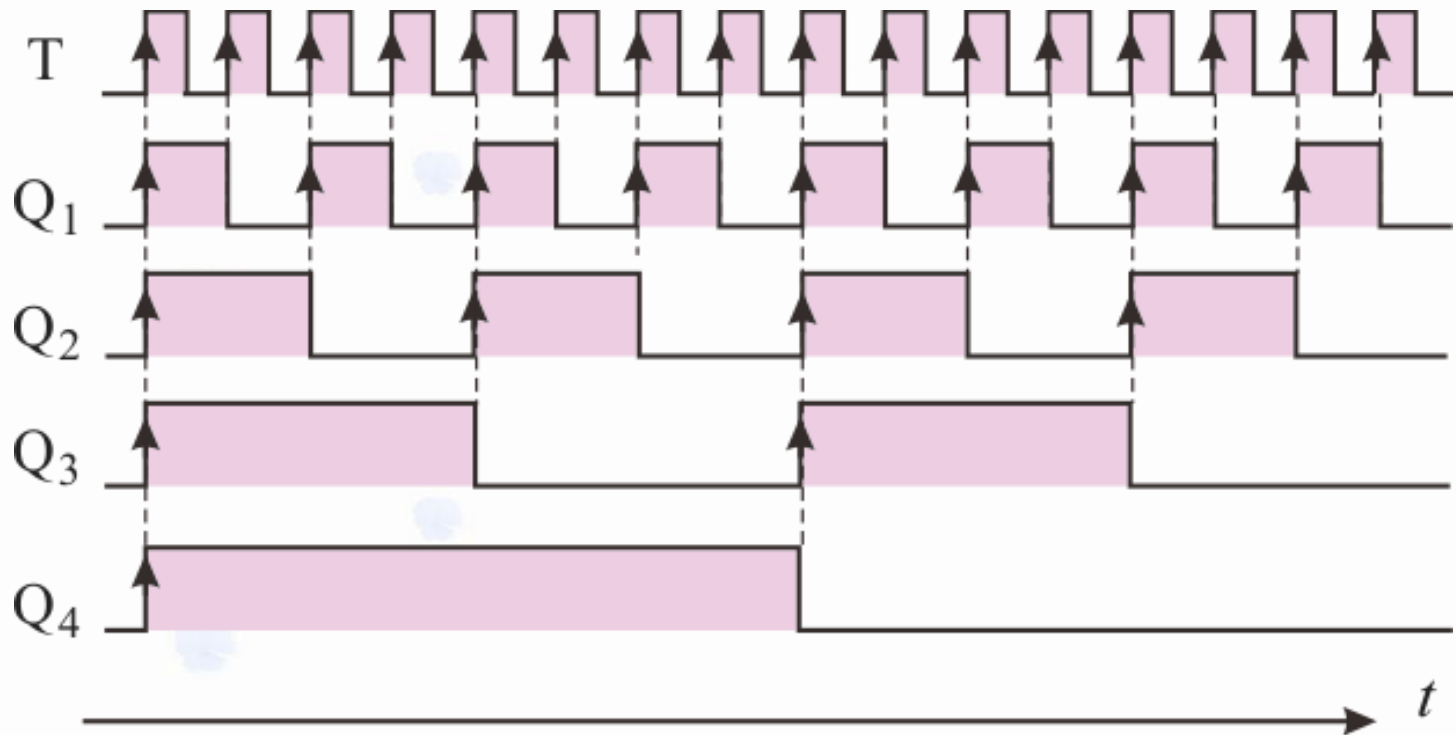
T	Q	Q
↓	0	0
↓	1	1
↑	0	1
↑	1	0

## 7.2.4 Sequential logic: Counters

Unsynchronized  
counter  
(ripple counter)



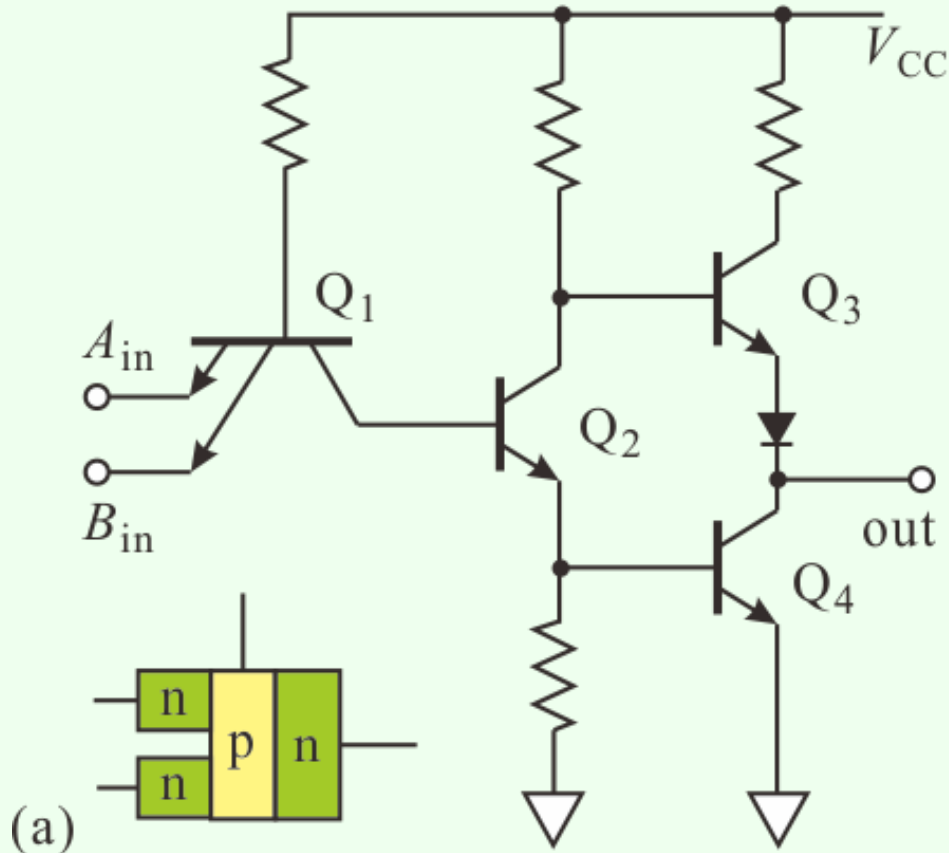
Timing  
chart



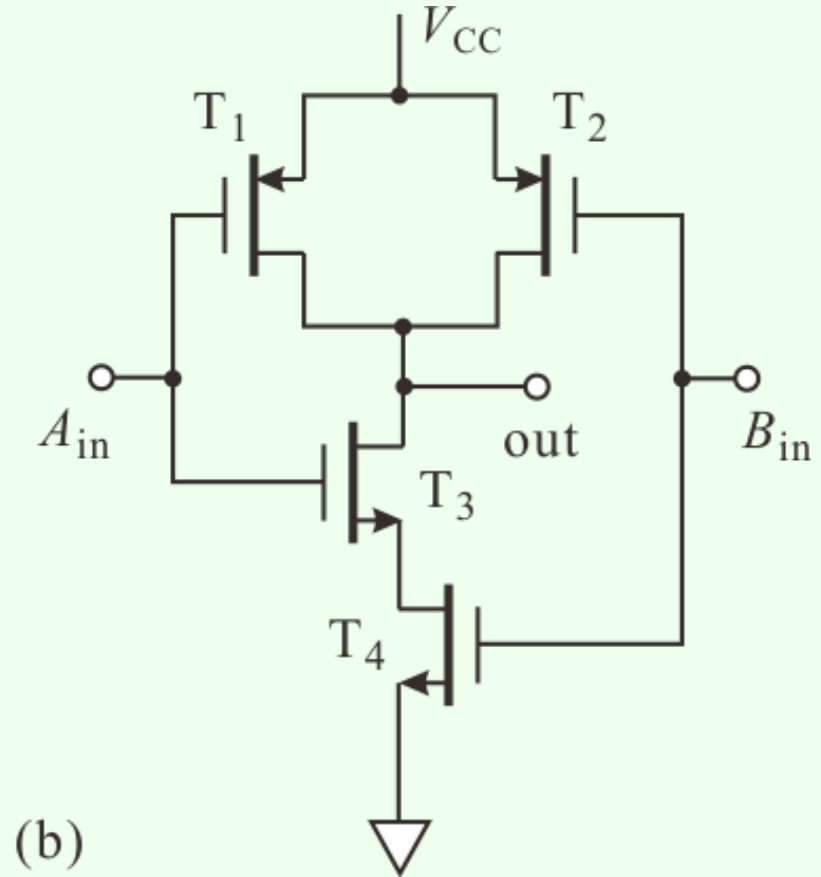


# 7.3 Implementation of logic gates

## NAND gates



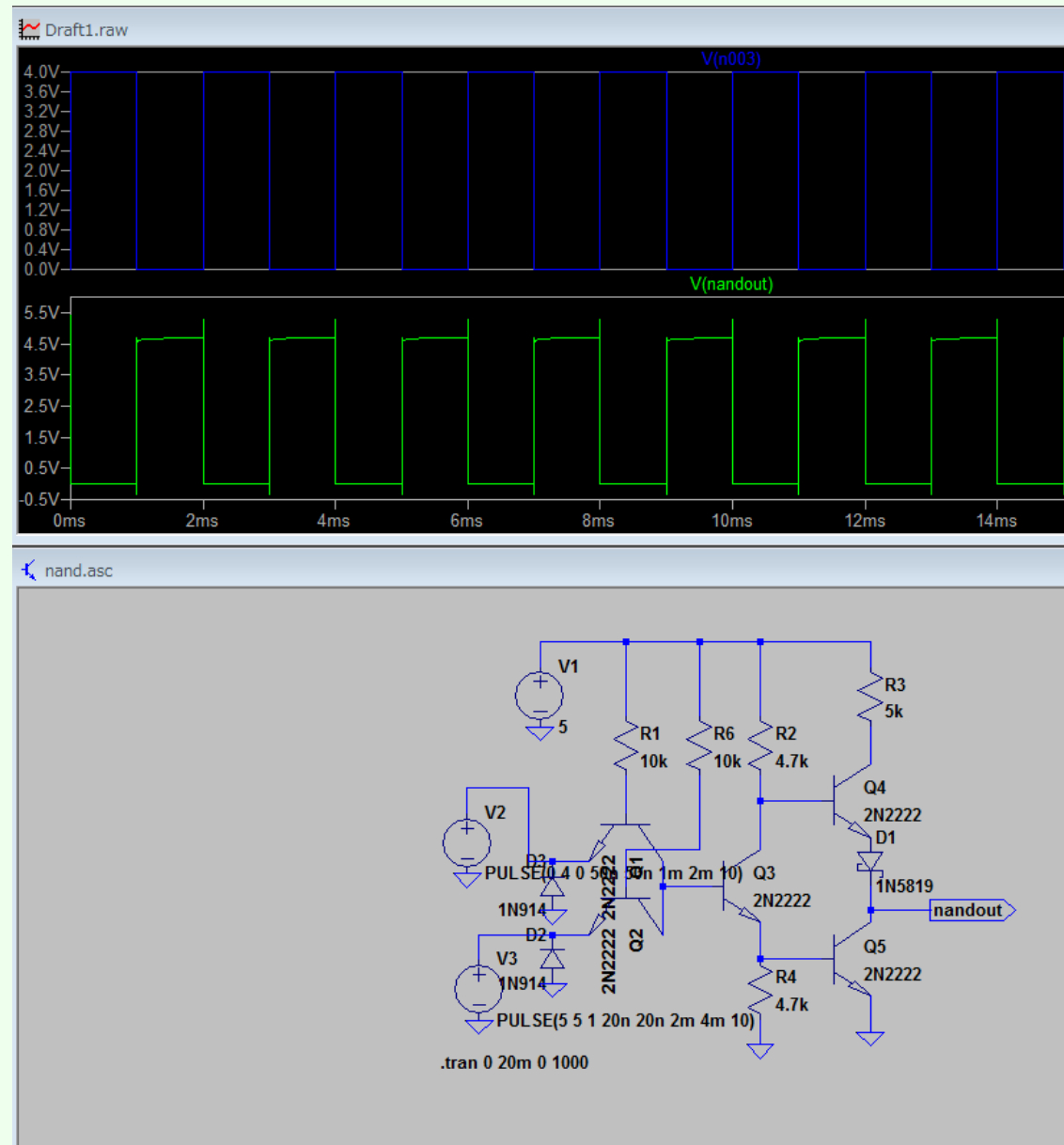
TTL (transistor-transistor logic)



CMOS (complimentary MOS)

# 7.3 Implementation of logic gates

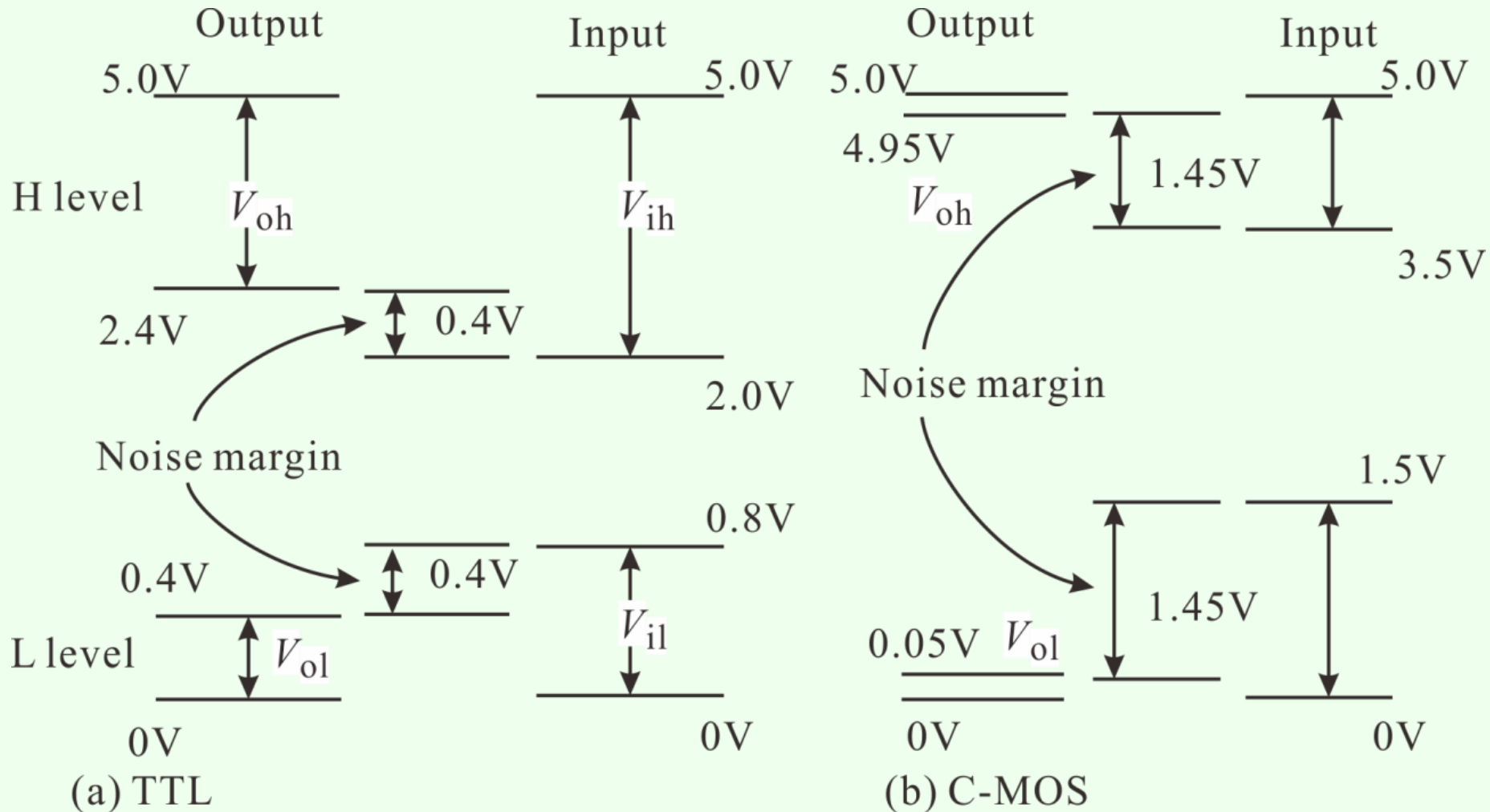
LT Spice  
simulation



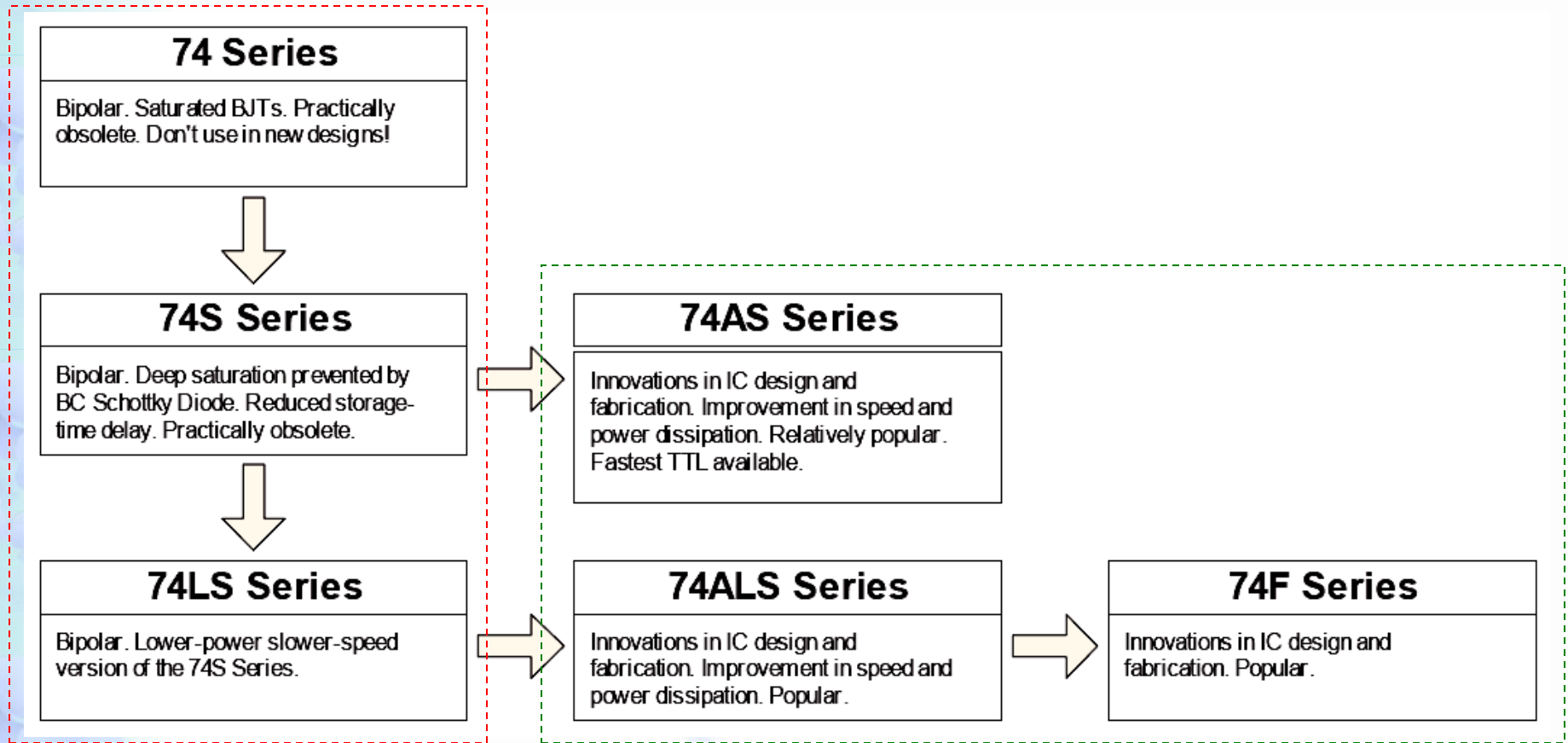


# 7.3 Implementation of logic gates

## Voltage levels diagram



# TTL logic family evolution

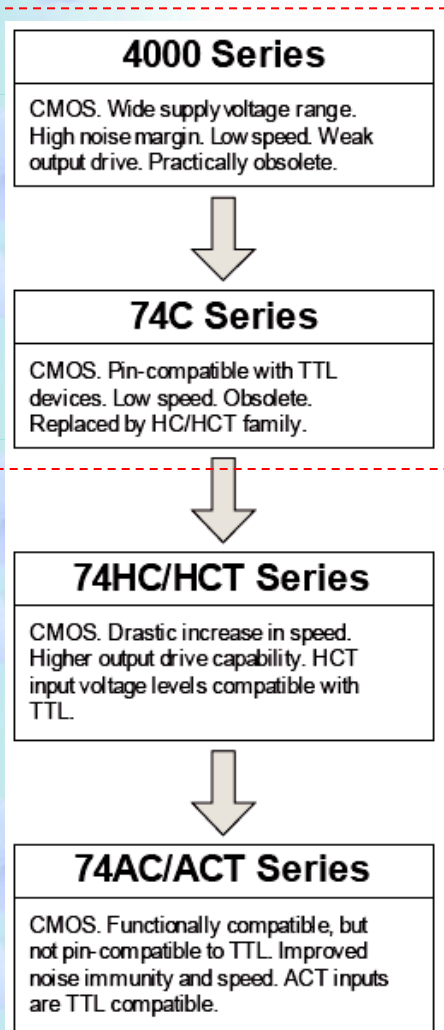


Legacy: don't use  
in new designs

Widely used today

# CMOS logic family evolution

obsolete



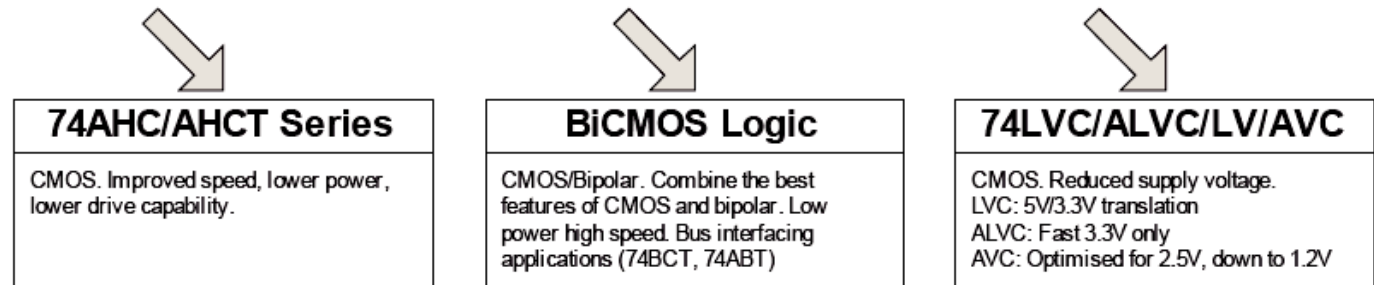
## General trend:

- Reduction of dynamic losses through successively decreasing supply voltages: 12V → 5V → 3.3V → 2.5V → 1.8V

CD4000

LVC/ALVC/AVC

- Power reduction is one of the keys to progressive growth of integration



# Summary

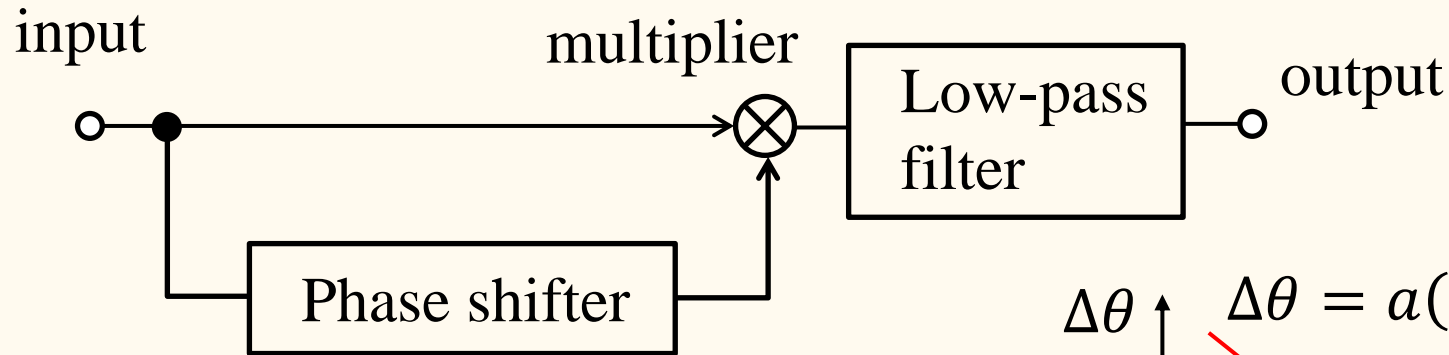
TTL

Logic Family	$T_{PD}$	$T_{rise/fall}$	$V_{IH,min}$	$V_{IL,max}$	$V_{OH,min}$	$V_{OL,max}$	Noise Margin
74	22ns		2.0V	0.8V	2.4V	0.4V	0.4V
74LS	15ns		2.0V	0.8V	2.7V	0.5V	0.3V
74F	5ns	2.3ns	2.0V	0.8V	2.7V	0.5V	0.3V
74AS	4.5ns	1.5ns	2.0V	0.8V	2.7V	0.5V	0.3V
74ALS	11ns	2.3ns	2.0V	0.8V	2.5V	0.5V	0.3V
ECL	1.45ns	0.35ns	-1.165V	-1.475V	-1.025V	-1.610V	0.135V
4000	250ns	90ns	3.5V	1.5V	4.95V	0.05V	1.45V
74C	90ns		3.5V	1.5V	4.5V	0.5V	1V
74HC	18ns	3.6ns	3.5V	1.0V	4.9V	0.1V	0.9V
74HCT	23ns	3.9ns	2.0V	0.8V	4.9V	0.1V	0.7V
74AC	9ns	1.5ns	3.5V	1.5V	4.9V	0.1V	1.4V
74ACT	9ns	1.5ns	2.0V	0.8V	4.9V	0.1V	0.7V
74AHC	3.7ns		3.85V	1.65V	4.4V	0.44V	0.55V

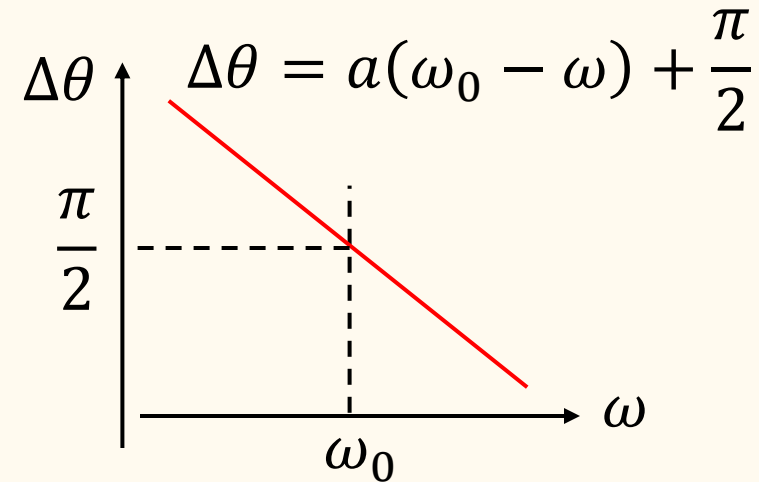
CMOS

# Exercise F-1

Show that the following circuit works as a demodulator of frequency modulation (FM) signal (quadrature demodulator).



Here the phase shifter gives the shift proportional to the frequency difference between input and the carrier frequency  $\omega_0$ . The shift at  $\omega_0$  is  $\pi/2$  as shown in the right (this can be achieved with resonant circuits). The low-pass filter cuts components with frequencies as high as  $\omega_0$ .



## Exercise F-1

(hint) Assume the original signal  $f(t)$  is much slower than the carrier  $A \cos(\omega_0 t)$ . Then the input can be approximated as

$$s(t) = A \cos\{[\omega_0 + k_f f(t)]t\}.$$

Then the phase shifter output is

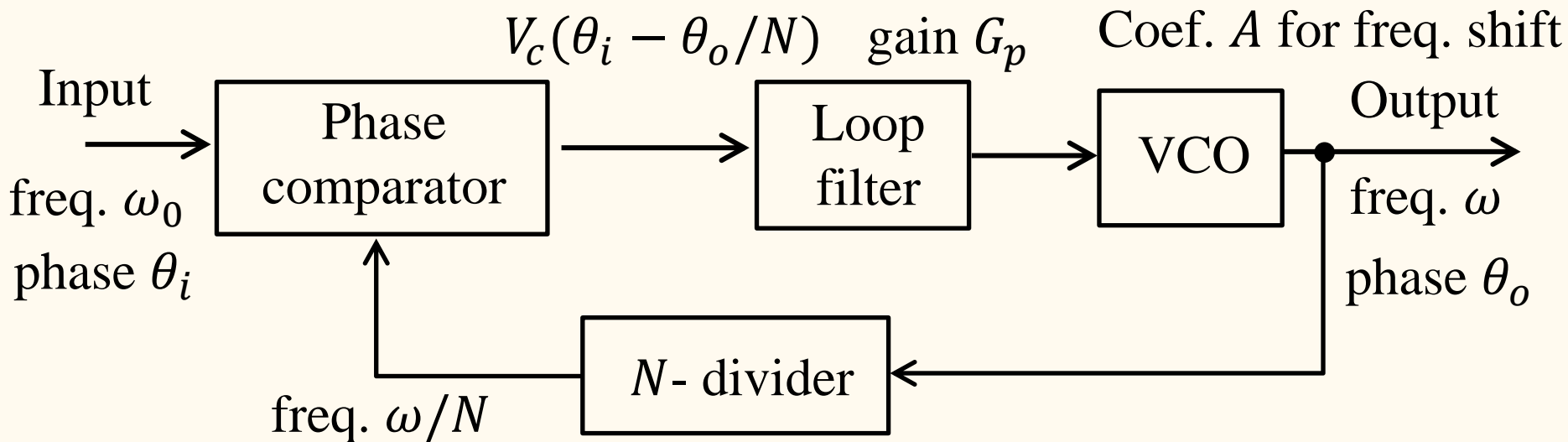
$$q_{\text{ps}}(t) = A \sin\{[\omega_0 + k_f f(t)]t - ak_f f(t)\}.$$

Taking product and high-frequency filtering gives ...  
(use  $ak_f f(t) \ll 1$ ).



# Exercise F-2

In the following phase lock loop (PLL) circuit, the initial ( $t = 0$ ) oscillation frequency of voltage-controlled oscillator (VCO)  $\omega$  deviates from  $N\omega_0$  by  $\Delta\omega$ . Obtain the relaxation time of  $\omega$  to  $N\omega_0$ .



(hint) Here we can put  $\theta_i = 0$  hence input =  $V_i \sin \omega_0 t$  without losing generality. Similarly output =  $V_o \sin[N\omega_0 t + \theta_o(t)]$ .  
Now  $\omega = N\omega_0 + d\theta_o/dt$  and it is easy to write  $d\theta_o/dt$  with  $A$ ,  $G_p$ ,  $V_c$ ,  $\theta_o(t)$  and a constant.

## Exercise F-3

Solve the difference equation below with z-transform.

$$\begin{cases} x(n) - 2x(n-1) = n & (n \geq 0) \\ x(n) = 0 & (n < 0) \end{cases}$$

(hint) z-transform of  $n$  is  $\frac{z}{(z-1)^2}$  as in the table (slide no.14).

Then z-transform of  $x(n) : X(z)$  is easily obtained. Inverse z-transform gives  $x(n)$ .

Answer sheet submission deadline: 11<sup>th</sup> Jan. 2017.



電子回路論第13回

Electric Circuits for Physicists

東京大学理学部・理学系研究科  
物性研究所  
勝本信吾

Shingo Katsumoto







# Outline

7.2 Sequential digital circuit

7.3 Implementation of logic gates

7.4 Circuit implementation and simplification  
of logic operation

7.5 DA/AD converter circuits

7.6 Digital filters (digital signal processing)

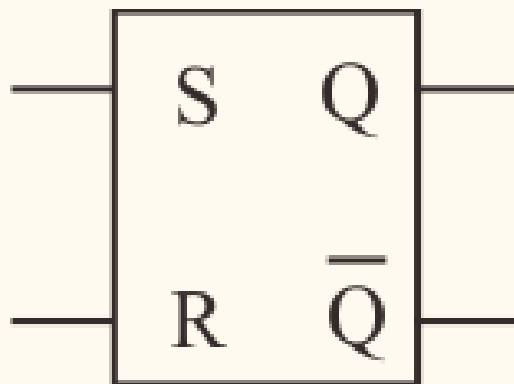
## 7.2.3 Sequential logic: Flip-Flop (FF)

RS (reset-set) Flip-Flop (FF)

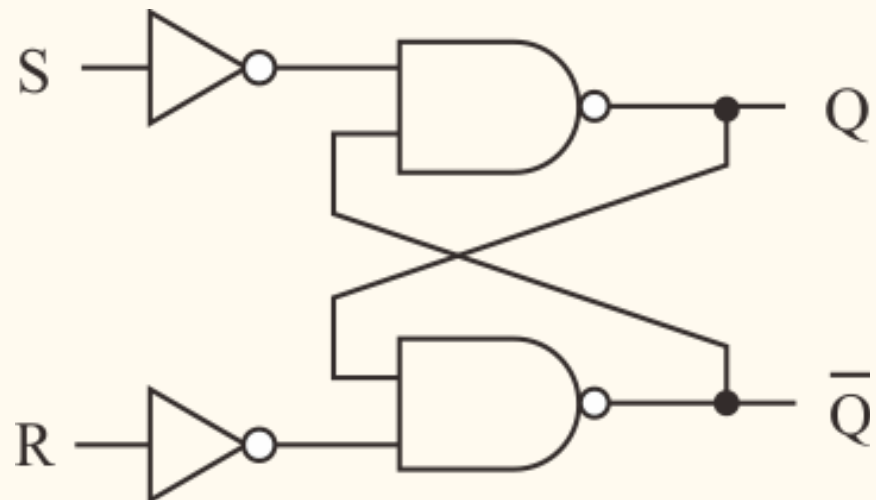
Truth table

S	R	Q	$\bar{Q}$	Response
0	0	Q	$\bar{Q}$	no change
0	1	0	1	reset
1	0	1	0	set
1	1	undetermined		

Symbol



Equivalent circuit with discrete gates





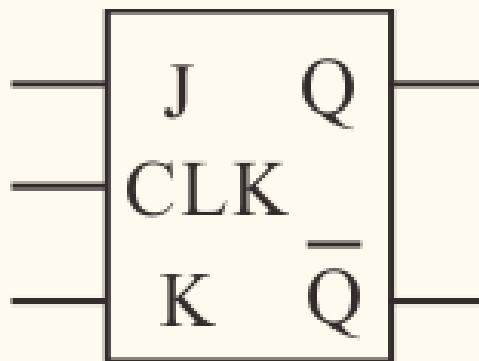
## 7.2.3 Sequential logic: Flip-Flop (FF)

JK Flip-Flop

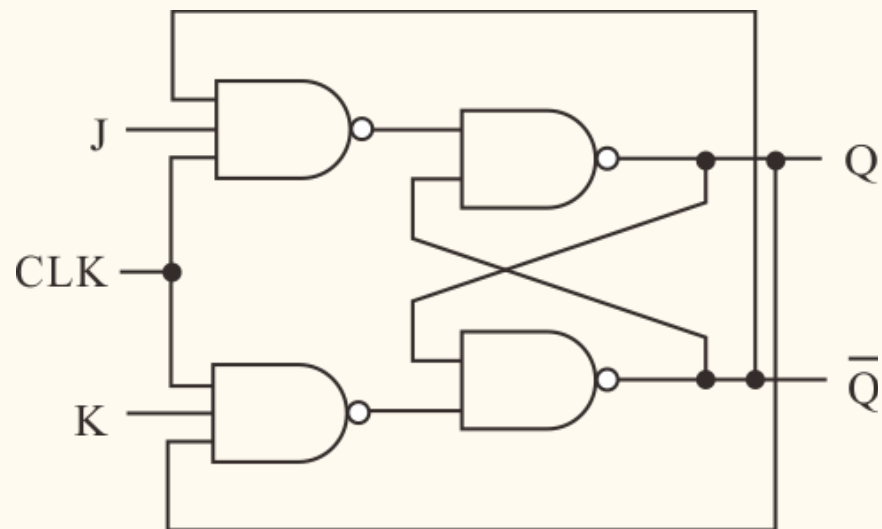
Truth table

J	K	Q	Q for the next CLK
0	0	0	0
0	0	1	1
0	1	—	0
1	0	—	1
1	1	0	1
1	1	1	0

Symbol



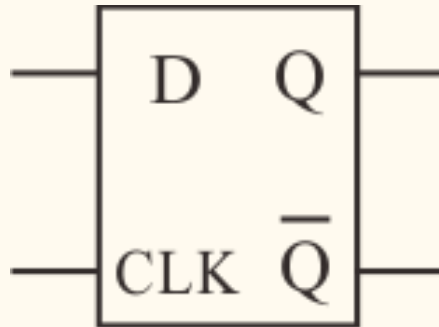
Equivalent circuit with discrete gates



## 7.2.3 Sequential logic: D-FF, T-FF

D-FF

Symbol

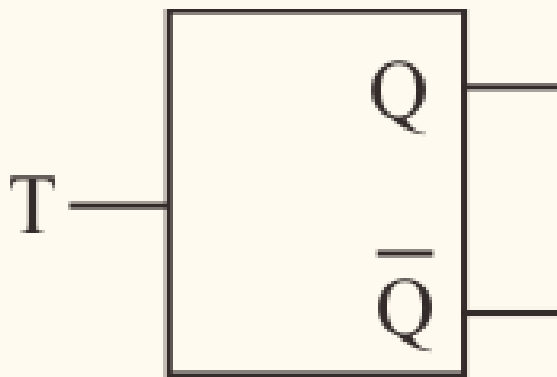


Truth table

D	CLK	Q
0	↑	0
1	↑	1
—	↓	Q (hold)

T-FF

Symbol

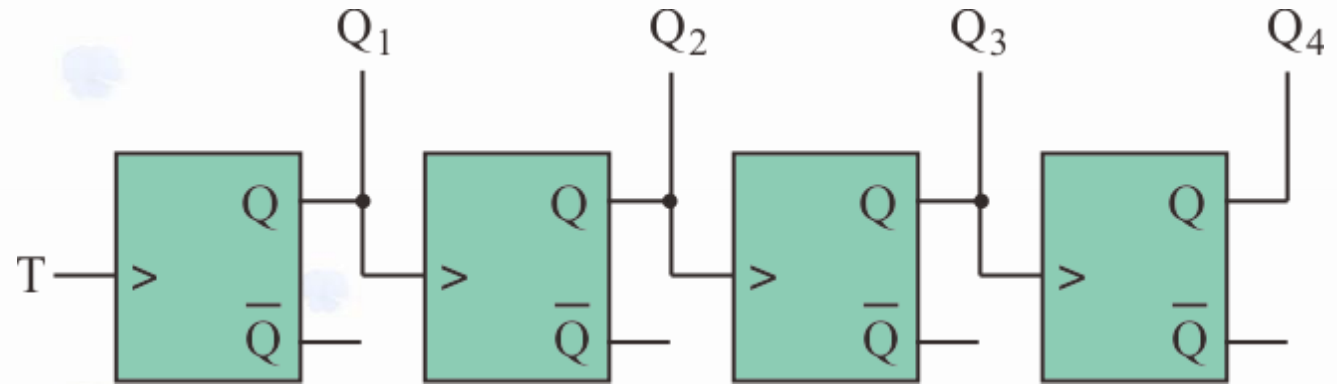


Truth table

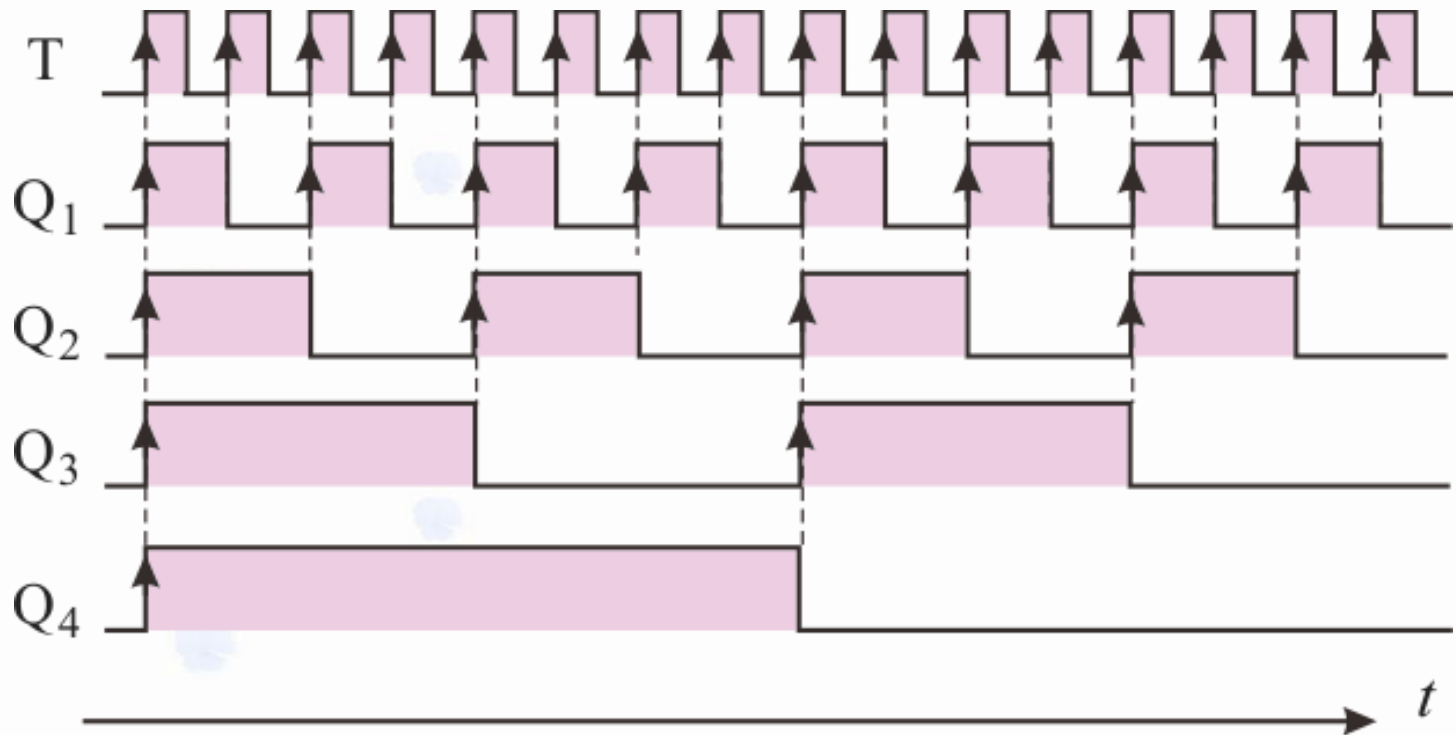
T	Q	Q
↓	0	0
↓	1	1
↑	0	1
↑	1	0

## 7.2.4 Sequential logic: Counters

Unsynchronized  
counter  
(ripple counter)



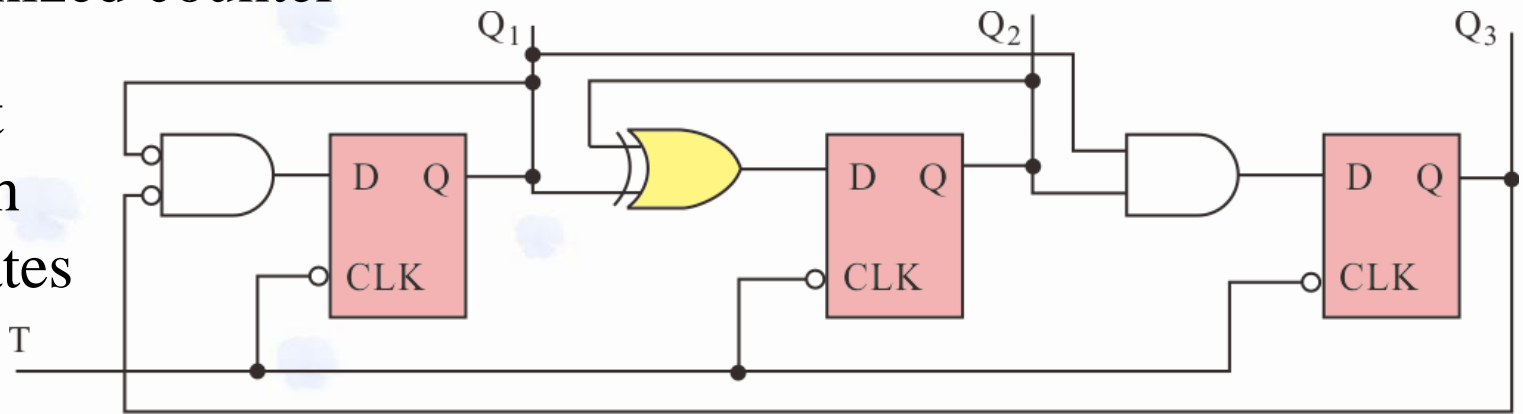
Timing  
chart



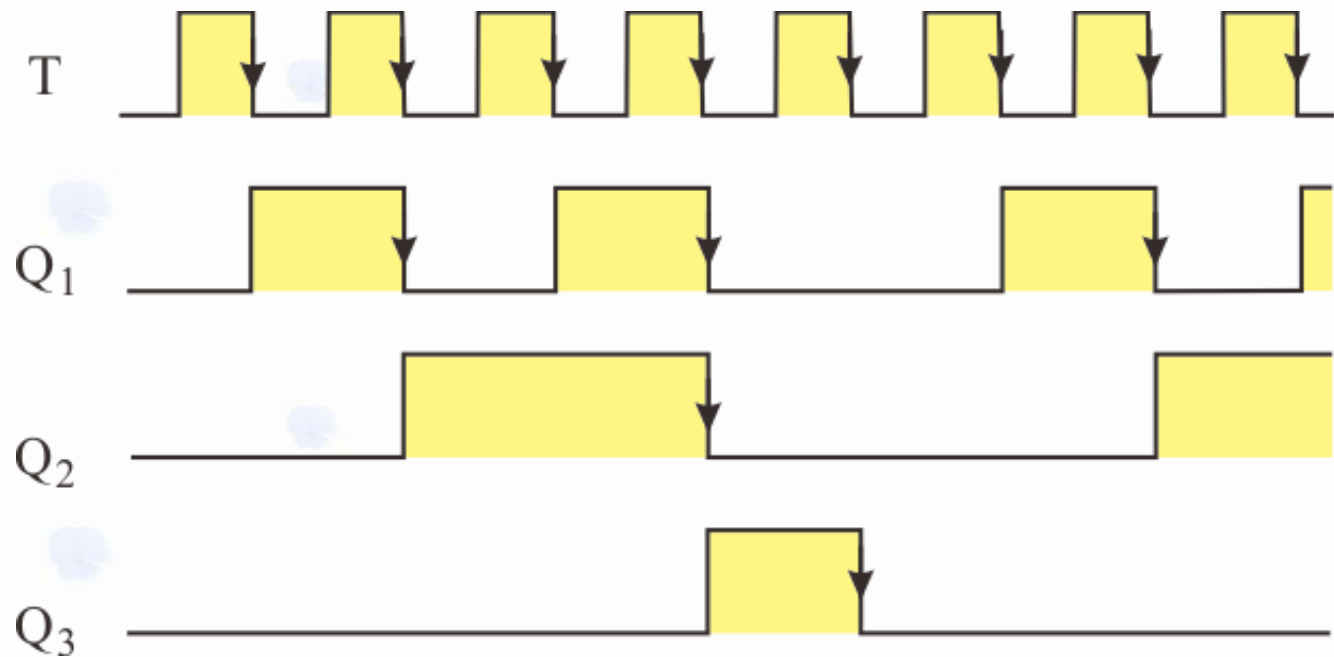
# 7.2.4 Sequential logic: Counters

## Synchronized counter

Equivalent circuit with discrete gates



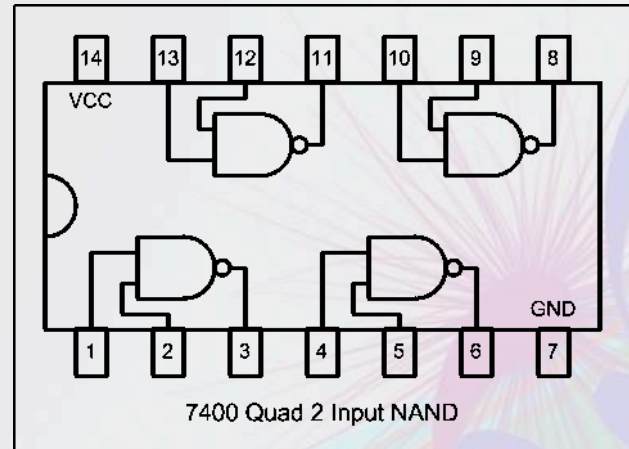
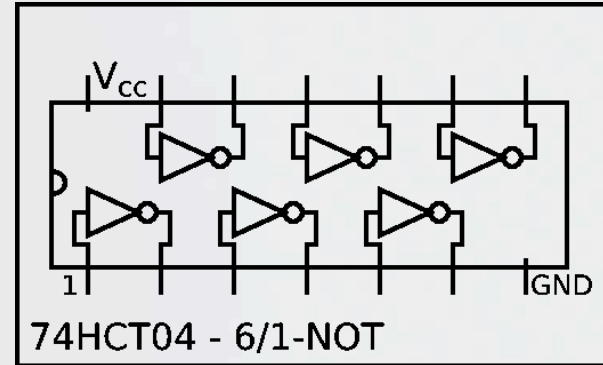
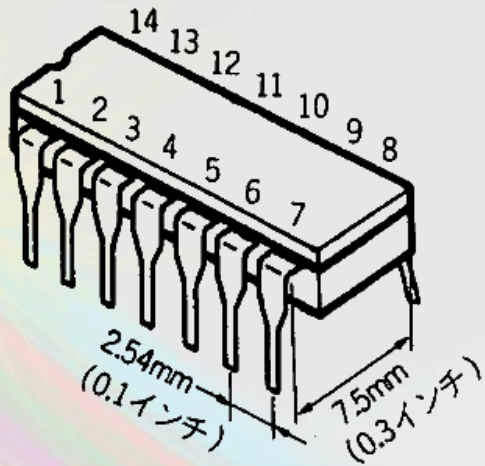
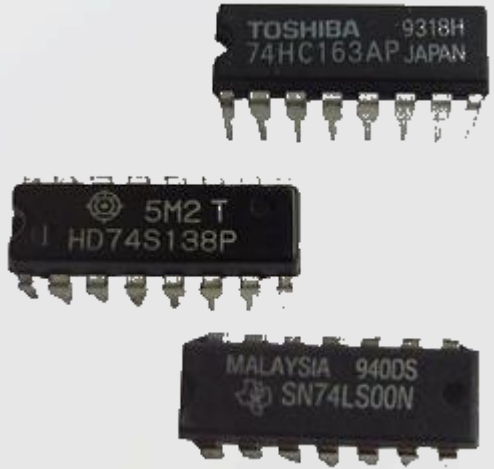
Timing chart



# Standard gate logic IC packaging

Full pitch

Half pitch surface mount





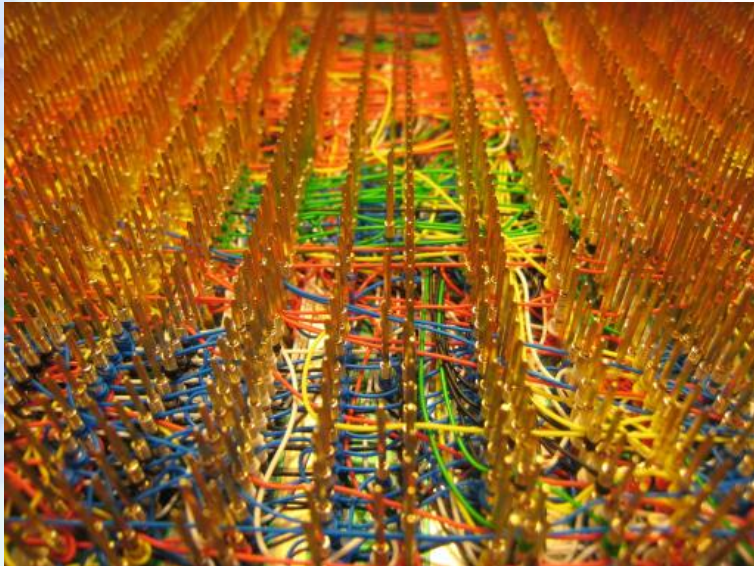
# Mounting of logic ICs



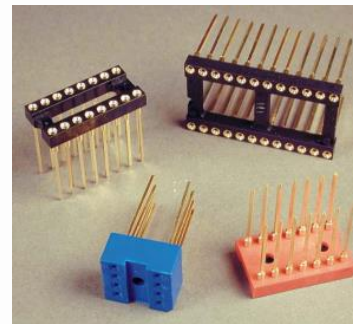
Printed board with soldering



Surface mounting



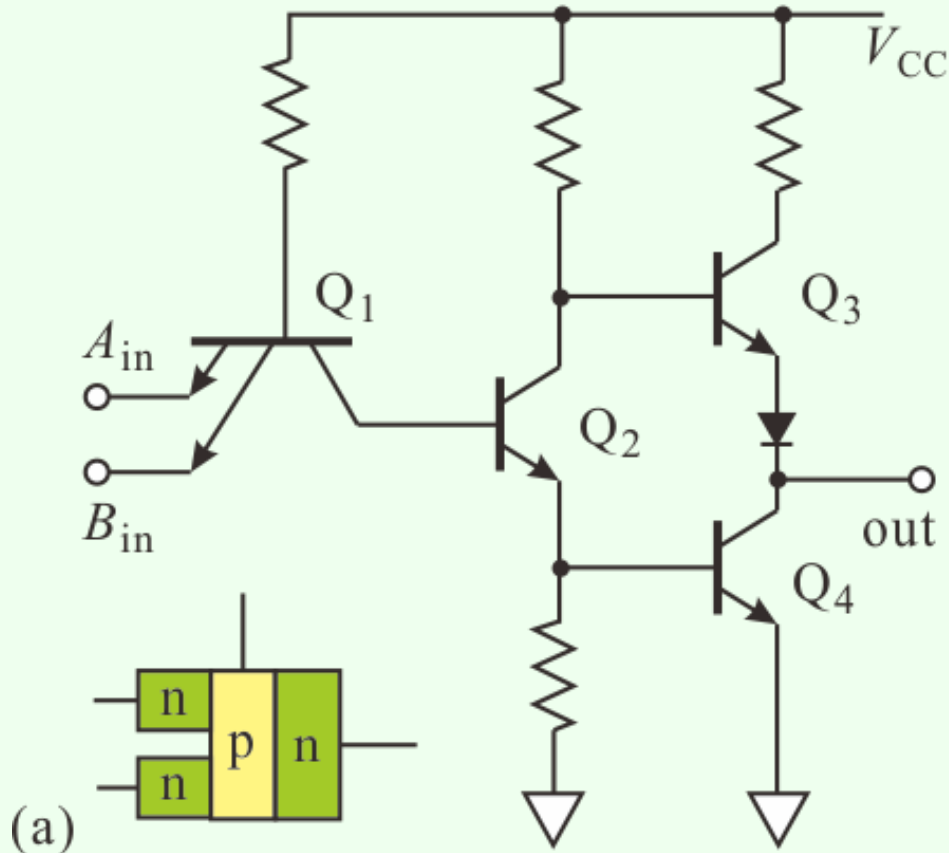
Wire wrapping



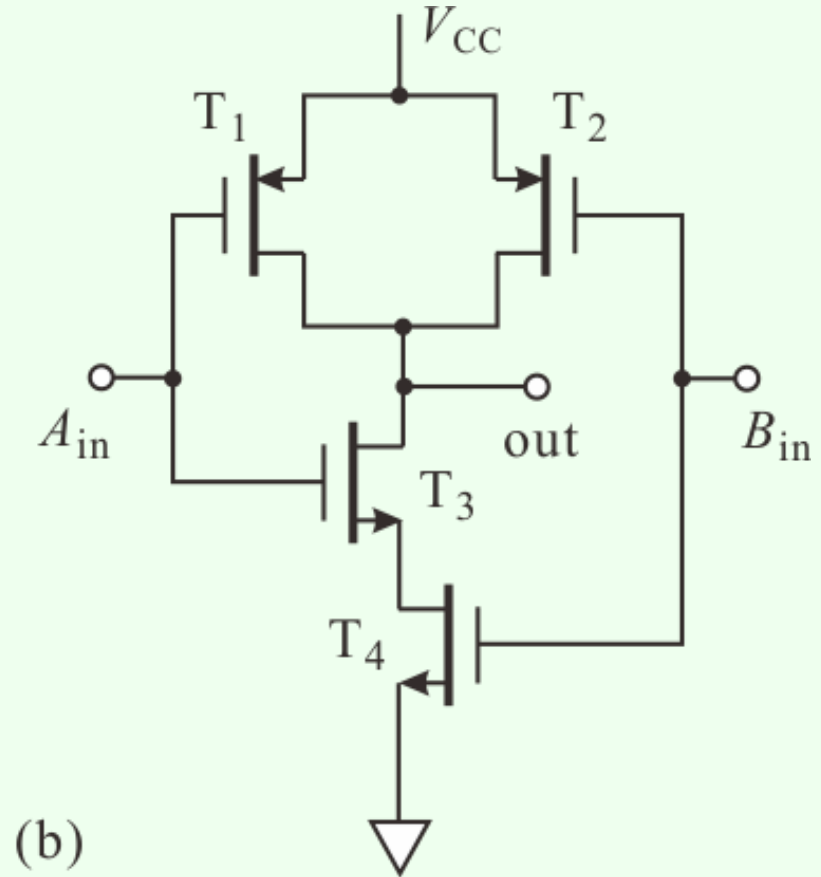


# 7.3 Implementation of logic gates

## NAND gates



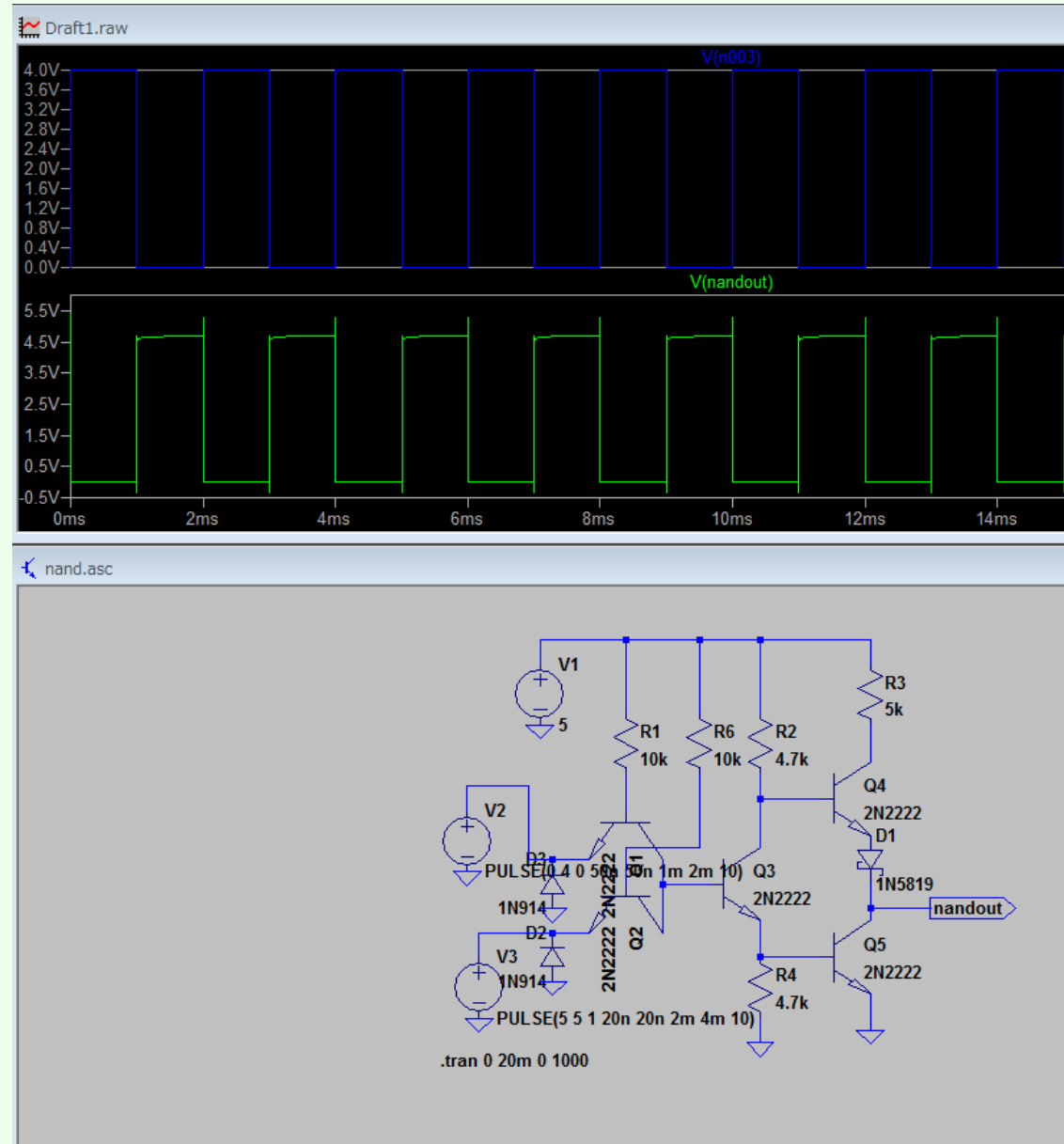
TTL (transistor-transistor logic)



CMOS (complimentary MOS)

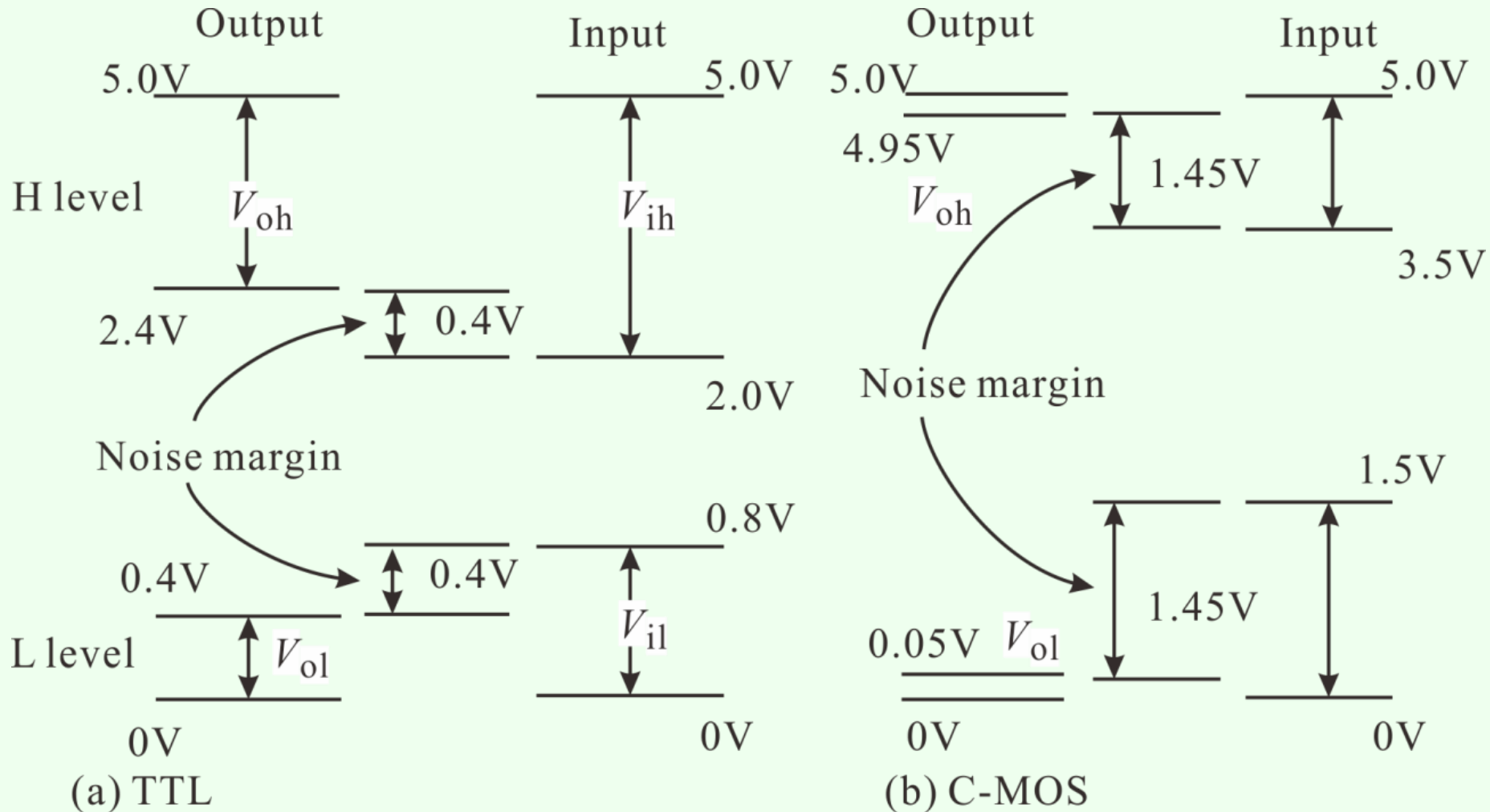
# 7.3 Implementation of logic gates

## LT Spice simulation

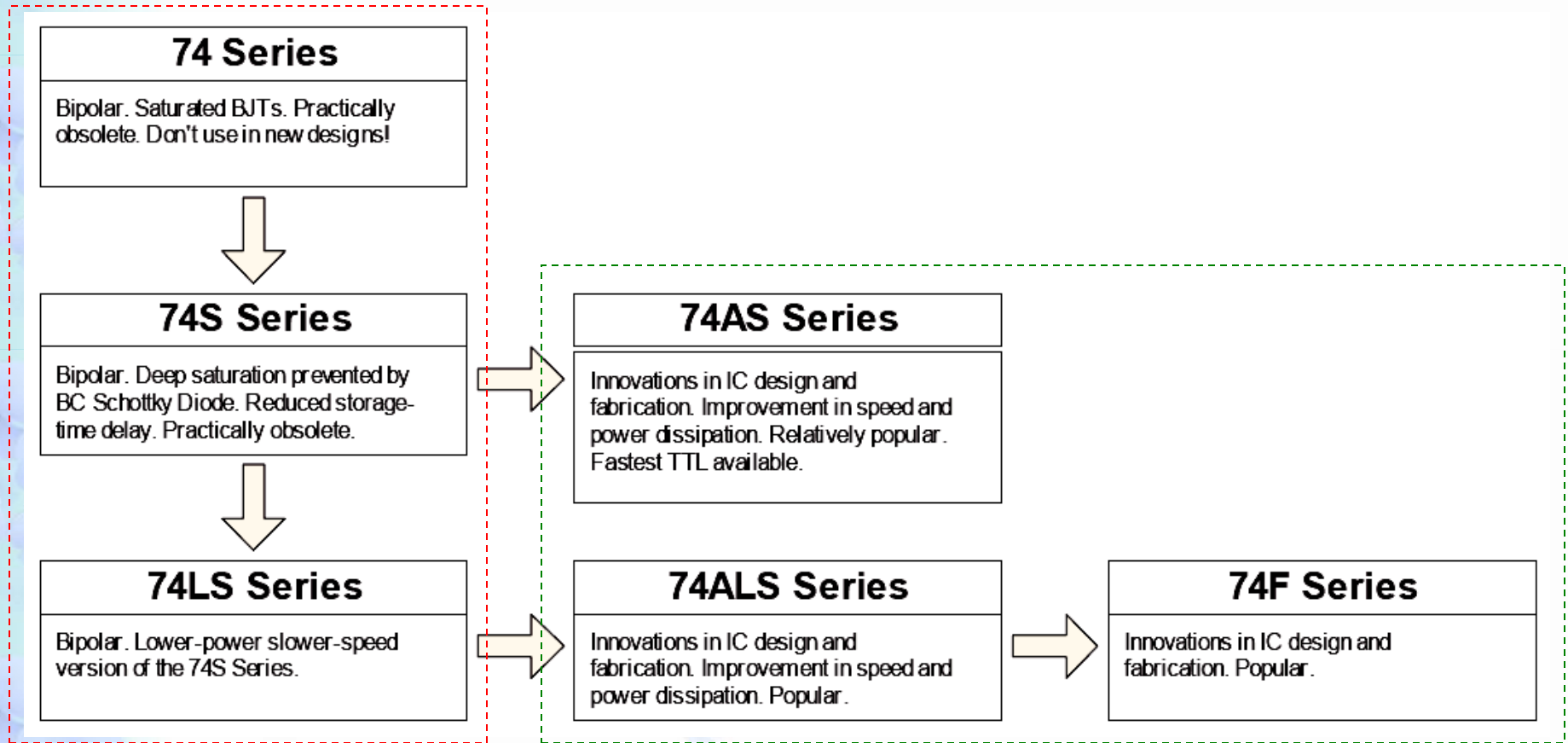


# 7.3 Implementation of logic gates

## Voltage levels diagram



# TTL logic family evolution

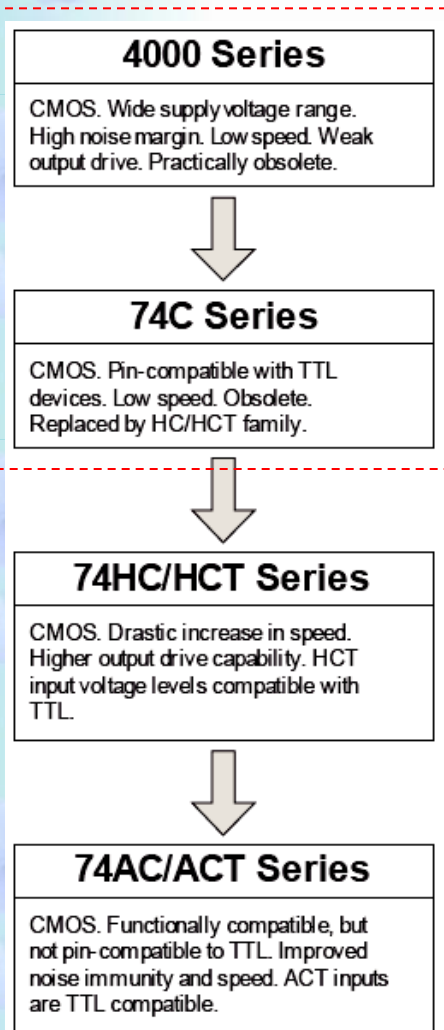


Legacy: don't use  
in new designs

Widely used today

# CMOS logic family evolution

obsolete



## General trend:

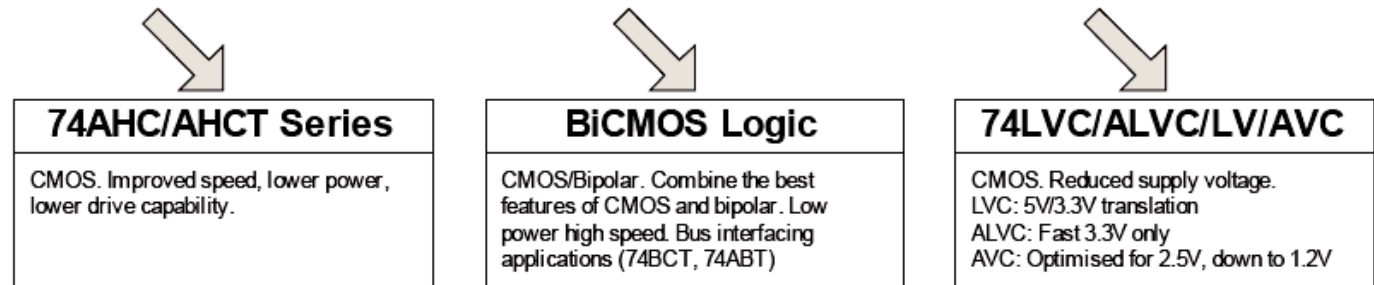
- Reduction of dynamic losses through successively decreasing supply voltages:

12V → 5V → 3.3V → 2.5V → 1.8V

CD4000

LVC/ALVC/AVC

- Power reduction is one of the keys to progressive growth of integration



# Summary

TTL

Logic Family	$T_{PD}$	$T_{rise/fall}$	$V_{IH,min}$	$V_{IL,max}$	$V_{OH,min}$	$V_{OL,max}$	Noise Margin
74	22ns		2.0V	0.8V	2.4V	0.4V	0.4V
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74AS	4.5ns	1.5ns	2.0V	0.8V	2.7V	0.5V	0.3V
74ALS	11ns	2.3ns	2.0V	0.8V	2.5V	0.5V	0.3V
ECL	1.45ns	0.35ns	-1.165V	-1.475V	-1.025V	-1.610V	0.135V
4000	250ns	90ns	3.5V	1.5V	4.95V	0.05V	1.45V
74C	90ns		3.5V	1.5V	4.5V	0.5V	1V
74HC	18ns	3.6ns	3.5V	1.0V	4.9V	0.1V	0.9V
74HCT	23ns	3.9ns	2.0V	0.8V	4.9V	0.1V	0.7V
74AC	9ns	1.5ns	3.5V	1.5V	4.9V	0.1V	1.4V
74ACT	9ns	1.5ns	2.0V	0.8V	4.9V	0.1V	0.7V
74AHC	3.7ns		3.85V	1.65V	4.4V	0.44V	0.55V

CMOS



## 7.4 Circuit implementation and simplification of logic operation

Truth table  $\rightarrow$  Simplification  $\rightarrow$  Circuit diagram

Simplification  $\left\{ \begin{array}{l} \text{Visual method: Karnaugh mapping} \\ \text{Quine-McClusky algorithm} \end{array} \right.$

Product of all the logic variables: **canonical expansion**

principal disjunctive canonical expansion (主加法標準展開)

$$Y = \sum_j \prod_{i=1}^n g_i(a_{ij})$$

$$\text{Ex) } Y = \bar{A} \cdot \bar{B} \cdot C \cdot D + B \cdot C \cdot D + A \cdot B \cdot \bar{C} + A \cdot \bar{B} \cdot C \cdot D$$

$$\begin{aligned} Y &= \bar{A} \cdot \bar{B} \cdot C \cdot D + (A + \bar{A}) \cdot B \cdot C \cdot D + A \cdot B \cdot \bar{C} \cdot (D + \bar{D}) + A \cdot \bar{B} \cdot C \cdot D \\ &= \bar{A} \cdot \bar{B} \cdot C \cdot D + A \cdot B \cdot C \cdot D + \bar{A} \cdot B \cdot C \cdot D + A \cdot B \cdot \bar{C} \cdot D \\ &\quad + A \cdot B \cdot \bar{C} \cdot \bar{D} + A \cdot \bar{B} \cdot C \cdot D \end{aligned}$$

Or in binary:  $Y = 0011 + 1111 + 0111 + 1101 + 1100 + 1011$

# Quain-McClusky algorithm

Classification  
with the number  
of 1

Num.of 1	smallest	compress1	compress2
2	0011	0_11	__11
	1100	_011	__11
3	0111	110_	
	1011	_111	
	1101	1_11	
4	1111	11_1	

$Y = \_11 + 110\_ + 11\_1$  First simplification

	smallest					
	0011	1100	0111	1011	1101	1111
__11	⊙		⊙	⊙		⊙
110_		⊙			⊙	
11_1					○	○

$Y = \_11 + 110\_$  Final form



(A and B) or (A and not B) or (not A and B) ☆

Examples Random

Input:

$(A \wedge B) \vee (A \wedge \neg B) \vee (\neg A \wedge B)$   
(A AND B) OR (A AND (NOT B)) OR ((NOT A) AND B)

$e_1 \wedge e_2 \wedge \dots$  is the logical AND function  
 $\neg \text{expr}$  is the logical NOT function  
 $e_1 \vee e_2 \vee \dots$  is the logical OR function

Truth table:

A	B	$(A \wedge B) \vee (A \wedge \neg B) \vee (\neg A \wedge B)$
T	T	T
T	F	T
F	T	T
F	F	F

Minimal forms:

More Text notation

DNF	$A \vee B$
CNF	$A \vee B$
ANF	$(A \wedge B) \vee A \vee B$
NOR	$\neg(A \vee B)$
NAND	$\neg A \wedge \neg B$
AND	$\neg(\neg A \wedge \neg B)$
OR	$A \vee B$

$e_1 \underline{\vee} e_2 \underline{\vee} \dots$  is the logical XOR function  
 $e_1 \underline{\vee} e_2 \underline{\vee} \dots$  is the logical NOR function

New to Wolfram|Alpha?

Take the Tour >>

New! Wolfram Problem Generator

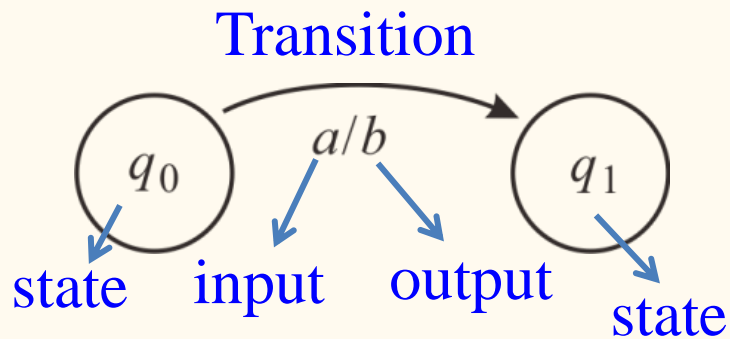
Need a hint?

Step-by-step solutions?

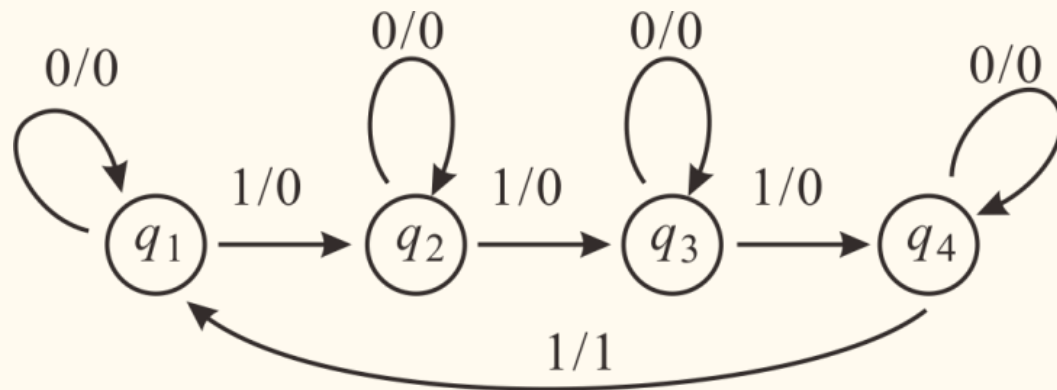
Find x such that  $3x - 7 = 0$

# Design of sequential logic circuit: State diagram

State (transition) diagram:



Ex) 2-bit counter with two T-FF



FF output:

$$Q_n^{(1)}, Q_n^{(2)}$$

Karnaugh  
map  
simplification

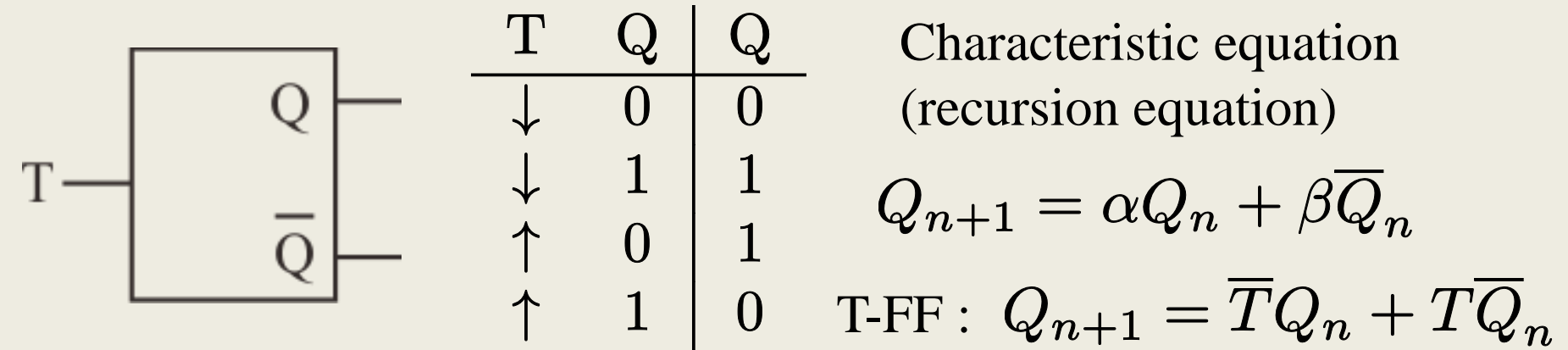
		input $x$					
		0			1		
		next		out	next		out
$Q_n^{(1)}$	$Q_n^{(2)}$	$Q_{n+1}^{(1)}$	$Q_{n+1}^{(2)}$	$y$	$Q_{n+1}^{(1)}$	$Q_{n+1}^{(2)}$	$y$
0	0	0	0	0	1	0	0
0	1	0	1	0	1	1	0
1	0	1	0	0	0	1	0
1	1	1	1	0	0	0	1

Recursion equation:

$$Q_{n+1}^{(1)} = \bar{x} \cdot Q_n^{(1)} + x \cdot \overline{Q_n^{(1)}}$$

$$Q_{n+1}^{(2)} = \bar{x} \cdot Q_n^{(2)} + Q_n^{(2)} \cdot \overline{Q_n^{(1)}} + x \cdot \overline{Q_n^{(2)}} \cdot Q_n^{(1)}$$

# Design of sequential logic circuit: State diagram

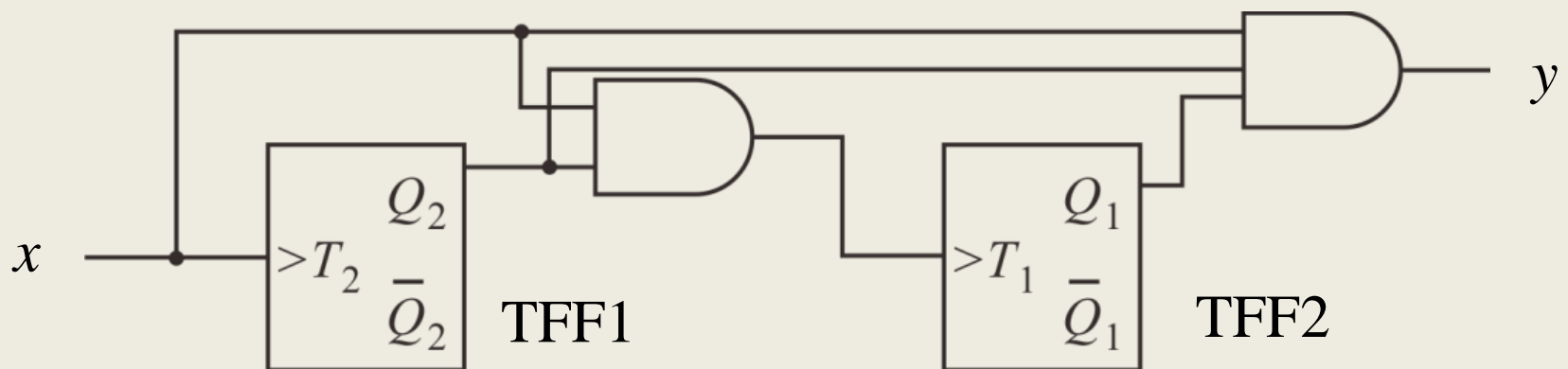


$$Q_{n+1}^{(1)} = \bar{x} \cdot Q_n^{(1)} + x \cdot \bar{Q}_n^{(1)},$$

$$y = \overline{xQ_n^{(1)} Q_n^{(2)}}$$

$$Q_{n+1}^{(2)} = (\bar{x} + \bar{Q}_n^{(1)}) \cdot Q_n^{(2)} + (x \cdot Q_n^{(1)}) \cdot \bar{Q}_n^{(2)}$$

$$= \overline{(x \cdot Q_n^{(1)})} \cdot Q_n^{(2)} + (x \cdot Q_n^{(1)}) \cdot \bar{Q}_n^{(2)}$$



# 7.5 AD/DA converter circuit

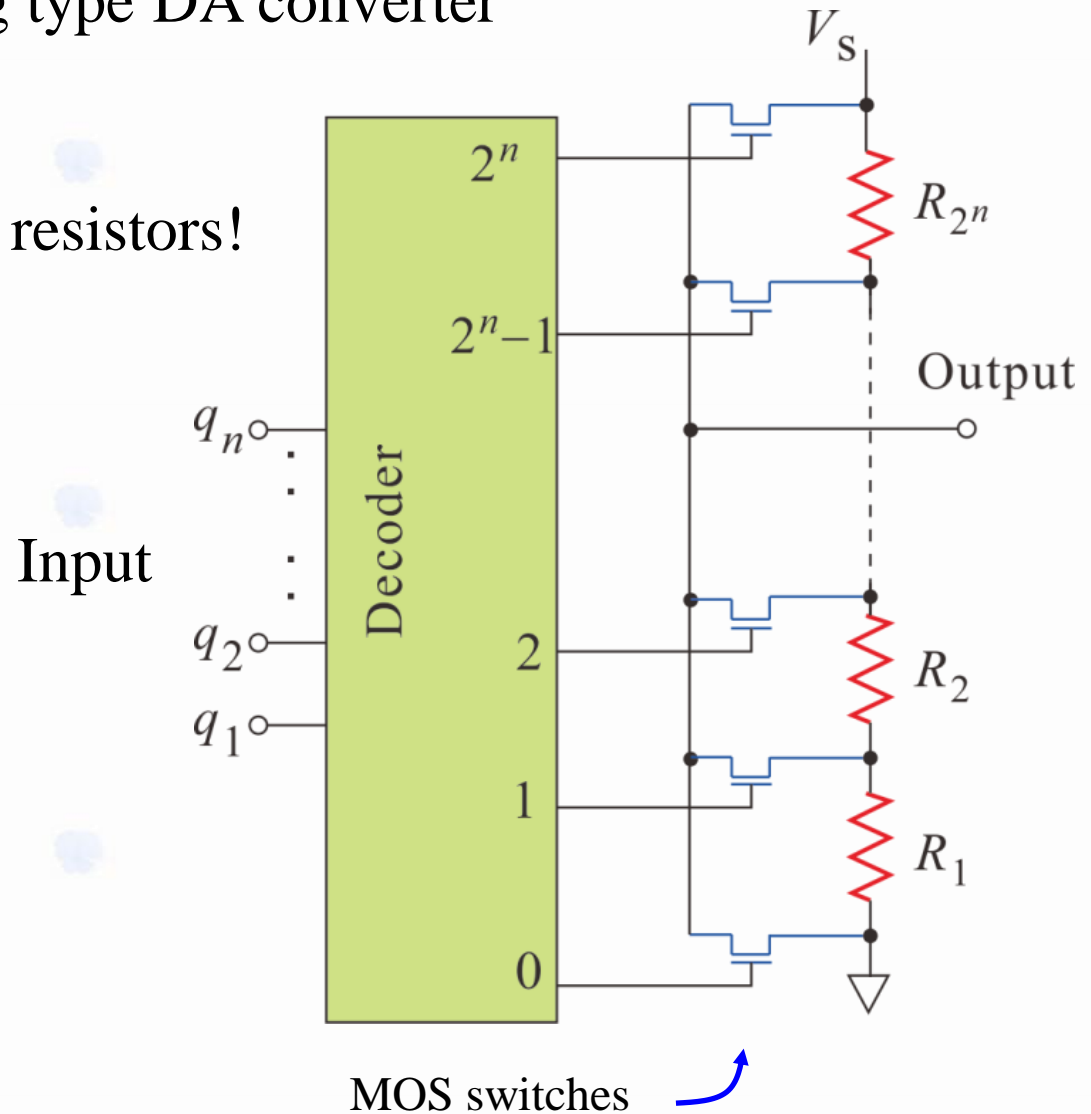
## 7.5.1 Digital to Analog conversion

### Resistor string type DA converter

$n$  bits converter

→  $2^n$  outputs!,  $2^n$  resistors!

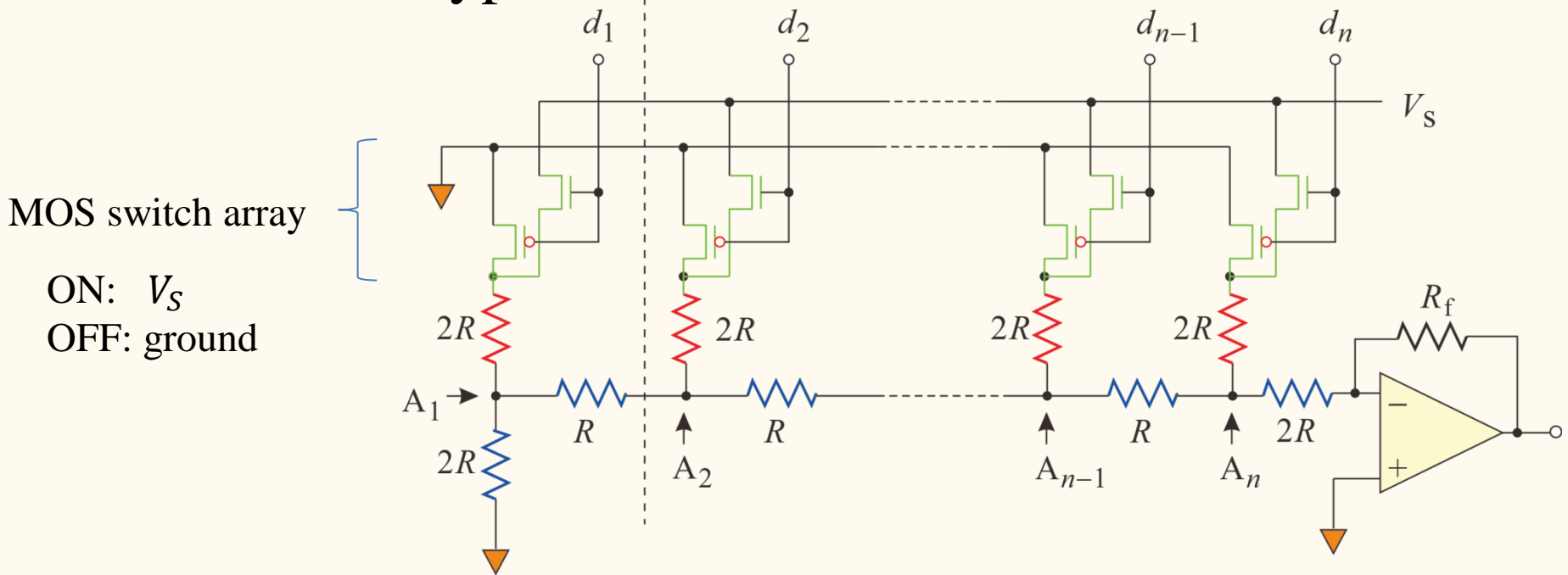
$$V_{\text{out}} = \frac{p_{\text{input}}}{2^n} V_S$$





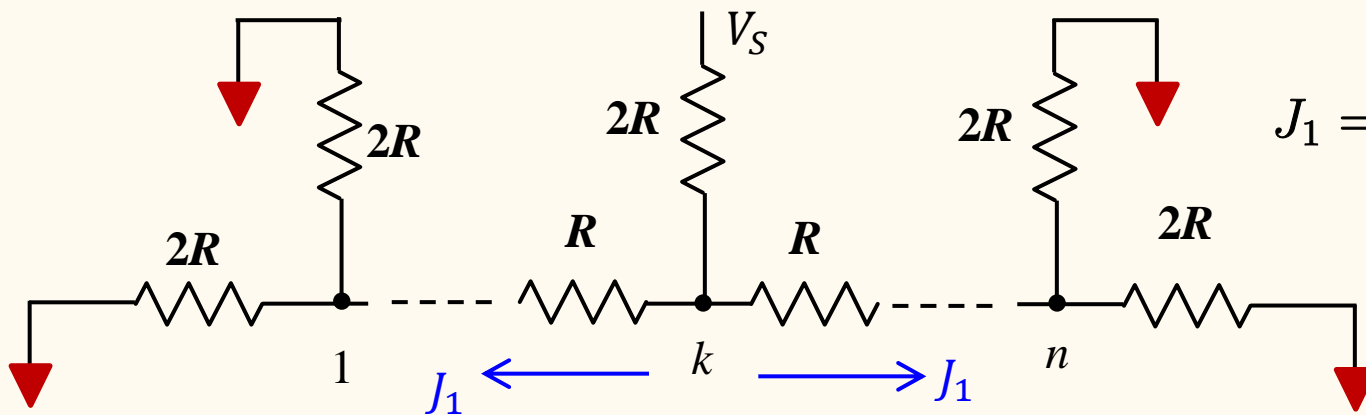
# 7.5.1 Digital to Analog conversion

## Resistor ladder type DA converter



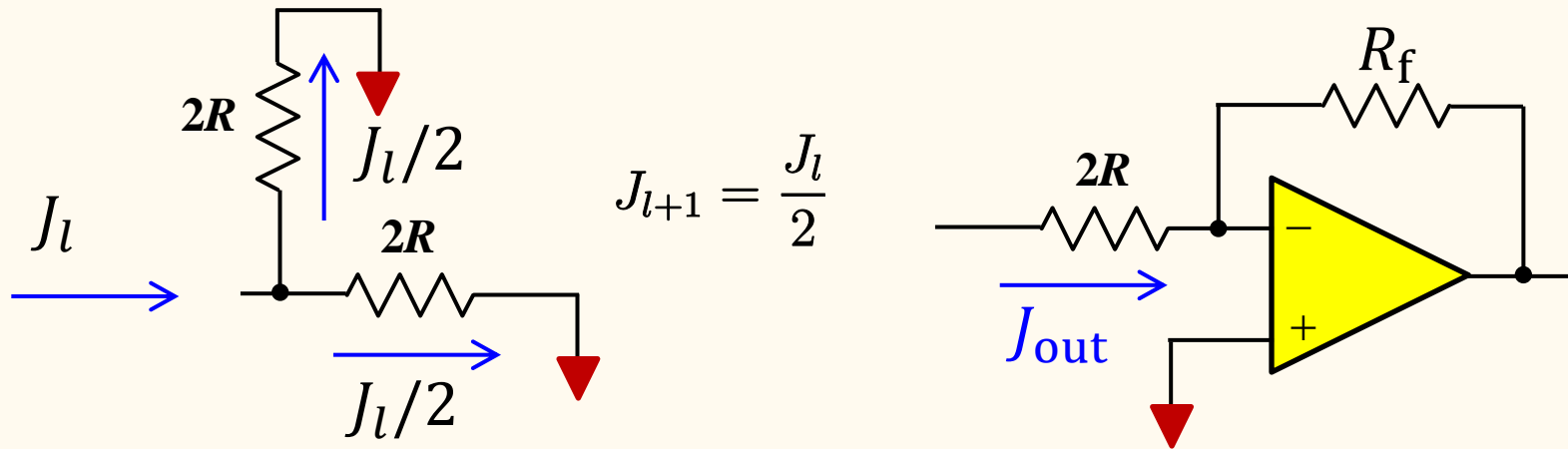
Input  $(0,0, \dots, 0,1,0, \dots, 0)$

$d_k = 1$ , others = 0



$$J_1 = \frac{V_S}{2 \cdot (2R + R)} = \frac{V_S}{6R}$$

# 7.5.1 Digital to Analog conversion



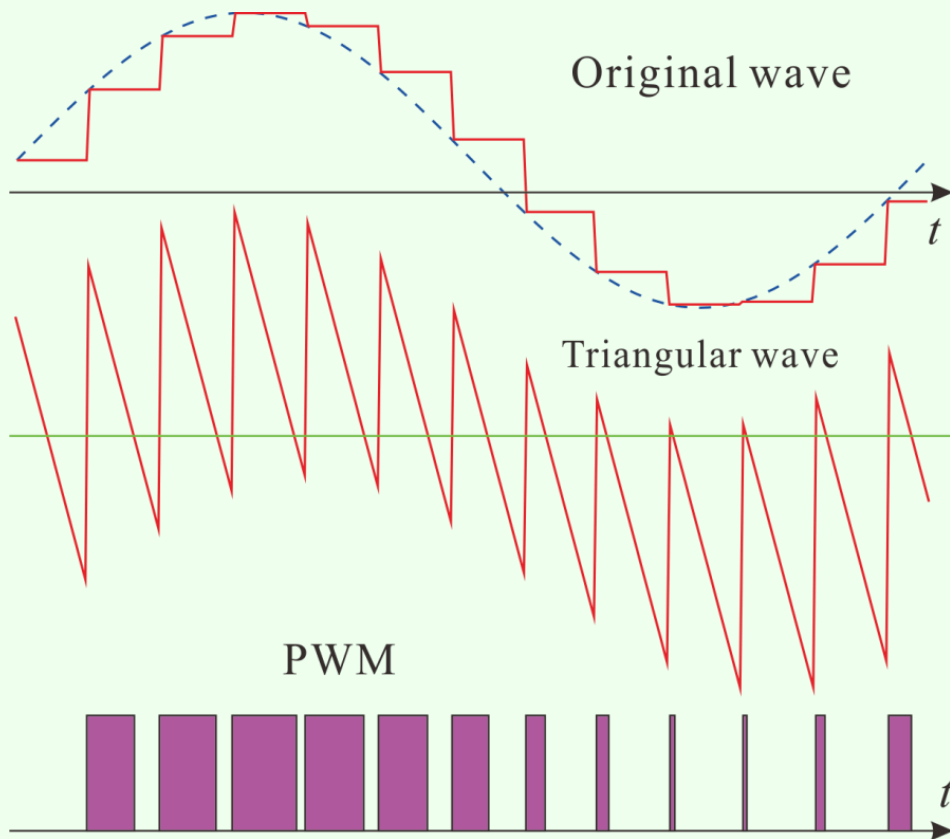
$$J_{out} \left( \begin{array}{ccc} 0 \cdots 0 & 1 & 0 \cdots 0 \\ n & k & 1 \end{array} \right) = \frac{V_S}{3R} \left( \frac{1}{2} \right)^{n-k+1} = \frac{V_S}{6 \cdot 2^n R} 2^k$$

From the superposition theorem:

$$V_{out}(\{d_i\}) = -\frac{1}{3 \cdot 2^n} \frac{R_f}{2R} V_S \sum_{k=1}^n 2^k d_k$$

# 7.5.1 Digital to Analog converter

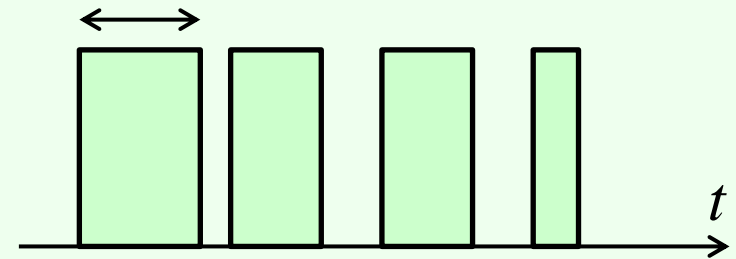
Pulse width modulation (PWM)



D-class amplifier

Digital signal  $\rightarrow$

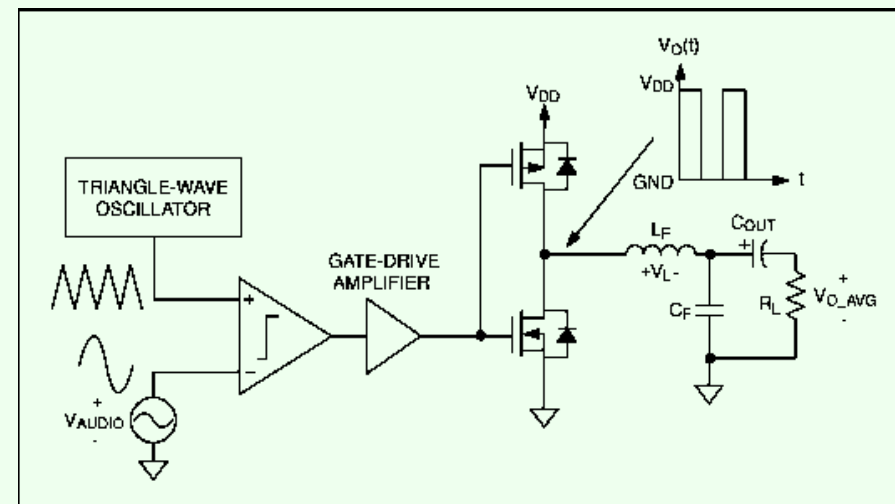
PWM signal with a counter



Low pass

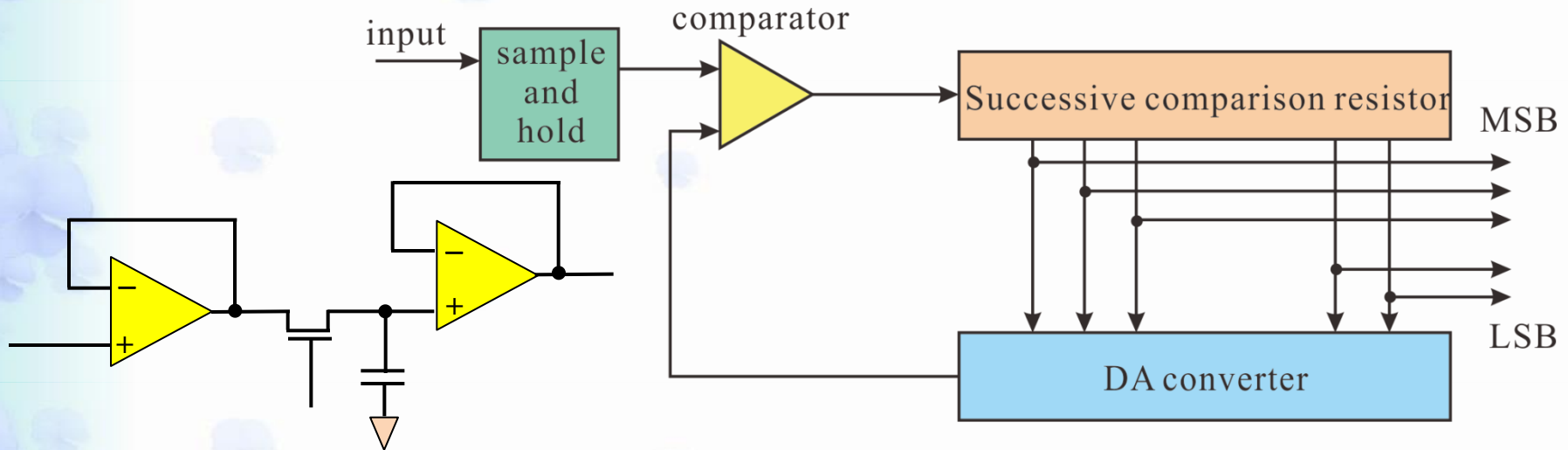


Analog signal

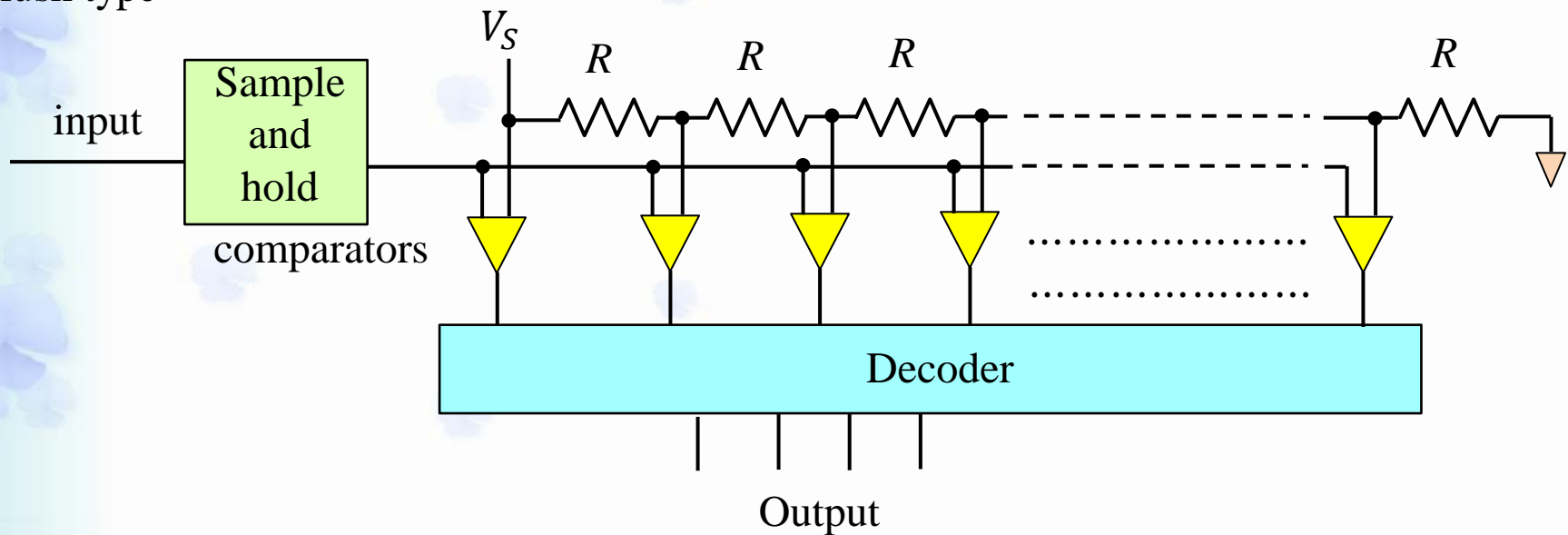


# 7.5.2 Analog-Digital converter

## Successive comparison type AD converter

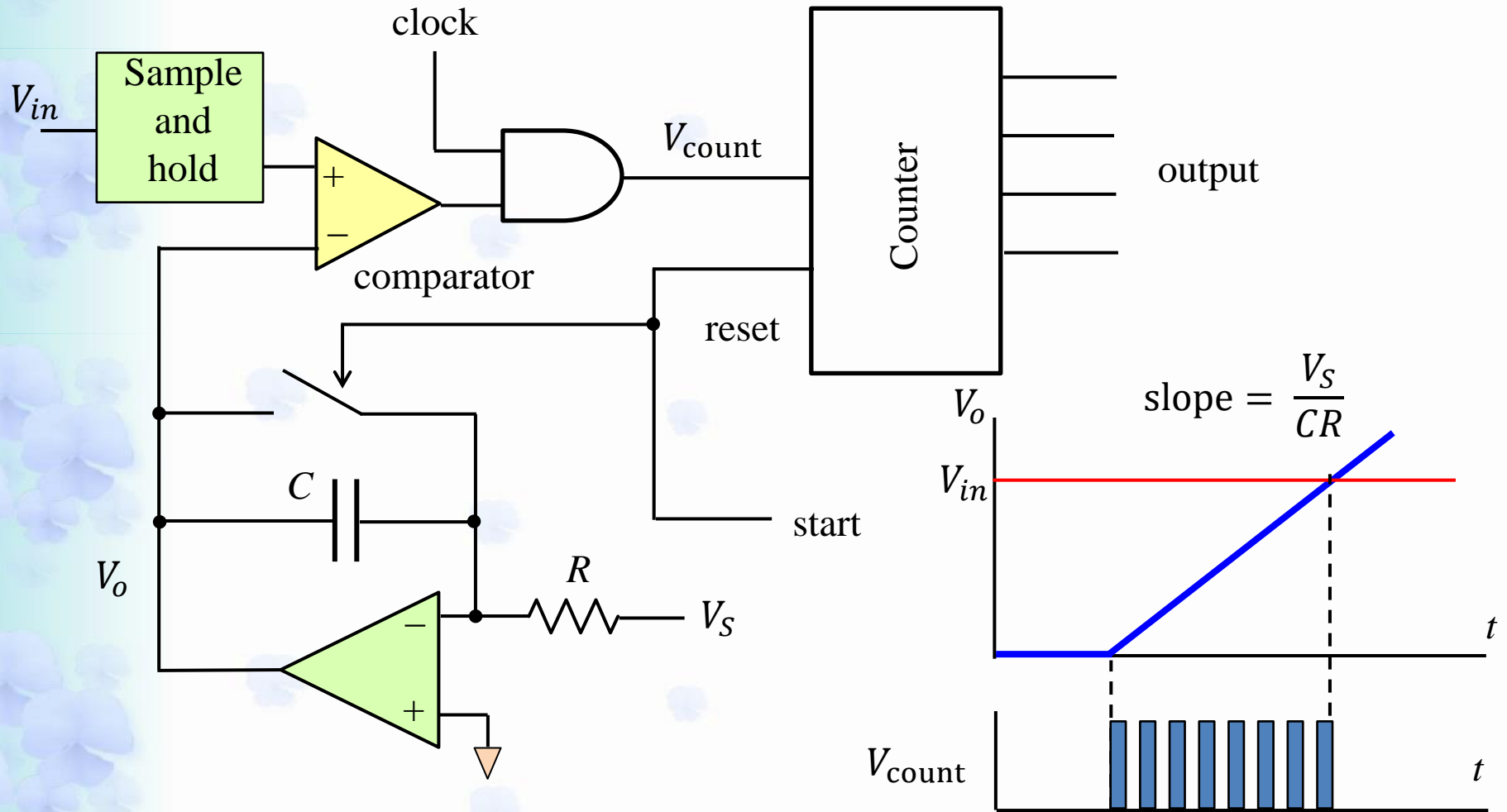


## Flush type

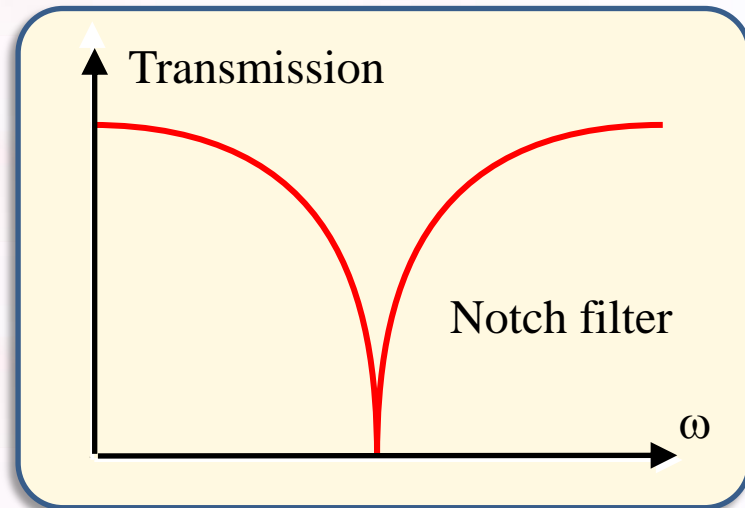
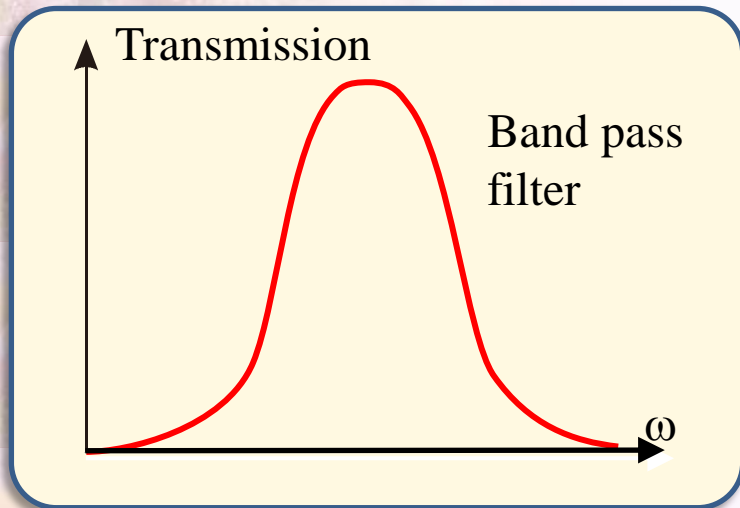
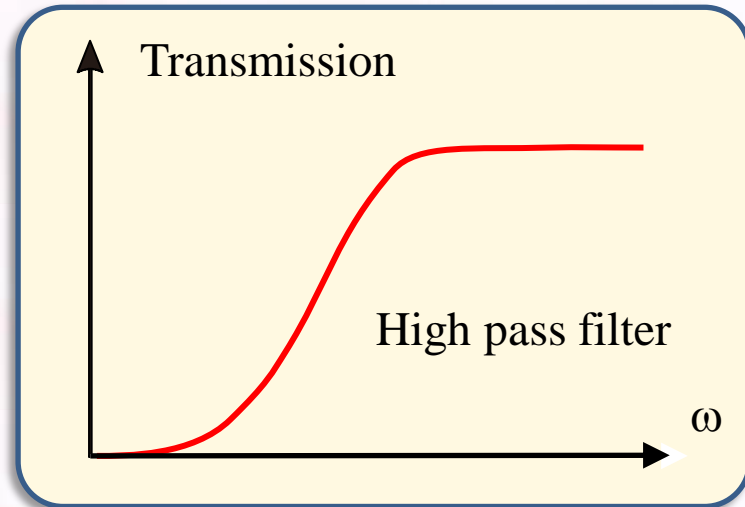
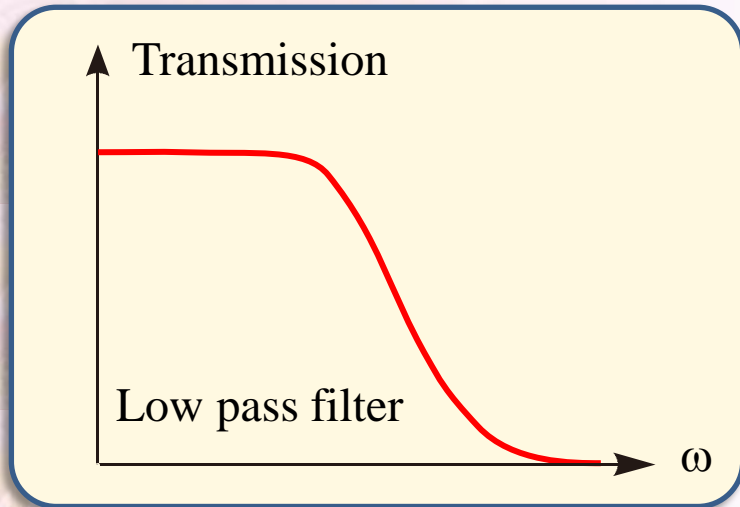


# 7.5.2 Analog-Digital converter

## Integrating Analog-Digital Converter



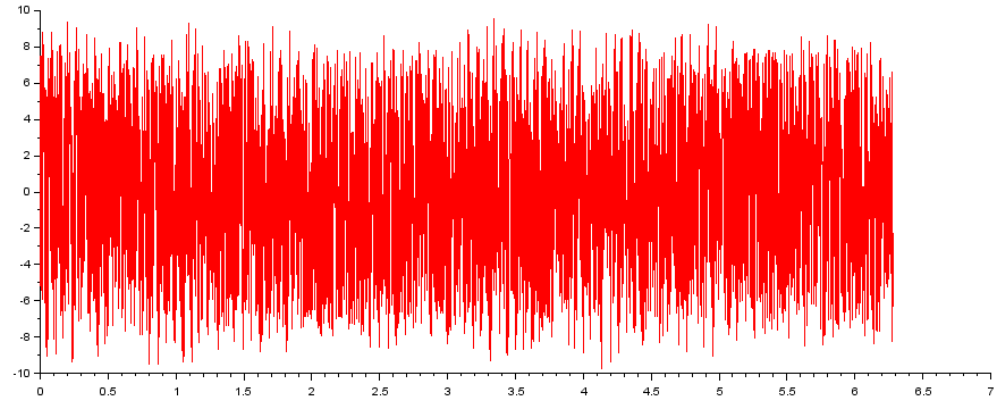
# Filter Circuit



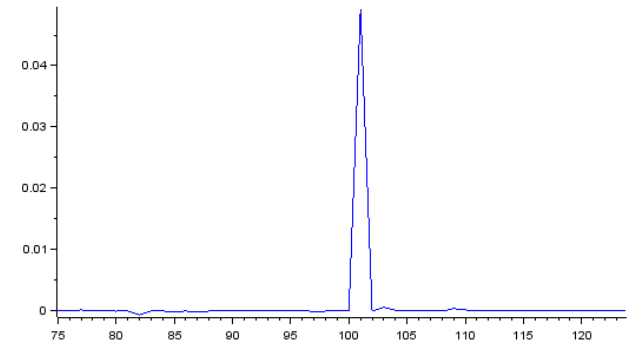
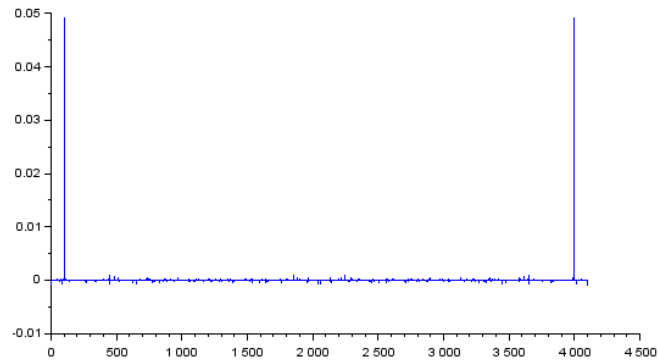


# An example for retrieving data from noise

Signal with noise

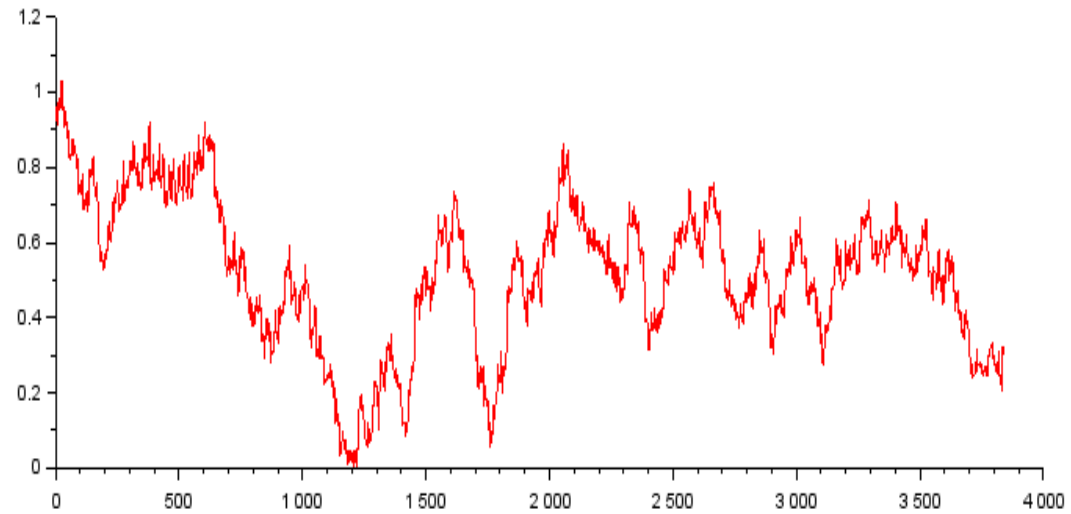


Detection of carrier

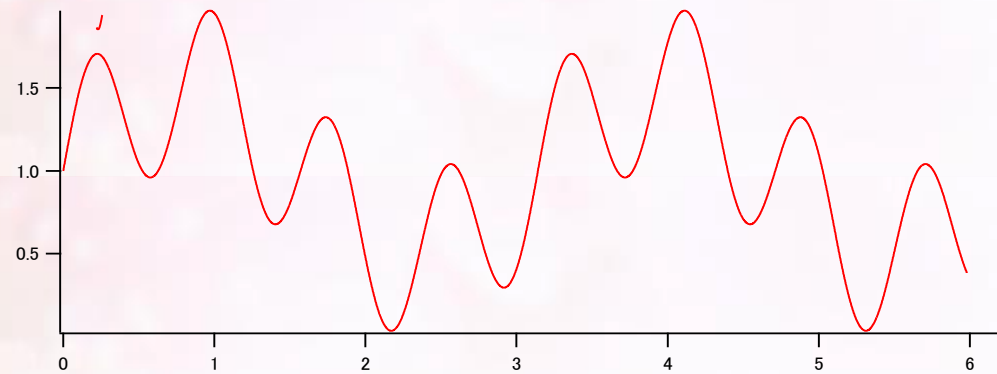


# Results

Frequency filter



Original signal



## 7.6 Digital filter (as a digital signal processing)

Digital filtering:

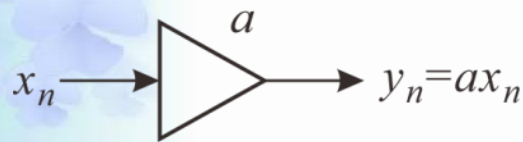
$$\{x_i\} = (x_0, x_1, \dots)$$



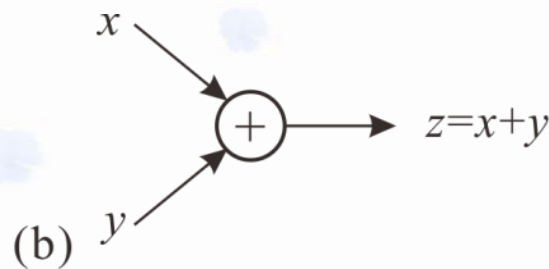
$$\{y_i\} = (y_0, y_1, \dots)$$

$$y_n = F(x_{n-k}, x_{n-k+1}, \dots, x_n)$$

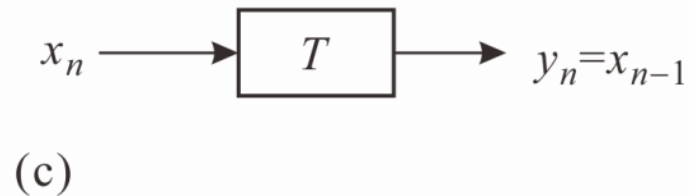
Block diagram representation of operations



constant multiplier

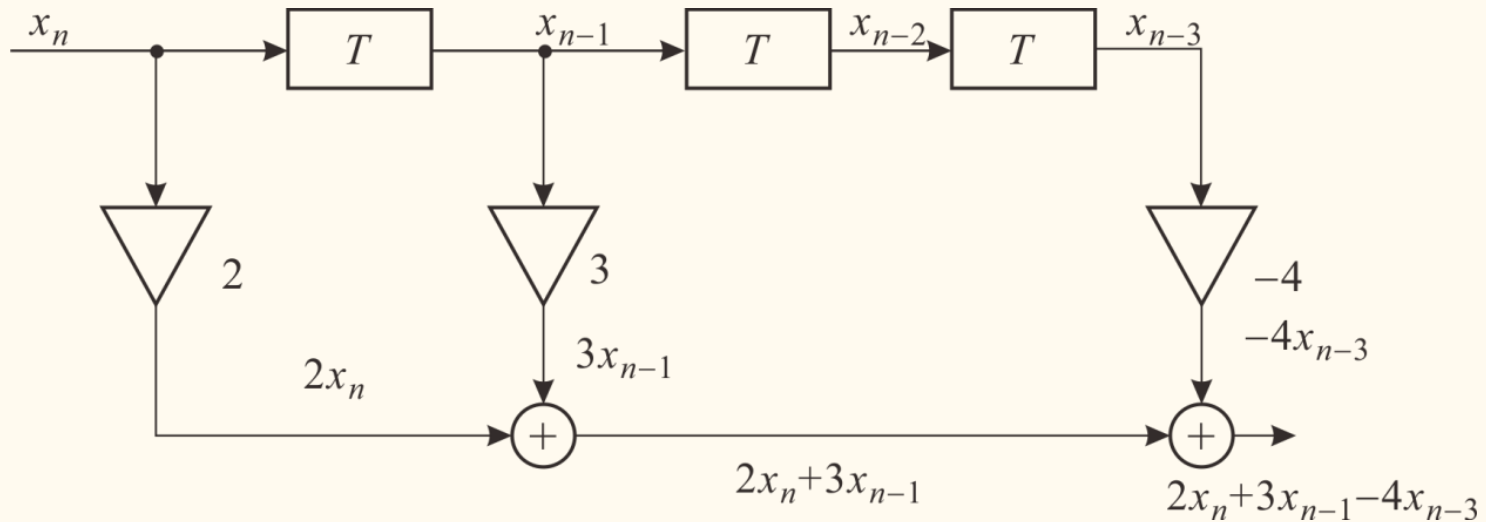


adder



delay (shift resistor)

# Block diagram example



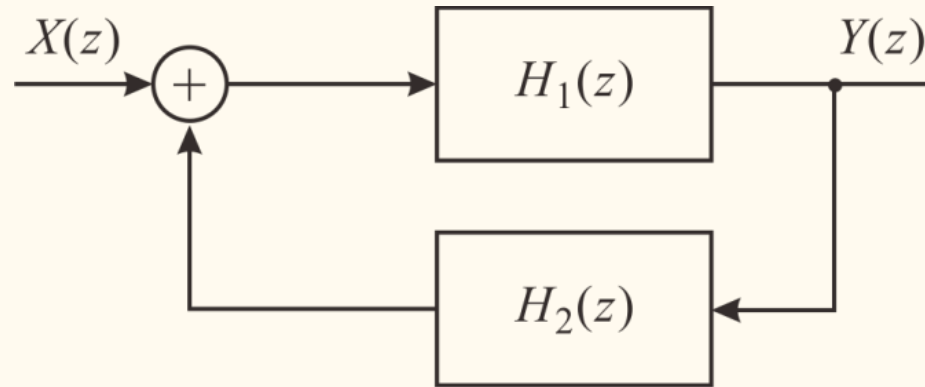
$$y_n = 2x_n + 3x_{n-1} - 4x_{n-3}$$

$$X(z) = \sum_{n=0}^{\infty} x_n z^{-n}, \quad Y(z) = \sum_{n=0}^{\infty} y_n z^{-n}$$

$$\begin{aligned} Y(z) &= 2X(z) + 3z^{-1}X(z) - 4z^{-3}X(z) \\ &= (2 + 3z^{-1} - 4z^{-3})X(z) \end{aligned}$$

$$\therefore H(z) \text{ (transfer function)} = 2 + 3z^{-1} - 4z^{-3}$$

# Feedback and transfer function



$$Y(z) = H_1(z)W(z) = H_1(z)(X(z) + H_2(z)Y(z)),$$

$$\therefore Y(z) = \frac{H_1(z)}{1 - H_1(z)H_2(z)}X(z)$$

$$H(z) = \frac{H_1(z)}{1 - H_1(z)H_2(z)}$$

$$\text{(transfer function)} = \frac{\text{(direct gain)}}{1 - \text{(feedback transfer gain)}}$$

# 電子回路論第14回 (最終回)

## Electric Circuits for Physicists

東京大学理学部・理学系研究科

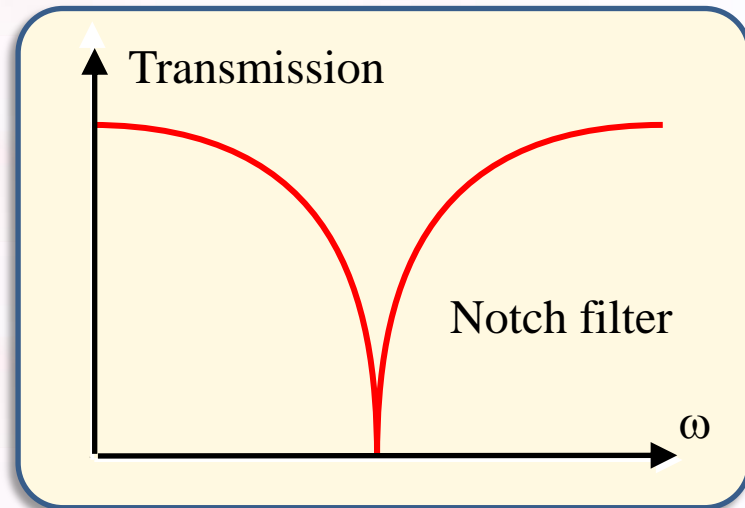
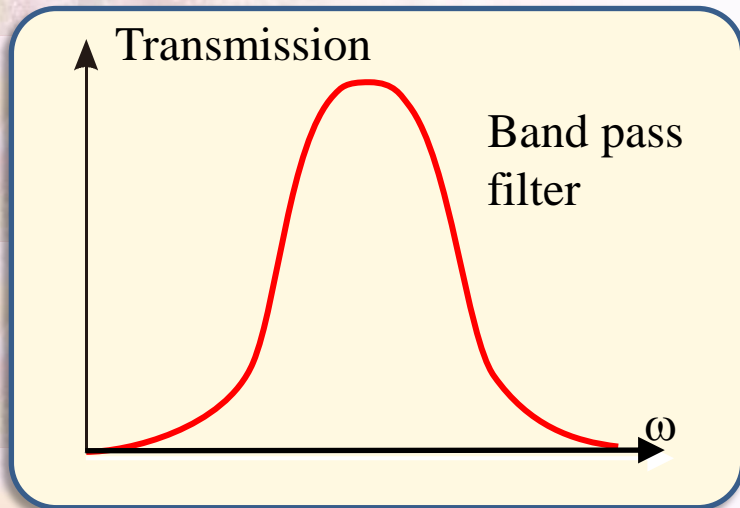
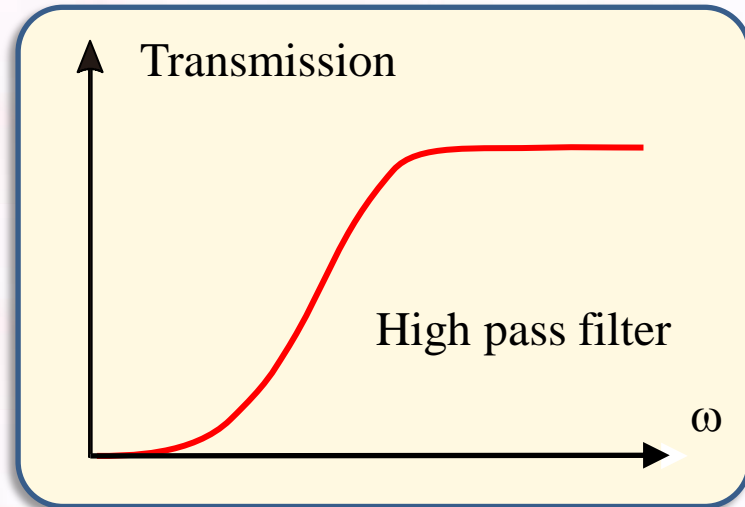
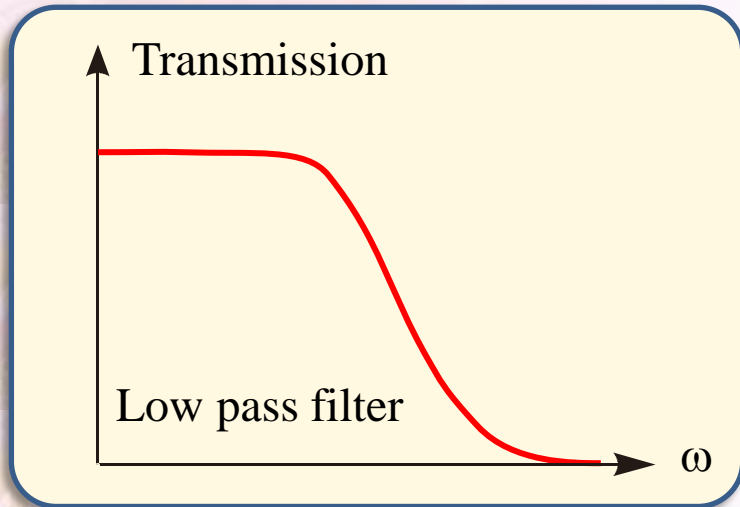
物性研究所

勝本信吾

Shingo Katsumoto

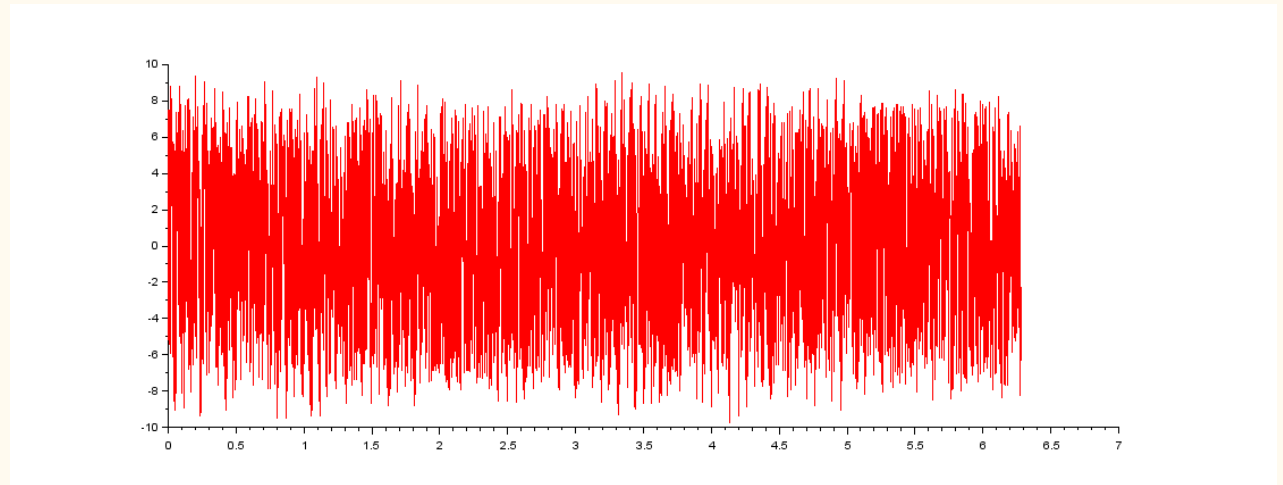


# Filter Circuit

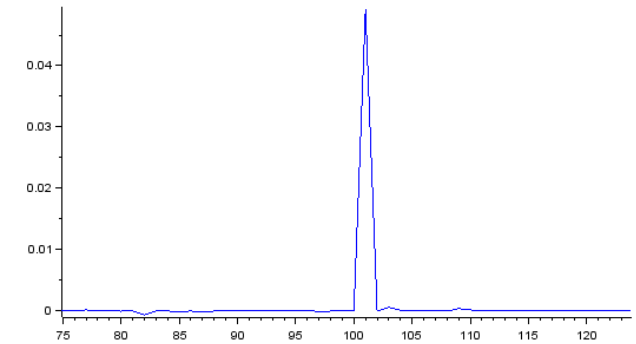
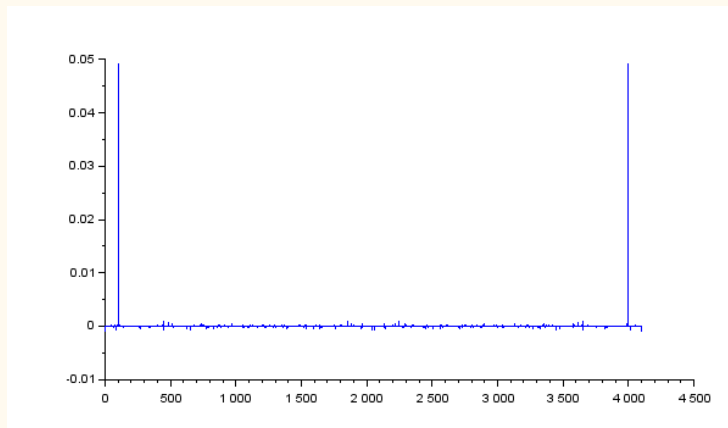


# An example for retrieving data from noise

Signal with noise

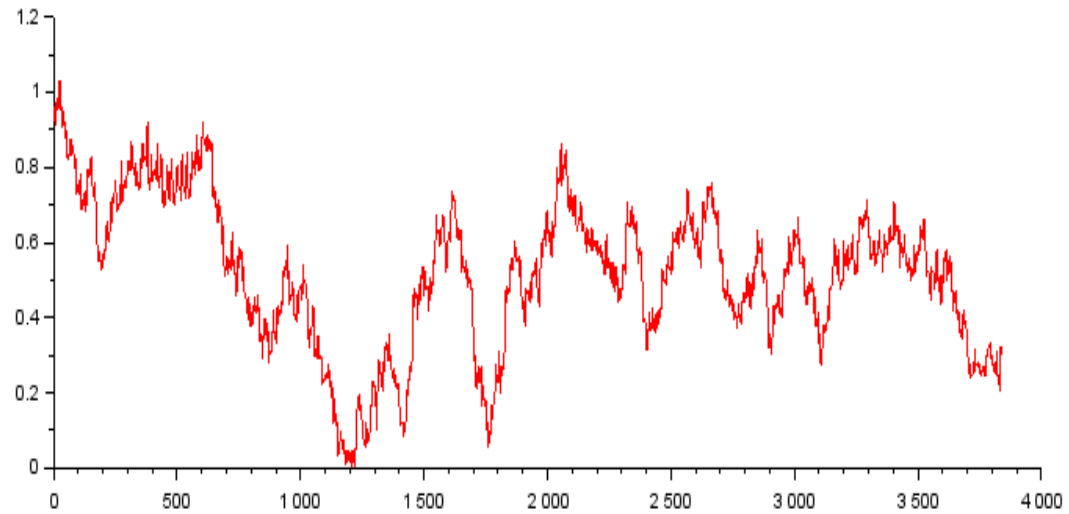


Detection of carrier

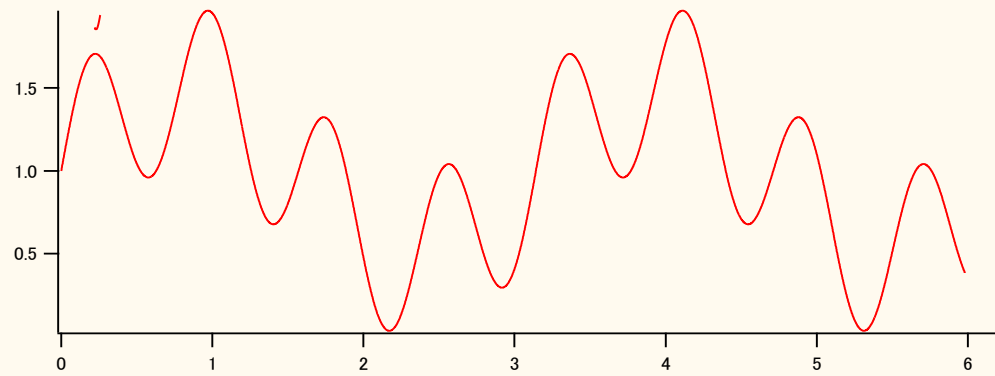


# Results

Frequency filter



Original signal



## 7.6 Digital filter (as a digital signal processing)

Digital filtering:

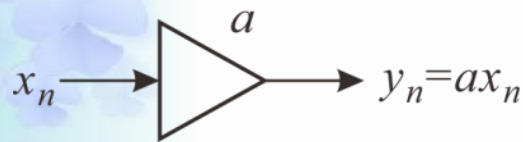
$$\{x_i\} = (x_0, x_1, \dots)$$



$$\{y_i\} = (y_0, y_1, \dots)$$

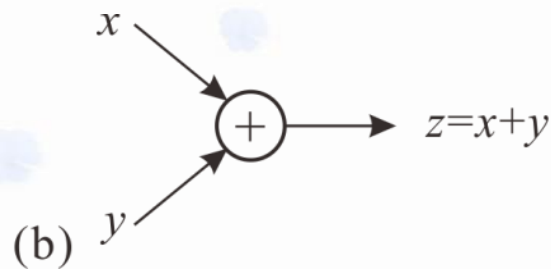
$$y_n = F(x_{n-k}, x_{n-k+1}, \dots, x_n)$$

Block diagram representation of operations



(a)

constant multiplier



(b)

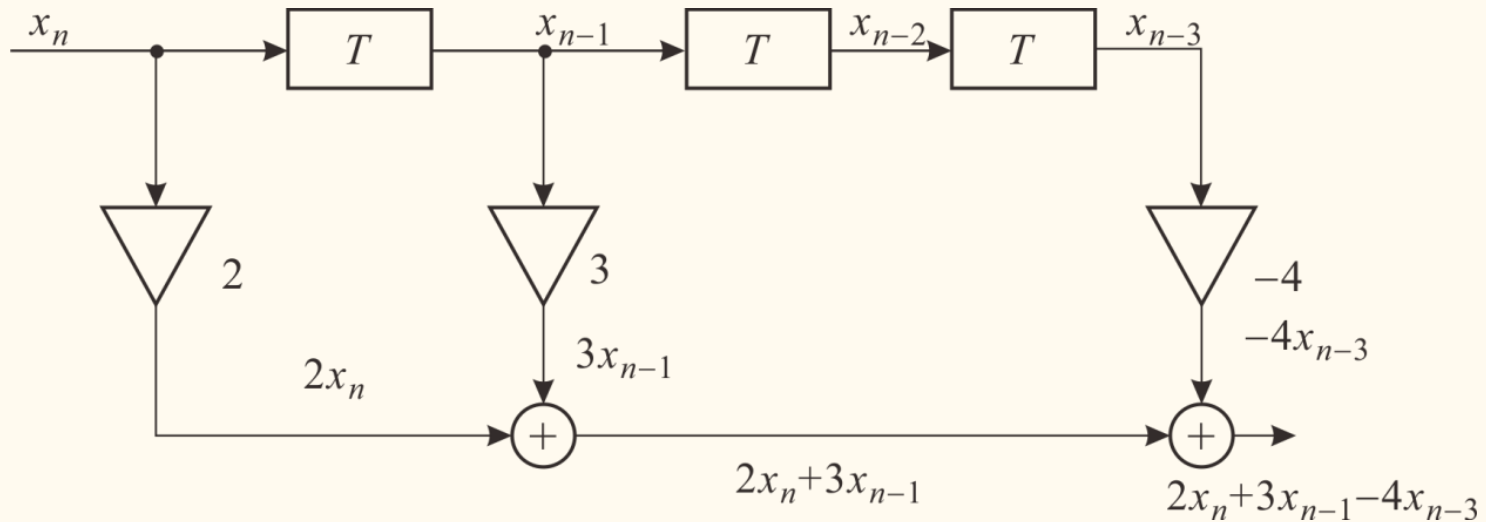
adder



(c)

delay (shift resistor)

# Block diagram example



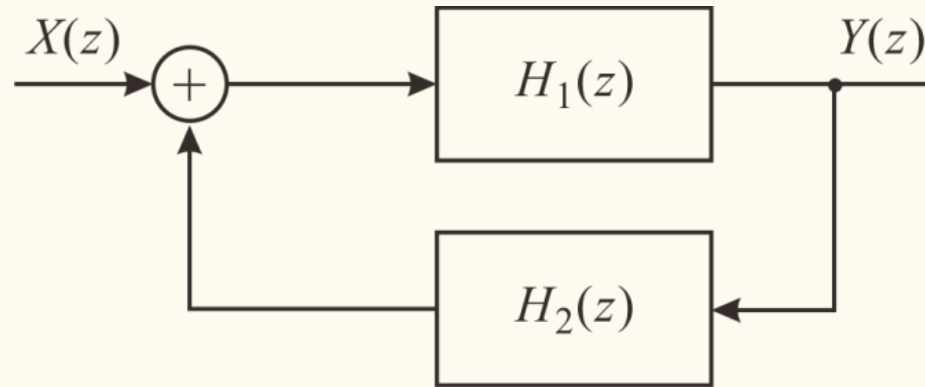
$$y_n = 2x_n + 3x_{n-1} - 4x_{n-3}$$

$$X(z) = \sum_{n=0}^{\infty} x_n z^{-n}, \quad Y(z) = \sum_{n=0}^{\infty} y_n z^{-n}$$

$$\begin{aligned} Y(z) &= 2X(z) + 3z^{-1}X(z) - 4z^{-3}X(z) \\ &= (2 + 3z^{-1} - 4z^{-3})X(z) \end{aligned}$$

$$\therefore H(z) \text{ (transfer function)} = 2 + 3z^{-1} - 4z^{-3}$$

# Feedback and transfer function



$$Y(z) = H_1(z)W(z) = H_1(z)(X(z) + H_2(z)Y(z)),$$

$$\therefore Y(z) = \frac{H_1(z)}{1 - H_1(z)H_2(z)}X(z)$$

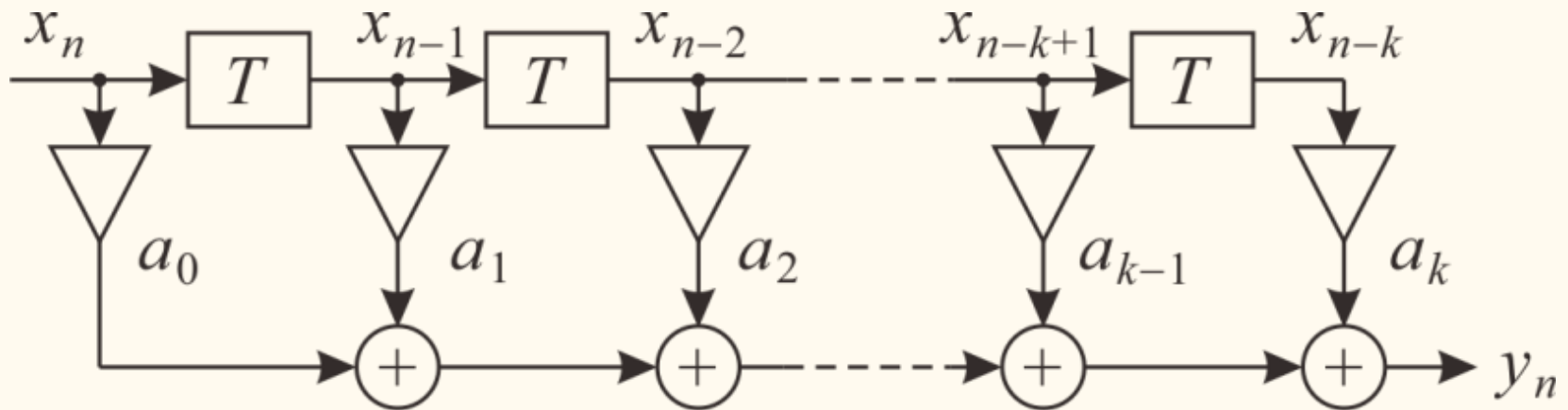
$$H(z) = \frac{H_1(z)}{1 - H_1(z)H_2(z)}$$

$$\text{(transfer function)} = \frac{\text{(direct gain)}}{1 - \text{(feedback transfer gain)}}$$



# FIR filter

Finite impulse response (FIR) filter

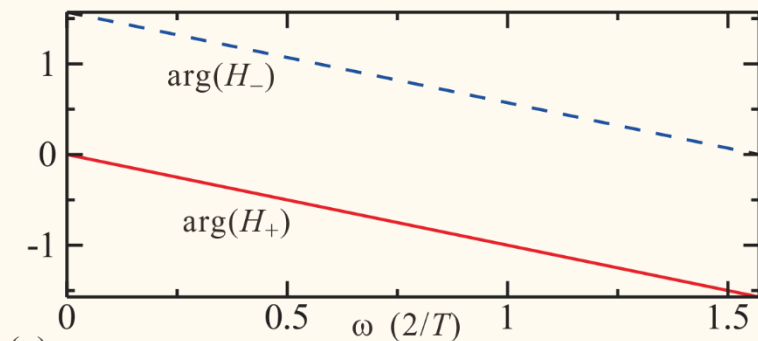
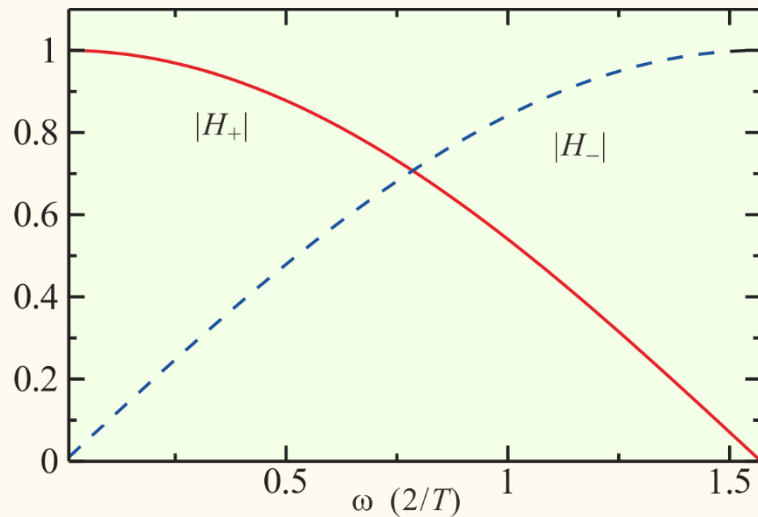


$$H(e^{i\omega\tau}) = \sum_{j=0}^k a_j e^{-ij\omega\tau}$$

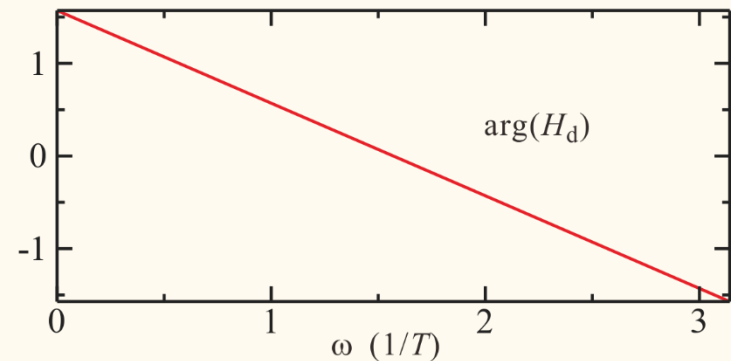
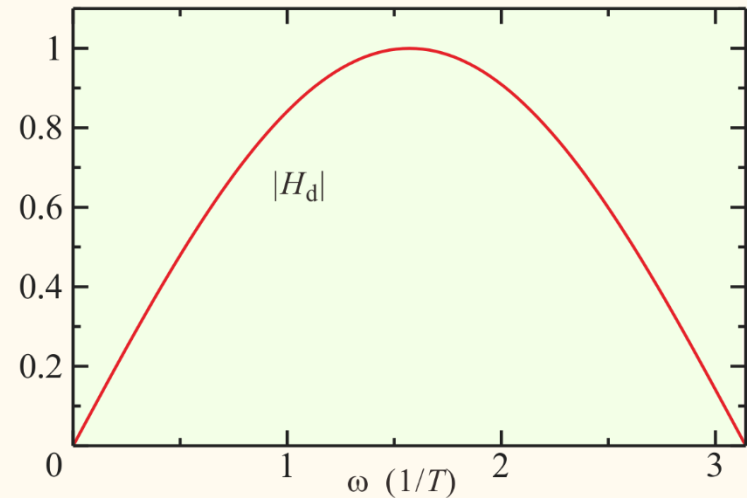
# A Simple example of FIR filter

Moving average, differentiation:  $F_{\pm}(x_n, x_{n-1}) = (x_n \pm x_{n-1})/2$

$$H_{\pm}(e^{i\omega\tau}) = e^{-i\omega\tau/2} \begin{pmatrix} \cos(\omega\tau/2) \\ i \sin(\omega\tau/2) \end{pmatrix}$$



(a)



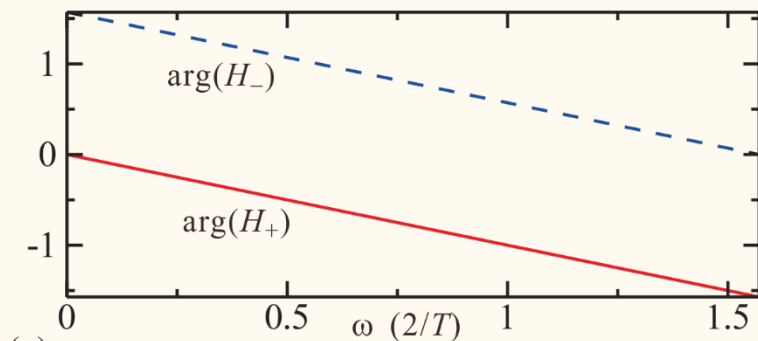
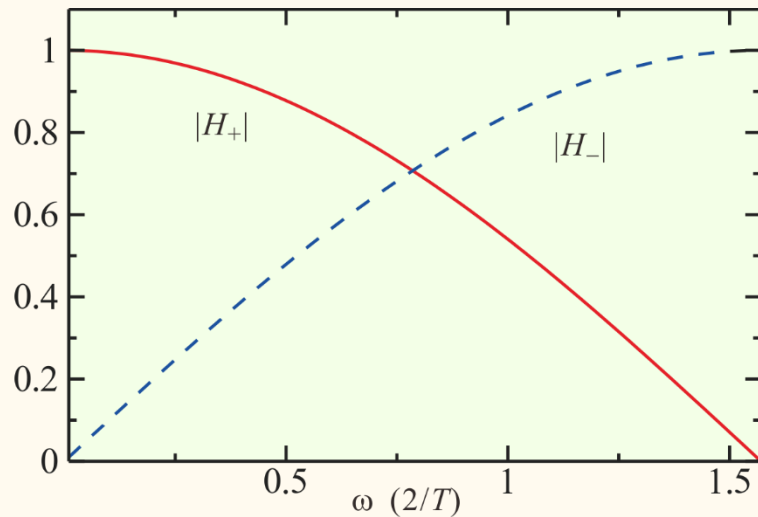
(b)

# A Simple example of FIR filter

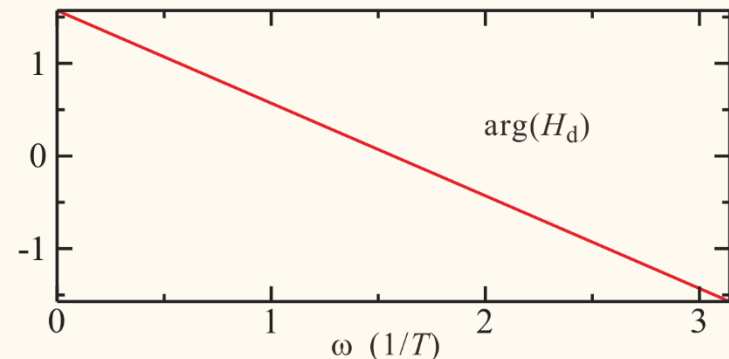
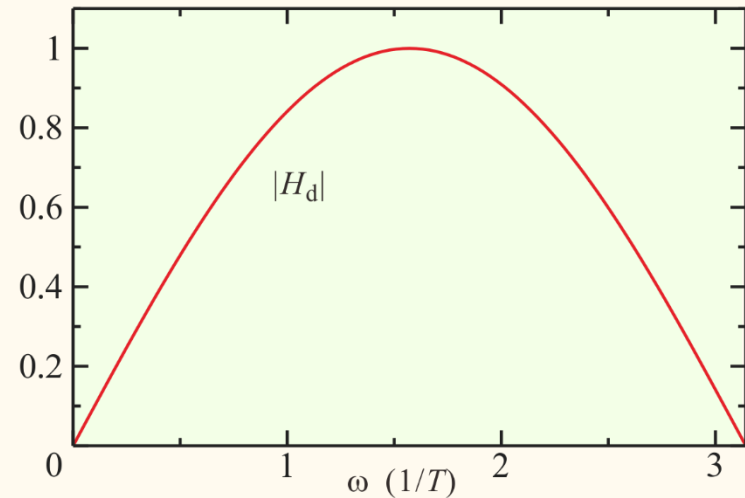
Differentiation of moving average:

$$F_d = [(x_n + x_{n-1}) - (x_{n-1} + x_{n-2})]/2 = [x_n - x_{n-2}]/2$$

$$H_d = (1 - e^{-2i\omega\tau})/2 = ie^{-i\omega\tau} \sin \omega\tau$$



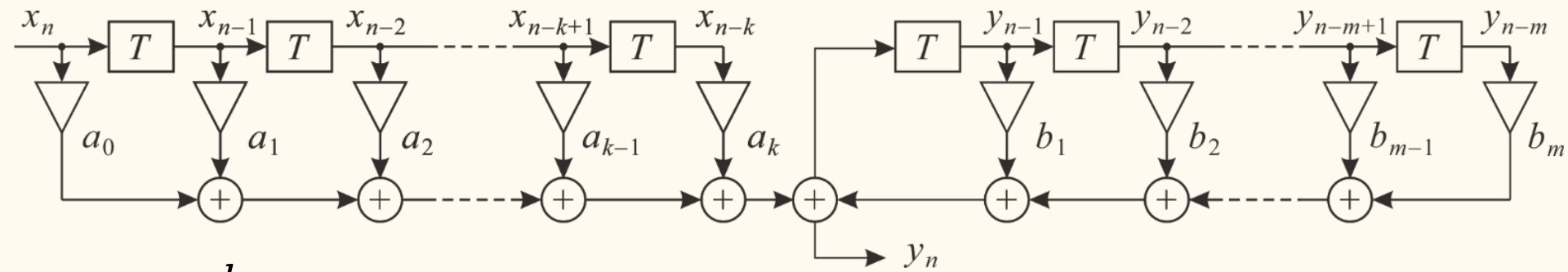
(a)



(b)

# IIR Filter

Infinite impulse response (IIR) filter:



$$y_n = \sum_{l=0}^k a_l x_{n-l} + \sum_{j=1}^m b_j y_{n-j} \quad \text{Stability condition: } \lim_{n \rightarrow \infty} y_n = 0$$

$$Y(z) = X(z) \sum_{l=0}^k a_l z^{-l} + Y(z) \sum_{j=1}^m b_j z^{-j}$$

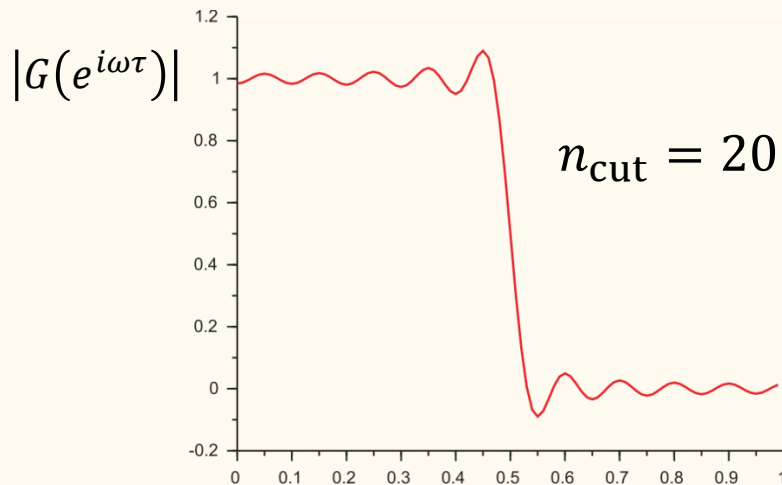
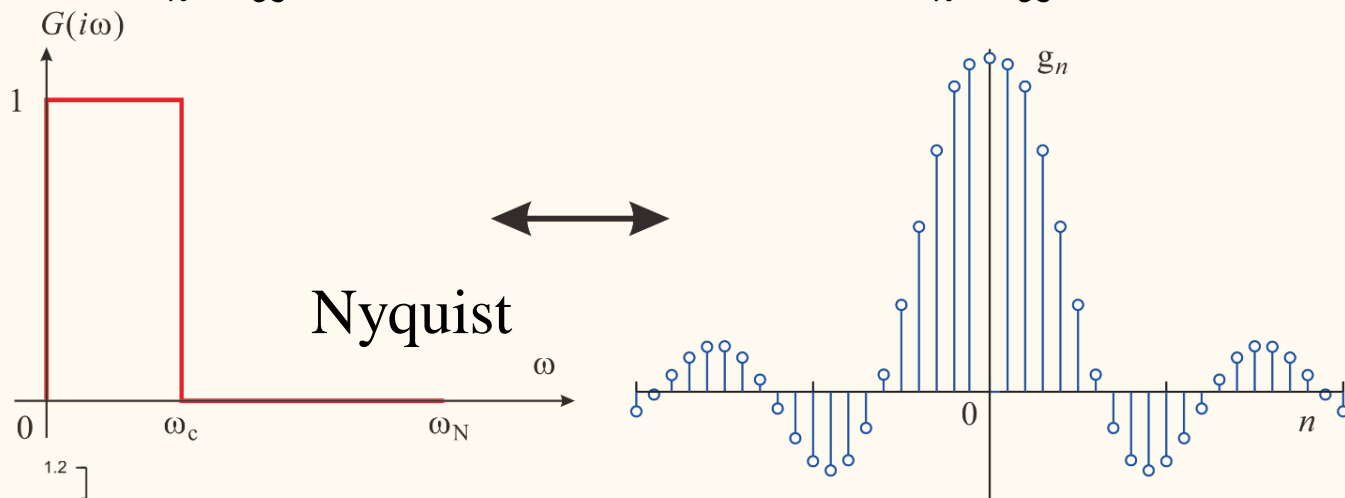
$$H(z) = \frac{Y(z)}{X(z)} = \sum_{l=0}^k a_l z^{-l} \bigg/ \left( 1 - \sum_{j=1}^m b_j z^{-j} \right)$$

Conversion of z-transform:  $|z| > 1$  the poles should be in  $|z| < 1$

# Design of FIR filter: Window function

Ideal low pass filter  $G(e^{i\omega\tau}) = \begin{cases} 1, & |\omega| \leq \omega_c, \\ 0, & \omega_c < |\omega| \leq \omega_N \text{ Nyquist frequency} \end{cases}$

$$G(e^{i\omega\tau}) = \frac{\omega_c}{\omega_N} \sum_{n=-\infty}^{\infty} \frac{1}{n\pi} \operatorname{sinc}\left(n \frac{\omega_c}{\omega_N}\right) e^{-ni\omega\tau} = \gamma_c \sum_{n=-\infty}^{\infty} \frac{1}{n\pi} \operatorname{sinc}(n\gamma_c) z^{-n}$$



Cut the series at a finite number

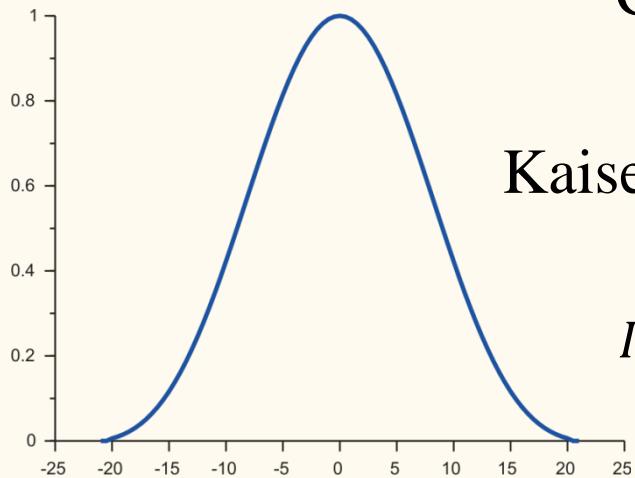
Ripples in frequency characteristics

$\omega/\omega_N$

# Design of FIR filter: Window function

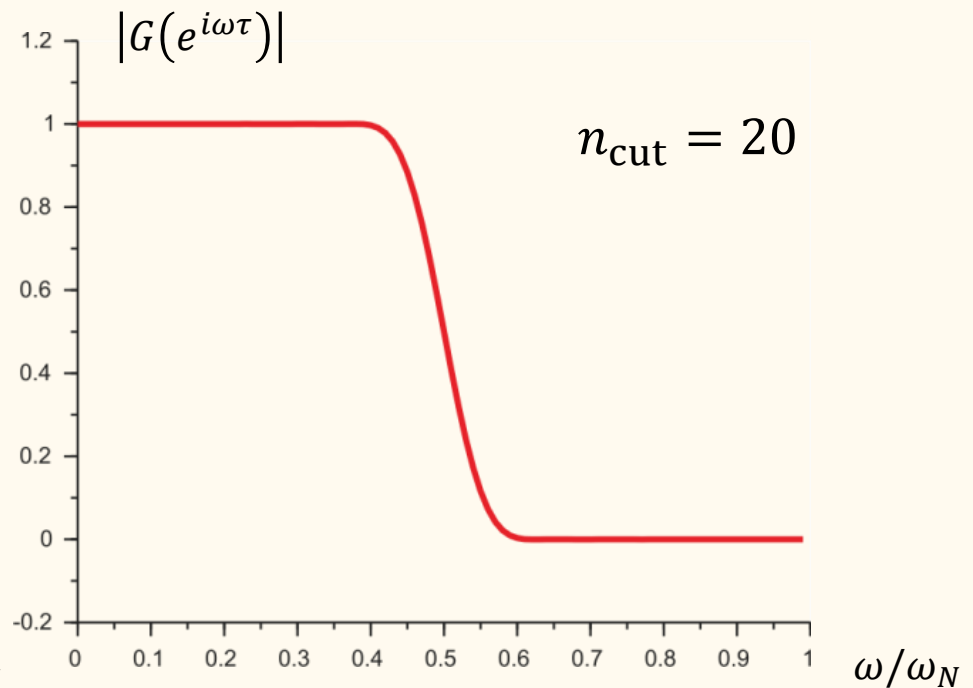
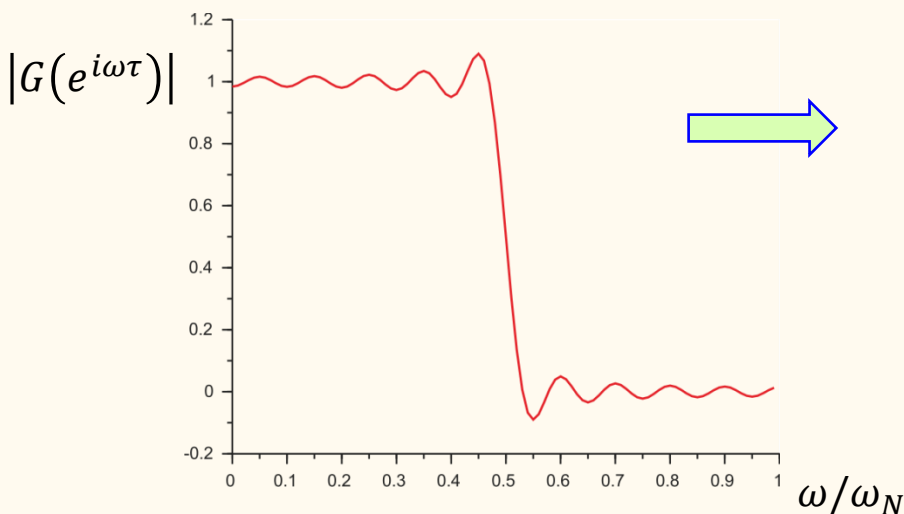
Sudden cutting of z-transform series  $\rightarrow$  Ripples

Cut with a smooth function



Kaiser window  $w_n = \begin{cases} \frac{I_0\left(\alpha\sqrt{1-(n/L)^2}\right)}{I_0(\alpha)} & |n| \leq L, \\ 0 & |n| > L \end{cases}$

$I_0$  : 0<sup>th</sup> order 1<sup>st</sup> type modified Bessel function





# Design of IIR filter

Transfer function: a rational function (有理式)

A way to design IIR filter: modification of [analog filter](#) transfer function

Remember: Butterworth filter

$$\Xi(s) = \sum_{k=0}^{N-1} \frac{\omega_k}{s - s_k}, \quad s_k = r_c \exp \left[ i \left\{ \frac{\pi}{2} + \frac{(2k+1)\pi}{2n} \right\} \right]$$

$$\xi(t) = \underbrace{u_H(t)}_{\swarrow} \sum_{k=0}^{n-1} w_k \exp(s_k t)$$

Heaviside function

$$h_n = h_{Hn} \sum_{k=0}^{n-1} w_k e^{n s_k},$$

Time discretization  
with  $\tau = 1$ :

$$\therefore H(z) = \sum_{k=0}^{n-1} \frac{w_k}{1 - \exp(s_k) z^{-1}}$$

# Design of IIR filter

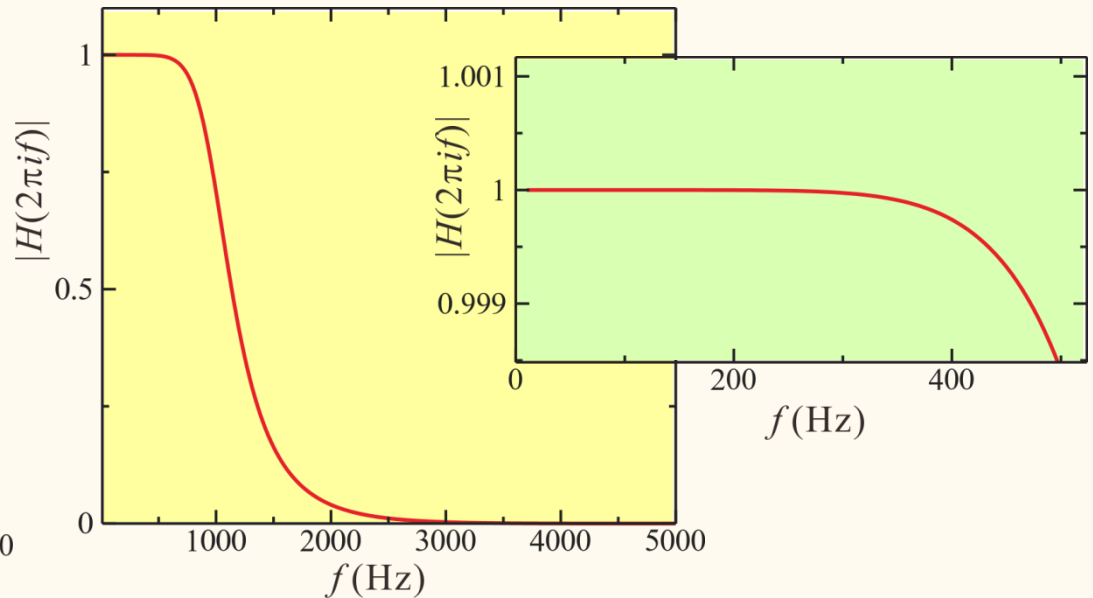
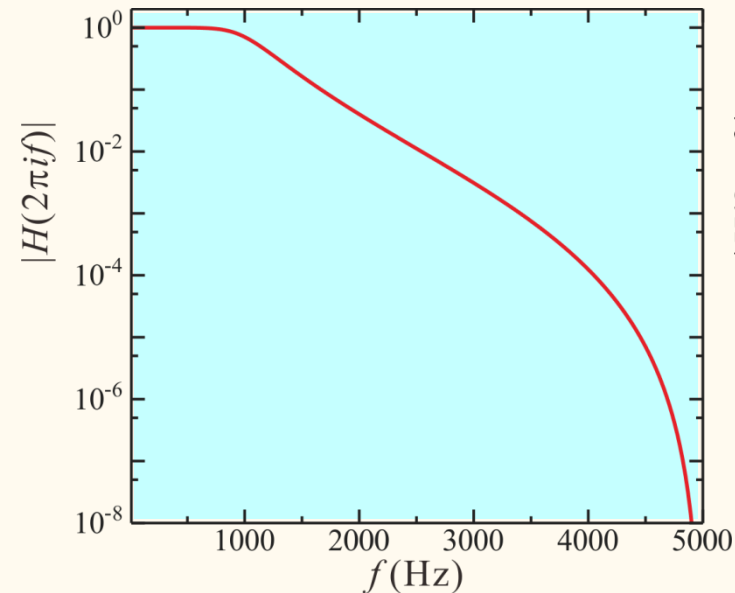
Impulse invariant method:

$$\frac{1}{s - s_k} \rightarrow \frac{1}{1 - \exp(s_k)z^{-1}}$$

Bilinear z-transform (双一次z变换法):  $s \rightarrow \frac{1 - z^{-1}}{1 + z^{-1}}$

4<sup>th</sup> Butterworth:

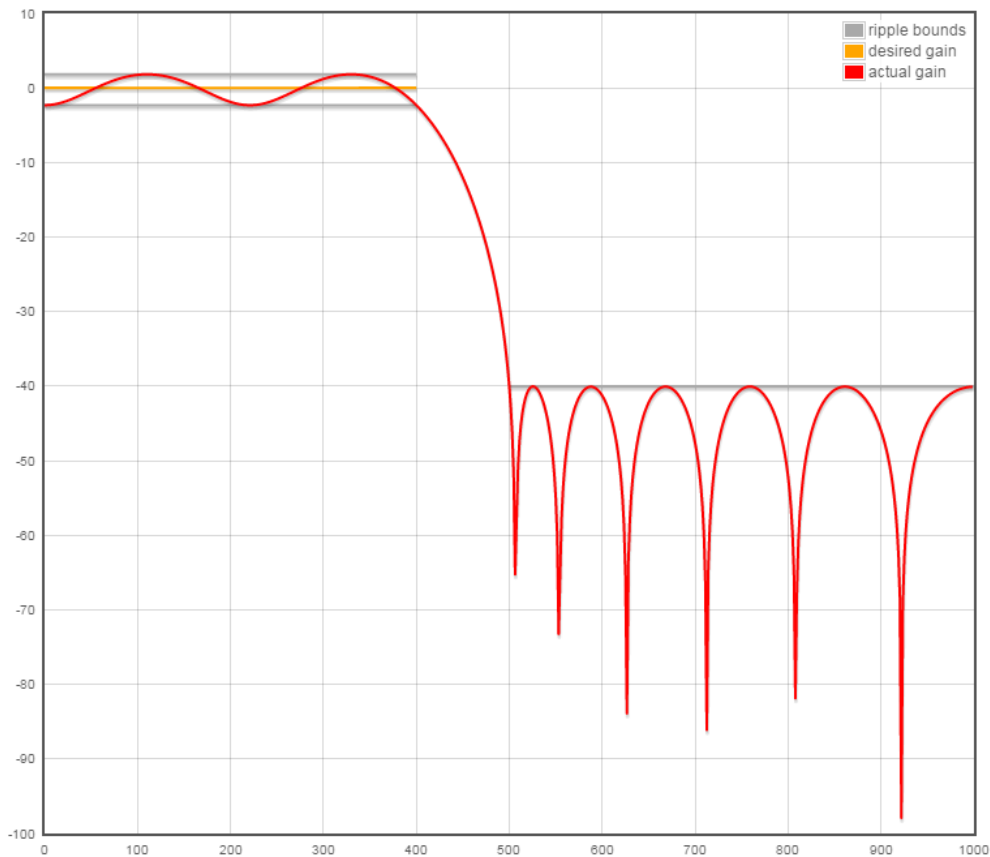
$$H(z) = \frac{b_0 + b_1z^{-1} + b_2z^{-2} + b_3z^{-3} + b_4z^{-4}}{1 - a_1z^{-1} - a_2z^{-2} - a_3z^{-3} - a_4z^{-4}}$$



# Digital filter design web application

<http://t-filter.engineerjs.com/>

Gain vs. Frequency   Impulse Response   Source Code   Feature Request   Enterprise   IIR Design



Legend:   
 - ripple bounds (grey)   
 - desired gain (yellow)   
 - actual gain (red)

```
-0.02010411882885732  
-0.05842798004352509  
-0.061178403647821976  
-0.010939393385338943  
0.05125096443534972  
0.033220867678947885  
-0.05855276971833928  
-0.08565500737264514  
0.063379599605449  
0.310854403656636  
0.4344309124179415  
0.310854403656636  
0.063379599605449  
-0.08565500737264514  
-0.05855276971833928  
0.033220867678947885  
0.05125096443534972  
-0.010939393385338943  
-0.061178403647821976  
-0.05842798004352509  
-0.02010411882885734
```

Buy me a beer   Tweet

Copyright © 2011 Peter Isza

add passband   add stopband   predefined

from	to	gain	ripple/att.	act. rpl
0 Hz	400 Hz	1	5 dB	4.14 dB
500 Hz	1000 Hz	0	-40 dB	-40.07 dB

sampling freq. 2000 Hz  
desired #taps minimum  
actual #taps 21

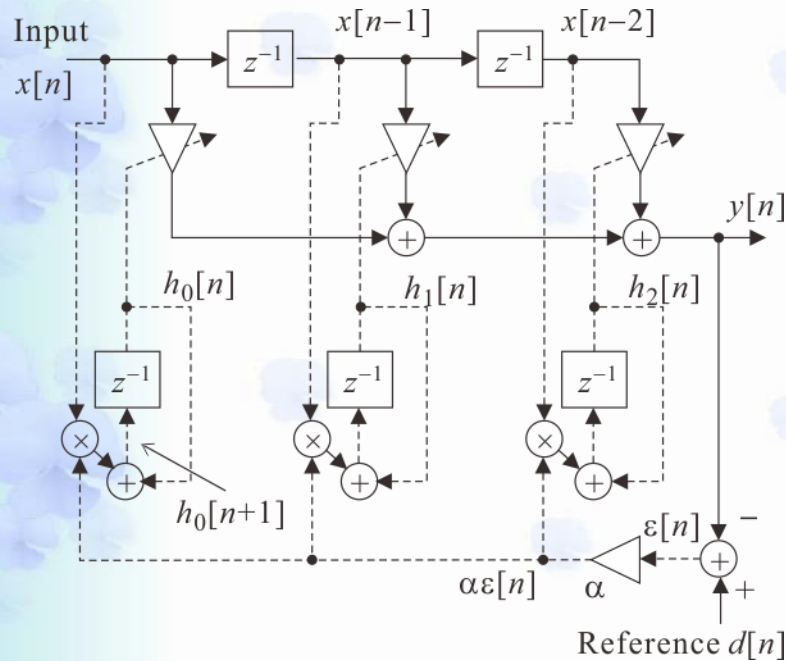
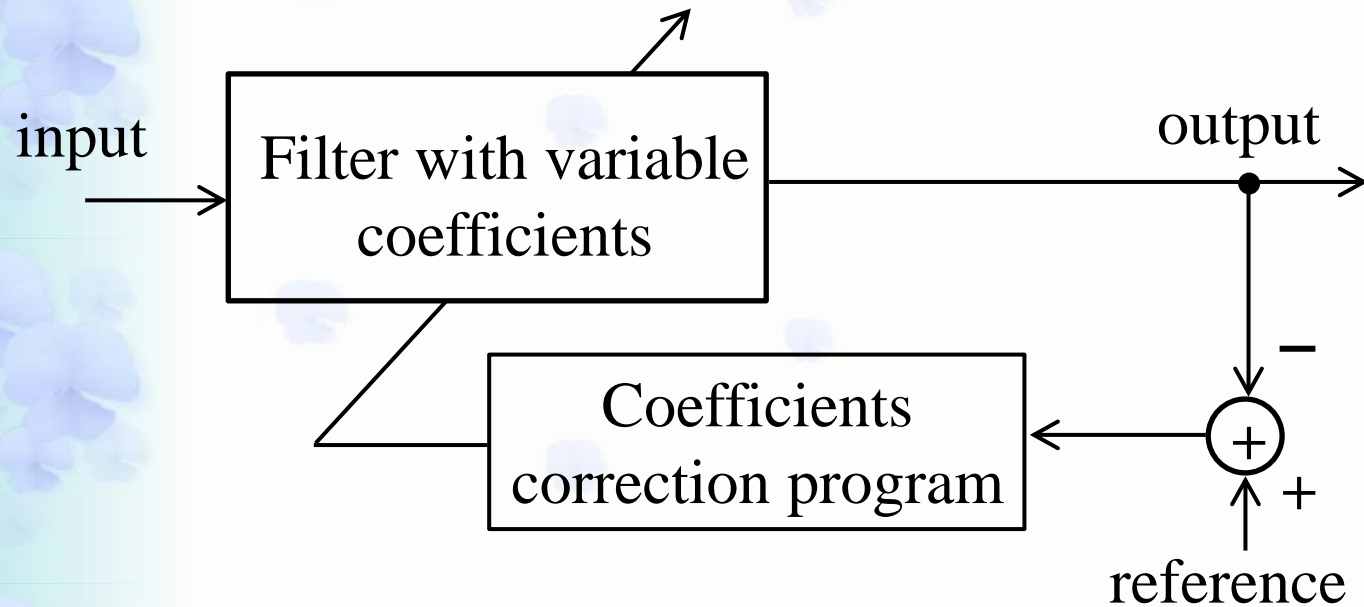
**DESIGN FILTER**

I am working on **TFilter2**. Screenshot here.

- CIC (Sinc) filters - faster than FIR for decimation
- the effect of quantization (fixed point) shown
- save/load/share configuration
- resampling, aliasing visualized
- signal chain

Buy me a beer to support the developer

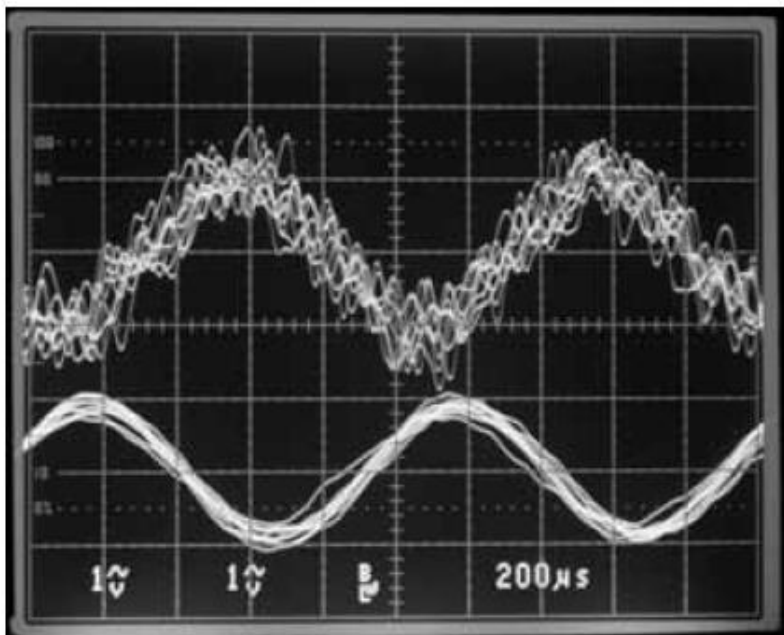
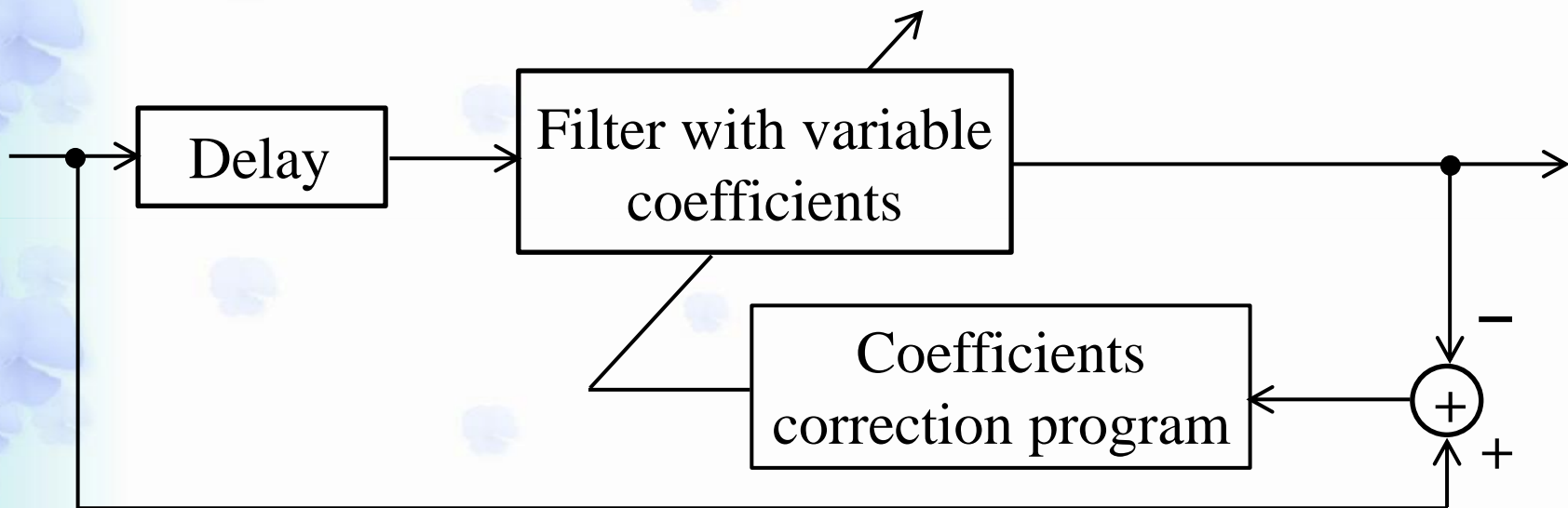
# Adaptive filter



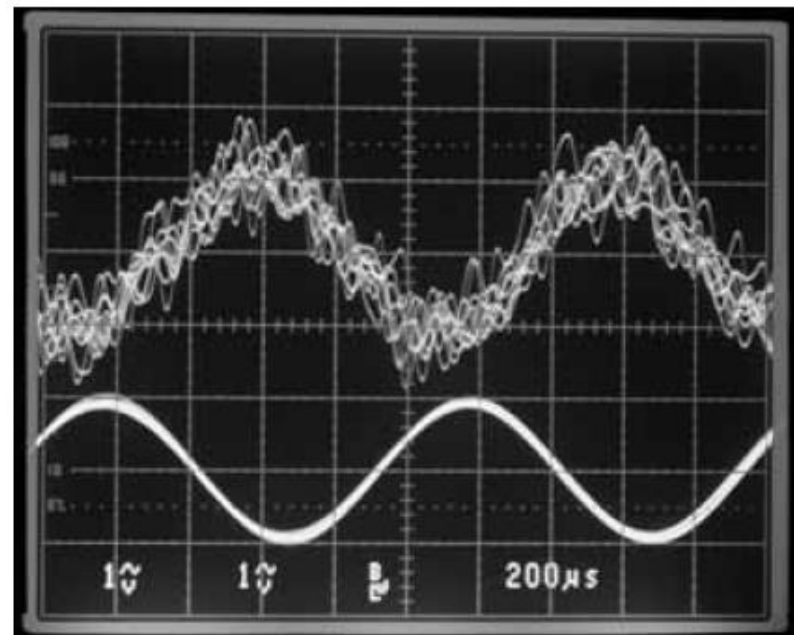
Least mean square method:

$$h_k[l + 1] = h_k[l] + 2\alpha\epsilon[l]x[l - k]$$

# Adaptive filter (adaptive line enhancer)



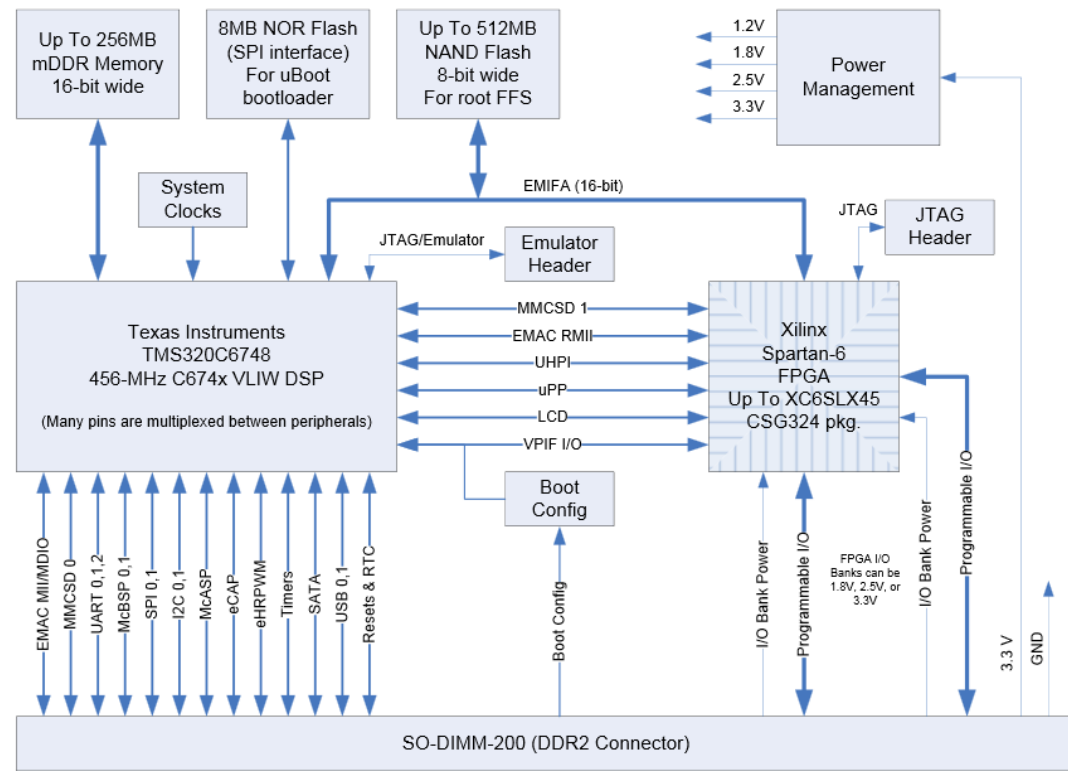
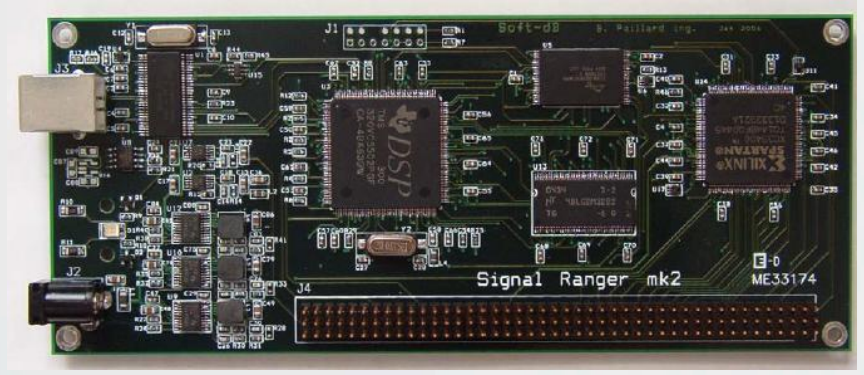
(a)  $\mu = 1 \times 10^{-3}$  の場合



(b)  $\mu = 1 \times 10^{-5}$  の場合

# Digital filter implementation

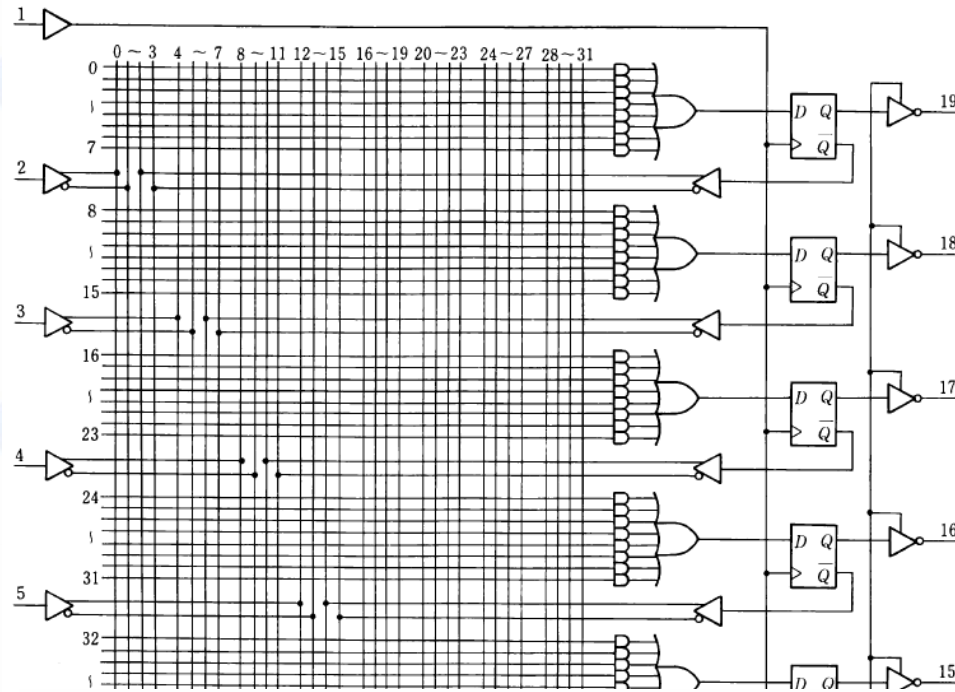
## Digital signal processing (DSP) board



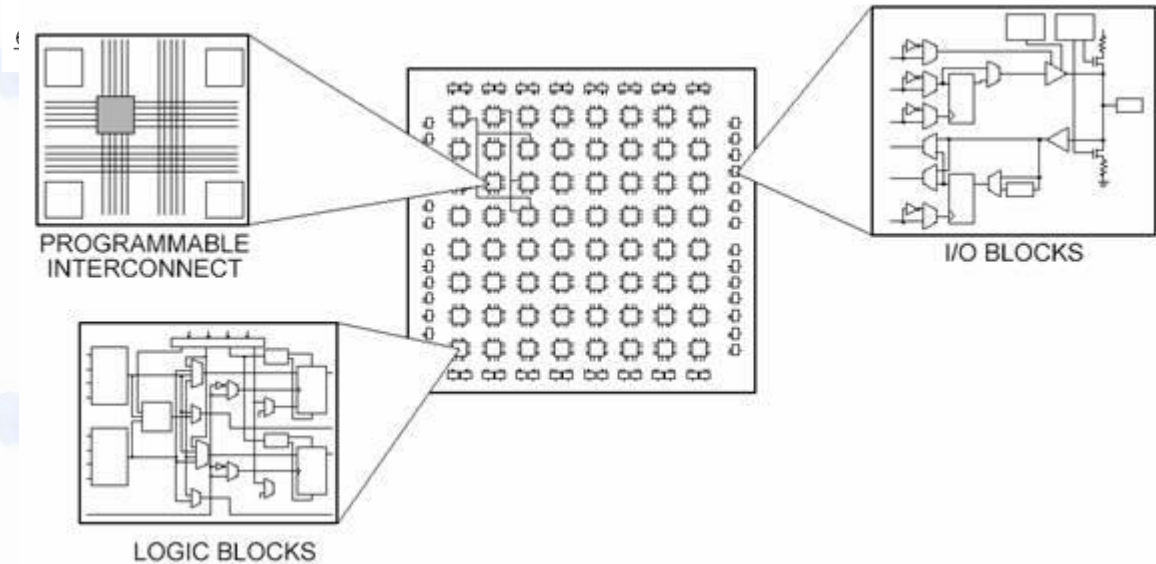


# PLD/FPGA with HDL

Example of programmable logic device (PLD) circuit



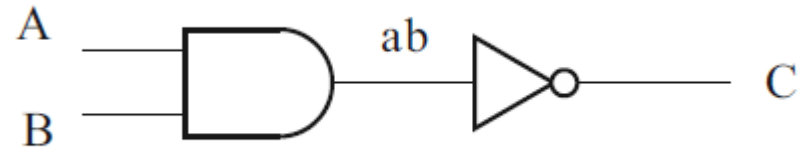
Example of field-programmable gate array (FPGA) circuit



FPGA  $\in$  PLD

# Hardware description language, HDL

```
-- Library declaration -----  
library IEEE;  
use IEEE, STD_LOGIC_1164.ALL;  
-- Entity declaration -----  
entity NAND_CIRCUIT is  
port(  
  A : in std_logic;  
  B : in std_logic;  
  C : out std_logic  
);  
end NAND_CIRCUIT;  
-- Architecture declaration -----  
architecture RTL of NAND_CIRCUIT is  
  signal ab : std_logic;  
begin  
  ab <= A and B;  
  C <= not ab;  
end RTL;
```



RTL: register transfer level

Cf. SPICE

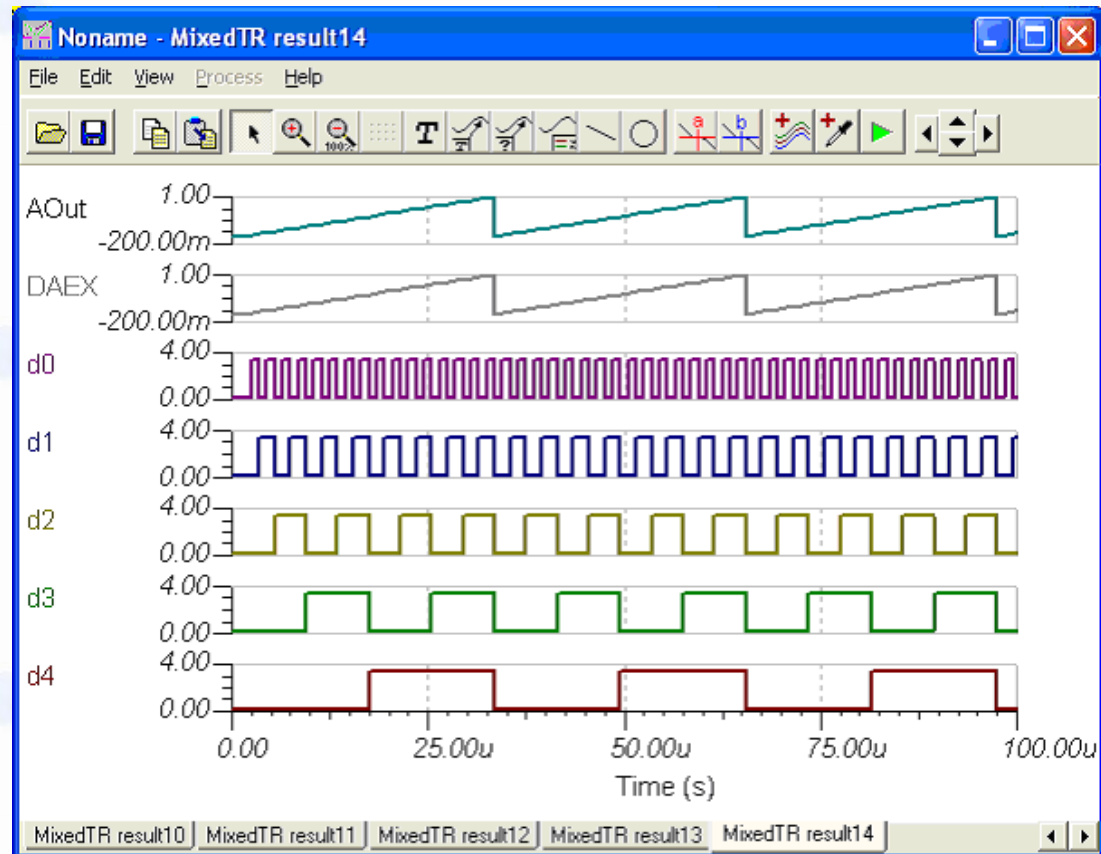
# Spice+HDL mixed circuit simulation

Easier logic circuit design

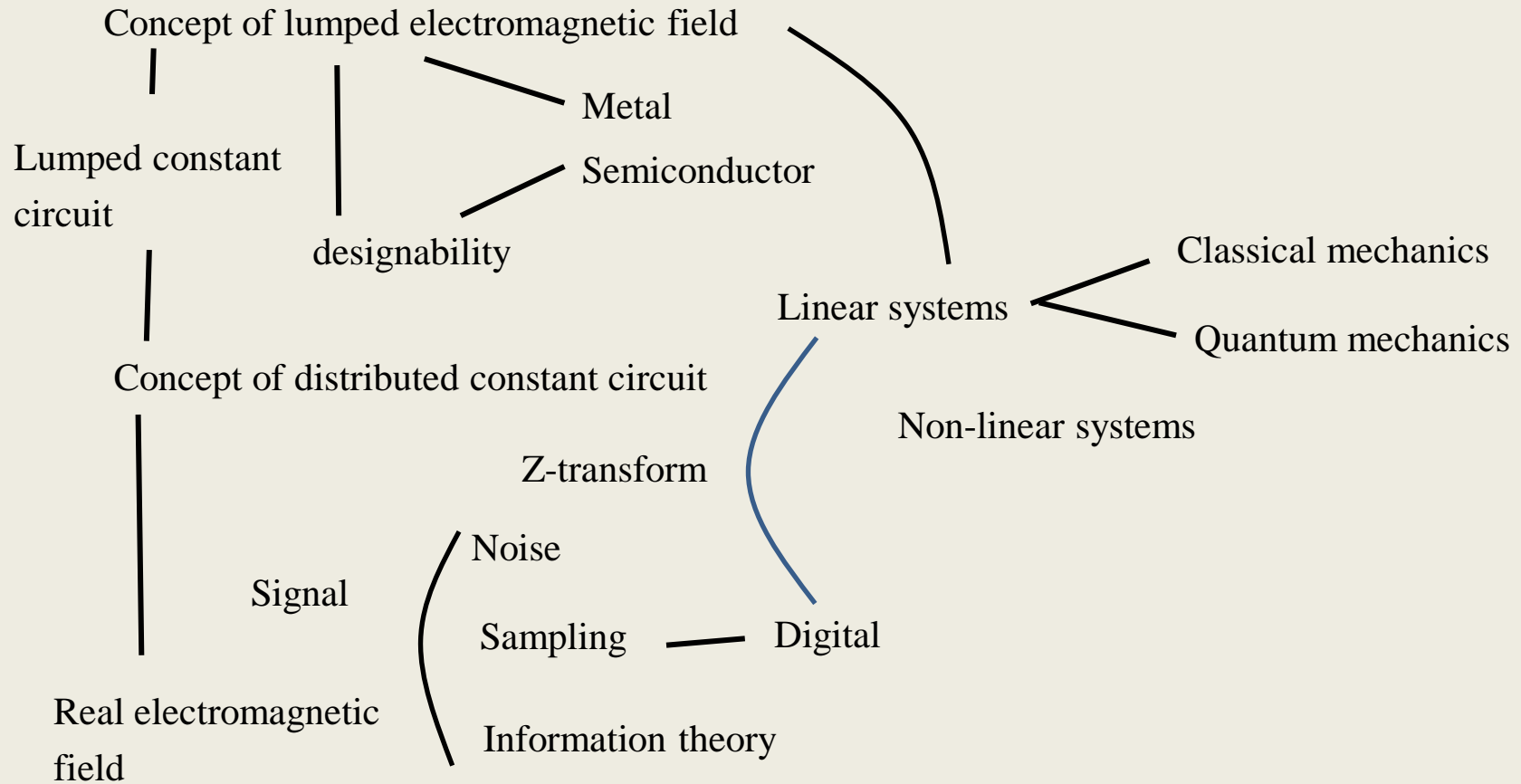
Polyphony: Python  $\rightarrow$  Verilog HDL <http://www.sinby.com/PolyPhony/index.html>

C-to-Hardware compiler (CHC) [http://anvil.co.jp/?page\\_id=296](http://anvil.co.jp/?page_id=296)

Mixed circuit simulation

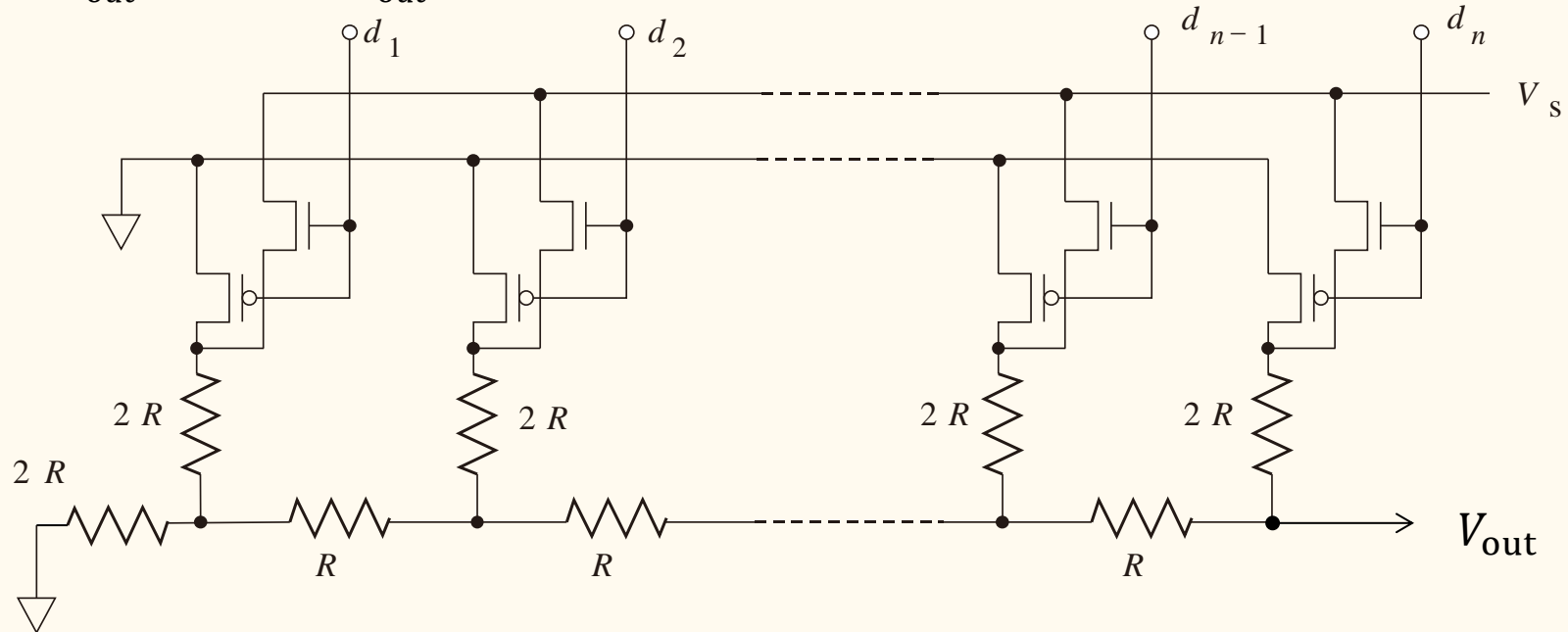


## Electric Circuits: Treasury of Languages and Concepts

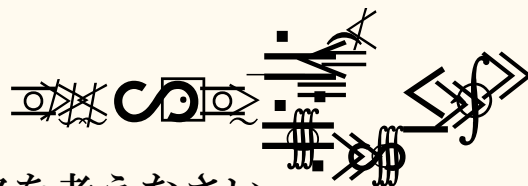


# 電子回路論レポート問題: 1. DA変換回路

(1) 次の図のような抵抗ラダー型DA変換回路を考える。講義で扱ったものと端の処理だけが違っている。この回路に2進数列 $\{d_k\}$  ( $k = 1, \dots, n$ )が入力されたとき、出力電圧 $V_{out}$ を求めよ。 $V_{out}$ は、高入力インピダンスアンプで受けるものとする。



(2) 手元に、 $\{R_0/2^k\}$  ( $k=0, \dots, n$ )の抵抗値列を持つ抵抗、抵抗値 $R_f$ の抵抗、OPアンプ、電圧 $V_s$ の標準電源、 $n+1$ 個の $n$ チャンネルMOSスイッチ、同じく $n+1$ 個の $p$ チャンネルMOSスイッチがある。これらを使って、2進数列 $\{d_k\}$ が入力された時に



を出力するDA変換器回路を考えなさい。

# 電子回路レポート問題 : 1. DA変換回路

(3) (2) と同様、に手元に、 $\{2^k C_0\}$  ( $k=0, \dots, n$ )の抵抗値列を持つキャパシタ、電圧 $V_S$ の標準電源、 $n+1$ 個の $n$ チャンネルMOSスイッチ、同じく $n+1$ 個の $p$ チャンネルMOSスイッチがある。これらを使って、2進数列 $\{d_k\}$ が入力された時に

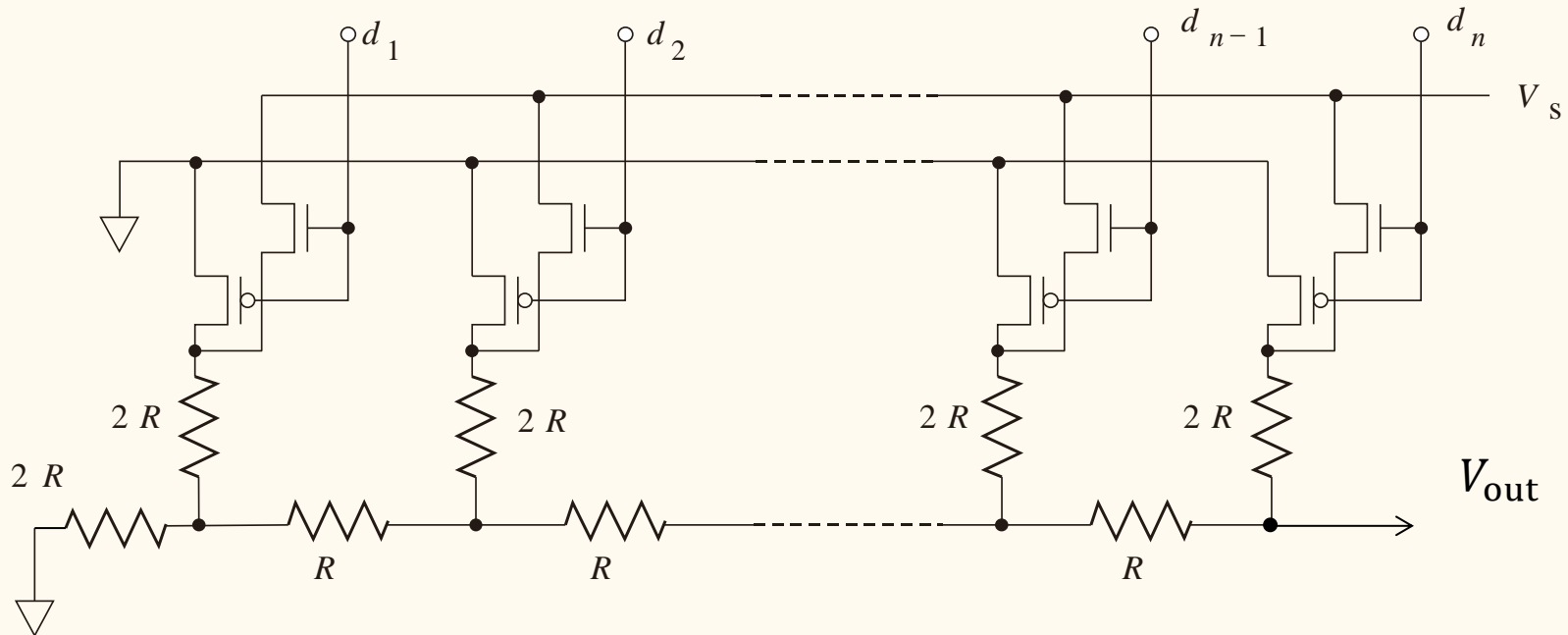
$$V_{\text{out}} = \frac{V_S}{2^{n+1} - 1} \sum_{k=0}^n d_k 2^k$$

という出力が得られるようなDA変換回路を考えなさい。ただし、出力は入力インピダンスが高くバイアス電流が無視できるような増幅器で受けることとする。



# Problems for the final report: 1. DA conversion circuits

(1) Let us consider the following resistance ladder DA conversion circuit. The right end is a bit different from the one we treated in the lecture. Calculate the output voltage  $V_{\text{out}}$  for the input  $\{d_k\}$  ( $k = 1, \dots, n$ ).



(2) We have resistors with values  $\{R_0/2^k\}$  ( $k = 0, \dots, n$ ), and  $R_f$ , an OP amp., a standard voltage source of the voltage  $V_S$ ,  $n + 1$  n-channel MOS switches,  $n + 1$  p-channel MOS switches. With these components, design a DA conversion circuit which has the output

$$V_{\text{out}} = -V_S \frac{R_f}{R_0} \sum_{k=0}^n d_k 2^k \quad \text{for the binary input } \{d_k\}.$$

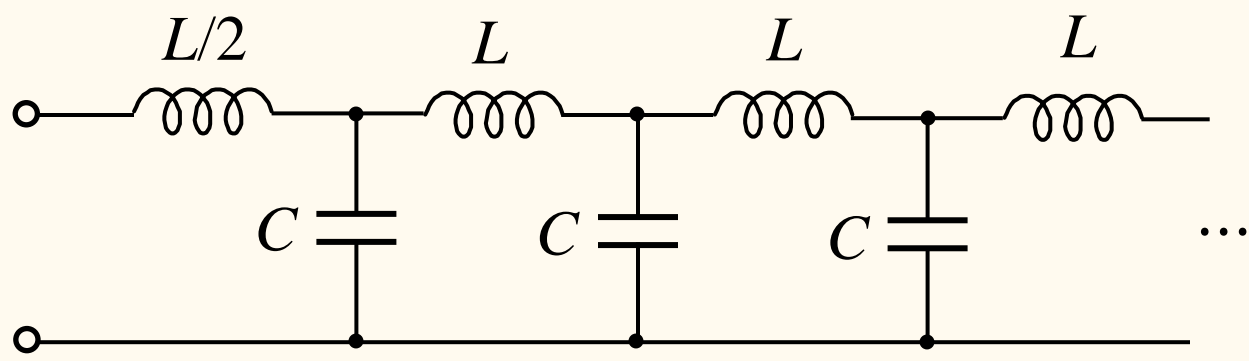
# Problems for the final report: 1. DA conversion circuits

(3) We have capacitors with values  $\{2^k C_0\}$  ( $k = 0, \dots, n$ ), a standard voltage source of the voltage  $V_S$ ,  $n + 1$  n-channel MOS switches,  $n + 1$  p-channel MOS switches. With these components, design a DA convertor circuit which has the output

$$V_{\text{out}} = \frac{V_S}{2^{n+1} - 1} \sum_{k=0}^n d_k 2^k$$

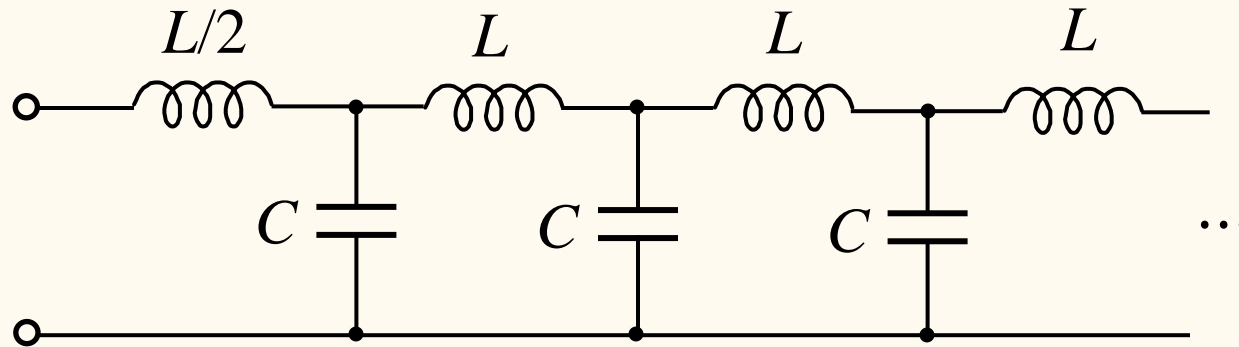
for the binary input  $\{d_k\}$ .

# 電子回路論レポート問題：2. 分布定数回路



上図のように，端のインダクタンス $L/2$ を除いて $L$ と $C$ が無限に繰り返す回路がある．この回路の，周波数軸上での透過域と減衰域を求めよ．また，左の端子から見たインピーダンスの周波数特性(周波数 $\omega$ に対するインピーダンス)を求めよ．

## Problems for the final report: 2. Distributed constant circuit



Consider the above circuit with  $L$ ,  $C$  infinite repetition to the right and the inductor  $L/2$  at the left end. Obtain the transmission range and the attenuation range in the frequency domain. And what is the total impedance from the left end for the frequency  $\omega$ .

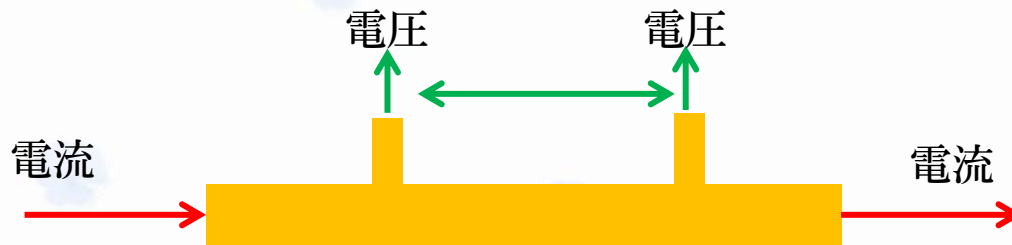
# 電子回路論レポート問題：3. OPアンプ回路

次のような回路部品がある。

高精度OPアンプ・・・4個

定電圧ダイオード(逆方向に電圧を印加するとツェナートンネルにより一定電圧を発生する) 2.5V・・・1個

これらを使って、低温で試料の電気抵抗を測定するための回路を構成しなさい。試料は下の図のように、電流端子、電圧端子が別に出た構造をしている。



ただし、

- (a) 抵抗, キャパシタ, インダクタの類の受動素子は適当に追加してよい。
- (b) OPアンプの電源を供給するためのトラッキング電源は準備されているものとする。
- (c) 測定抵抗の範囲は $100\Omega \sim 10\text{k}\Omega$ で、接触抵抗を含めて $50\text{k}\Omega$ 以内である。
- (d) OPアンプのオフセット電圧, バイアス電流は無視できるとする。従ってオフセット調整回路を入れる必要はない。

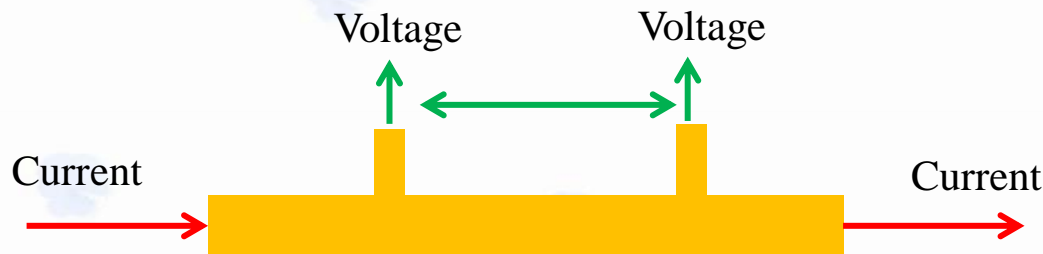
# Problems for the final report: 3. OP amp. circuit

We have the following components:

4 high precision operational amplifiers,

1 high precision Zener tunnel diode with the constant voltage 2.5V (this diode provide precise 2.5V for the reverse bias).

With these components, design a circuit to measure the electric resistance of a sample at low temperatures. The shape of the sample is shown below:



(a) You can add any passive elements (resistors, capacitors, inductors).

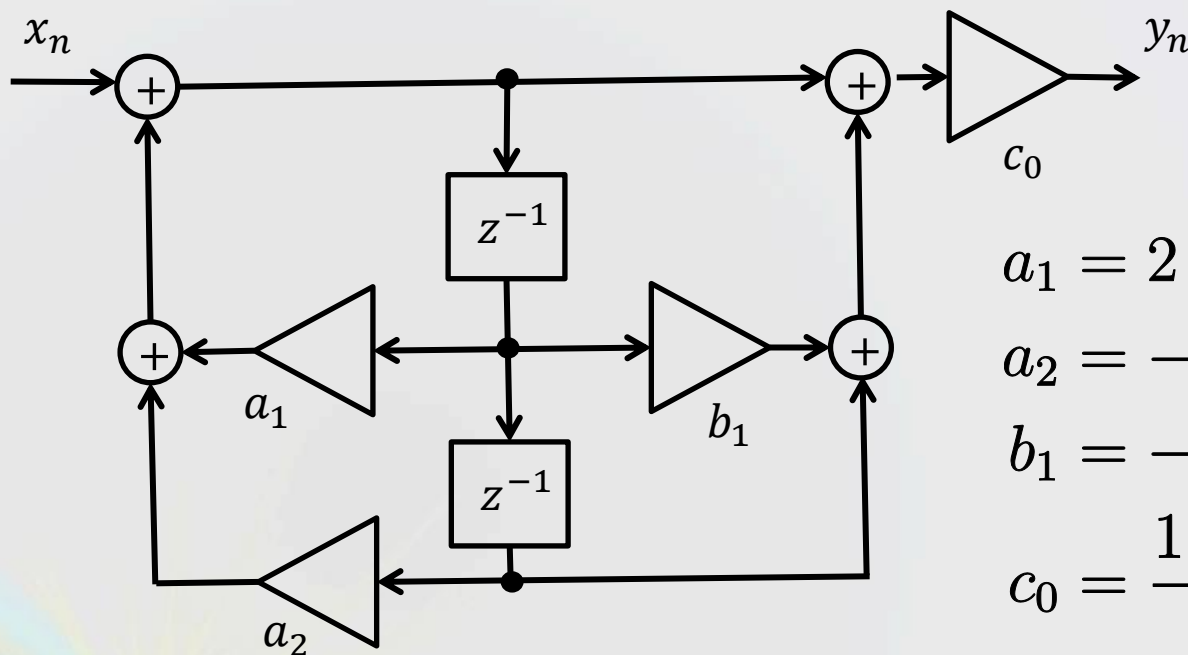
(b) The power supply for the OP amps. is ready.

(c) The sample resistance range is from  $100\Omega$  to  $10\text{k}\Omega$ , lower than  $50\text{k}\Omega$  including the contact resistance.

(d) The offset voltages, the bias currents of the OP amps. can be ignored. No need for the offset cancellation circuit.



# 電子回路論レポート問題:4. デジタル・フィルタ



$$a_1 = 2 \exp(-\pi g_0 \tau) \cos(2\pi f_0 \tau)$$

$$a_2 = -\exp(-2\pi g_0 \tau)$$

$$b_1 = -2 \cos(2\pi f_0 \tau)$$

$$c_0 = \frac{1 - a_1 - a_2}{2 + b_1}$$

- (1) 上のブロックダイアグラムから，出力 $y_n, y_{n-1}, y_{n-2}$ と入力 $x_n, x_{n-1}, x_{n-2}$ との関係式を示せ。
- (2) 係数 $a_1, a_2, b_1, c_0$ が右上のような関係を満たすとき，このフィルタはどのような周波数特性を示すか．ただし， $g_0 < f_0 < f_s/2$  (サンプリング周波数)を満たすとする．(  $20g_0 = 10f_0 = f_s$  としてグラフを描いてみよ． )



# 電子回路論レポート問題: 5 離散フーリエ変換

<http://kats.issp.u-tokyo.ac.jp/kats/electroniccircuit/report/reportdata.txt>

に, 4096点のデータが入っている. 各行に  $x f(x)$  という形で納められており, セパレーターはTAB記号 (ASCII番号9番)である.

このデータは, ある特定の周波数で励起した出力を取ったもので, 信号は特定の周波数成分で応答する. ただし, その振幅は完全に一定とは限らない.

(1) 離散フーリエ変換 (現実的には高速フーリエ変換, FFTをかけることになると思われる)を施し, パワースペクトルの主ピークから信号の周波数を特定せよ.

(2) 特定の窓 (幅 256点程度が適当)を使って部分的にフーリエ変換を施し, 上で求めた周波数に最も近い周波数成分振幅を求める. 窓の位置を  $x$  が小さい位置から100点刻み程度に動かし, 各点での振幅を窓位置に対してプロットせよ.

解答のみ記せばよい. プログラム等を示す必要はない.

# Problems for the final report: 5 Discrete Fourier Transform

<http://kats.issp.u-tokyo.ac.jp/kats/electroniccircuit/report/reportdata.txt>

contains data of 4096 points. Each line has a point in the form  $x \ f(x)$ .  
The separator between  $x$  and  $f(x)$  is TAB (ASCII No.9).

The data are signal responding to an excitation with a particular frequency. Hence the signal has the same central frequency but the amplitude is not necessarily constant.

(1) Apply discrete Fourier transformation (DFT, practically fast Fourier transformation) to the signal and extract the central frequency from the main peak.

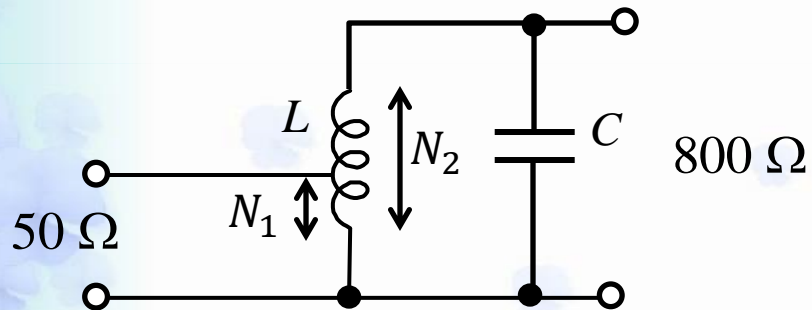
(2) Carry out DFT to a window with a shorter period (256 points is appropriate) and obtain the amplitude of the central frequency component. Shift the position of the window with a step size about 100 points. Plot the amplitude as a function of the window position.

You do not need to show your program codes for the analysis.

# 電子回路レポート問題：6 インピーダンス整合

FETを用いたアンプで信号ラインの特性インピーダンスとFETの入力インピーダンスとの間で整合を取りゲインを最大化すると、雑音も増幅され、雑音指数 (Noise figure, NF) が悪くなる。

そこで、 $50\ \Omega$  ラインの信号をFETから見たときのインピーダンスが $800\ \Omega$ 程度になるように変換する。入力は $80\ \text{MHz}$ ~ $90\ \text{MHz}$ の共鳴フィルタを構成する。



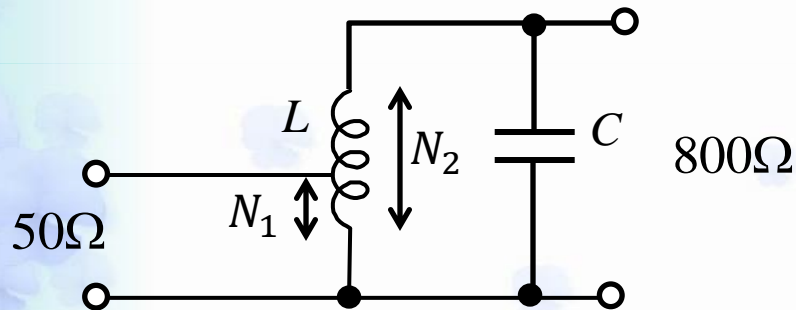
これを左図のようにコイルに中間タップを出すことで行う。全体のコイル巻き数 $N_2$ に対してタップの巻き数位置は $N_1$ とする。入力中心周波数は $85\ \text{MHz}$ 、共鳴幅(半値幅)は $10\ \text{MHz}$ とする。 $C$ と $L$ 及び $N_1$ の $N_2$ に対する比を求めよ。(有効数字3桁)

ここでは、コイルのインダクタンスは巻き数の2乗に比例するとする。



# Problems for the final report: 6 Impedance matching

In amplifiers with FETs, the noise matching condition, that optimizes the noise figure, usually deviates from the power matching one. The impedance conversion circuit shown below thus converts the transmission line characteristic impedance  $50\ \Omega$  into  $800\ \Omega$ . The input to FET also constitutes a resonance filter for 80 MHz to 90 MHz.



The coil in the left has a tap at the winding number  $N_1$  in the total winding number  $N_2$ . The central frequency of input is 85 MHz, the resonance width (peak width at half height) is 10 MHz. Calculate  $C$ ,  $L$ , and the ratio of  $N_1$  to  $N_2$ . (significant digits =3)  
Assume the inductances are proportional to squares of the winding numbers.